

Weakly Supervised Learning of Semantic Parsers for Mapping Instructions to Actions

Yoav Artzi and Luke Zettlemoyer
University of Washington

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Semantic Parsing

Show me all papers about semantic parsing



$\lambda x. paper(x) \wedge topic(x, SEMPAR)$

Less
Supervision

Answers
Demonstrations
Situated examples

More
Domains

Databases
Large knowledge-bases
Instructions
Referring expressions
Regular expressions

Later this session

Semantic Parsing

Show me all papers about semantic parsing



$\lambda x. paper(x) \wedge topic(x, SEMPAR)$

Sup
Less
More
Domains

Modeling

Situated
Parsing

Executing Navigation Instructions

place your back against the
wall of the t intersection

turn left

go forward along the pink
flowered carpet hall two
segments to the
intersection with the
brick hall

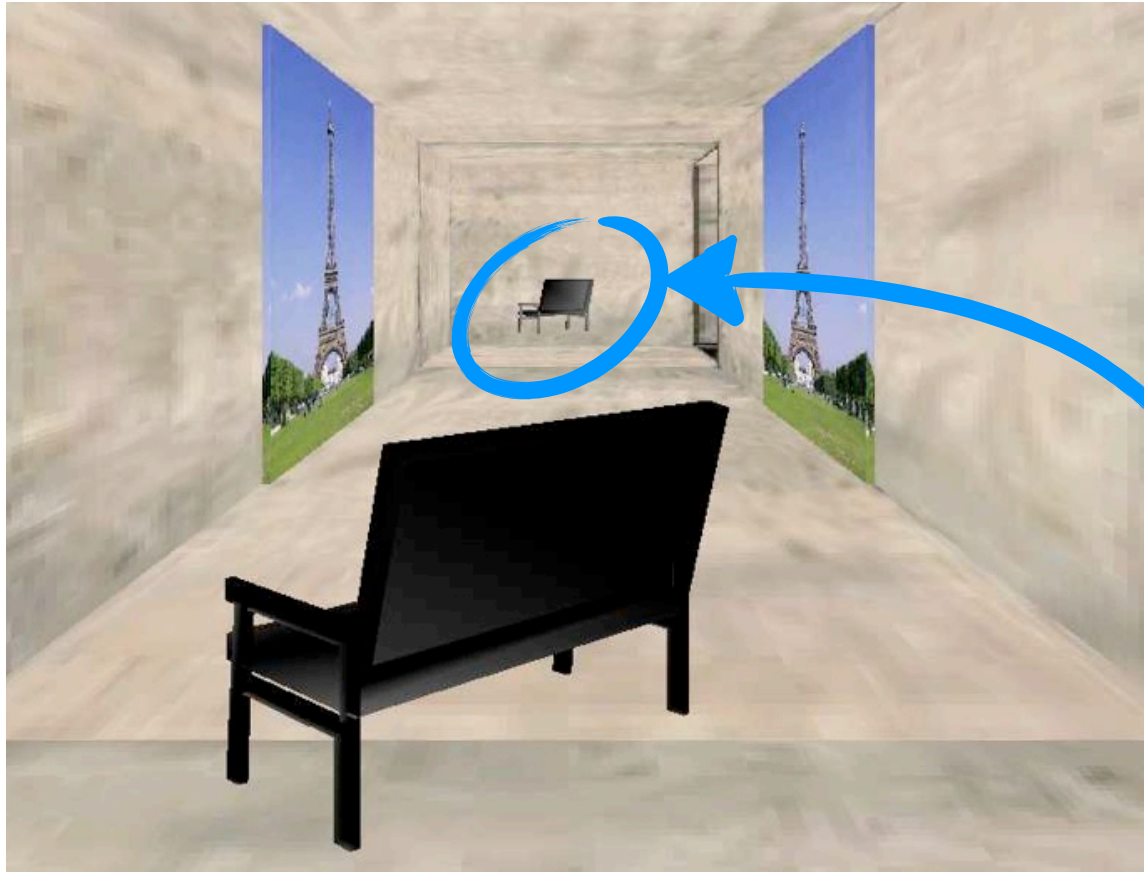


Resolve Referents



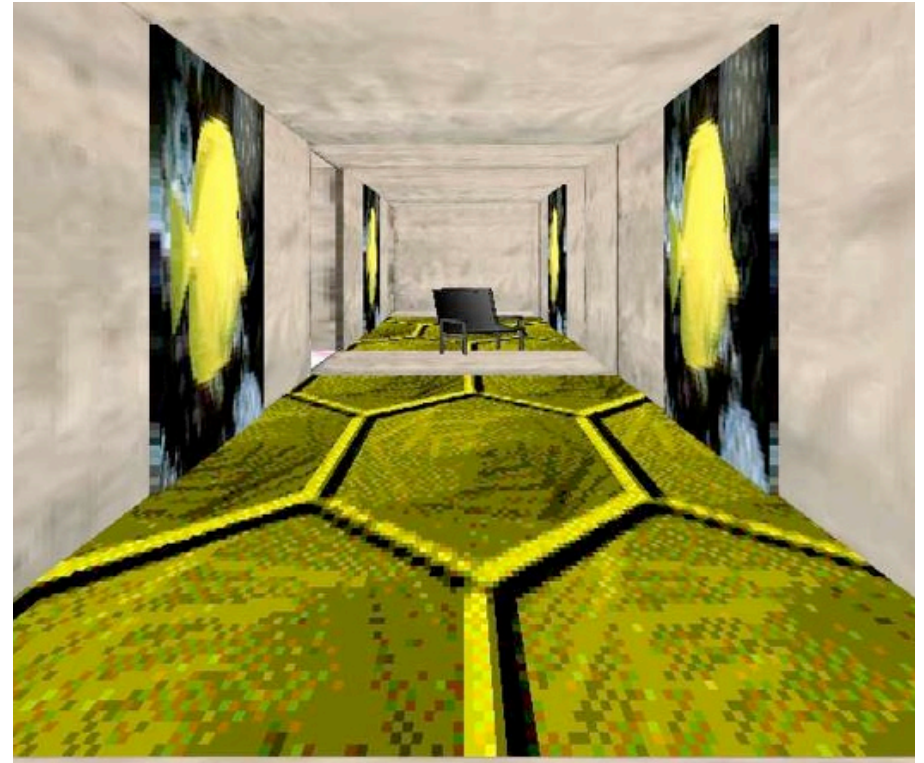
go to the next sofa

Resolve Referents



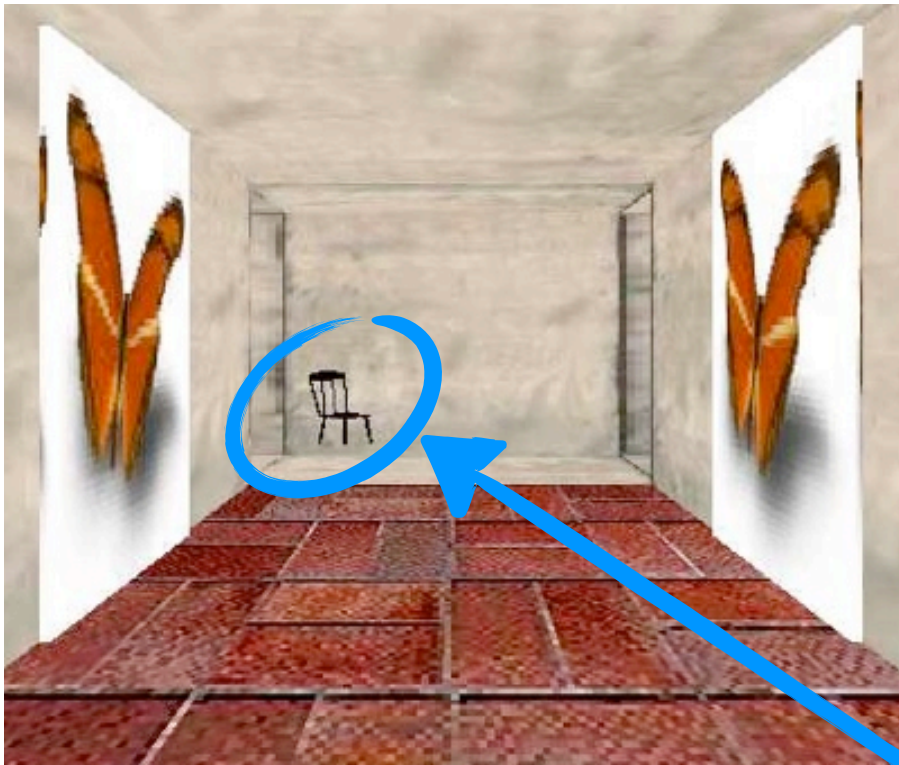
go to the next sofa

Disambiguate Word Sense



go to the chair

Disambiguate Word Sense



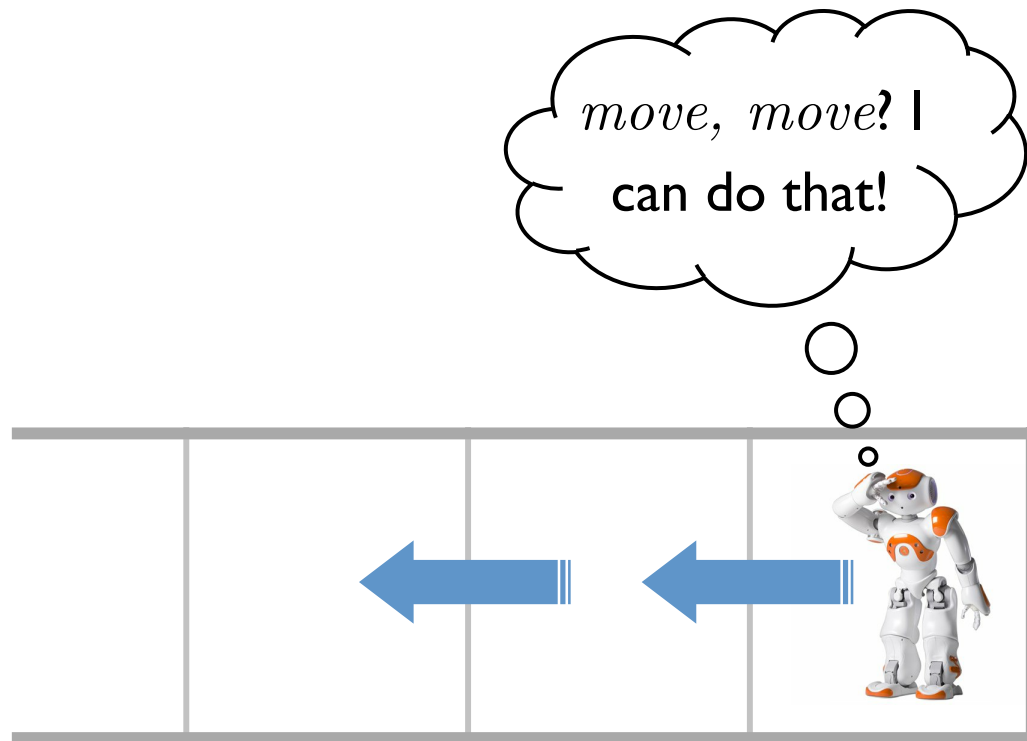
go to the chair

Identify Executable Actions



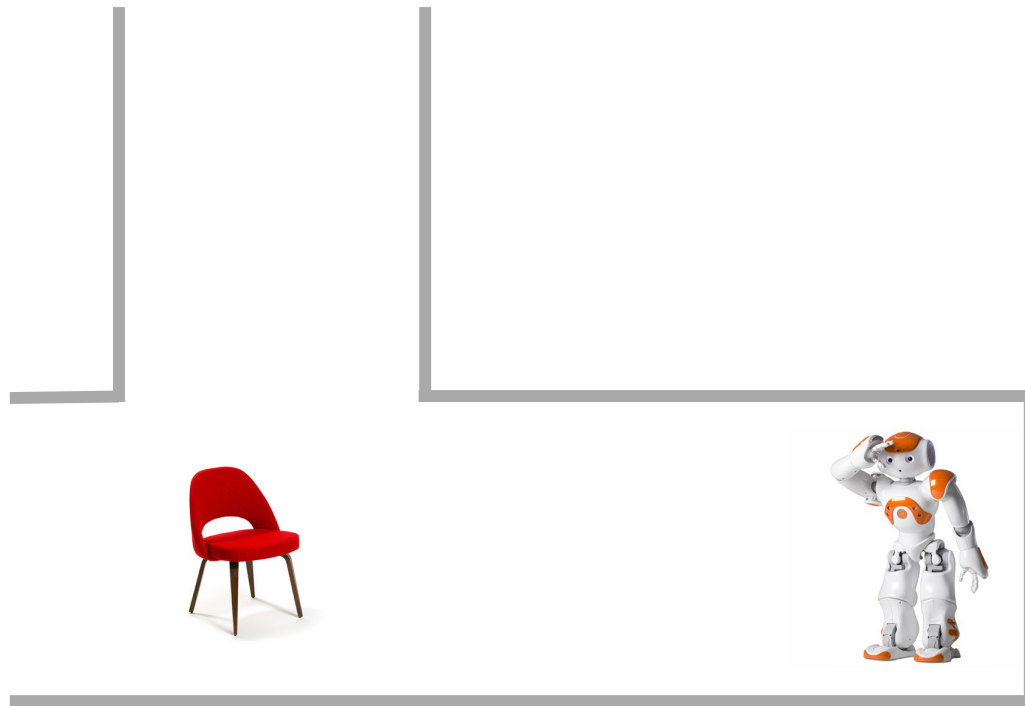
walk forward twice

Identify Executable Actions



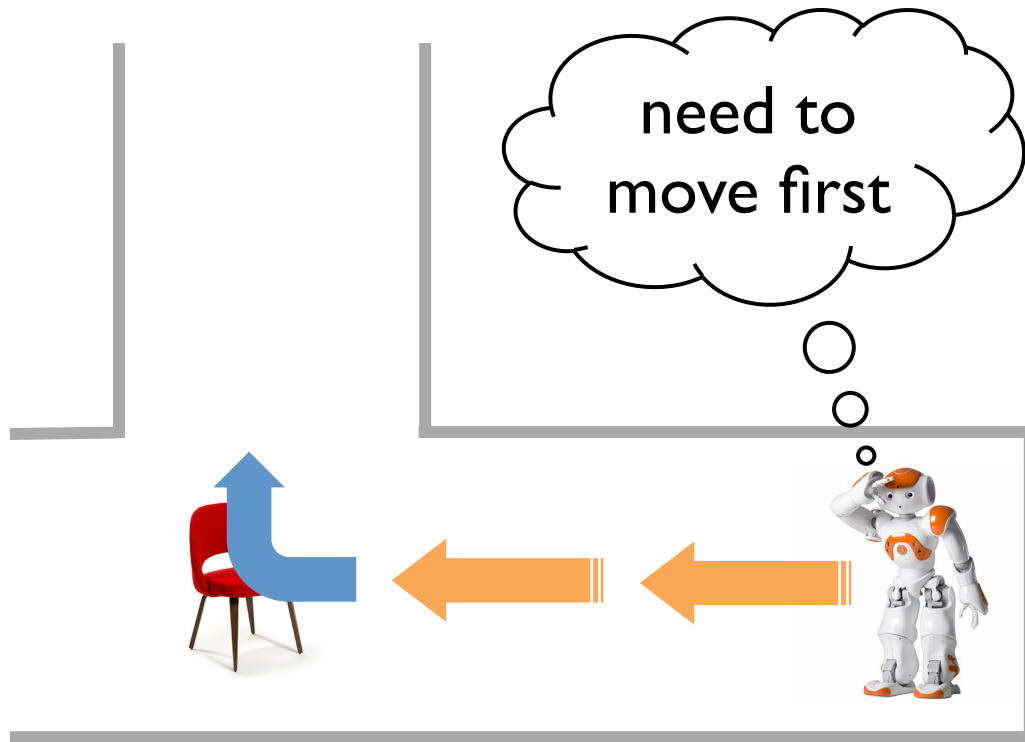
walk forward twice

Understand Implicit Requests



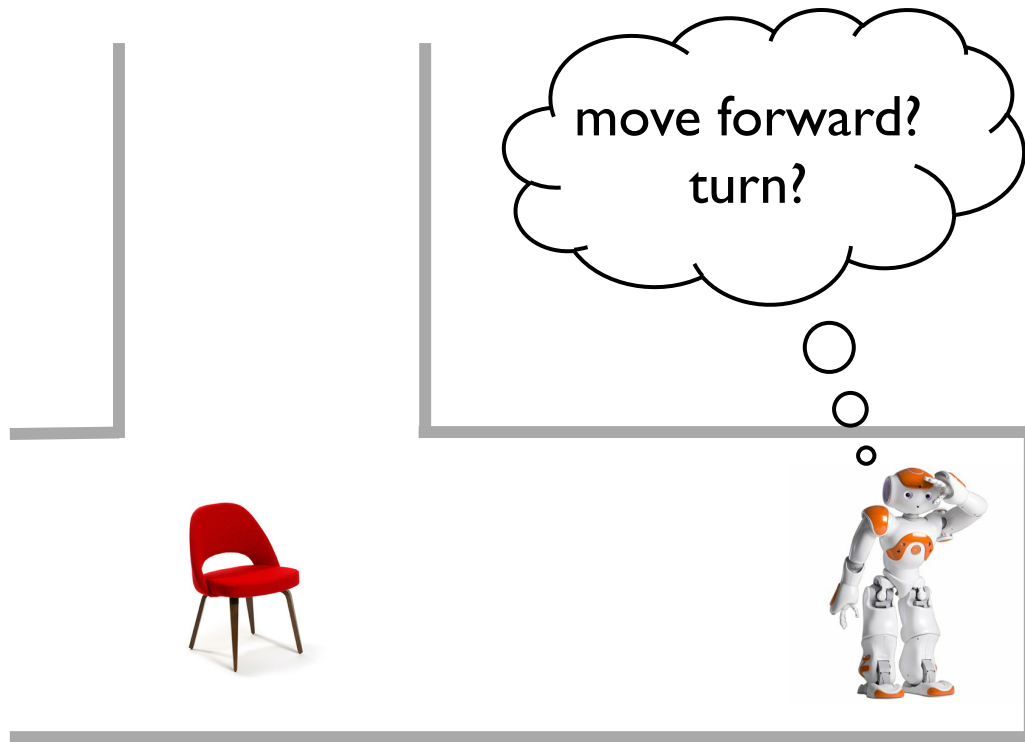
at the chair, turn right

Understand Implicit Requests



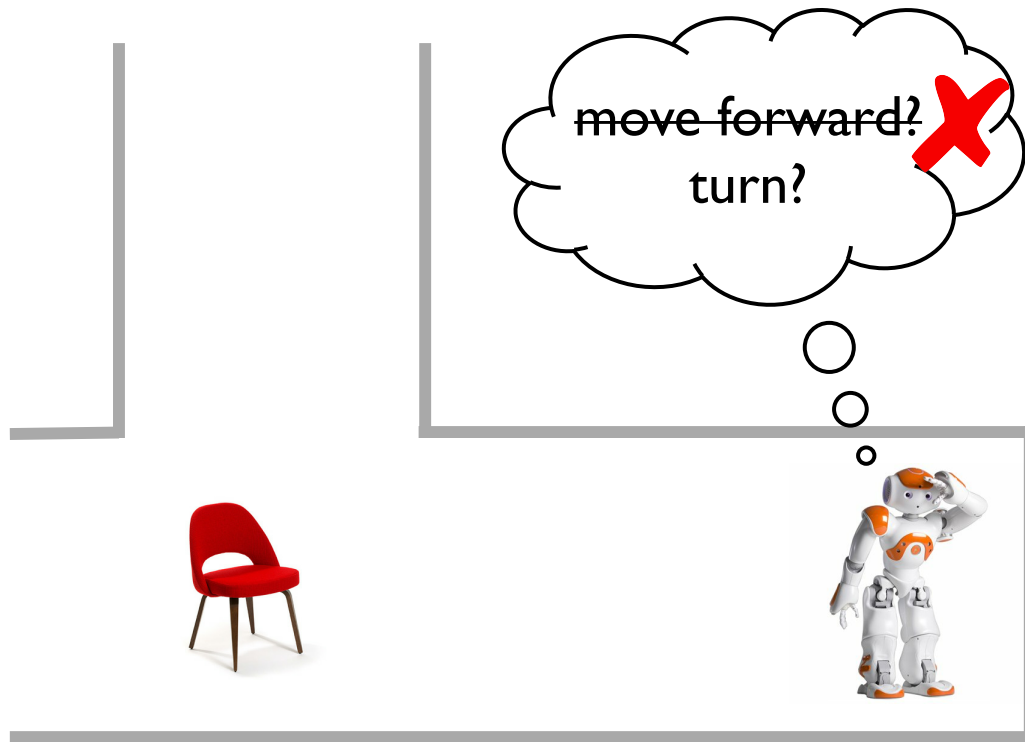
at the chair, turn right

Grounded Learning



turn to face the chair

Grounded Learning



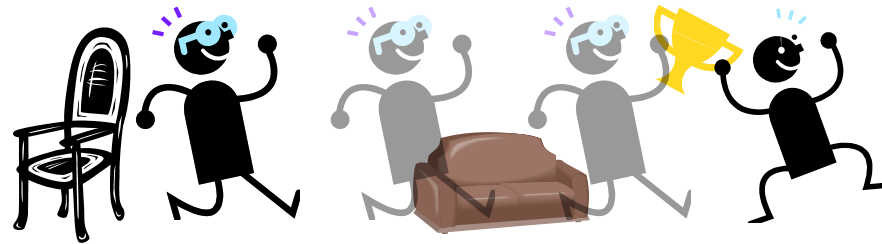
turn to face the chair

Learning Signal

Instruction:

at the chair, move forward three steps past the sofa

Demonstration:

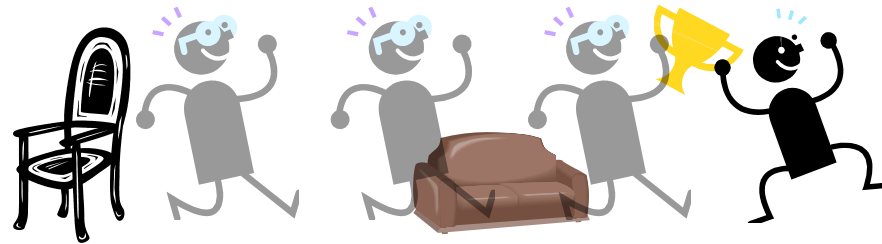


Learning Signal

Instruction:

at the chair, move forward three steps past the sofa

Demonstration:



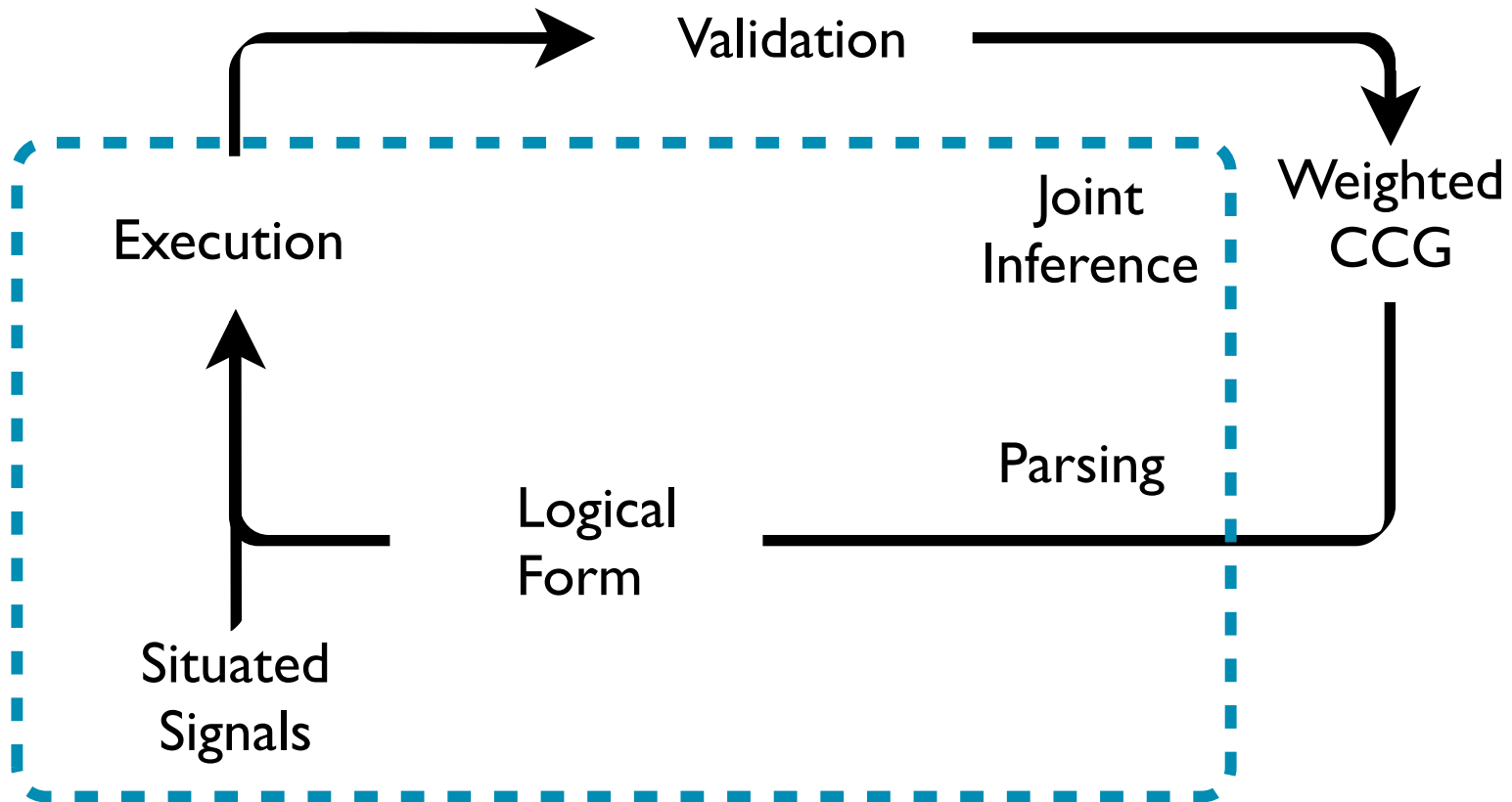
During learning: validate executions of different interpretations against demonstrations

Learning

Demonstrations

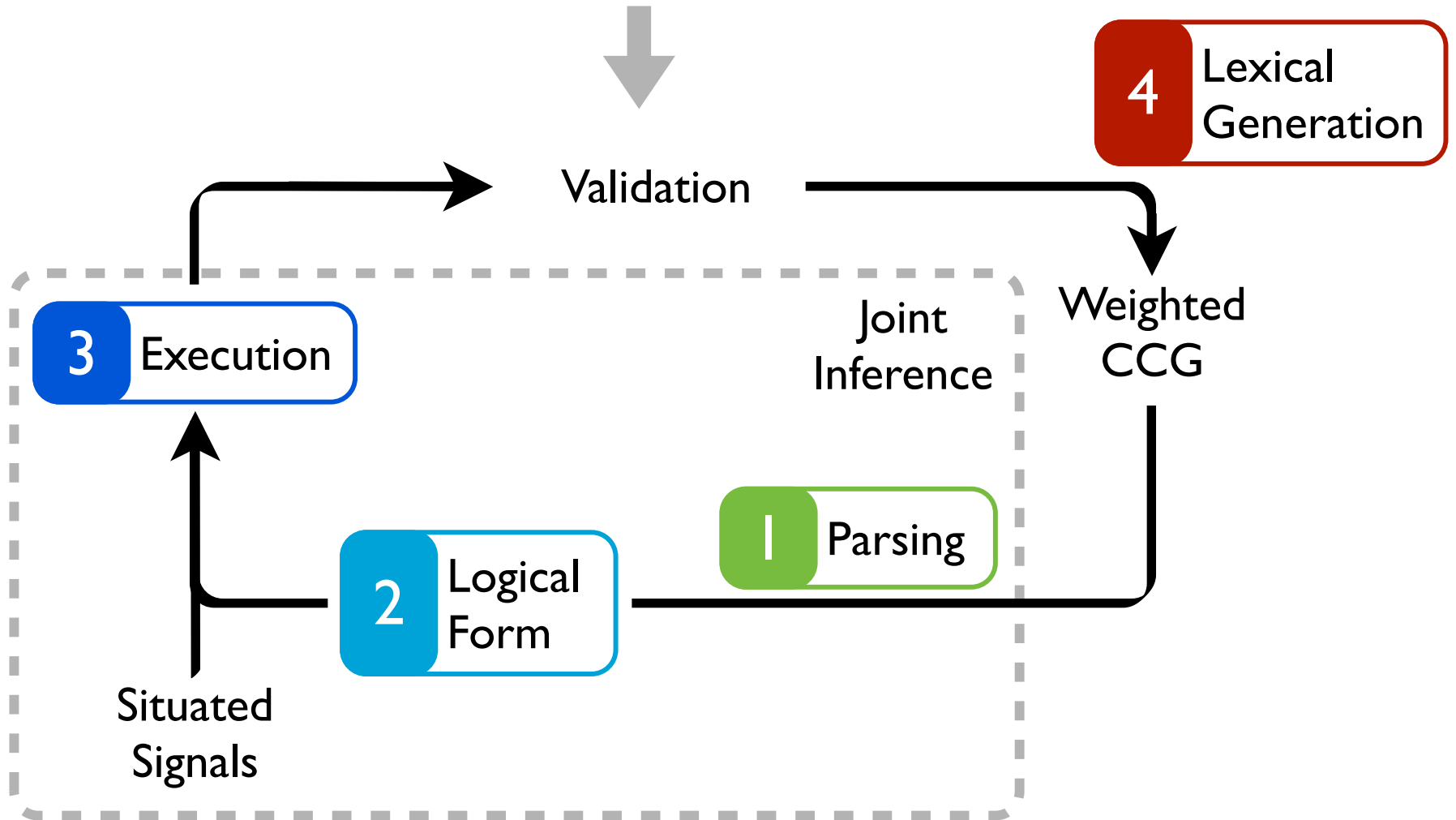


Validation



Learning

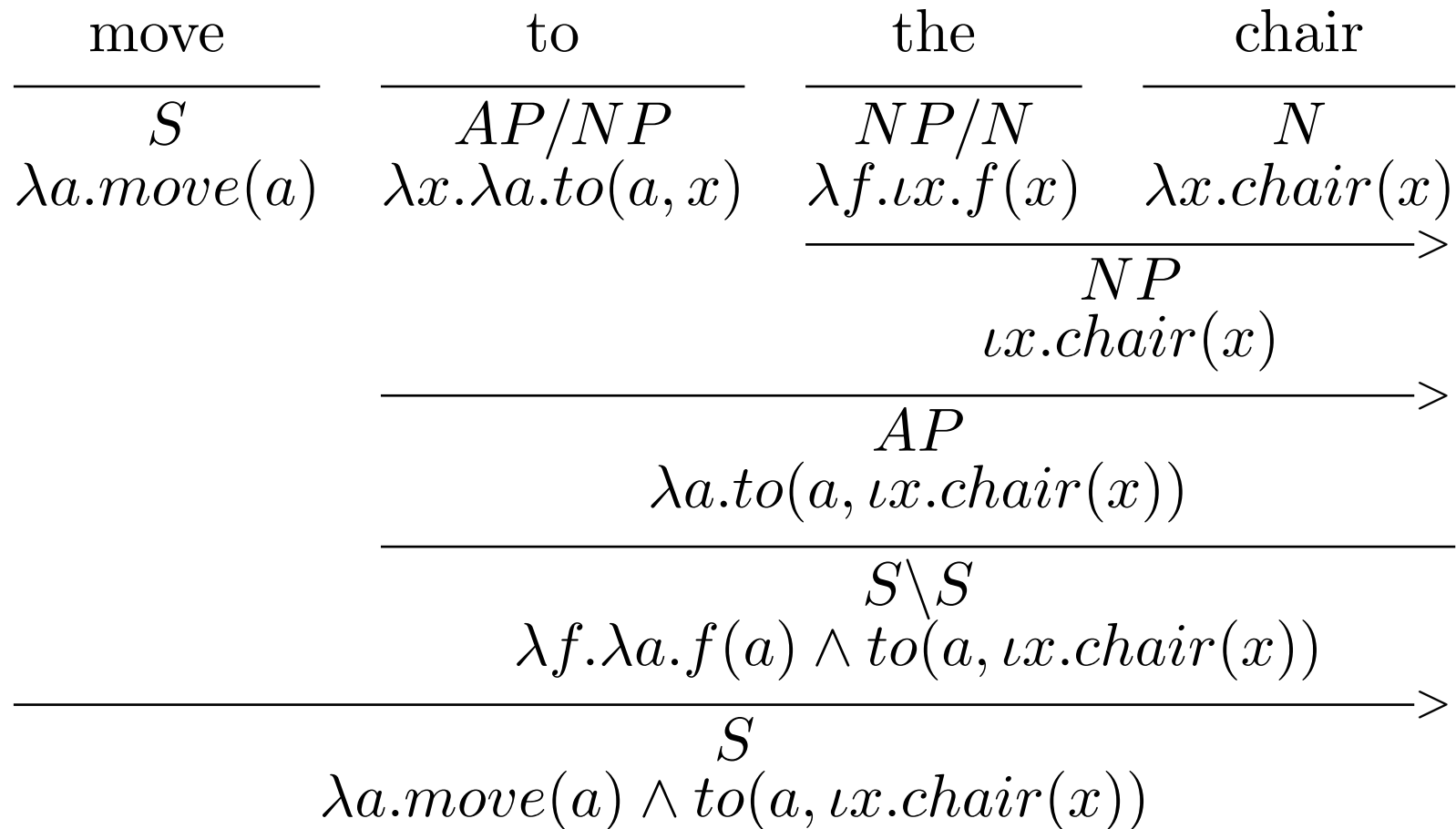
Demonstrations



Combinatory Categorical Grammars

move	to	the	chair
S	AP/NP	NP/N	N
$\lambda a.move(a)$	$\lambda x.\lambda a.to(a, x)$	$\lambda f.\iota x.f(x)$	$\lambda x.chair(x)$
		NP	
		$\iota x.chair(x)$	
		AP	
		$\lambda a.to(a, \iota x.chair(x))$	
		$S \setminus S$	
		$\lambda f.\lambda a.f(a) \wedge to(a, \iota x.chair(x))$	
		S	
		$\lambda a.move(a) \wedge to(a, \iota x.chair(x))$	

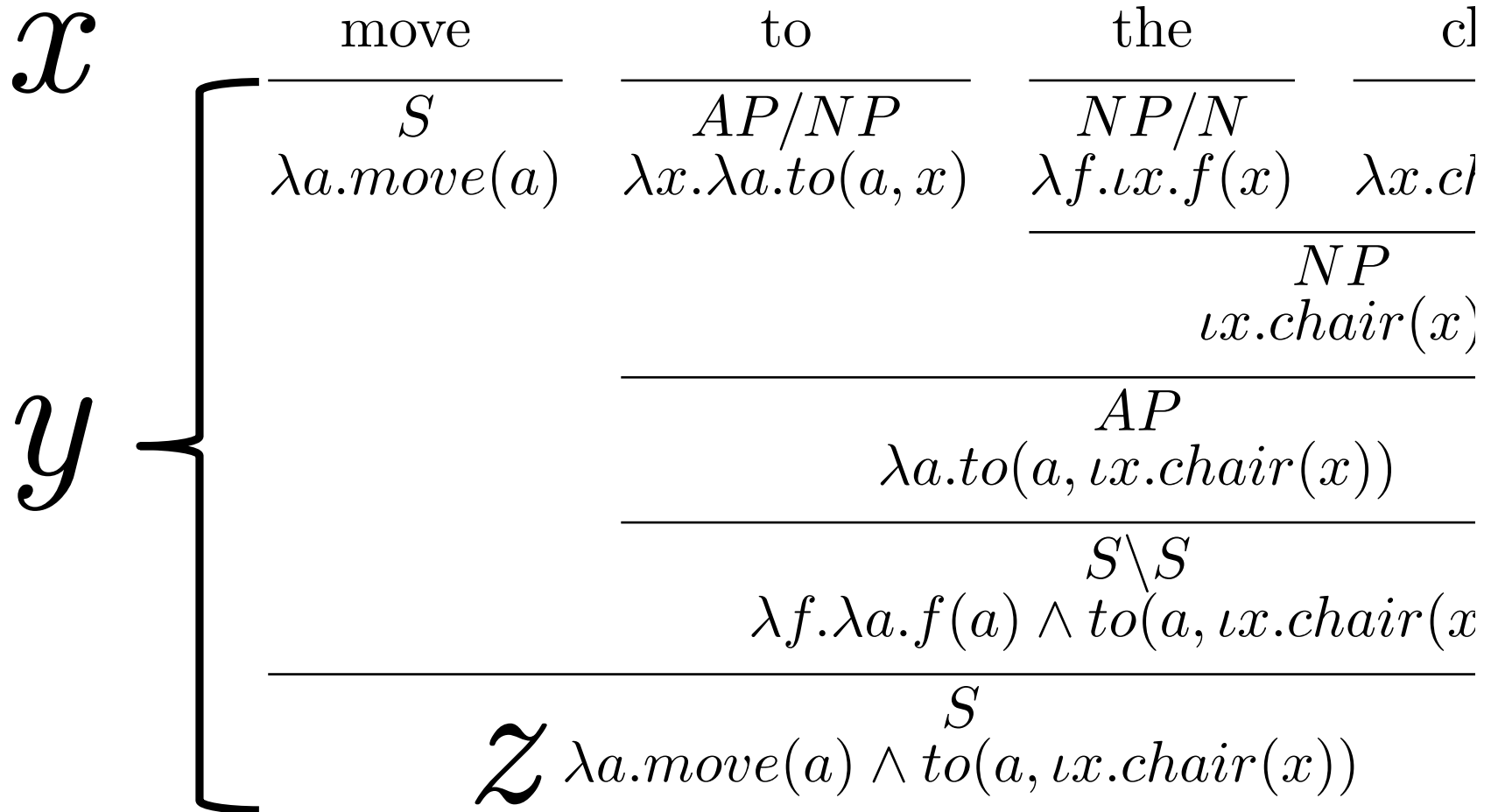
Combinatory Categorical Grammars



Lexicon

Combinators

Combinatory Categorical Grammars



Lexicon

Combinators

Weighted Linear CCGs

- Given a weighted linear model:

- CCG lexicon Λ
- Feature function $f : X \times Y \rightarrow \mathbb{R}^m$
- Weights $w \in \mathbb{R}^m$

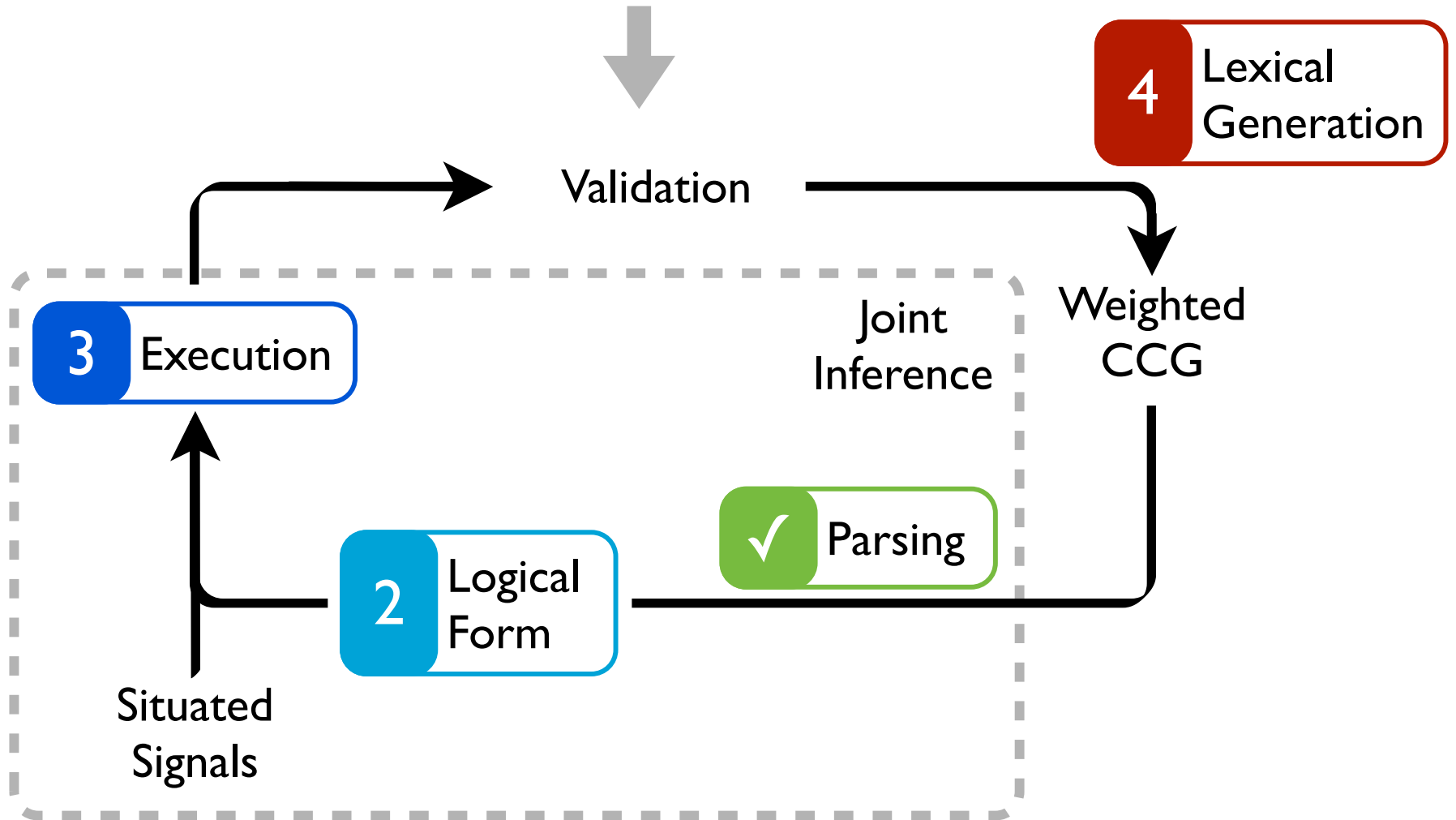
- The best parse is:

$$y^* = \arg \max_y w \cdot f(x, y)$$

- We consider all possible parses y for sentence x given the lexicon Λ

Learning

Demonstrations



Modeling for Semantic Parsing

Nouns

Sets of entities

PPs and adjectives

Constrain sets

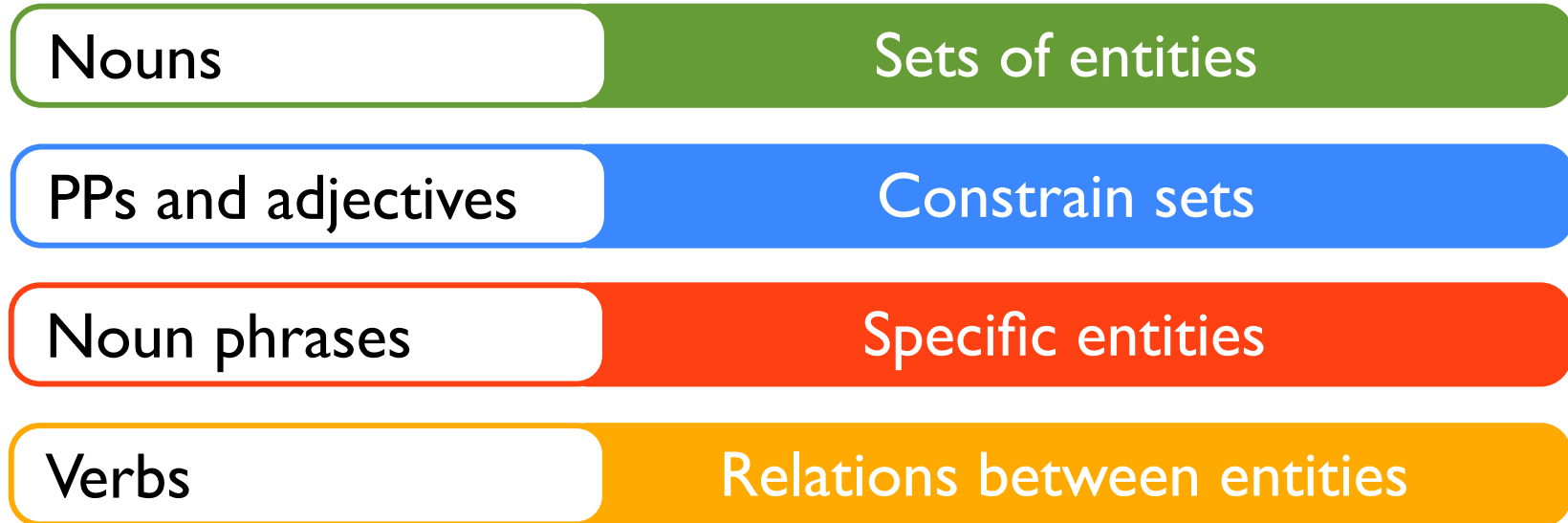
Noun phrases

Specific entities

Verbs

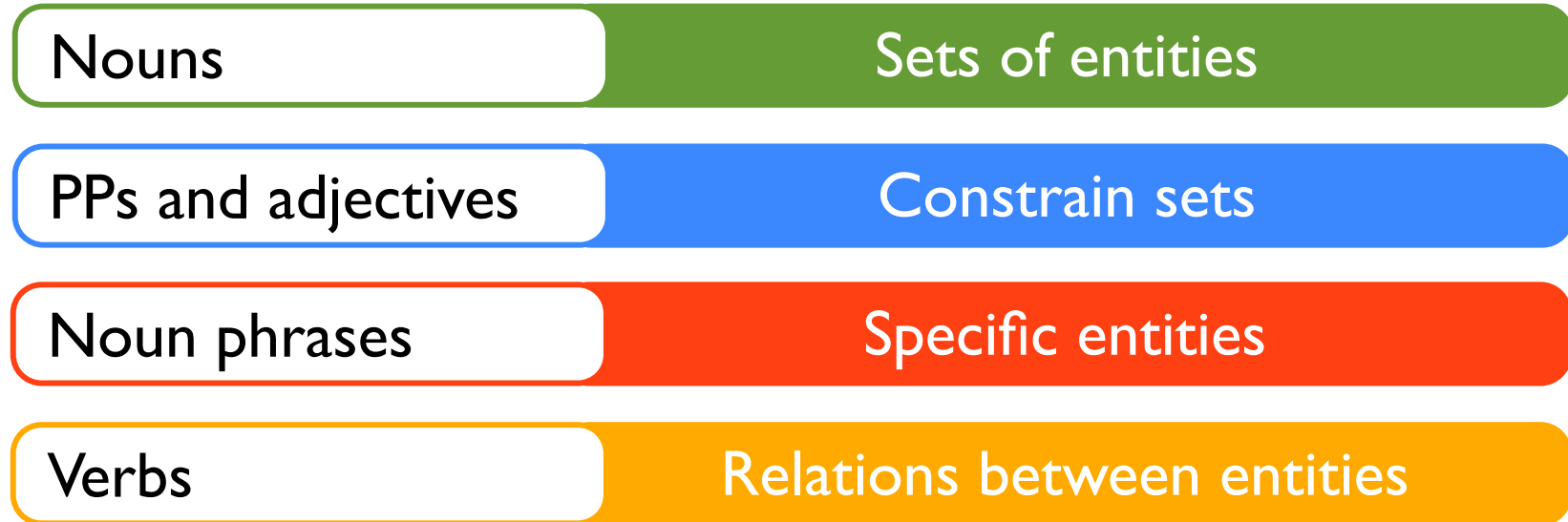
Relations between entities

Modeling for Semantic Parsing



Works well for natural language interfaces for DBs

Modeling for Semantic Parsing



Previous work on instructional language
adopted procedural representation

[Matuszek et al. 2010; 2012; Chen, Mooney 2011; Chen 2012; Kim, Mooney 2012]

Modeling for Semantic Parsing

Nouns

Sets of entities

PPs and adjectives

Constrain sets

Noun phrases

Specific entities

Verbs

Relations between entities

Previous work on instructional language
adopted procedural representation

How can we use this approach for instructions?

Modeling for Semantic Parsing

Name objects

Nouns

Sets of entities

PPs and adjectives

Constrain sets

Noun phrases

Specific entities

Instructions to execute

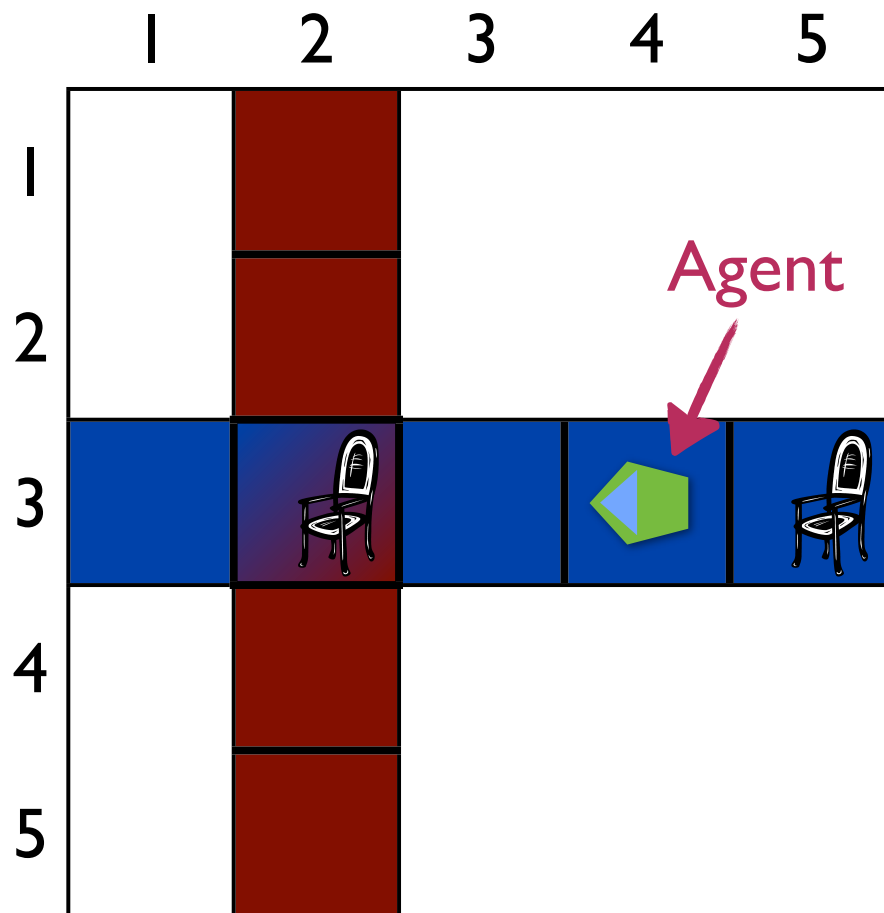
Verbs

Davidsonian Events

Imperatives

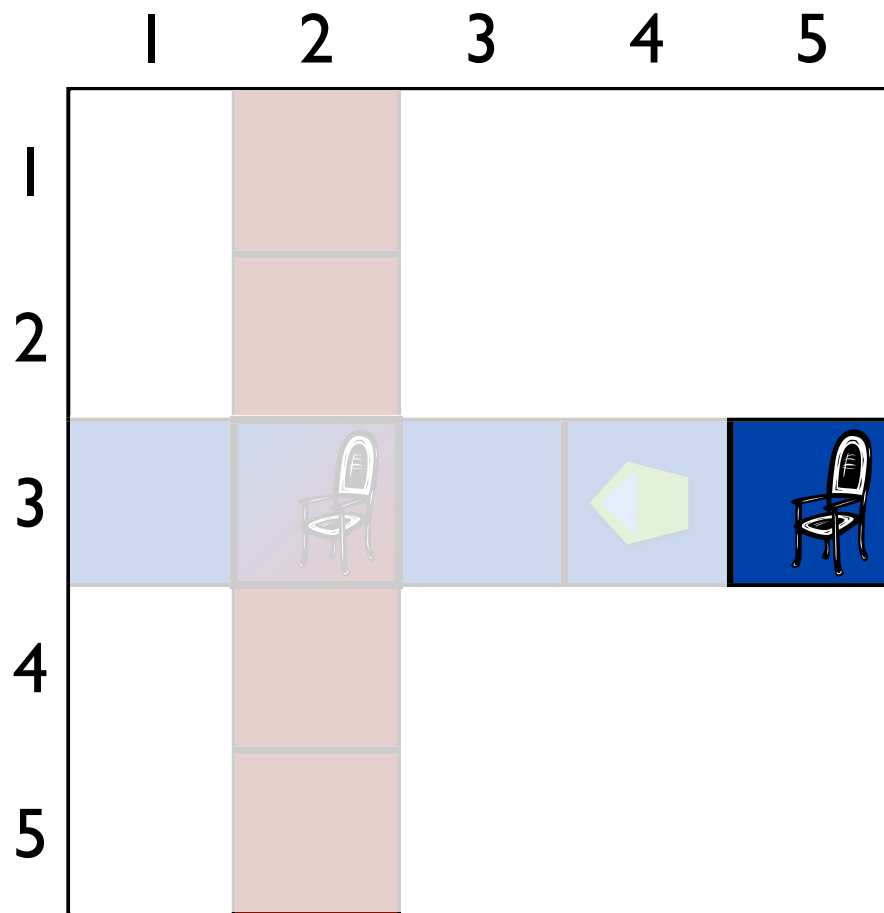
Sets of events

Spatial Environment Modeling



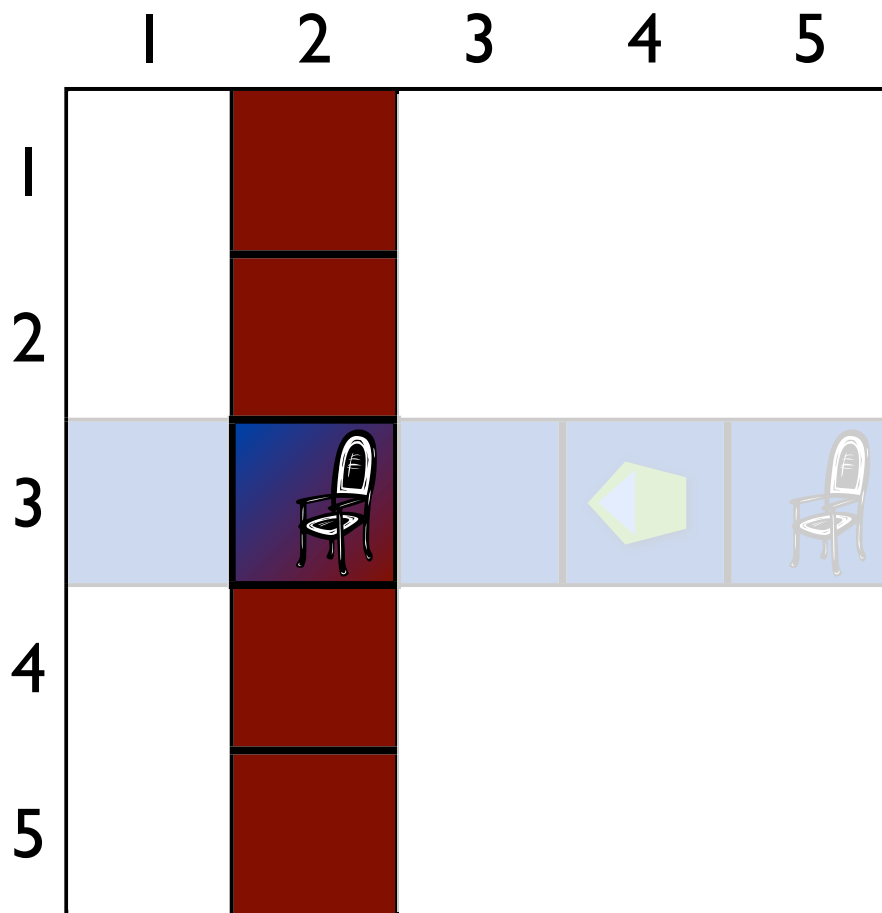
- Maps are graphs of connected positions
- Agent can move forward, turn right and turn left
- Agent perceives clusters of positions
- Clusters capture objects

Spatial Environment Modeling





- Maps are graphs of connected positions
- Agent can move forward, turn right and turn left
- Agent perceives clusters of positions
- Clusters capture objects

Spatial Environment Modeling



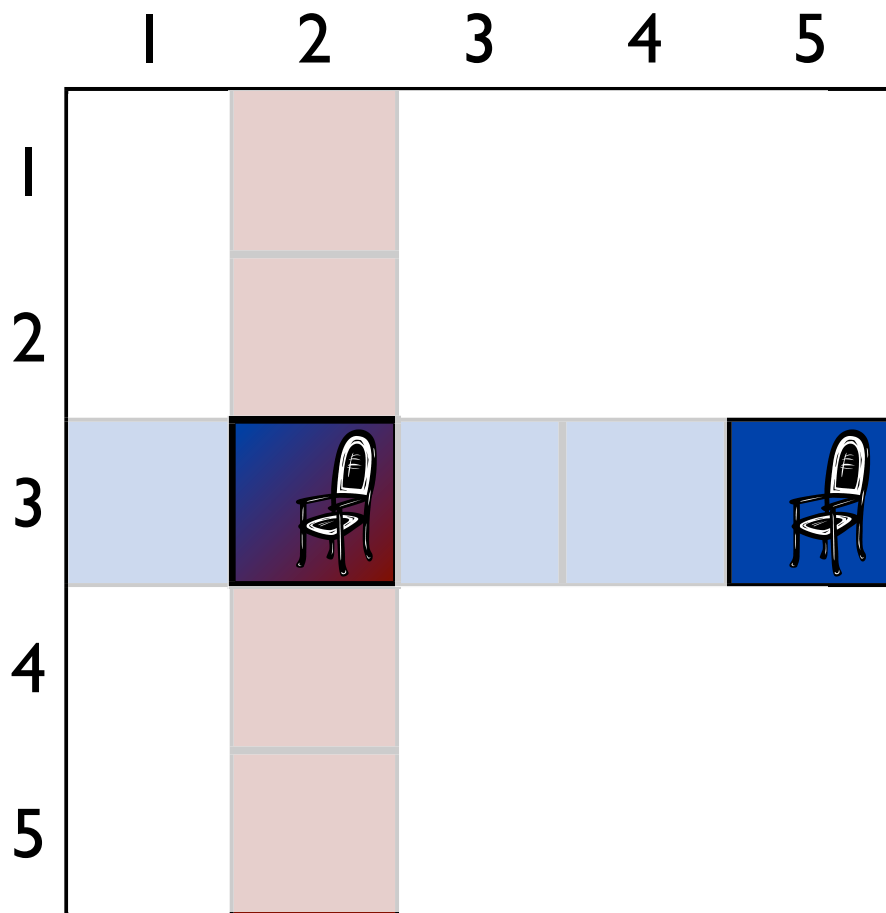
- Maps are graphs of connected positions
- Agent can move forward, turn right and turn left
- Agent perceives clusters of positions
- Clusters capture objects

Spatial Language

	1	2	3	4	5
1					
2					
3					
4					
5					

- Nouns
- Noun phrases
- Adjectives
- Prepositional phrases
- Spatial relations

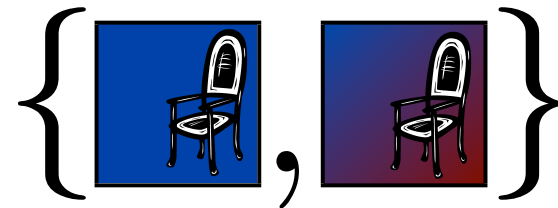
Spatial Language



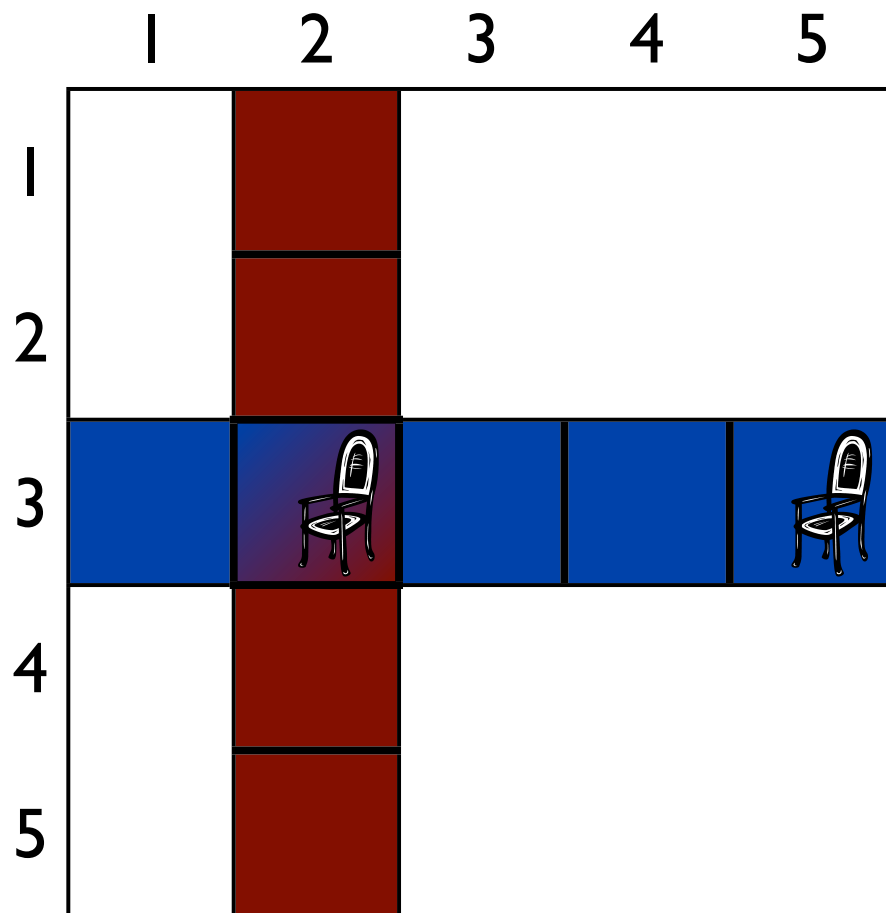
Nouns denote sets of objects

chair

$\lambda x.chair(x)$

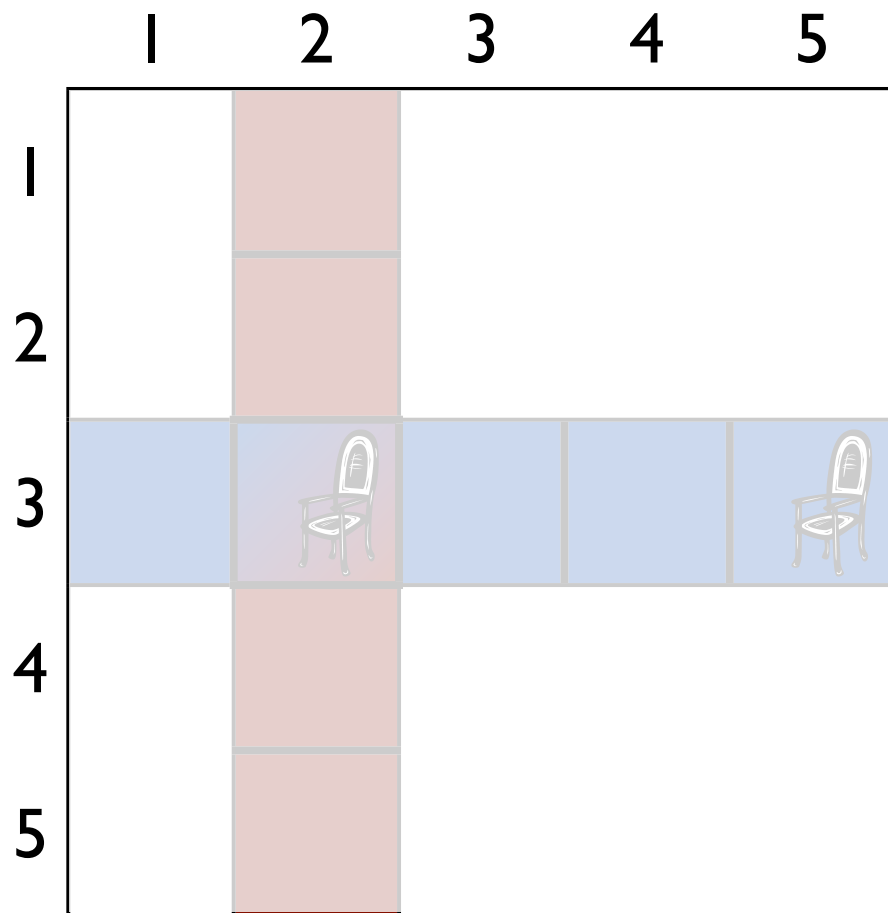


Spatial Language



Noun phrases name
specific entities

Spatial Language

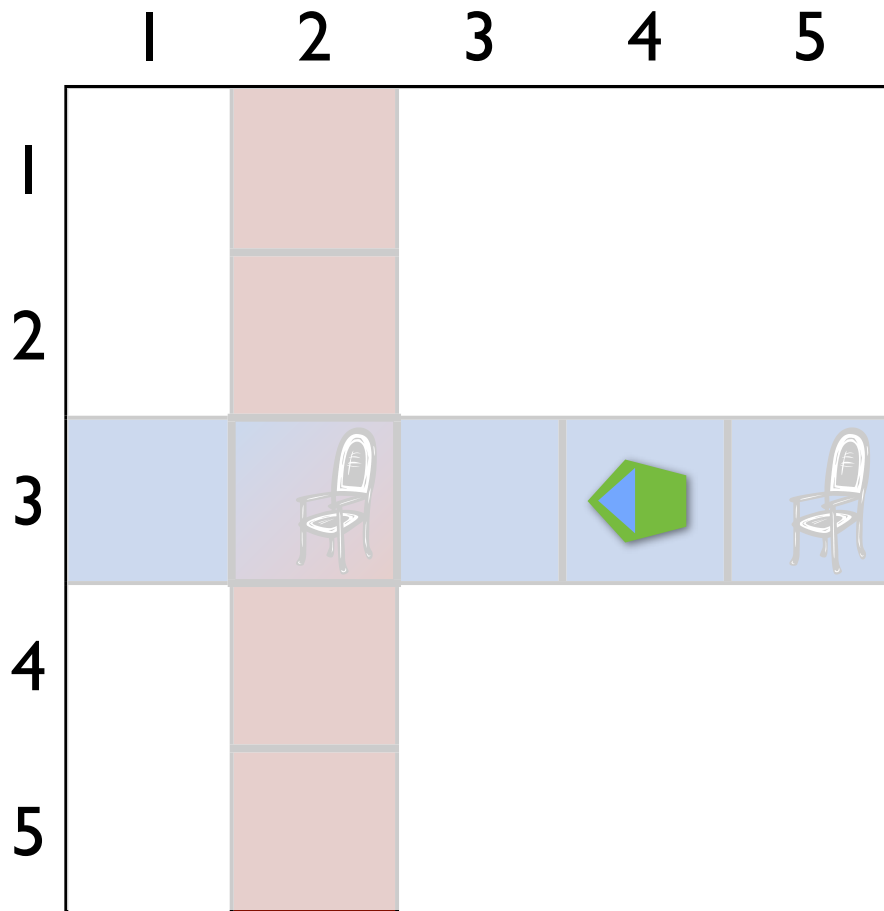


Noun phrases name
specific entities

the chair

$\exists x.chair(x)$

Spatial Language



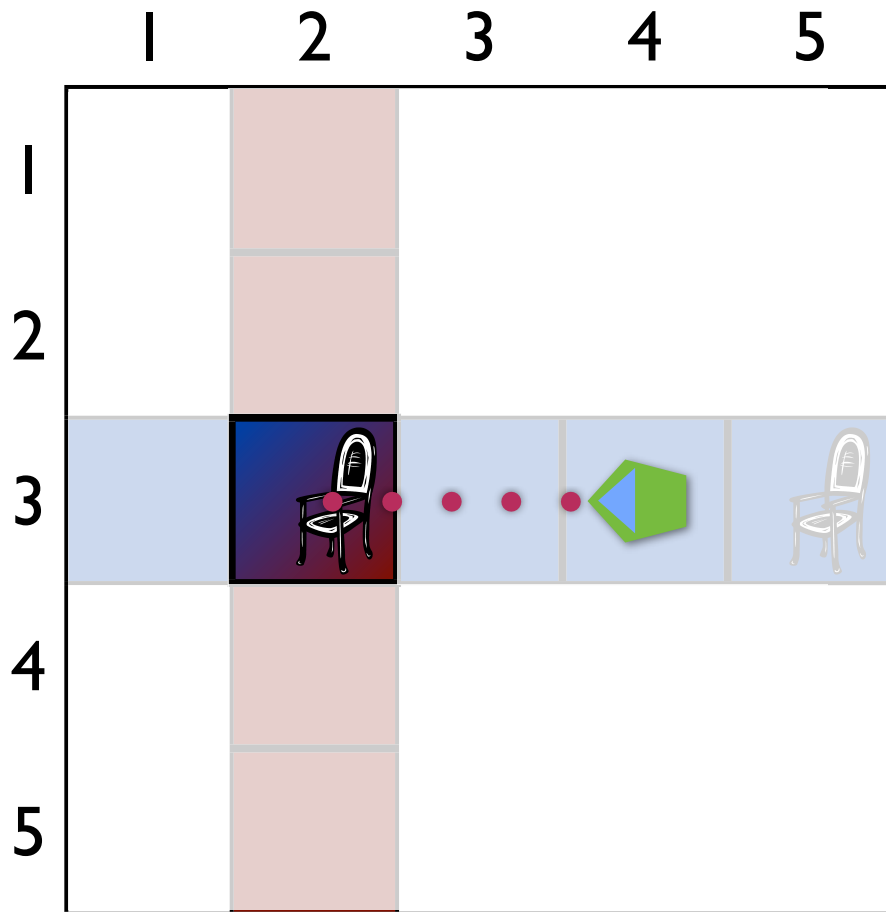
Noun phrases name specific entities

the chair

$\exists x.chair(x)$

Definite determiner depends on agent state

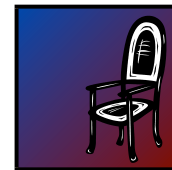
Spatial Language



Noun phrases name specific entities



the chair

$\exists x.chair(x)$



Definite determiner depends on agent state

Spatial Language

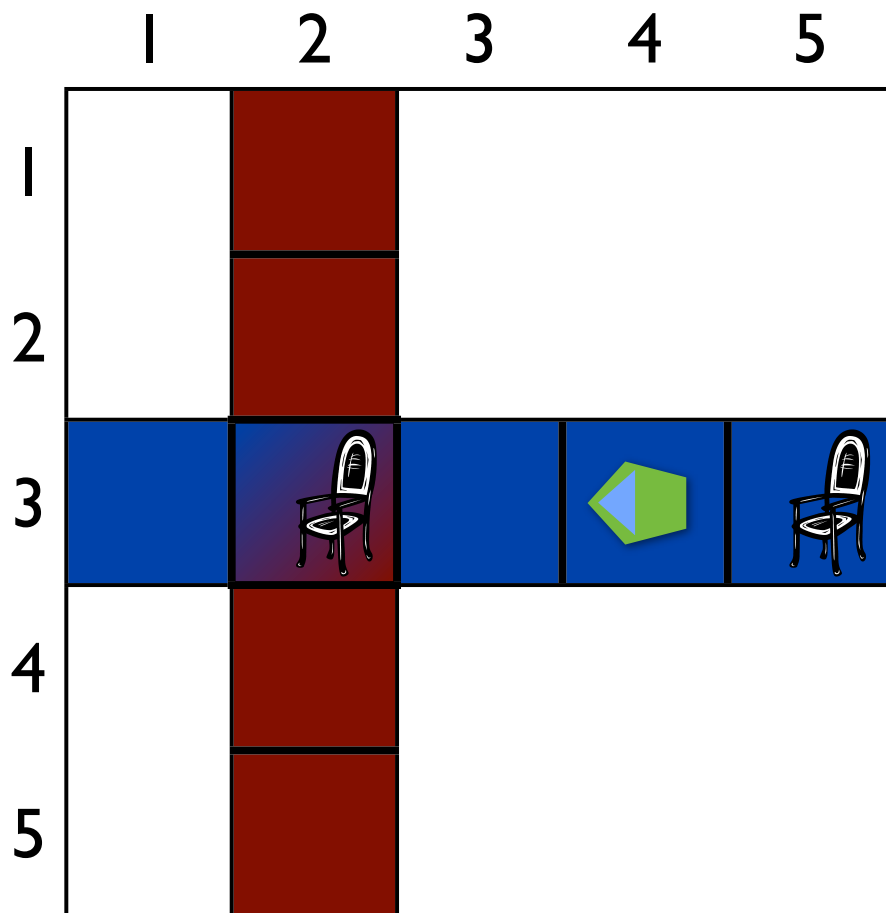
	1	2	3	4	5
1					
2					
3					
4					
5					

- Nouns
- Noun phrases
- Adjectives
- Prepositional phrases
- Spatial relations

Modeling Instructions

- Sequences of identical actions are events
- Use Neo-Davidsonian event semantics
- Represent imperatives as sets of events

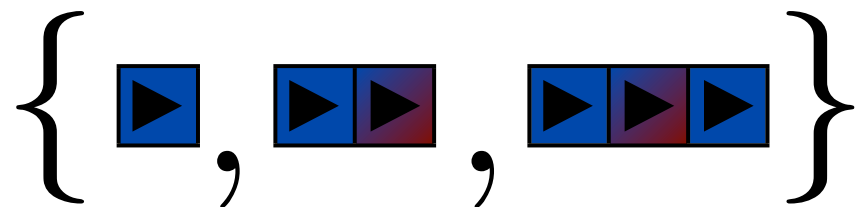
Modeling Instructions



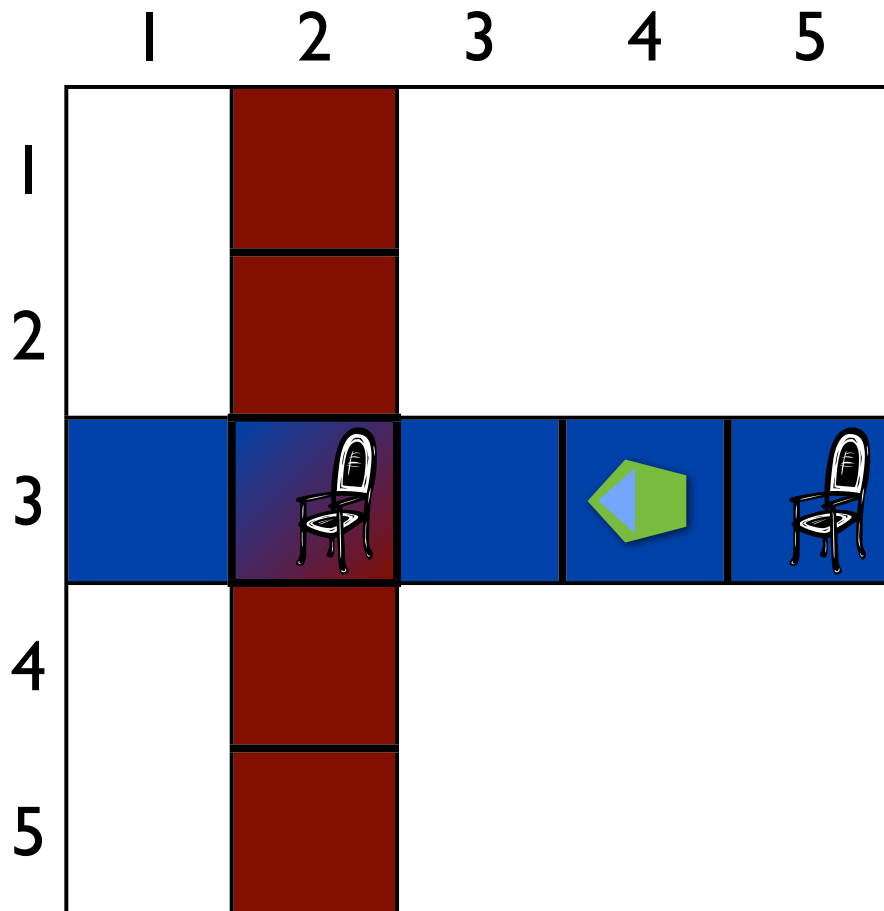
Imperatives are sets of events

move

$\lambda a.move(a)$



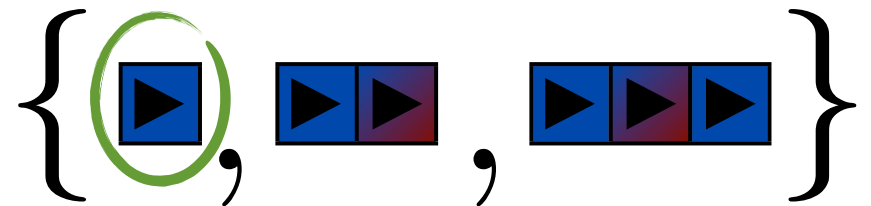
Modeling Instructions



Imperatives are sets of events

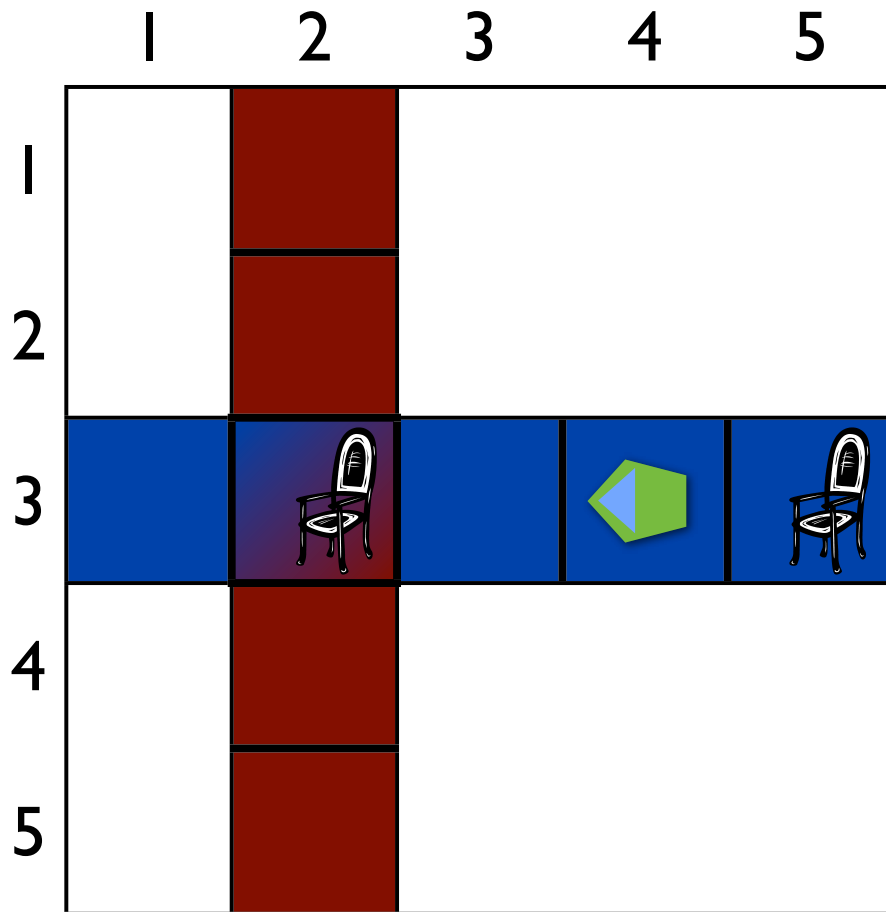
move

$\lambda a.move(a)$



Disambiguate by preferring shorter sequences

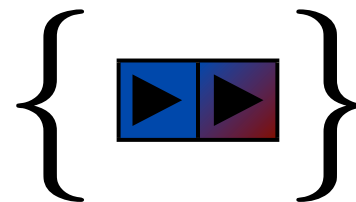
Modeling Instructions



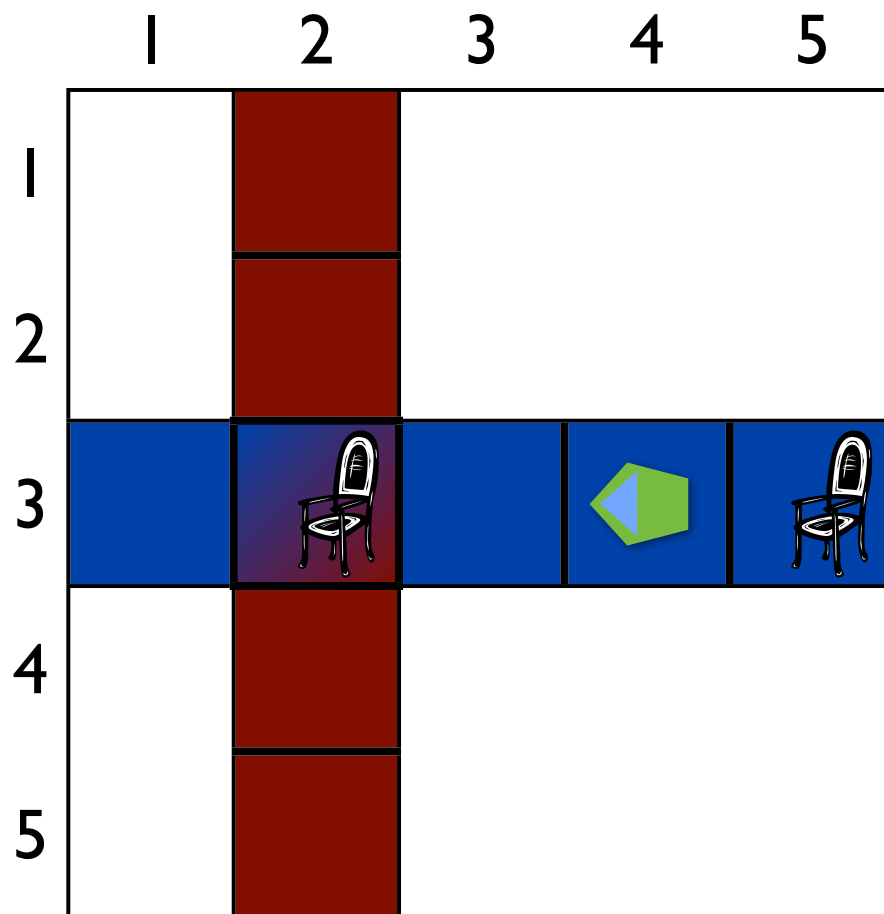
Events can be modified
by adverbials

go to the chair

$\lambda a.move(a) \wedge$
 $to(a, \iota x.chair(x))$



Executing Logical Forms

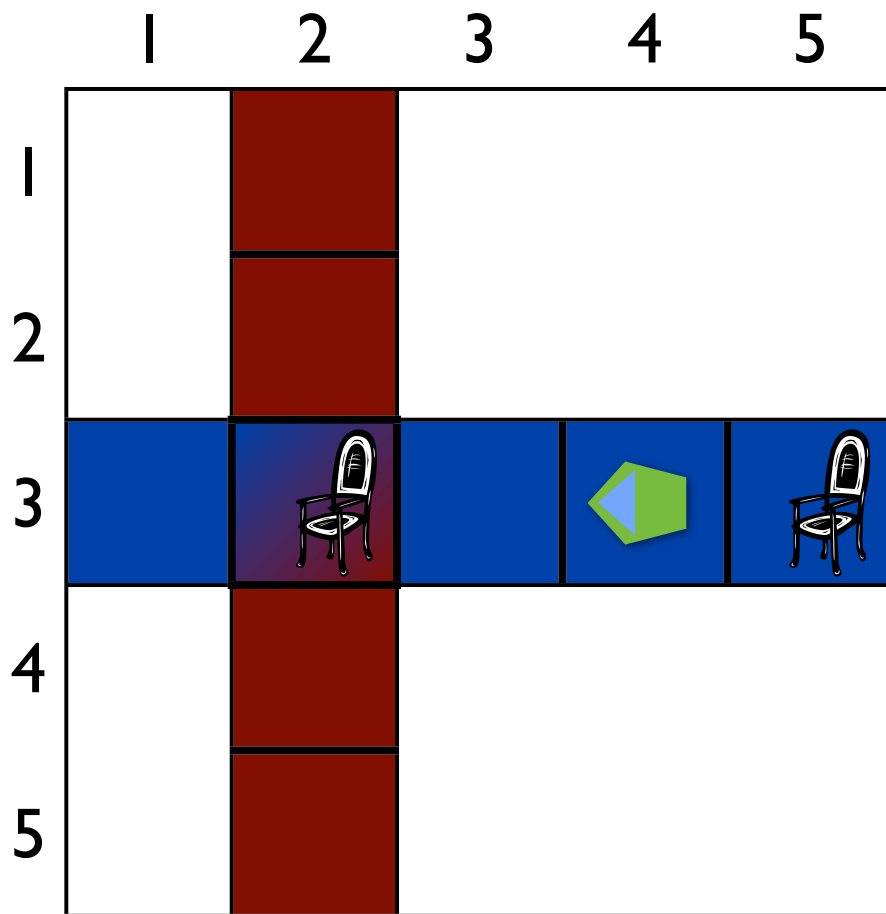


go to the chair

$\lambda a.move(a) \wedge to(a, \iota x.chair(x))$

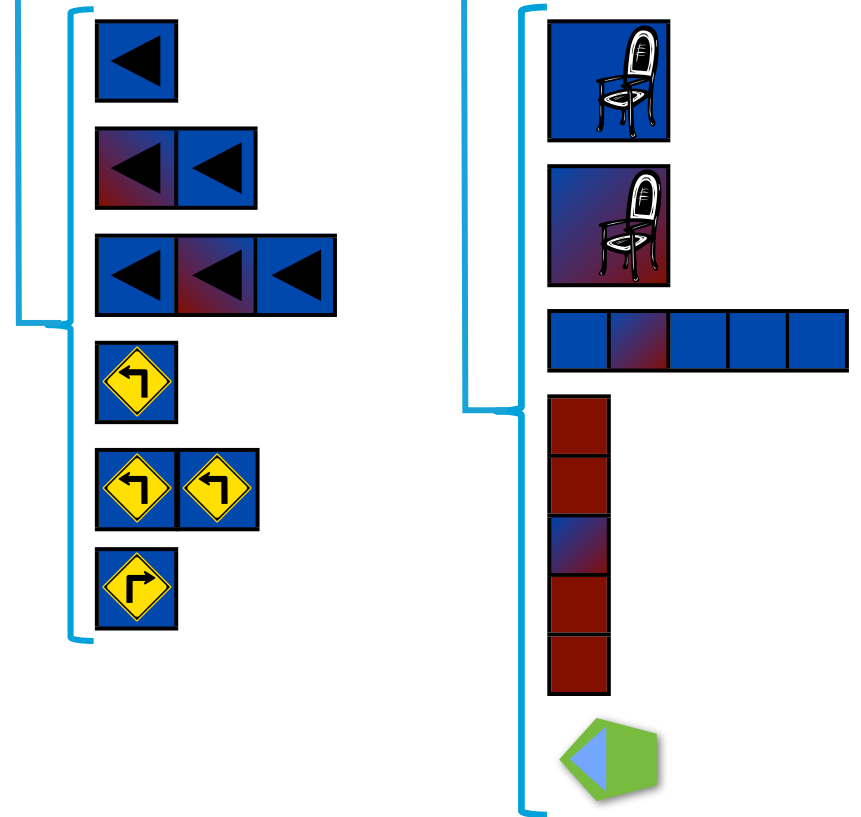
Consider all variable assignments to find satisfying ones

Executing Logical Forms

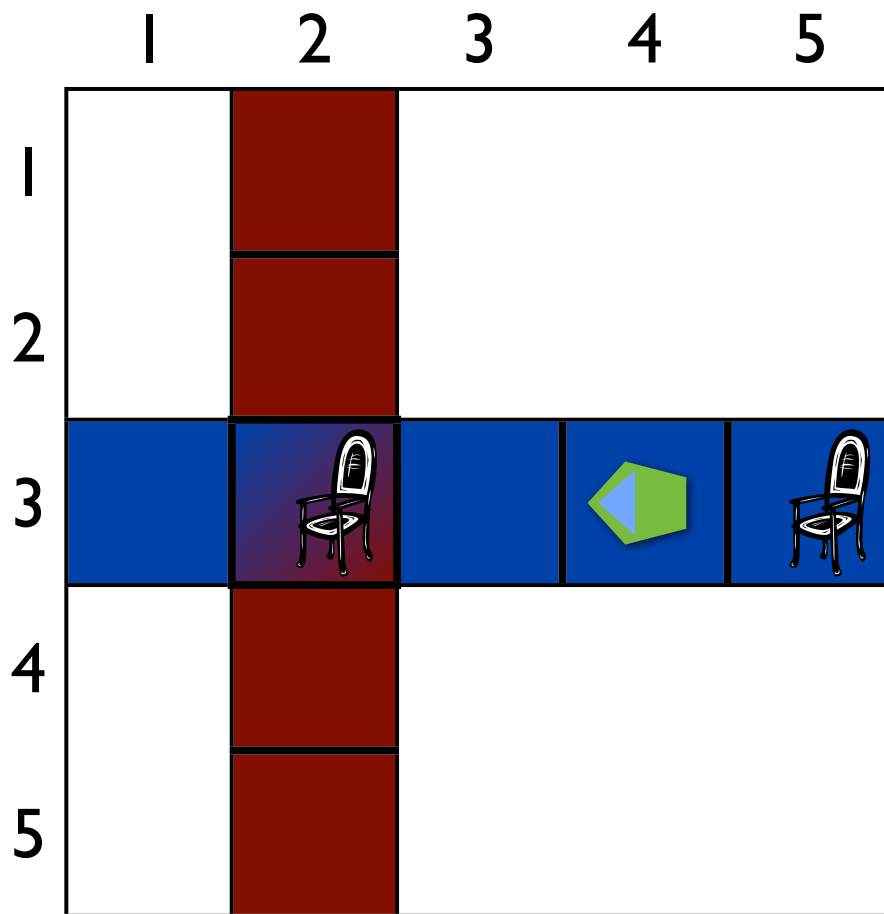


go to the chair

$\lambda a. move(a) \wedge to(a, \iota x. chair(x))$

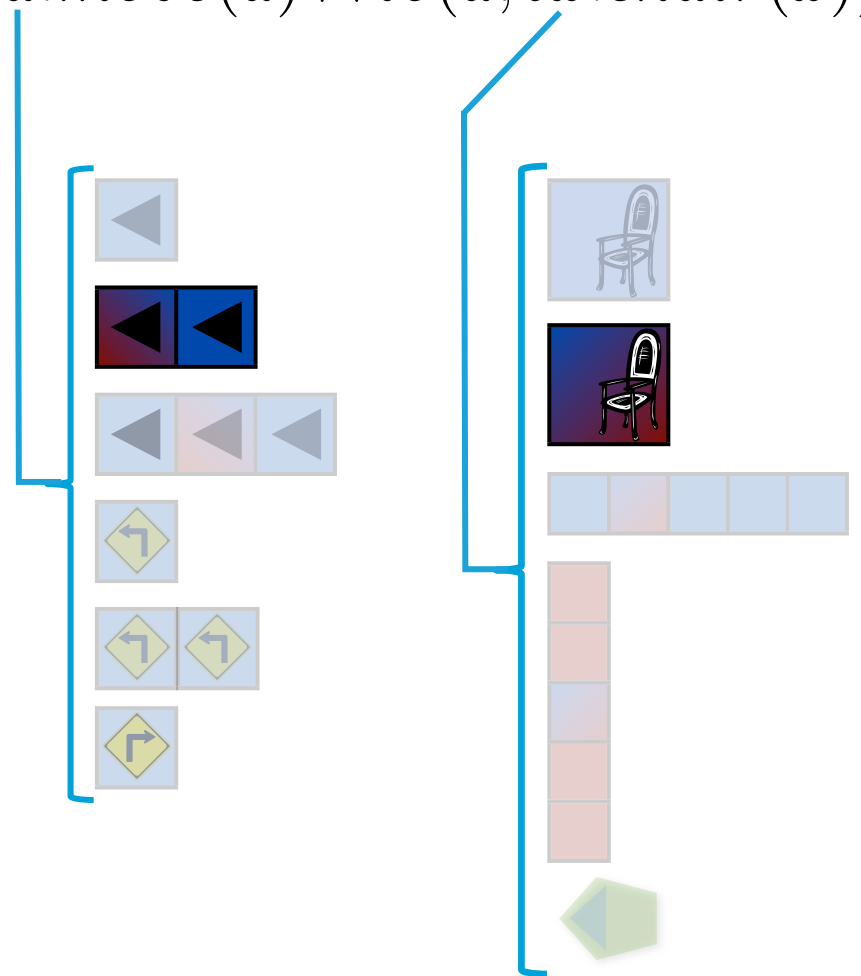


Executing Logical Forms

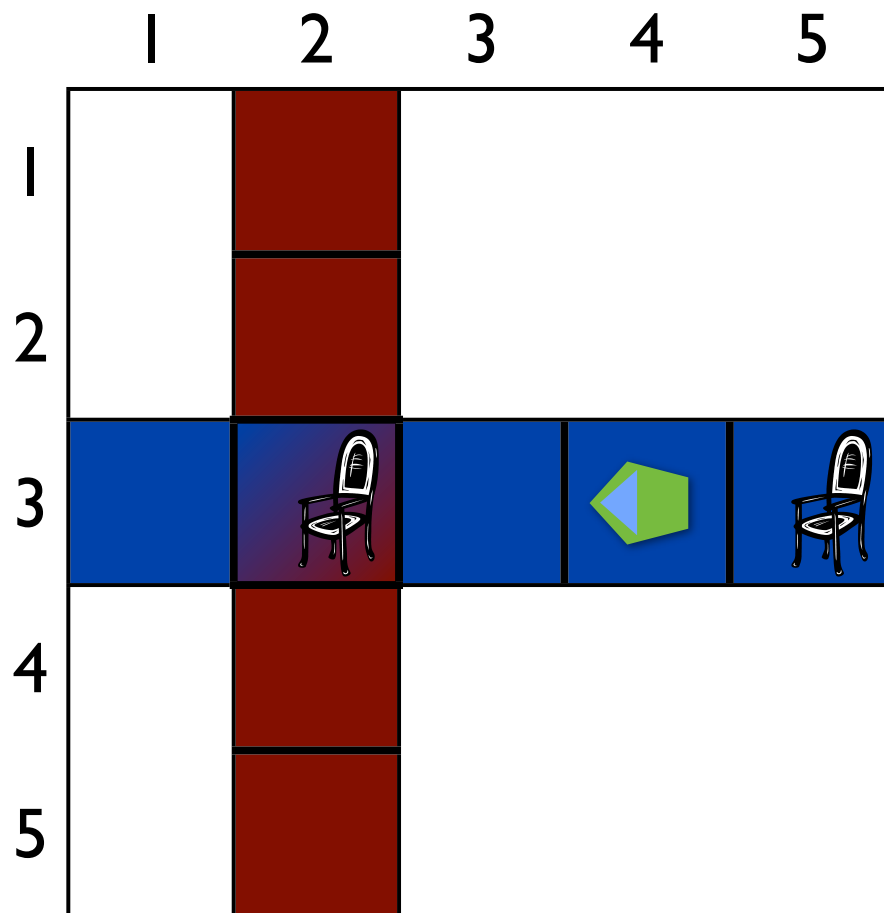


go to the chair

$\lambda a. move(a) \wedge to(a, \iota x. chair(x))$



Dynamic Models



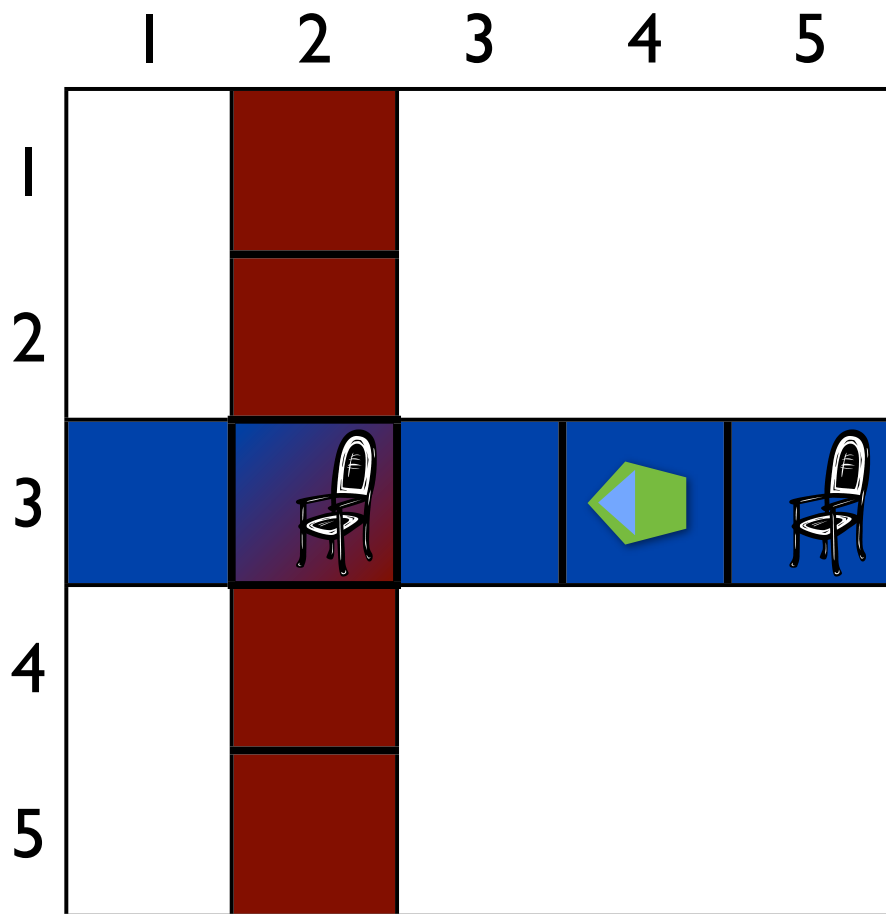
World models change during execution

move until you reach the chair

$\lambda a.move(a) \wedge$

$post(a, intersect(\iota x.chair(x), you))$

Dynamic Models

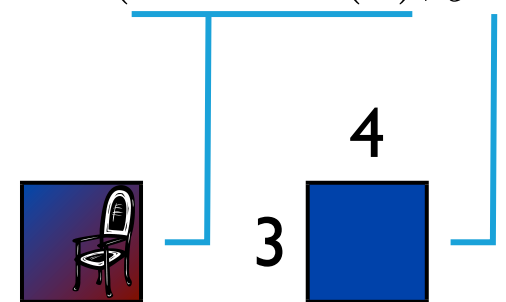


World models change during execution

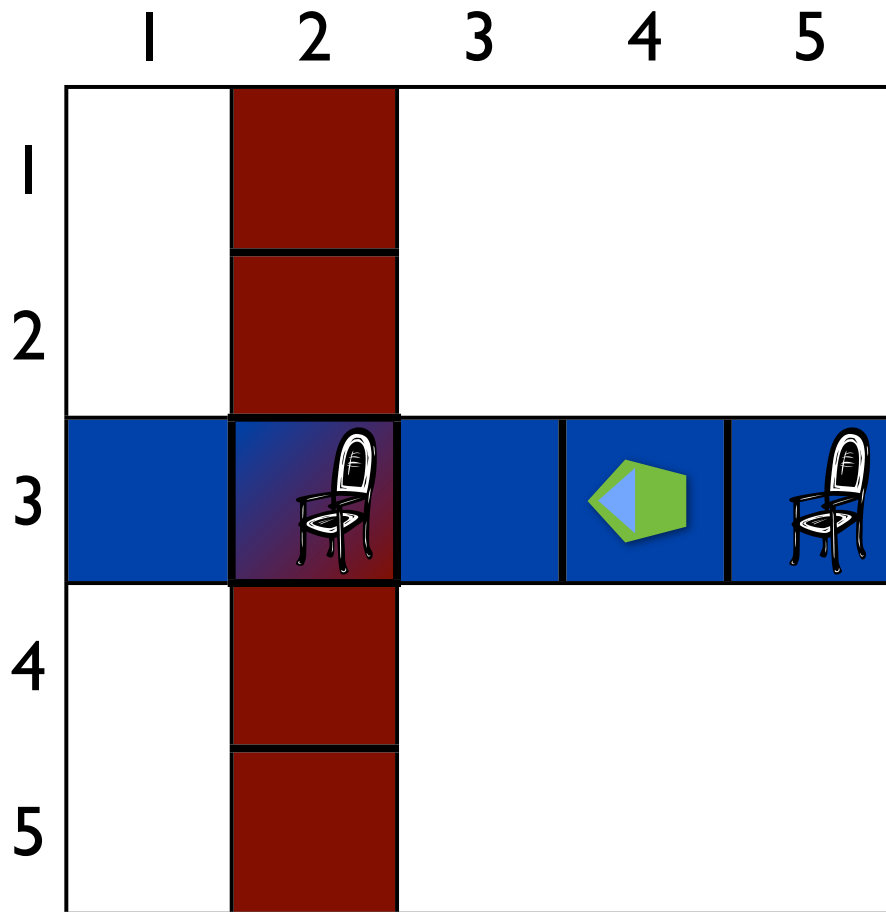
move until you reach the chair

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Dynamic Models

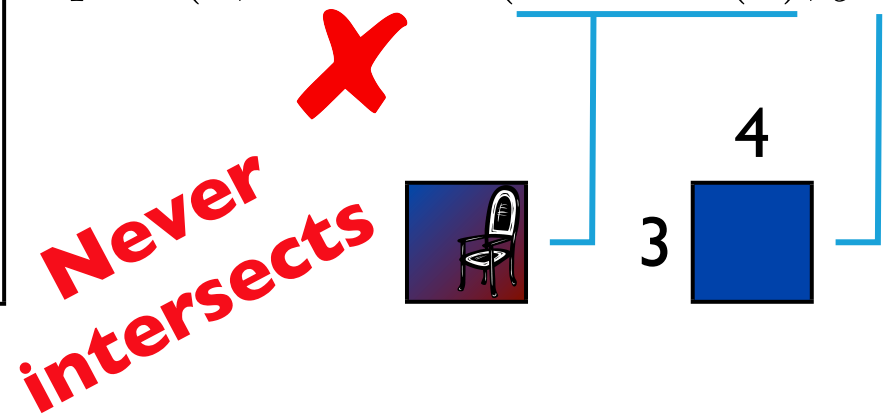


World models change during execution

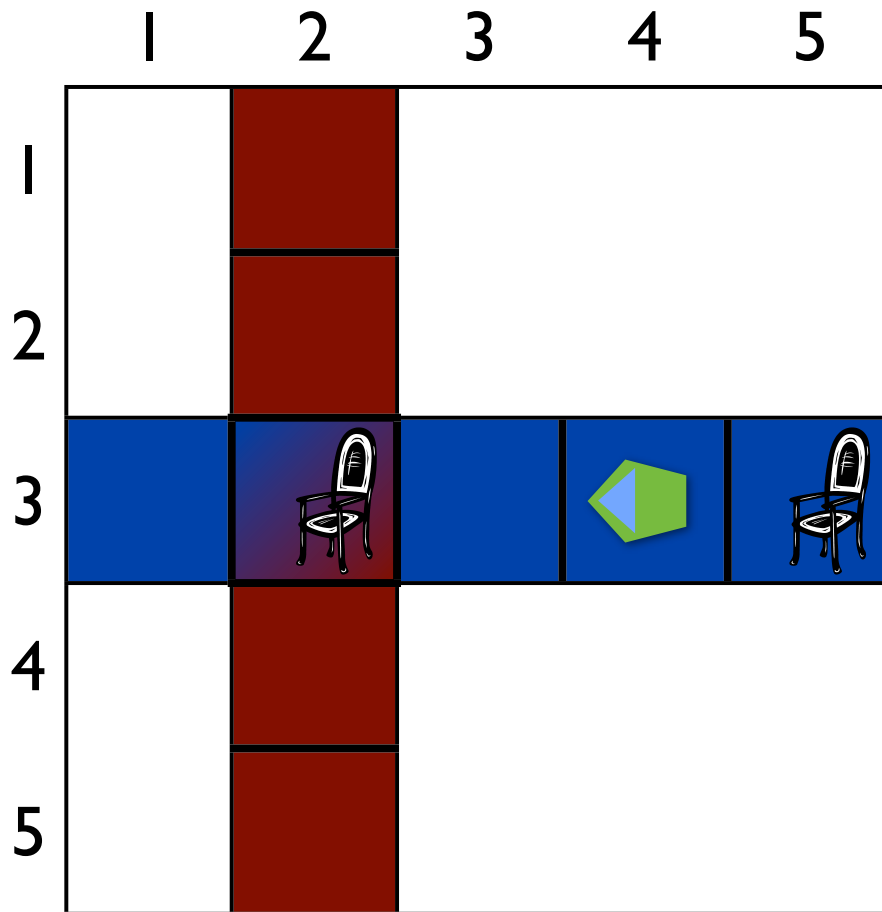
move until you reach the chair

$\lambda a.move(a) \wedge$

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Dynamic Models



World models change during execution

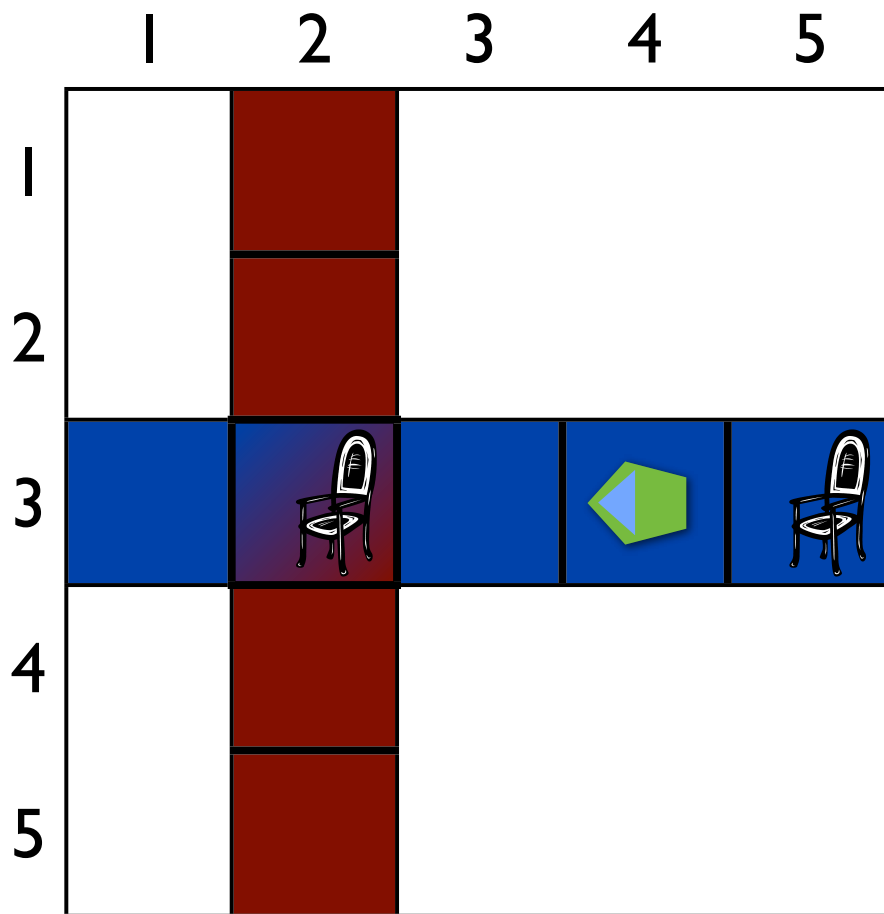
move until you reach the chair

$\lambda a.move(a) \wedge$

$post(a, intersect(\iota x.chair(x), you))$

Update model to reflect state change

Dynamic Models



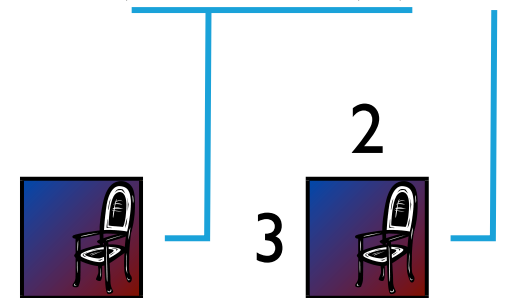
World models change during execution

move until you reach the chair

$\lambda a.move(a) \wedge$

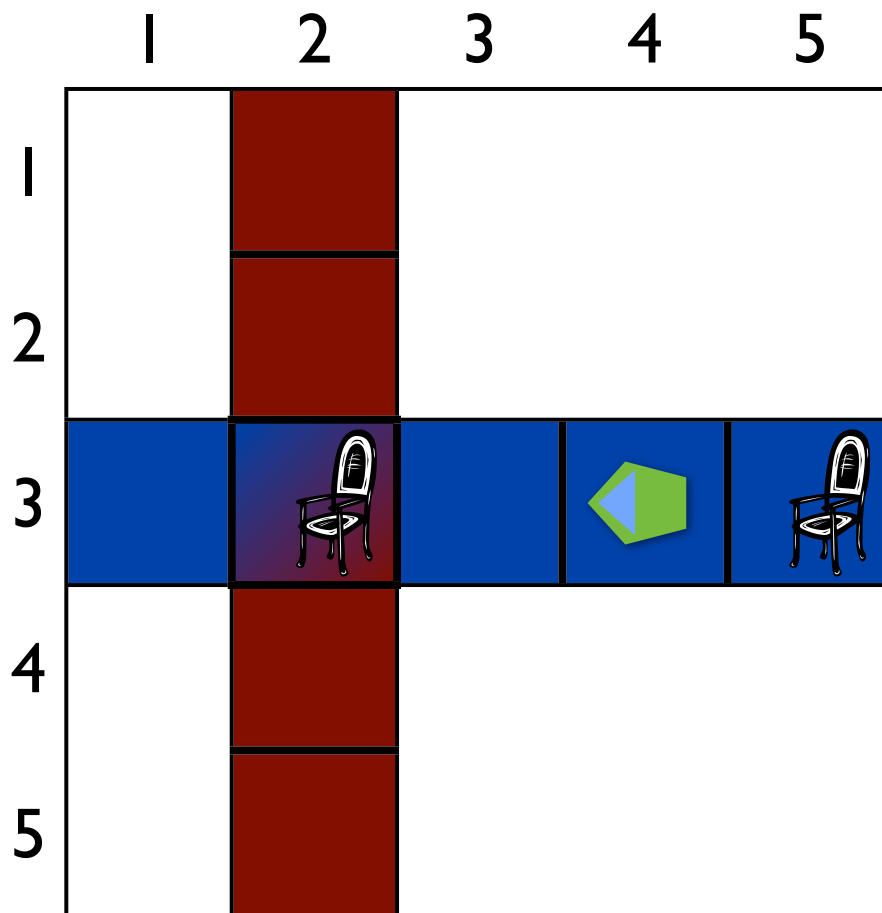
$post(a, intersect(\iota x.chair(x), you))$

Update



Update model to reflect state change

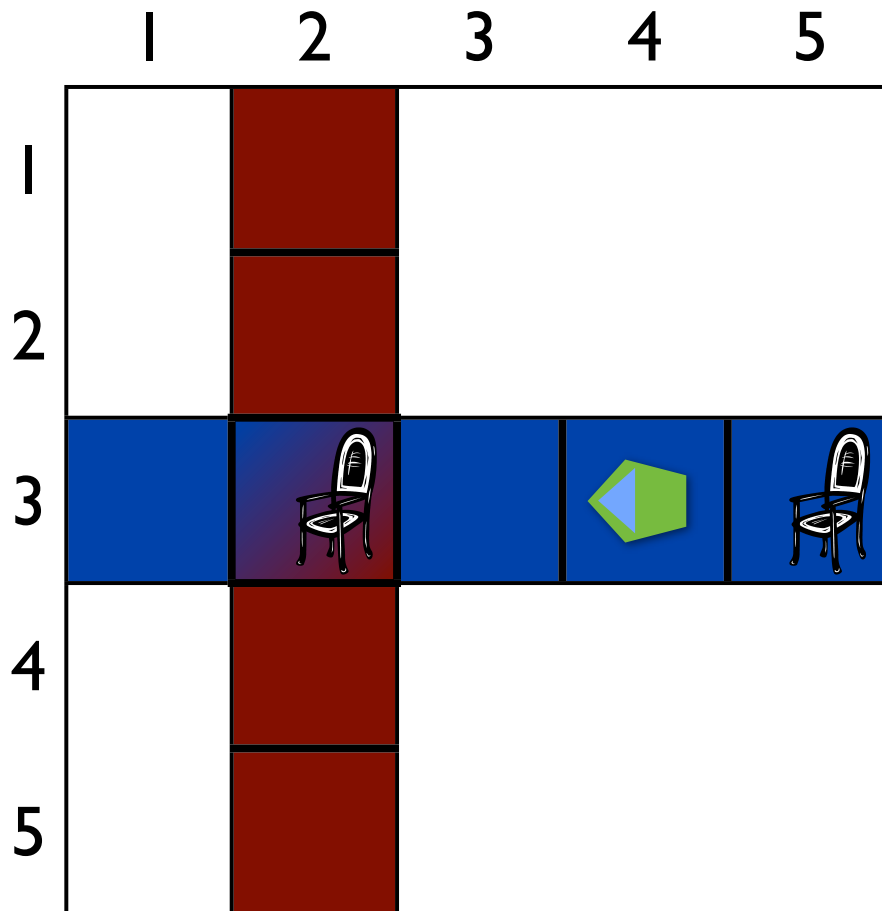
Implicit Actions



Consider actions with
prefixed implicit actions
at the chair, turn left

$$\lambda a. turn(a) \wedge dir(a, left) \wedge$$
$$pre(a, intersect(\iota x. chair(x), you))$$

Implicit Actions

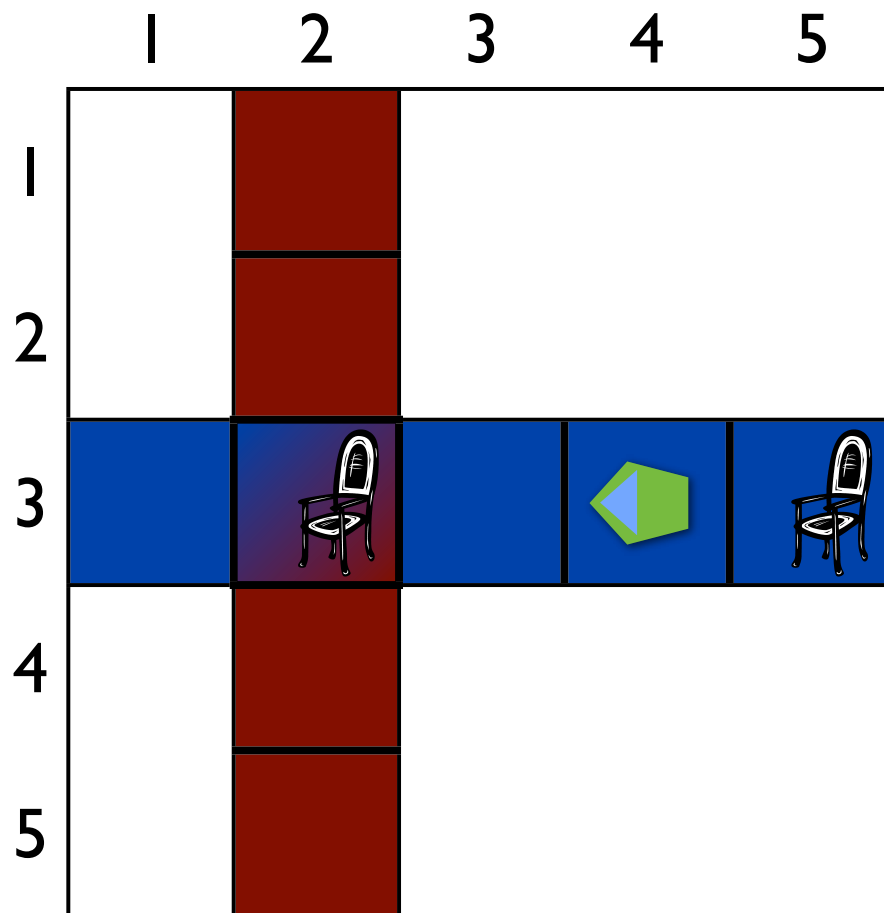


Consider actions with
prefixed implicit actions
at the chair, turn left

$\lambda a. turn(a) \wedge dir(a, left) \wedge$
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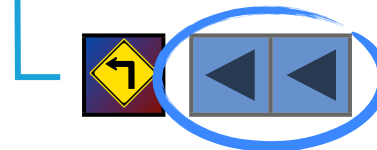


Implicit Actions



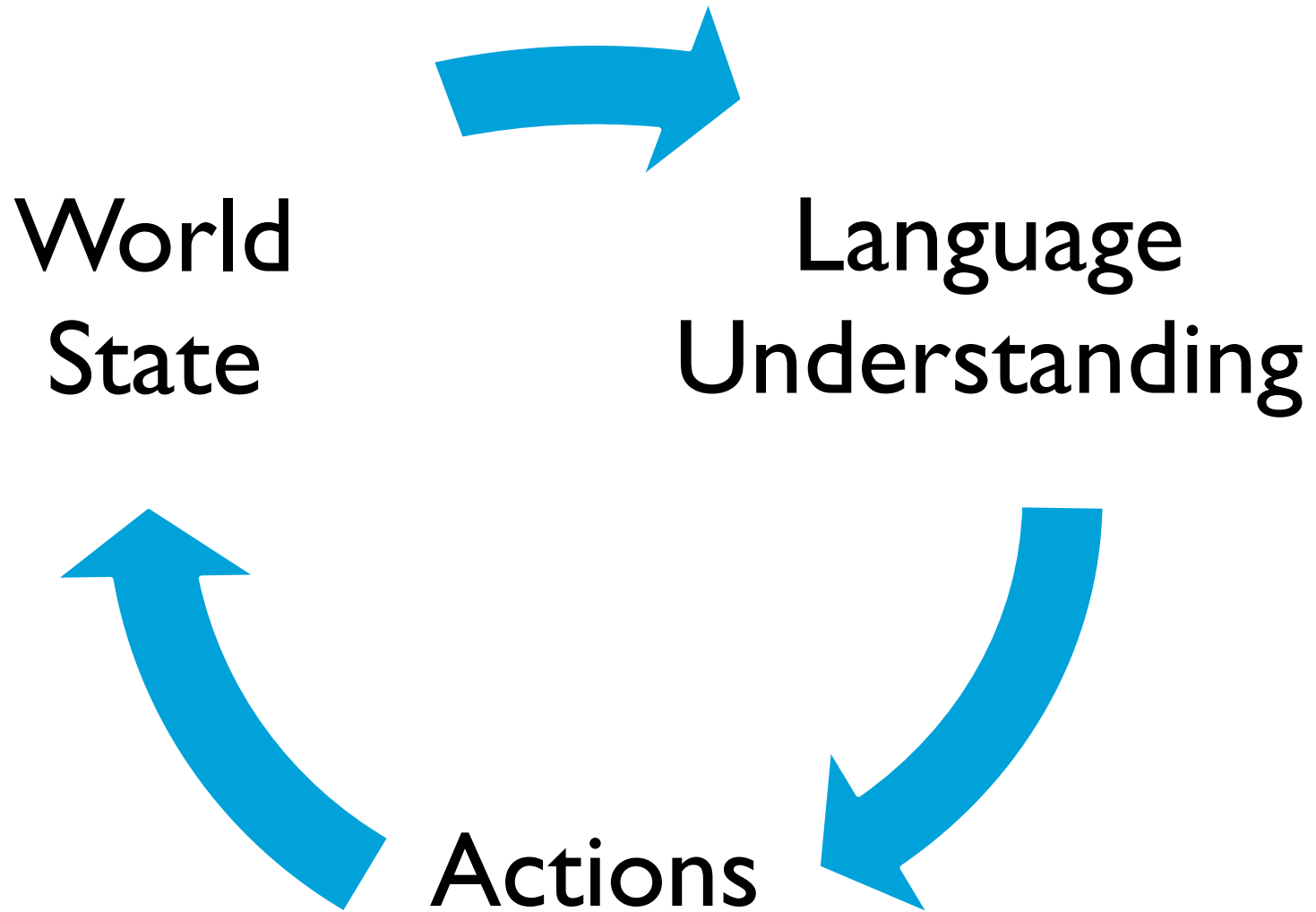
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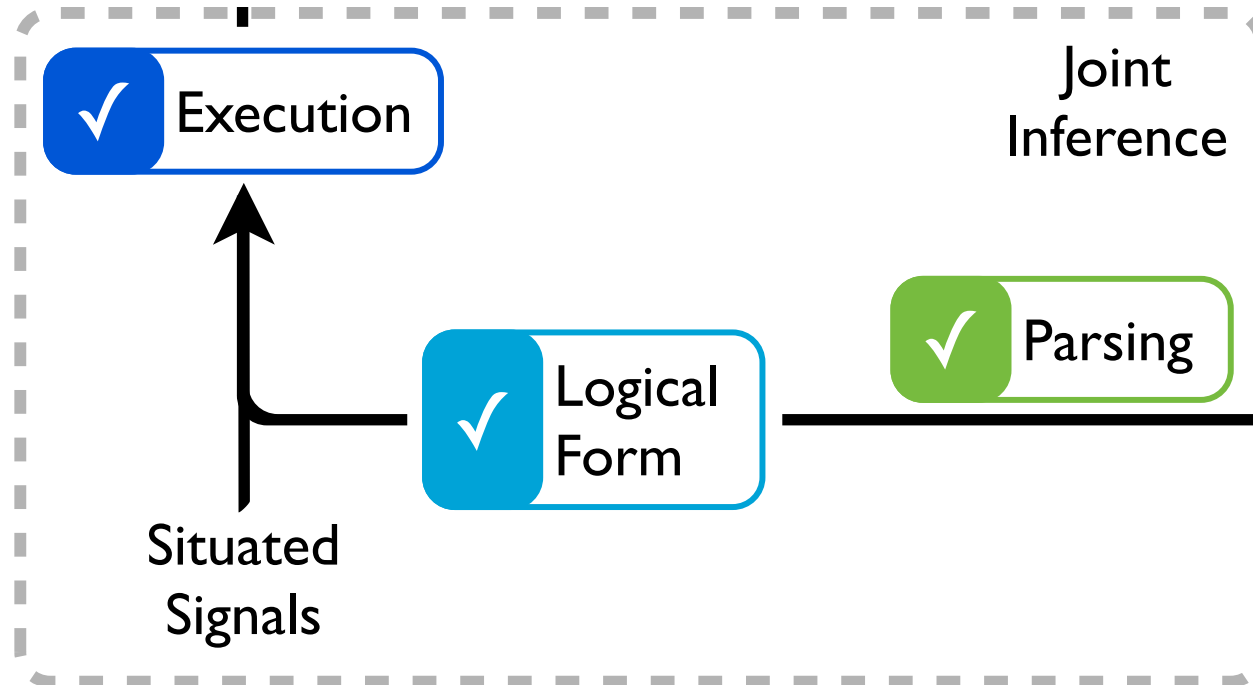


Implicit actions

Joint Inference



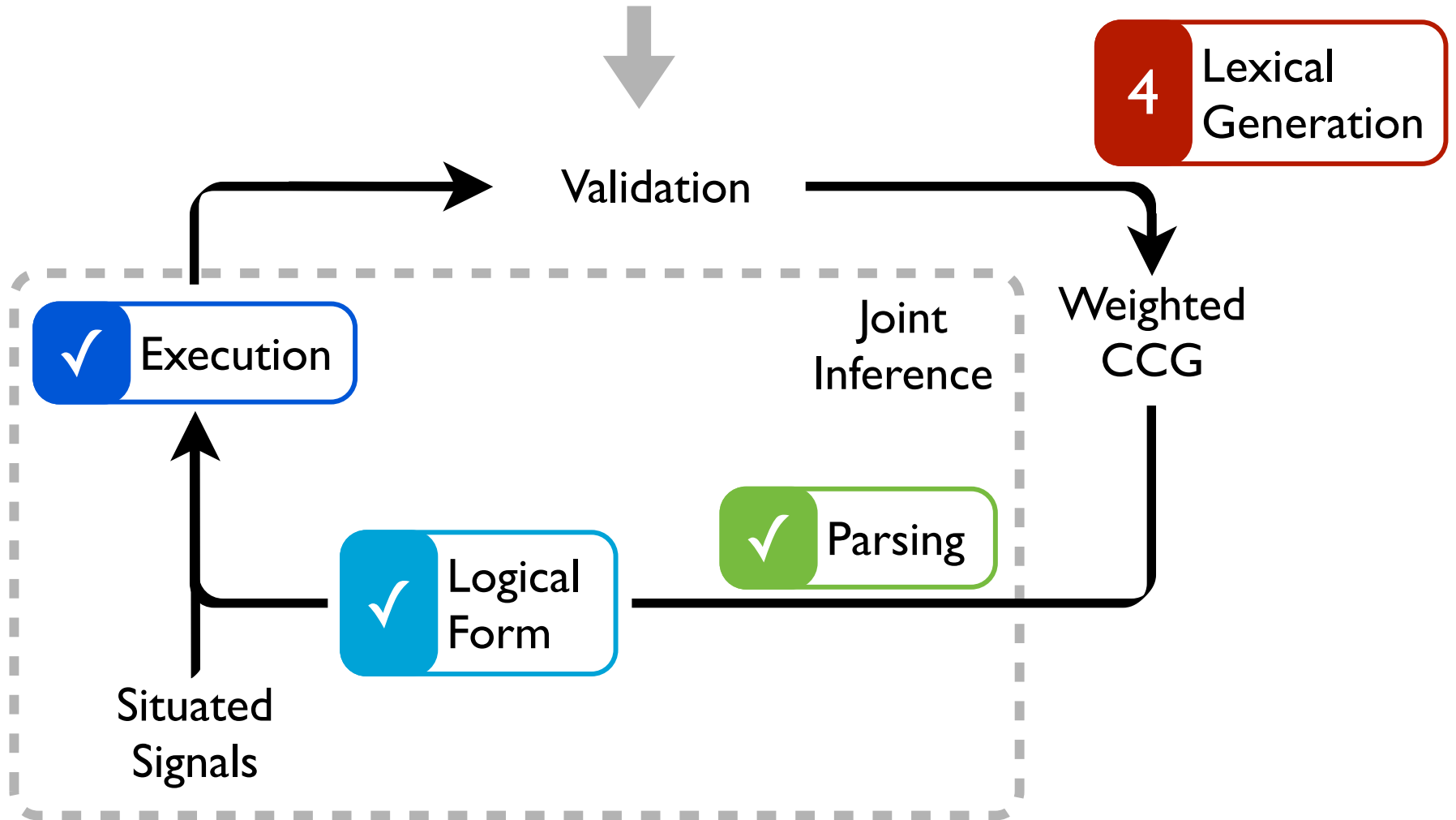
Learning



- Execution is integrated into parsing
- During parsing, execute logical forms and observe the result

Learning

Demonstrations



Learning

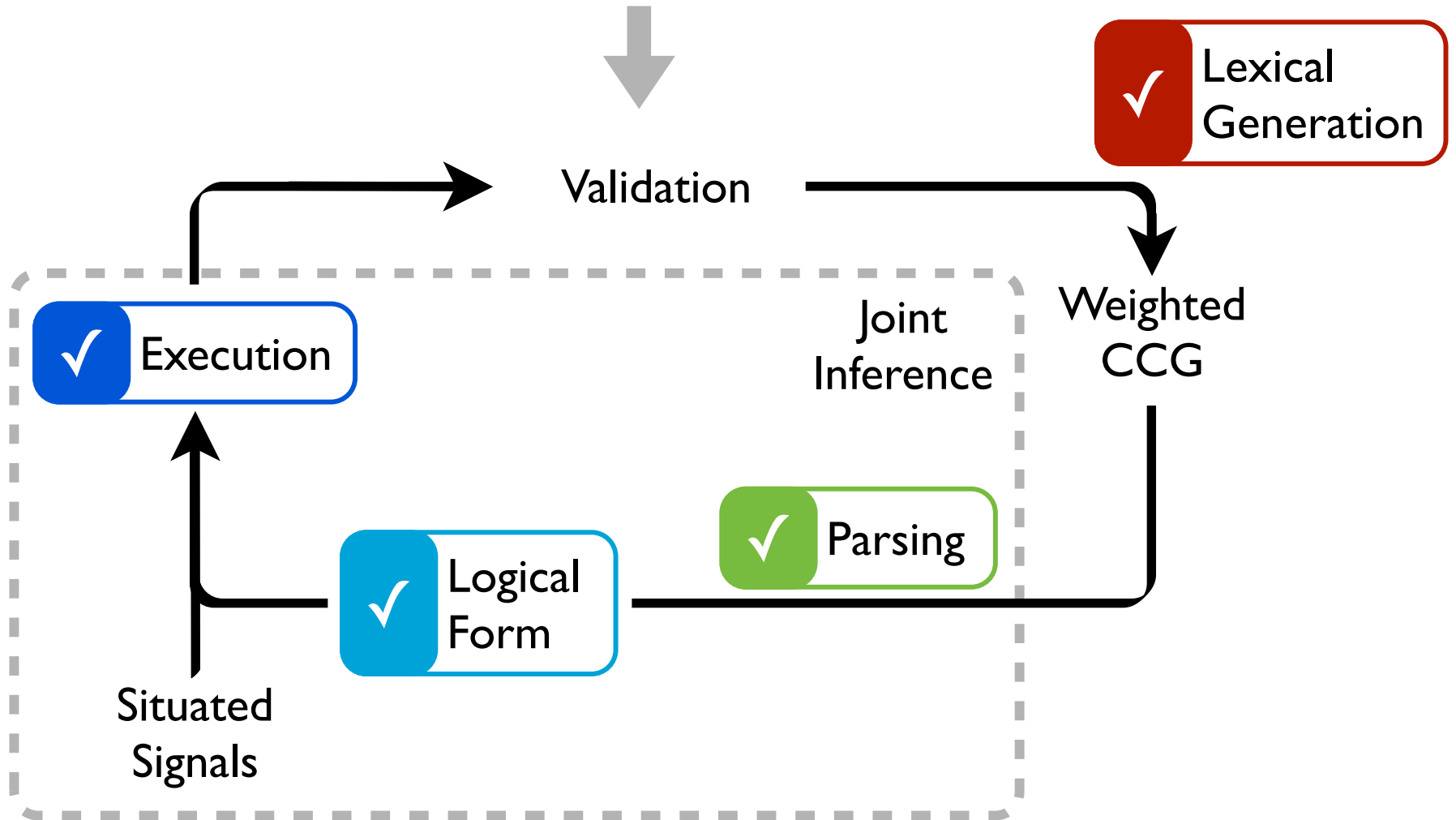
- Based on a small set of seed templates
- New coarse-to-fine parsing algorithm to gradually prune the potential lexical entries
- Conservative approach to introduce new entries to the model

4 Lexical Generation

Weighted CCG

Learning

Demonstrations



Validation-Driven Learning

- Online
- 2 steps:
 - Lexical generation
 - Parameter update
- Driven by a weak validation signal

Validation-Driven Learning

For T iterations, for each training sample:

- Step 1: Lexical generation
 - Generate a large number of potential lexical entries
 - Parse with the generated lexicon using the model
 - Select the best valid parses from the k-best parses
 - Add their lexical items to the lexicon
- Step 2: Update parameters

Validation-Driven Learning

For T iterations, for each training sample:

- Step 1: Lexical generation
- Step 2: Update parameters
 - Parse using the model
 - Split all parses into two sets:
max scoring valid and invalid
 - Find margin violating pairs between the sets
 - Do a perceptron-style update using these violations

Related Work

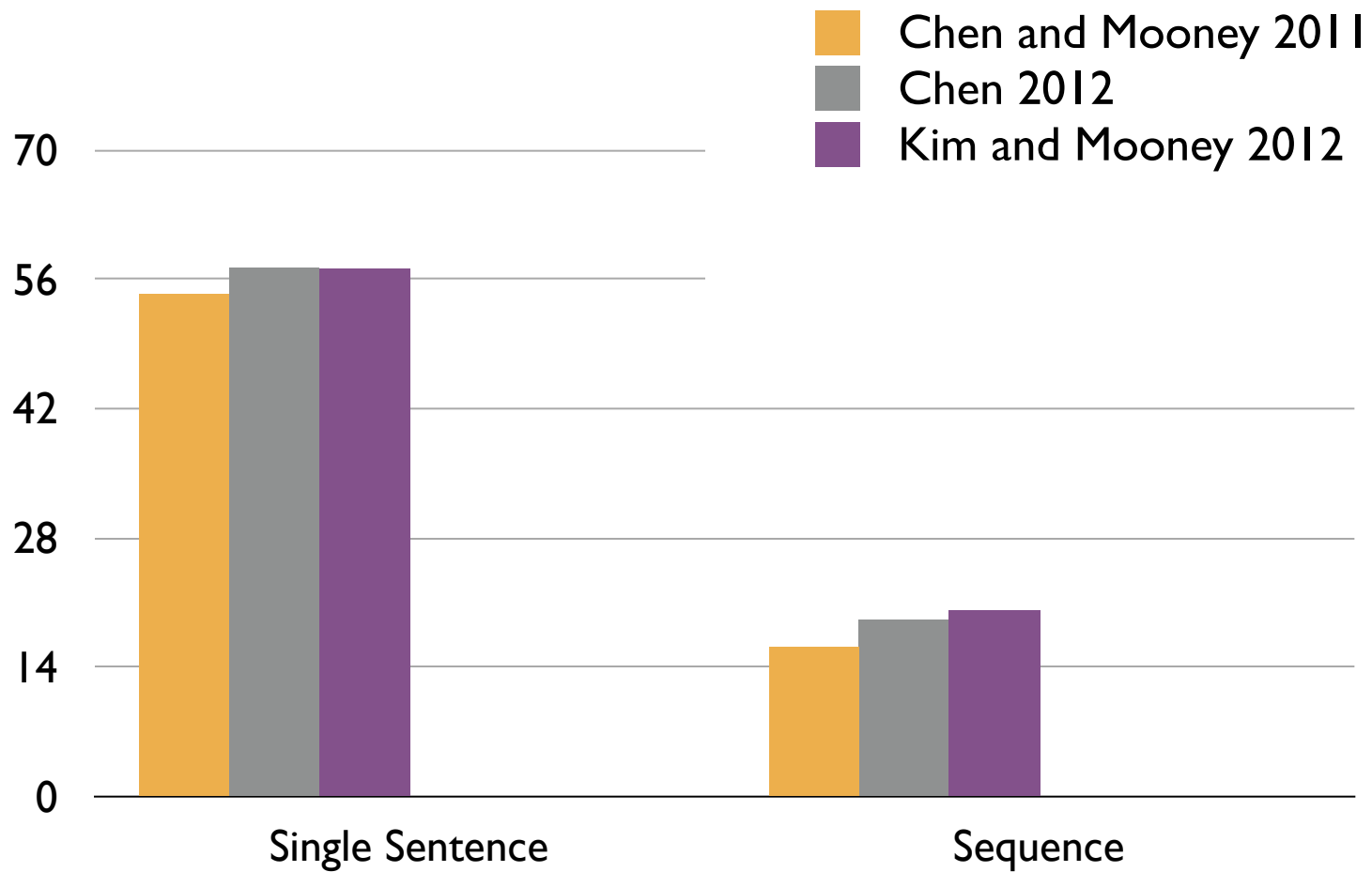
Supervised semantic parsing	[Kate, Mooney 2006; Wong, Mooney 2007; Muresan 2011]
with CCGs	[Zettlemoyer, Collins 2005; 2007; Kwiatkowski et al. 2010; 2011]
Weakly supervised semantic parsing	[Clarke et al. 2010; Goldwasser, Roth 2011; Liang et al. 2011; Kirshnamurthy, Mitchell 2012; Goldwasser et al. 2011]
Grounded Semantic Analysis	[Liang et al. 2009; Chen et al. 2010; Matuszek et al. 2012]
Executing Instructions with Shallow Representation	[Branavan et al. 2009; 2010; Vogel, Jurafsky 2010; Wei et al. 2009; Kollar et al. 2010; Tellex et al. 2011]
Non-joint Execution of Instructions	[Matuszek et al. 2010; 2012; Chen, Mooney 2011; Chen 2012; Kim, Mooney 2012]

Experimental Setup

- Seed lexicon from an annotated randomly selected 12 instruction sequences
- Features: lexical, type-raising usage and repetitions in logical coordinations
- Consider only executable parses as complete

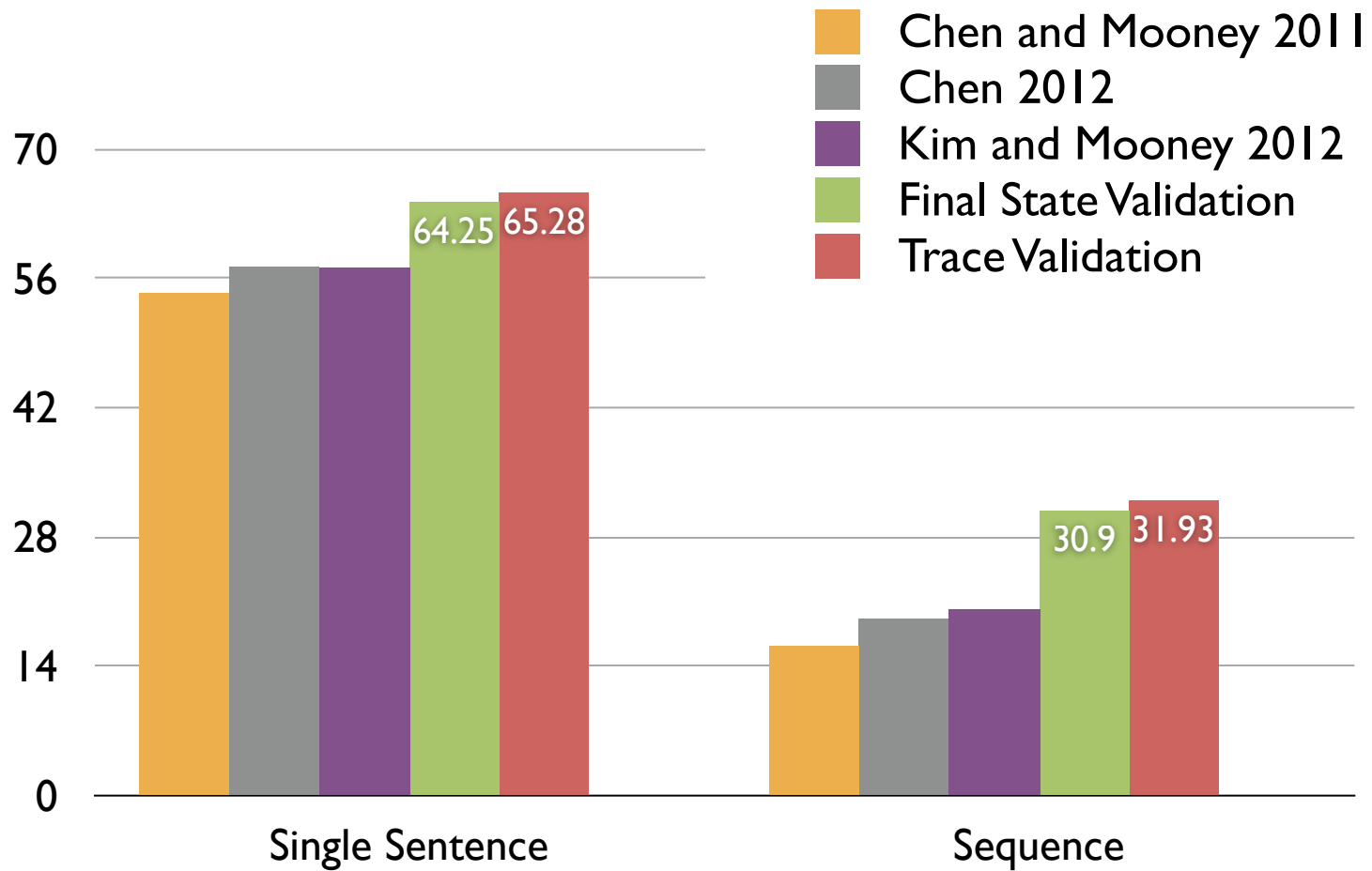
Results

SAIL Corpus - Cross Validation



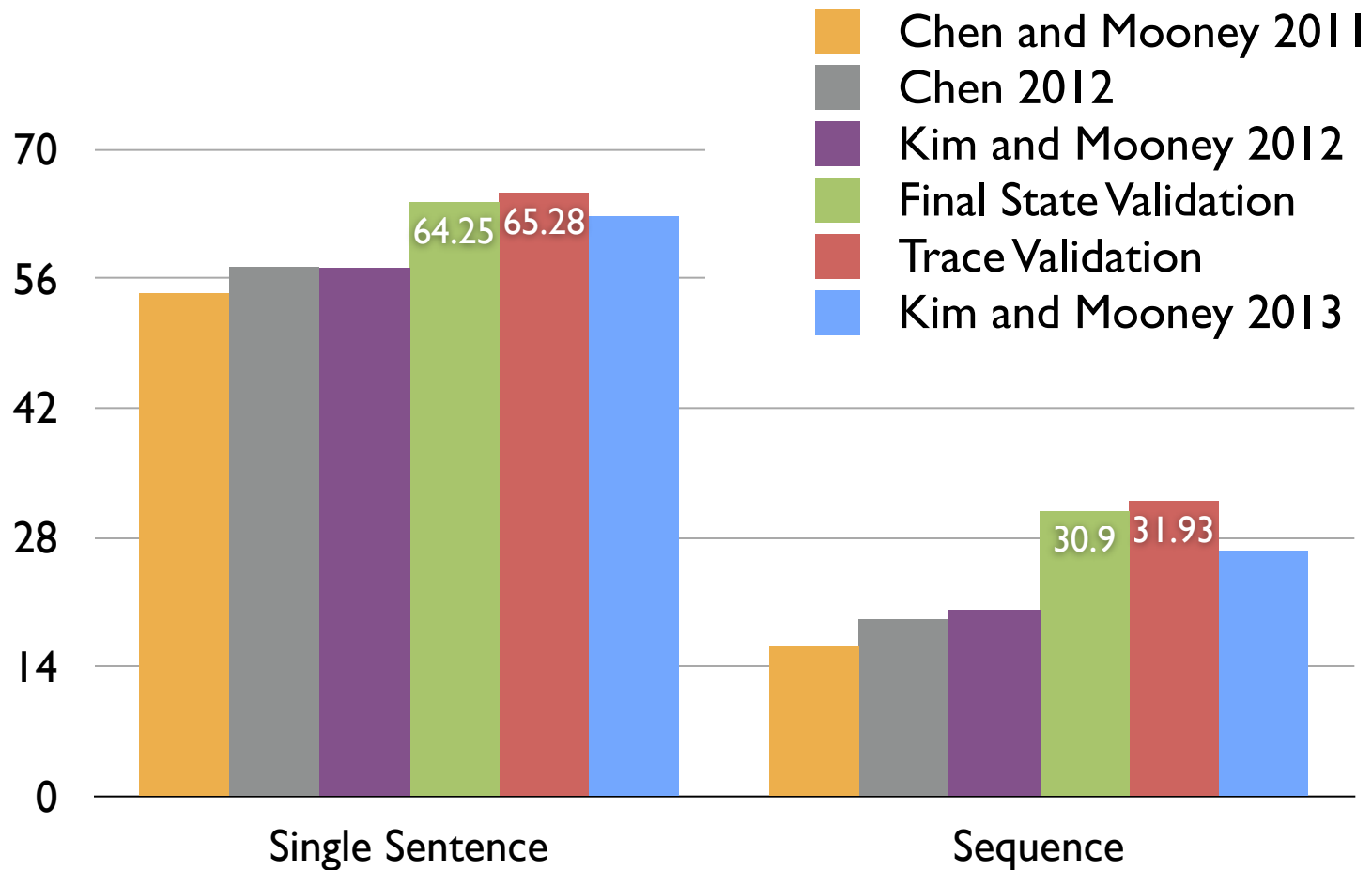
Results

SAIL Corpus - Cross Validation



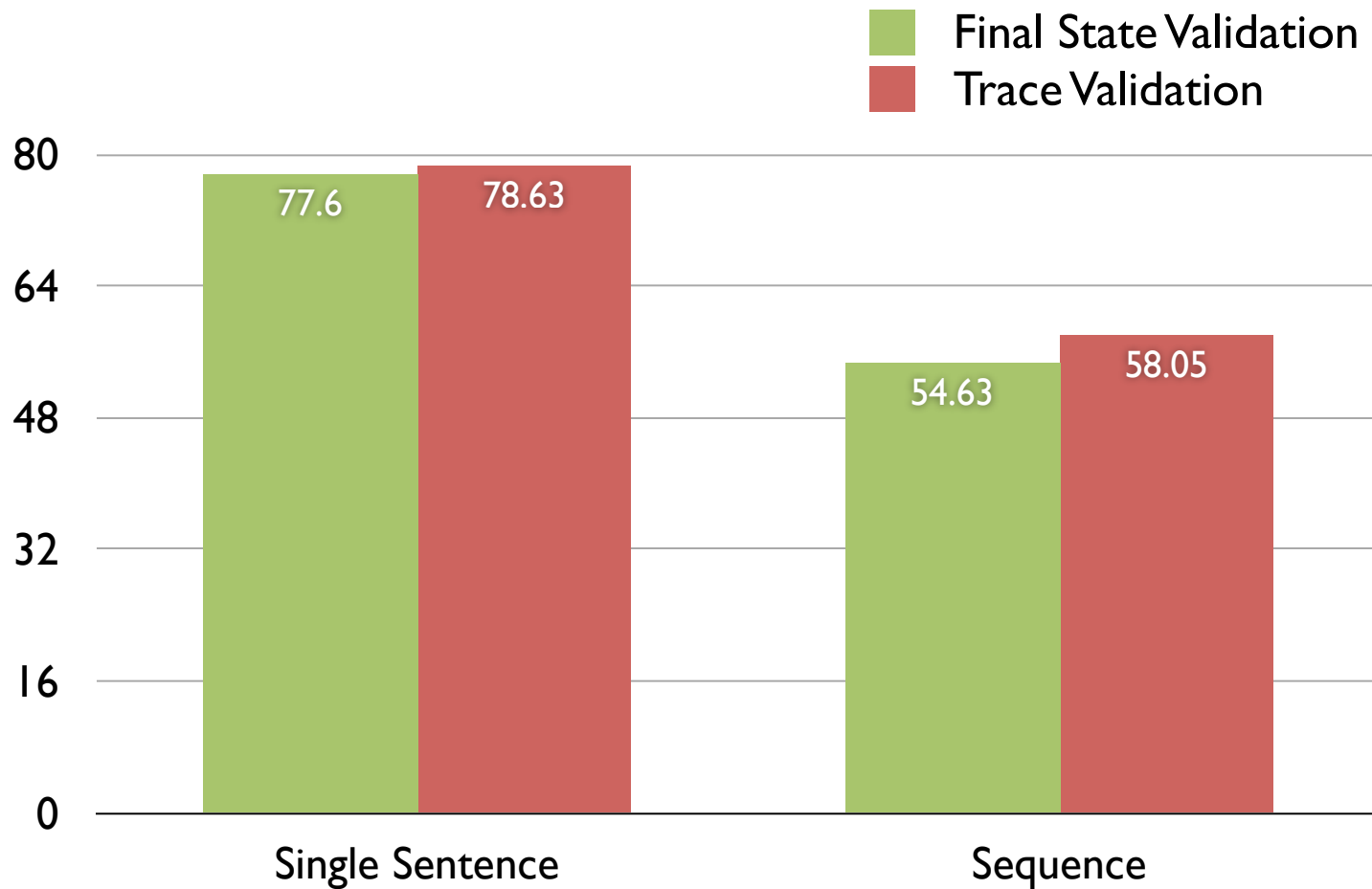
Results

SAIL Corpus - Cross Validation



Results

Oracle Corpus - Held-out Set



Contributions

- Linguistically-driven modeling of instructional language
- Joint inference for interpretation and execution of grounded language
- General weakly-supervised learning approach for semantic parsers

UW SPF

Open source semantic parsing framework

<http://yoavartzi.com/spf>

Semantic
Parser

Flexible High-Order
Logic Representation

Learning
Algorithms

UW SPF

Open source semantic parsing framework

<http://yoavartzi.com/spf>

Semantic
Parser

Flexible High-Order
Logic Representation

Learning
Algorithms

Navigation code and data available online

<http://yoavartzi.com/navi>

Coming up:
ACL tutorial

[fin]