

Real-Time Fluid Dynamics for Games

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Research

Alias|wavefront

Patent

Parts of this work protected under:

US Patent 6,266,071

Motivation

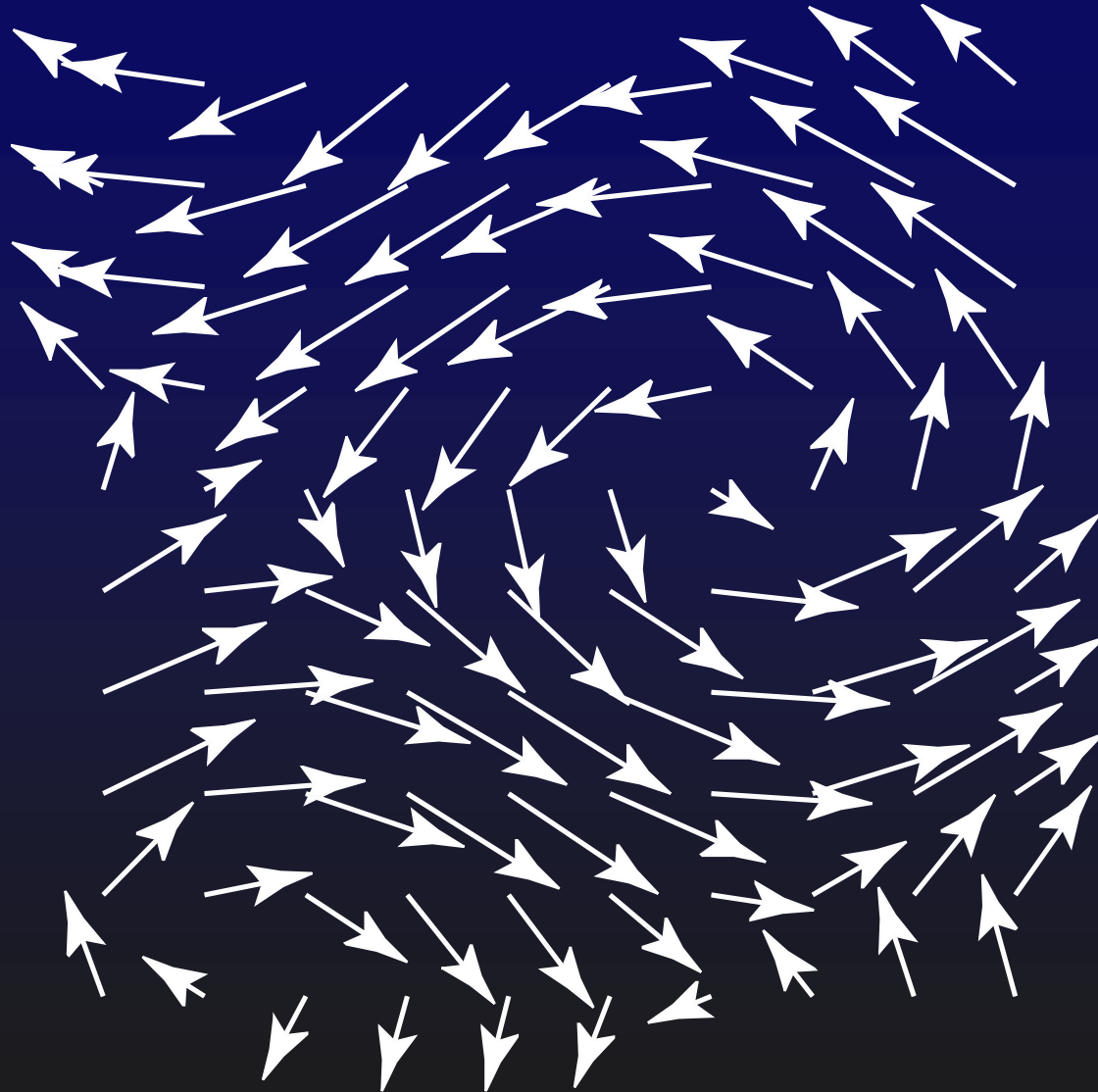
- **Has to Look Good**
- **Be Fast – Real-Time (Stable)**
- **And Simple to Code**

Important in Games !

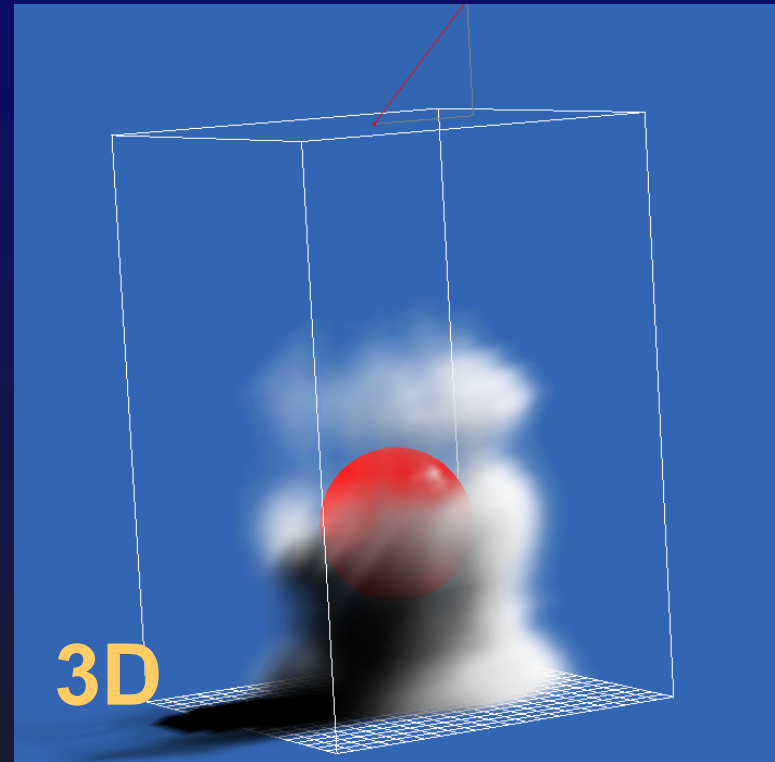
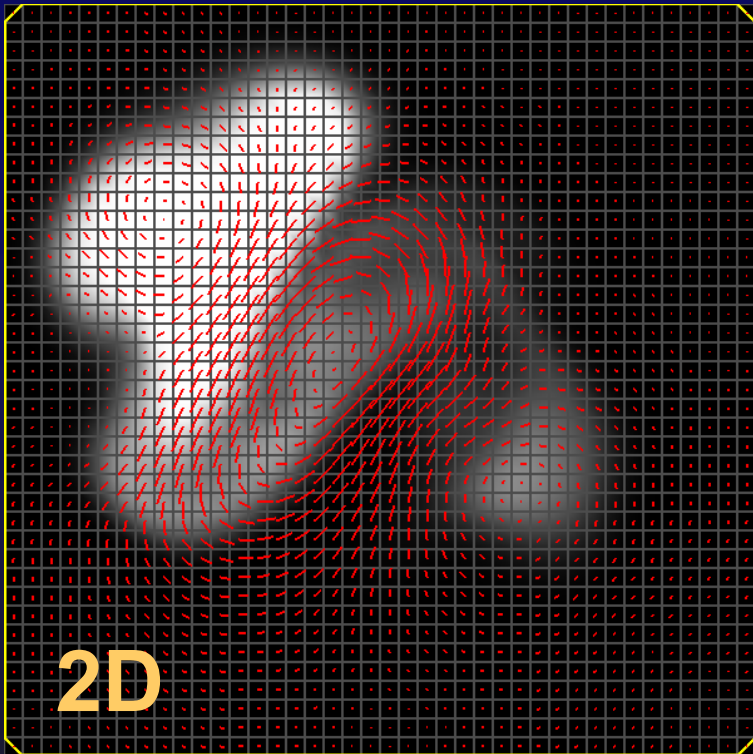
Fluid Mechanics

- **Natural Framework**
- **Lots of Previous Work !**
- **Very Hard Problem**
- **Visual Accuracy ?**

Fluid Mechanics



Main Application



Moving Densities

Main Application

While (Simulating)

Get Forces from UI

Get Source Densities from UI

Update Velocity Field

Update Density Field

Display Density

Navier-Stokes Equations

$$\frac{\partial \mathbf{u}}{\partial t} = -(\mathbf{u} \cdot \nabla) \mathbf{u} + \nu \nabla^2 \mathbf{u} + \mathbf{f}$$

Velocity

$$\frac{\partial \rho}{\partial t} = -(\mathbf{u} \cdot \nabla) \rho + \kappa \nabla^2 \rho + S$$

Density

Equations Very Similar

What Does it Mean ?

$$\boxed{\frac{\partial \rho}{\partial t}} = -(\mathbf{u} \cdot \nabla)\rho + \kappa \nabla^2 \rho + S$$

Over Time...

What Does it Mean ?

$$\frac{\partial \rho}{\partial t} = \boxed{-\mathbf{u} \cdot \nabla} \rho + \kappa \nabla^2 \rho + S$$

Density Follows Velocity...

What Does it Mean ?

$$\frac{\partial \rho}{\partial t} = -(\mathbf{u} \cdot \nabla) \rho + \boxed{\kappa \nabla^2 \rho} + S$$

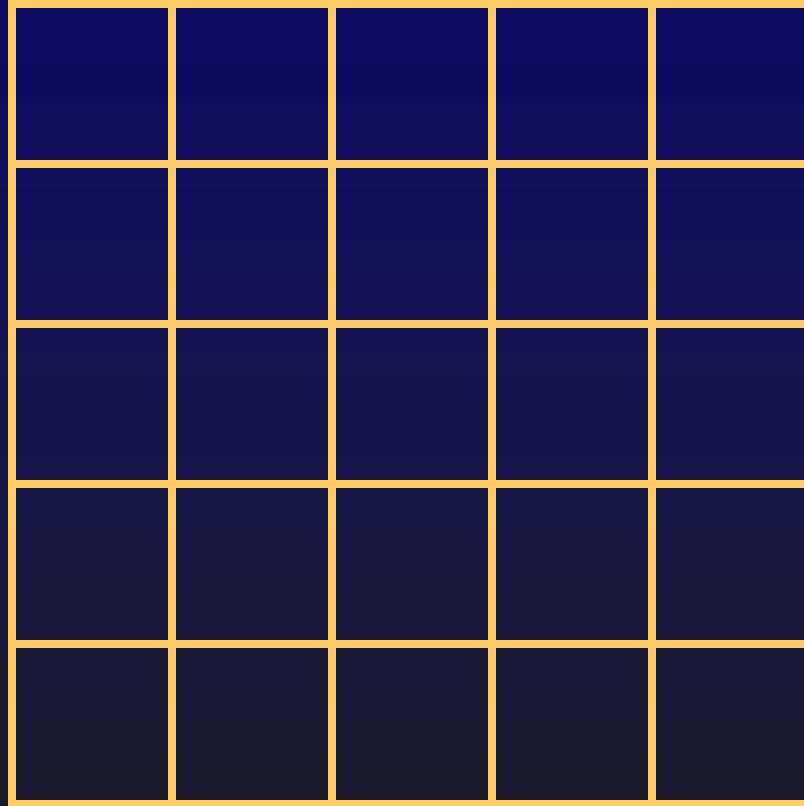
Density Diffuses at a Rate ... κ

What Does it Mean ?

$$\frac{\partial \rho}{\partial t} = -(\mathbf{u} \cdot \nabla) \rho + \kappa \nabla^2 \rho + S$$

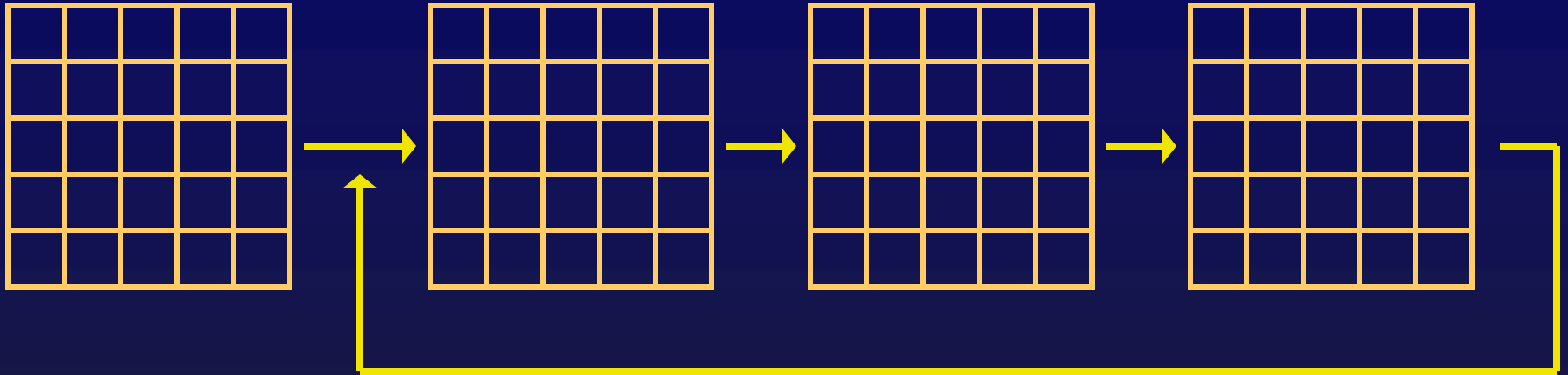
Density Increases Due to Sources...

Fluid in a Box



Density Constant in Each Cell

Simulation



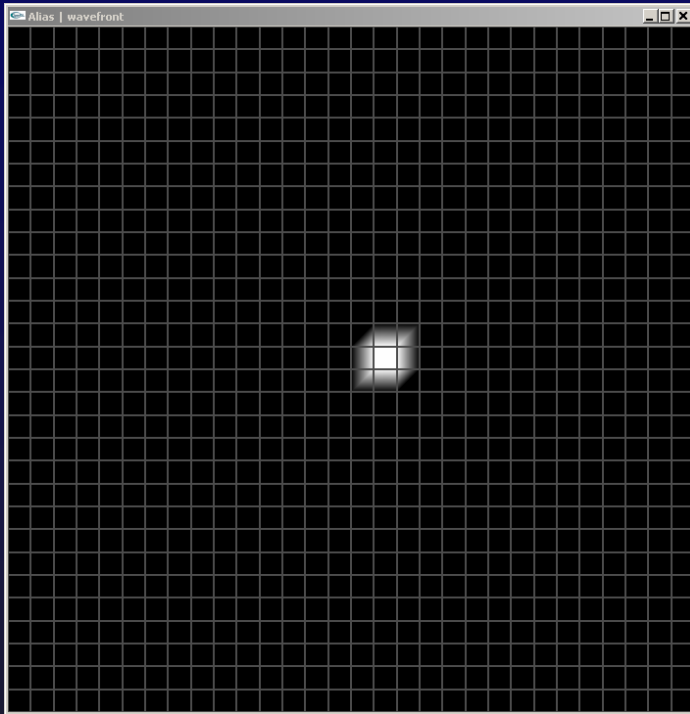
**Initial
State**

Add Sources

Diffuse

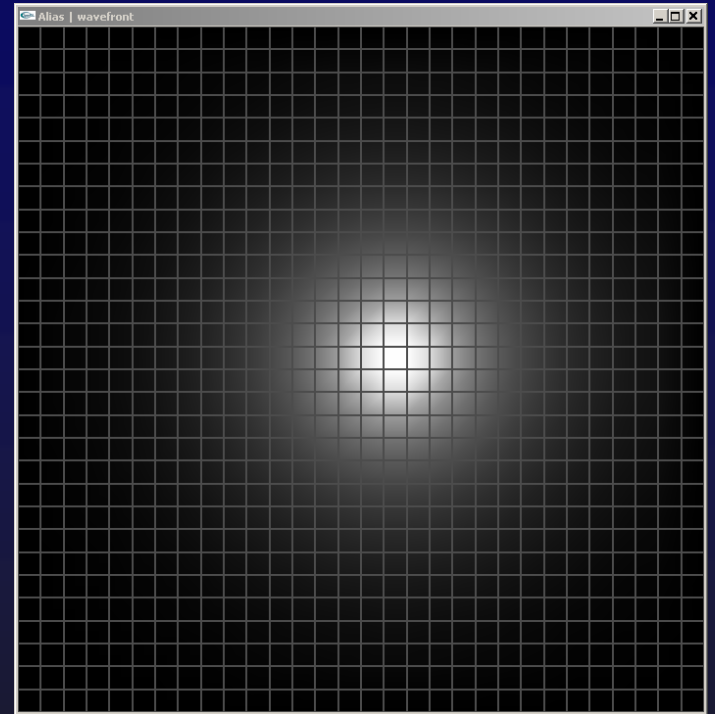
**Follow
Velocity**

Diffusion Step



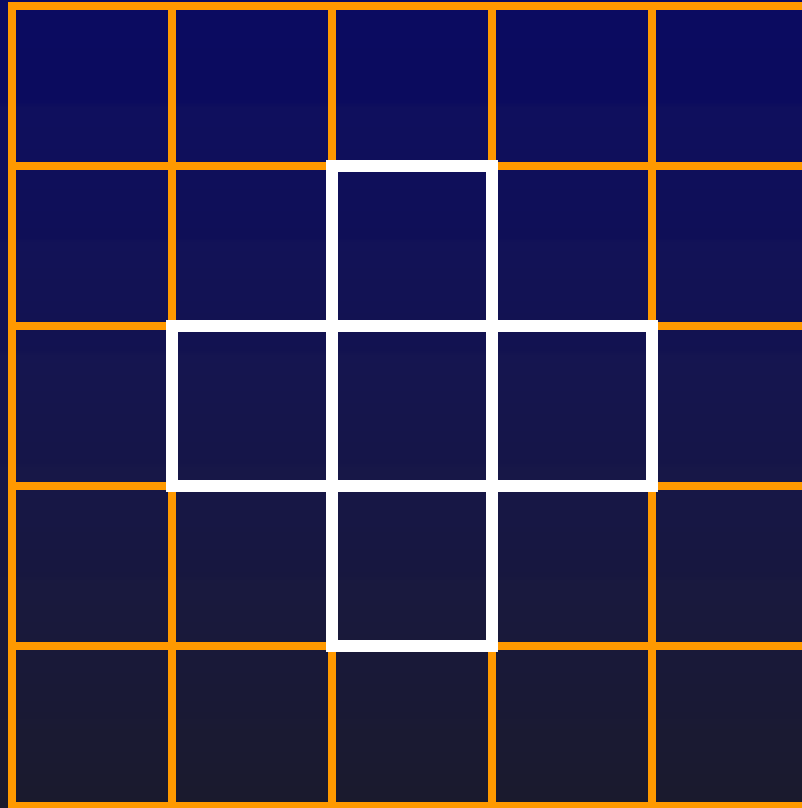
$\text{dens0}[i, j]$

→
 dt



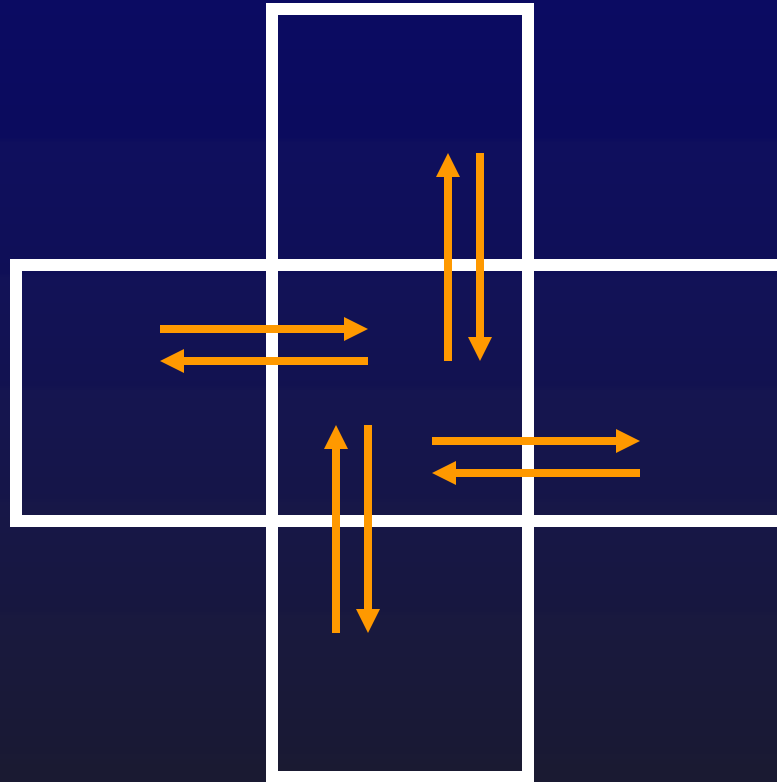
$\text{dens}[i, j]$

Diffusion Step



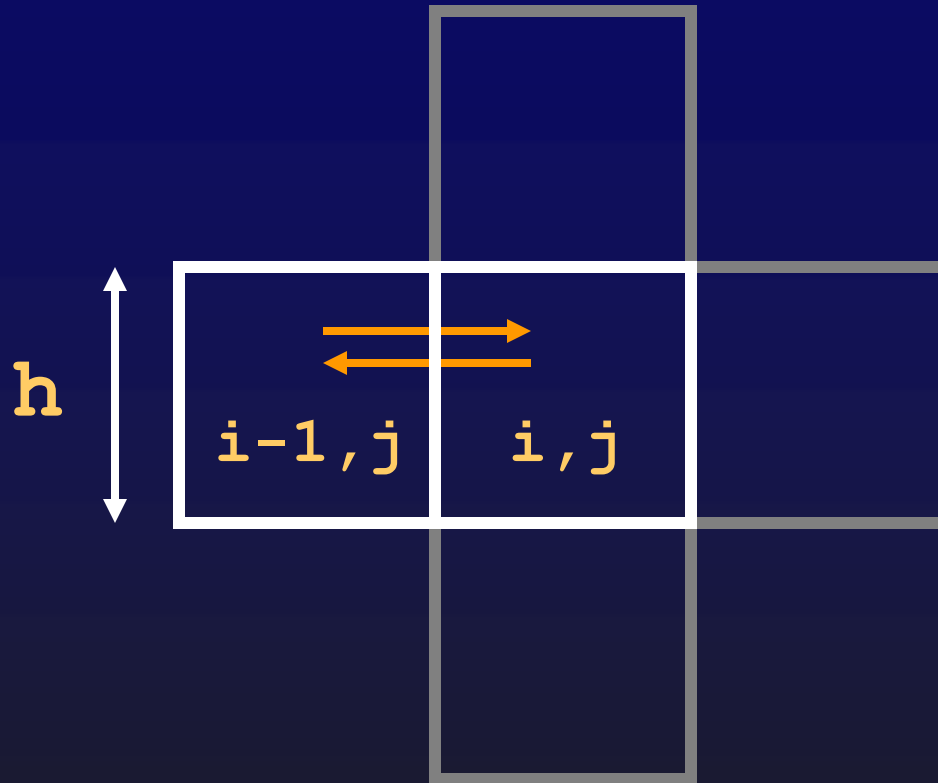
Exchanges Between Neighbors

Diffusion Step



Exchanges Between Neighbors

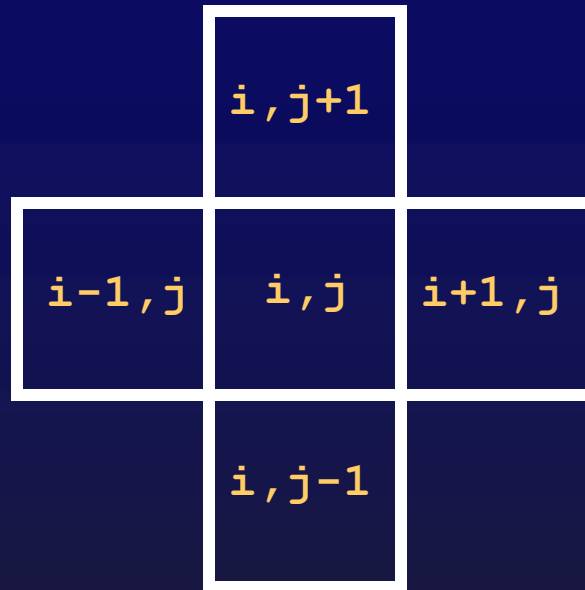
Diffusion Step



Change: Density Flux IN – Density Flux OUT

$$\text{diff} * dt * (\text{dens0}[i-1, j] - \text{dens0}[i, j]) / (h * h)$$

Diffusion Step



```
dens[i,j] = dens0[i,j] + a*(dens0[i-1,j]+dens0[i+1,j]+  
dens0[i,j-1]+dens0[i,j+1]-4*dens0[i,j]);
```

```
a = diff*dt/(h*h)
```

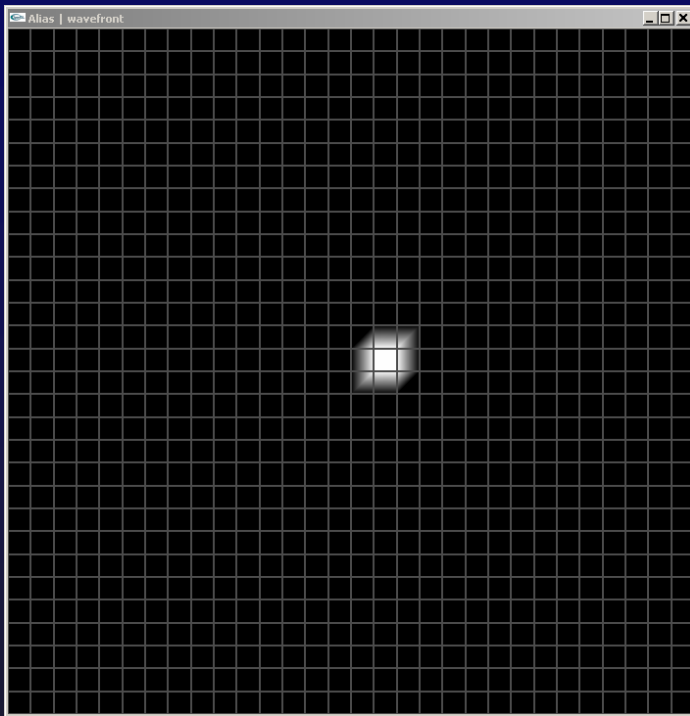
Diffusion Step

```
void diffuse_bad ( float * dens, float * dens0 )
{
    int i, j;
    float a = diff*dt/(h*h);

    for ( i=1 ; i<=N ; i++ ) {
        for ( j=1 ; j<=N ; j++ ) {
            dens[i,j] = dens0[i,j] + a*(dens0[i-1,j]+dens0[i+1,j]+
                dens0[i,j-1]+dens0[i,j+1]-4*dens0[i,j]);
        }
    }
}
```

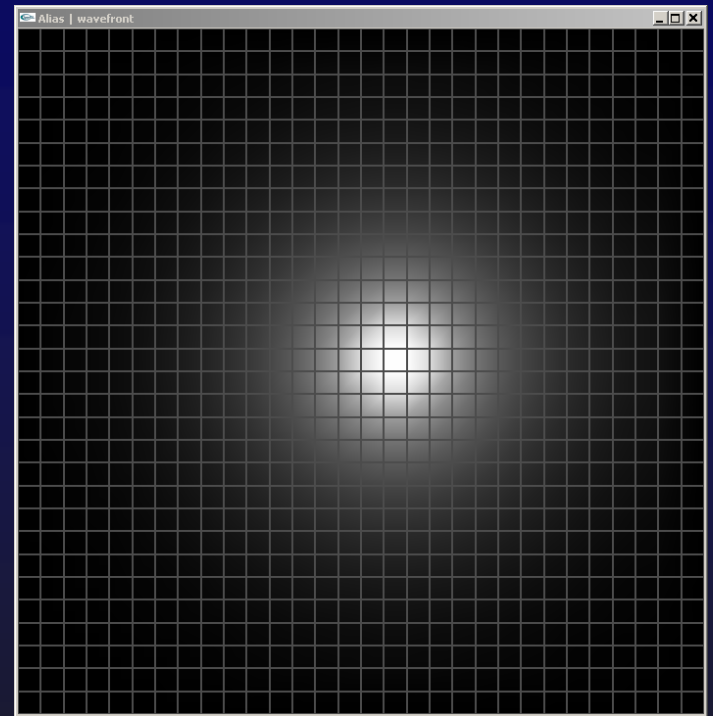
Simple But Doesn't Work: Unstable

Diffusion Step



$\text{dens0}[i, j]$

←
-dt



$\text{dens}[i, j]$

Diffuse Backwards: Stable

Diffusion Step

```
dens0[i,j] = dens[i,j] -  
    a*(dens[i-1,j]+dens[i+1,j]+  
        dens[i,j-1]+dens[i,j+1]-4*dens[i,j]);
```

Linear System: $Ax=b$

Use a Fast Sparse Solver

Linear Solvers

Gaussian Elimination	N^3
Gauss-Seidel Relaxation	N^2
Conjugate Gradient	$N^{1.5}$
Cyclical Reduction	$N \log N$
Multi-Grid	N

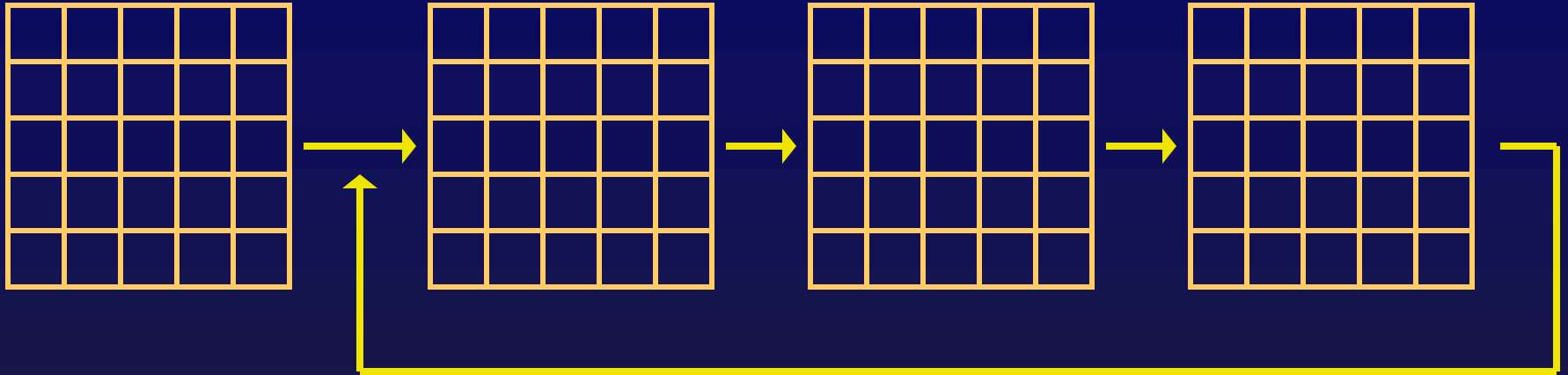
Diffusion Step

```
void lin_solve ( float * x, float * b, float a, float c )
{
    int i, j, n;

    for ( n=0 ; n<20 ; n++ ) {
        for ( i=1 ; i<=N ; i++ ) {
            for ( j=1 ; j<=N ; j++ ) {
                x[i,j] = (b[i,j] + a*(x[i-1,j]+x[i+1,j]+
                                     x[i,j-1]+x[i,j+1]))/c;
            }
        }
    }
}

void diffuse ( float * dens, float * dens0 )
{
    float a = diff*dt/(h*h);
    lin_solve ( dens, dens0, a, 1+4*a );
}
```


Simulation



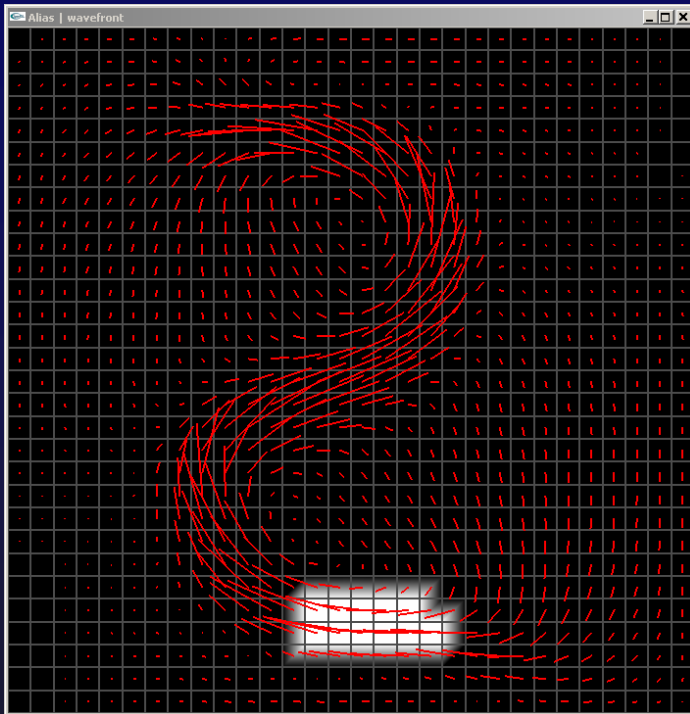
**Initial
State**

Add Sources

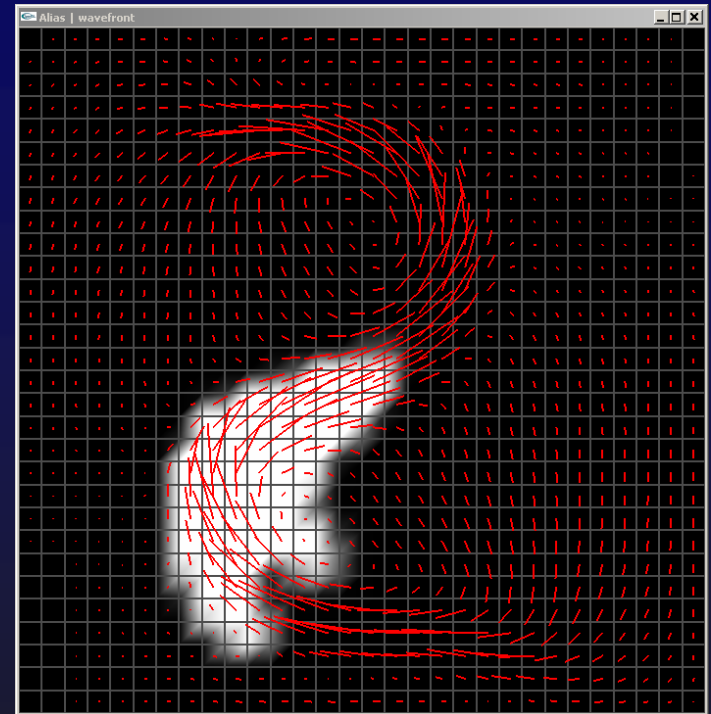
Diffuse

**Follow
Velocity**

Follow Velocity



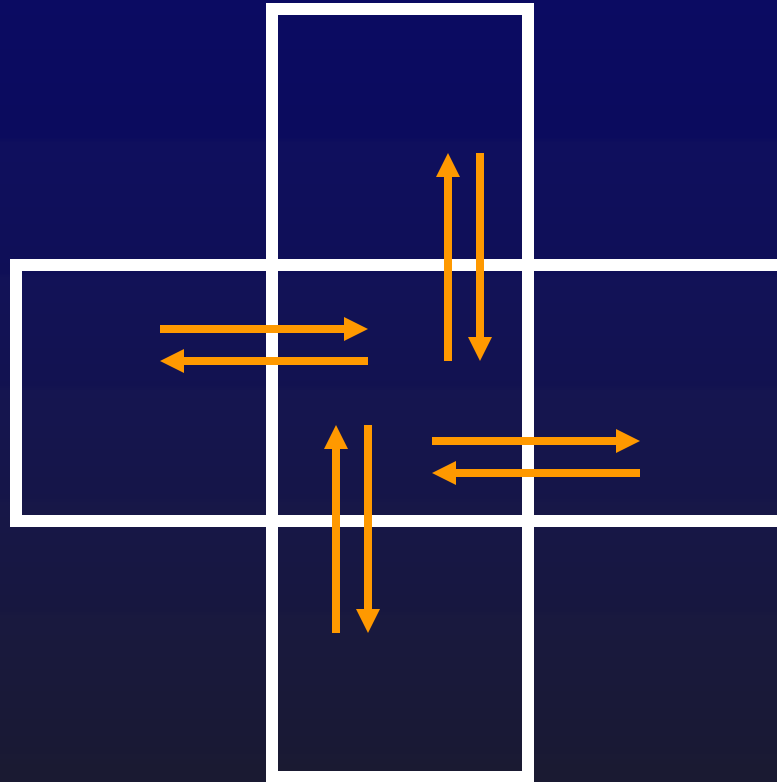
→
dt



$\text{dens0}[i, j]$
 $u[i, j], v[i, j]$

$\text{dens}[i, j]$

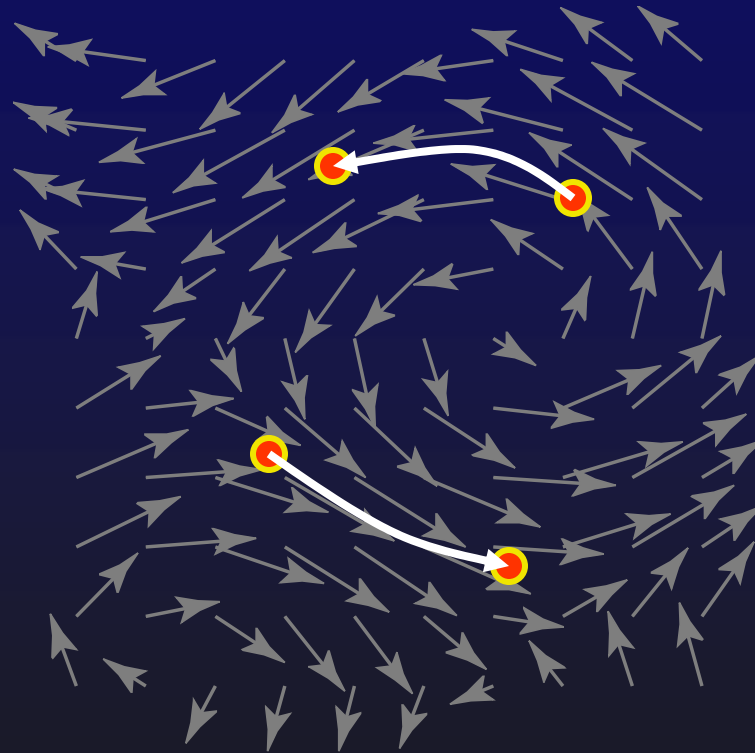
Follow Velocity



Fluxes Depend on Velocity

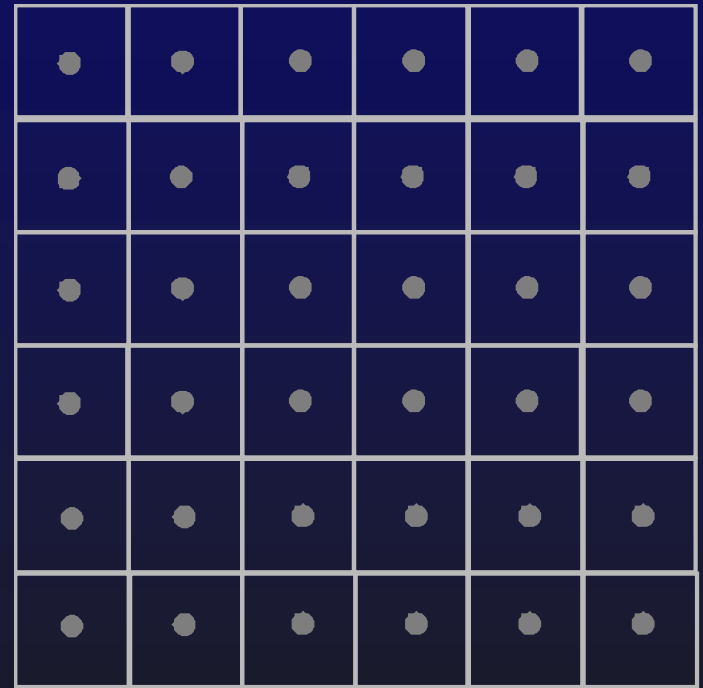
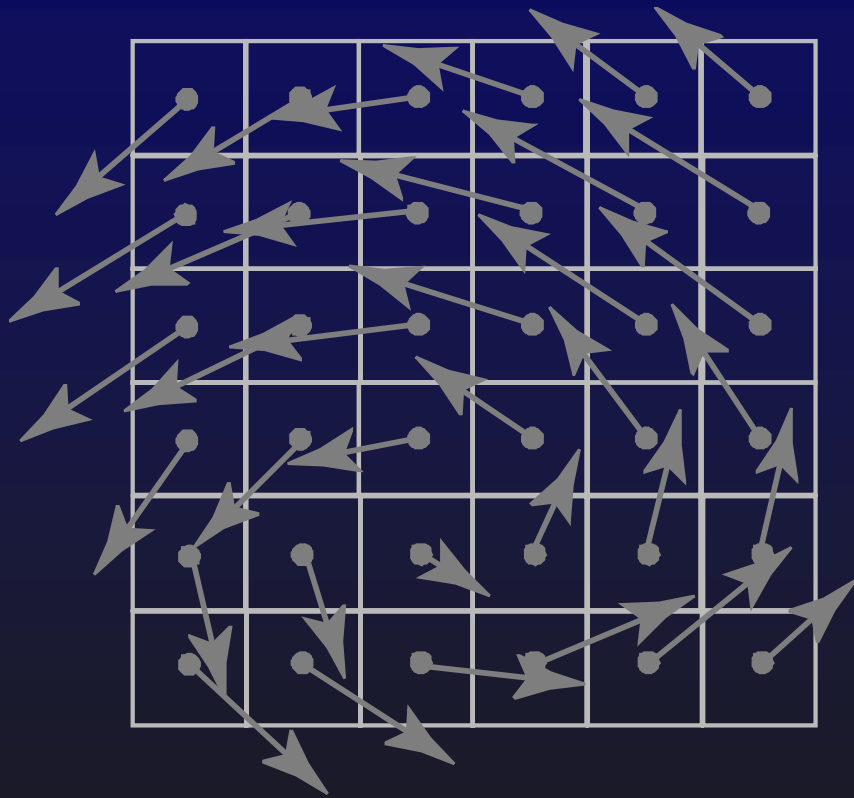
Follow Velocity

Better Idea:



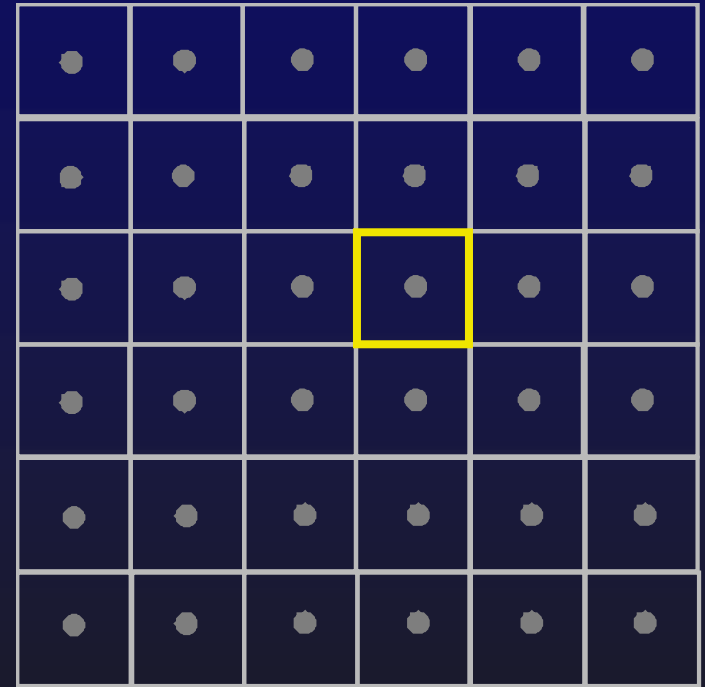
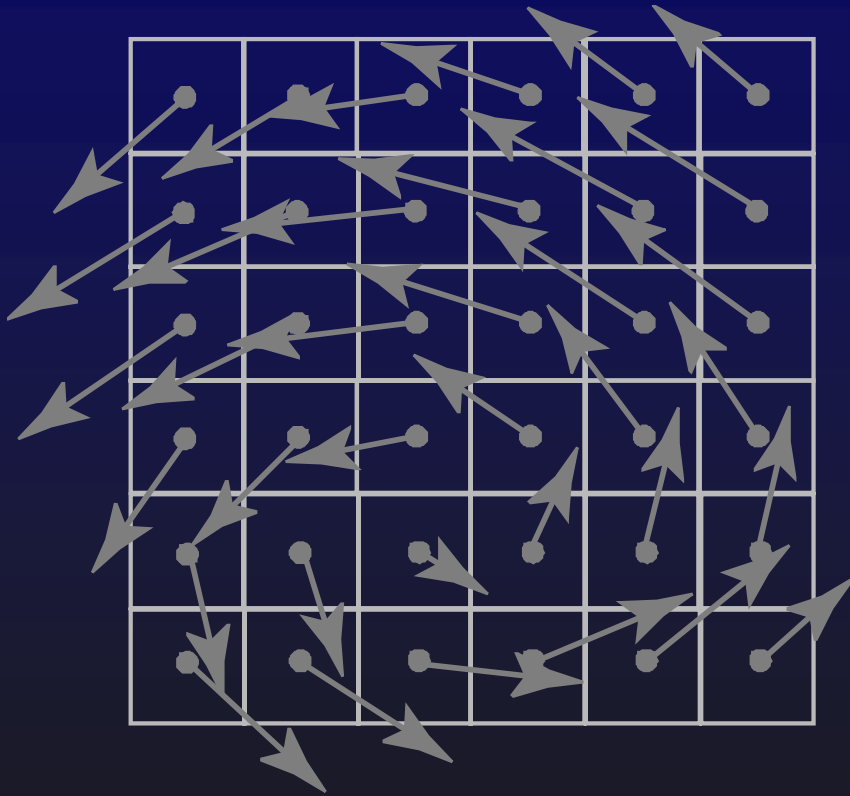
Step Easy If Density Were Particles

Follow Velocity



Follow Velocity

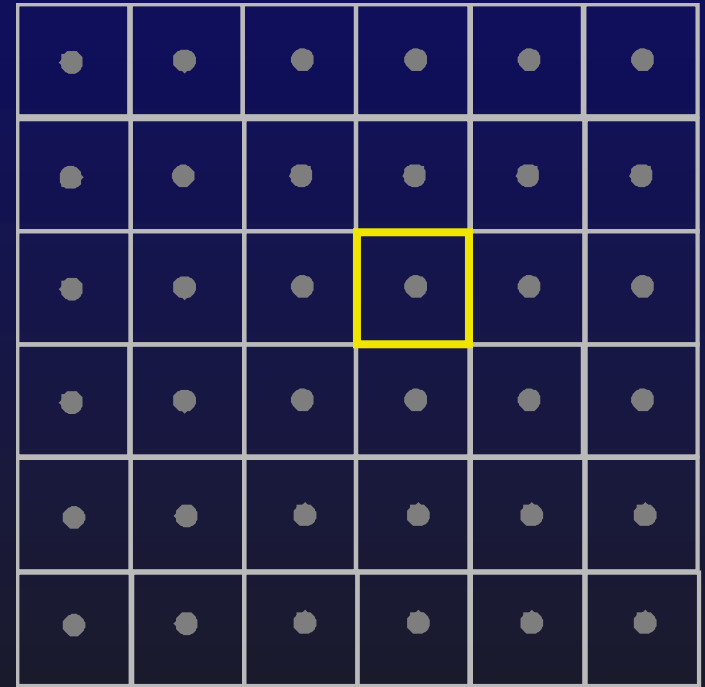
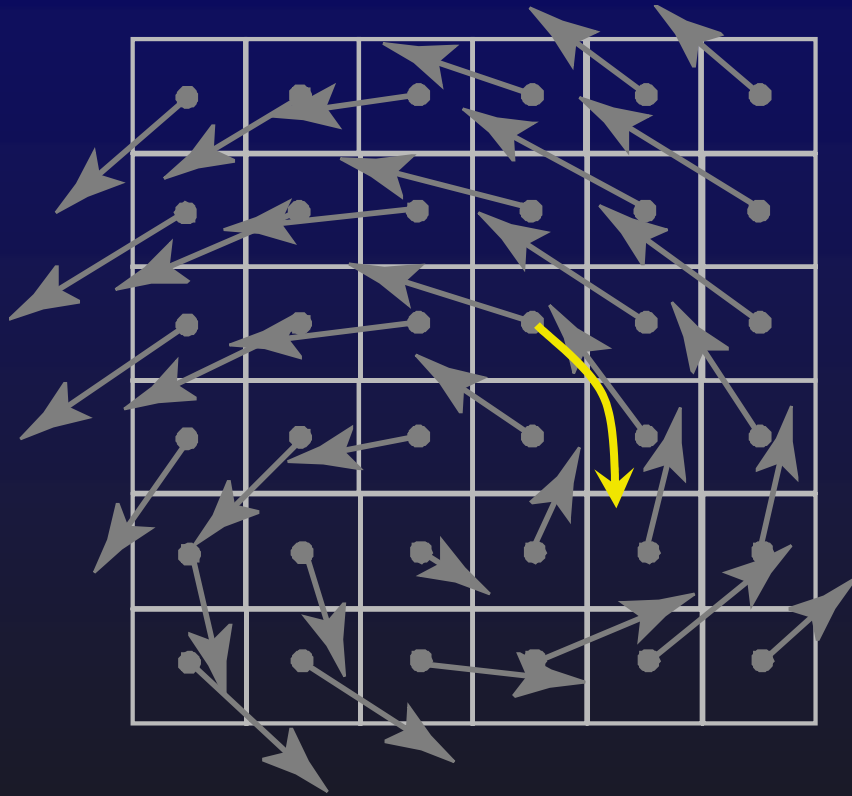
For Each Cell...



`dens[i, j]`

Follow Velocity

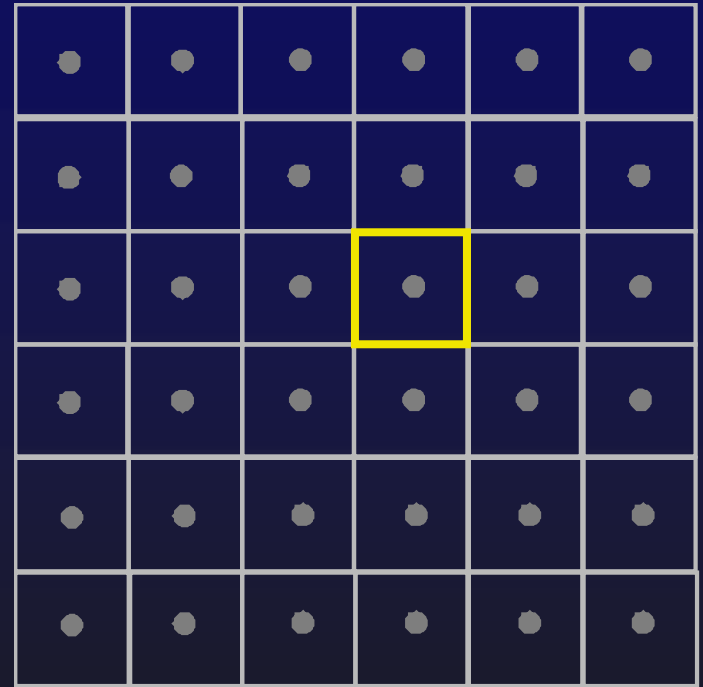
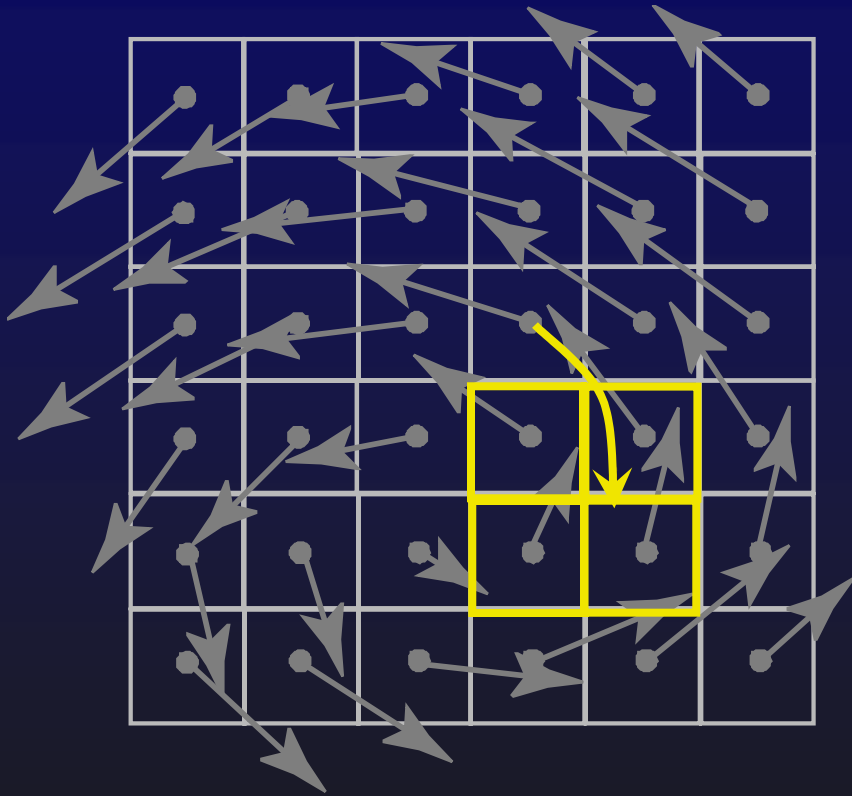
Trace BackWard



```
x = i-dt*u[i,j];  
y = j-dt*v[i,j];
```

Follow Velocity

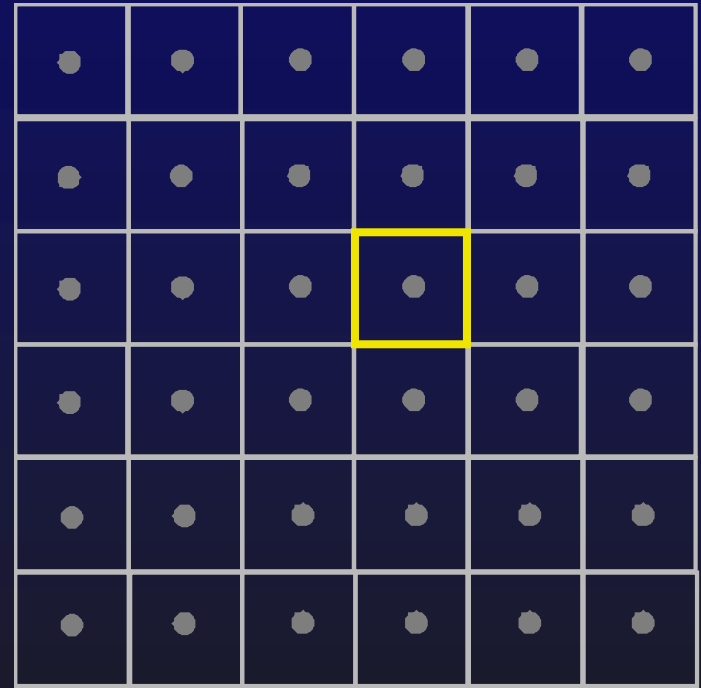
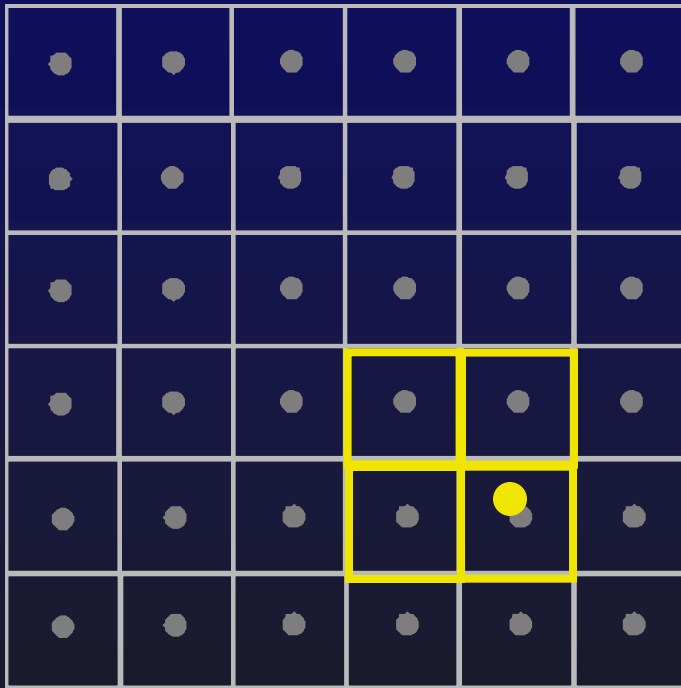
Find Four Neighbors



```
i0 = (int)x; i1=i0+1; s=x-i0;  
j0 = (int)y; j1=j0+1; t=y-j0;
```


Follow Velocity

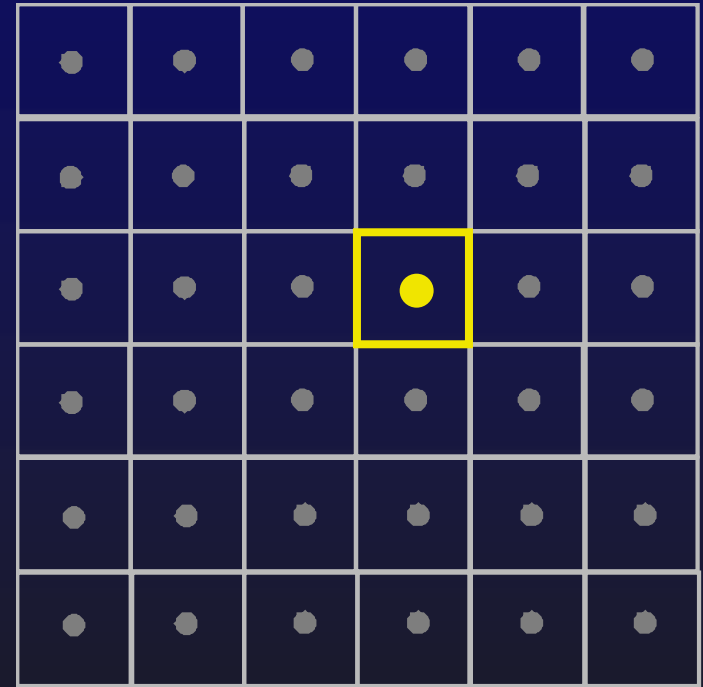
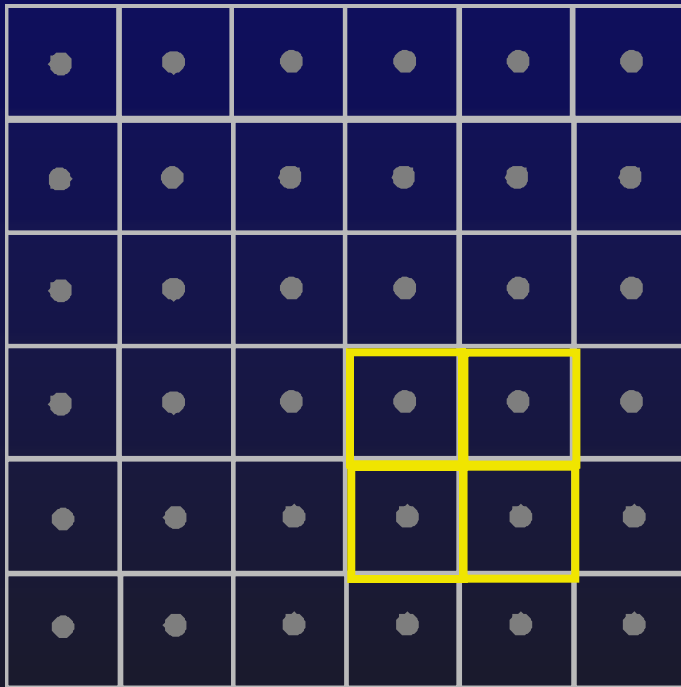
Interpolate From Neighbors



$$d = (1-s) * ((1-t) * \text{dens0}[i0, j0] + t * \text{dens0}[i0, j1]) + s * ((1-t) * \text{dens0}[i1, j0] + t * \text{dens0}[i1, j1]);$$

Follow Velocity

Set Interpolated Value in Cell



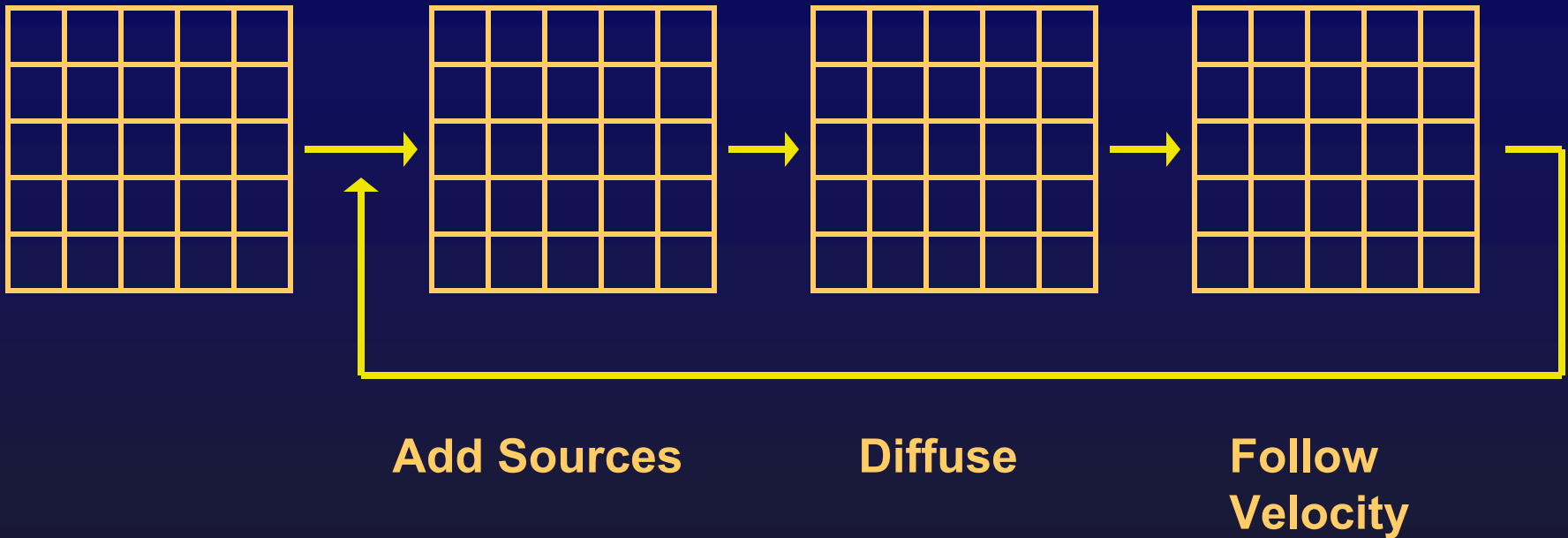
```
dens[i,j] = d;
```

Follow Velocity

```
void advect ( float * dens, float * dens0,
float * u, float * v )
{
    int i, j, i0, j0, i1, j1;
    float x, y, s0, t0, s1, t1;

    for ( i=1 ; i<=N ; i++ ) {
        for ( j=1 ; j<=N ; j++ ) {
            x = i-dt*u[i,j]; y = j-dt*v[i,j];
            if (x<0.5) x=0.5; if (x>N+0.5) x=N+0.5;
            if (y<0.5) y=0.5; if (y>N+0.5) y=N+0.5;
            i0=(int)x; i1=i0+1; j0=(int)y; j1=j0+1;
            s1 = x-i0; s0 = 1-s1; t1 = y-j0; t0 = 1-t1;
            dens[i,j] = t0*(s0*dens0[i0,j0]+s1*dens0[i0,j1])+
                t1*(s0*dens0[i1,j0]+s1*dens0[i1,j1]);
        }
    }
}
```

Simulation



```
void dens_step ()  
{  
    add_sources (dens) ;  
    SWAP (dens , dens0) ; diffuse (dens , dens0) ;  
    SWAP (dens , dens0) ; advect (dens , dens0 , u , v) ;  
}
```

Navier-Stokes Equations

$$\frac{\partial \mathbf{u}}{\partial t} = -(\mathbf{u} \cdot \nabla) \mathbf{u} + \nu \nabla^2 \mathbf{u} + \mathbf{f}$$

Velocity

$$\frac{\partial \rho}{\partial t} = -(\mathbf{u} \cdot \nabla) \rho + \kappa \nabla^2 \rho + S$$

Density

Velocity Solver

```
void velocity_step ()
{
    add_sources (u) ;
    add_sources (v) ;
    SWAP (u, u0) ; SWAP (v, v0) ;
    diffuse (u, u0) ;
    diffuse (v, v0) ;
    SWAP (u, u0) ; SWAP (v, v0) ;
    advect (u, u0, u0, v0) ;
    advect (v, v0, u0, v0) ;
    project (u, v, u0, v0) ;
}
```

```
void dens_step ()
{
    add_sources (dens) ;

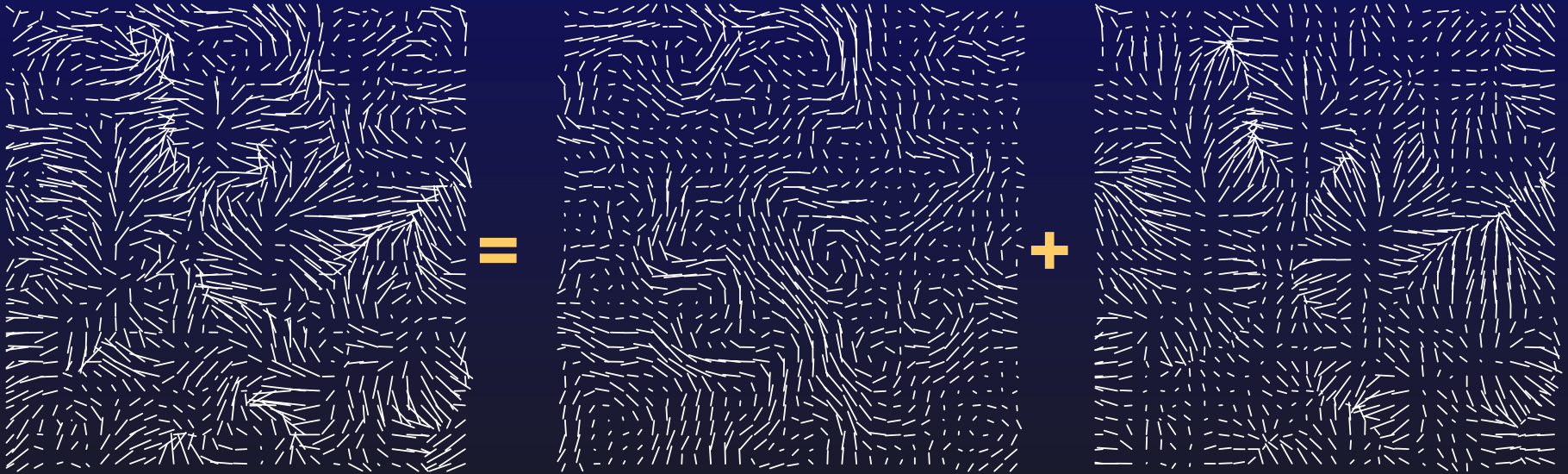
    SWAP (dens, dens0) ;
    diffuse (dens, dens0) ;

    SWAP (dens, dens0) ;
    advect (dens, dens0, u, v) ;
}
```

**Reuse Density Solver Code
Except for one Routine...**

Projection Step

Hodge Decomposition:



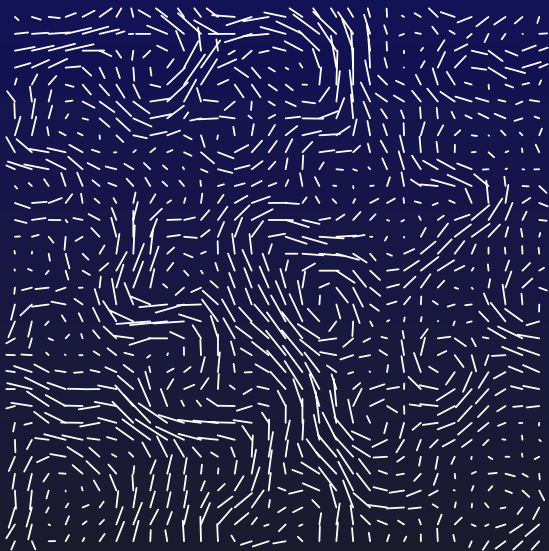
Any Field

Mass Conserving

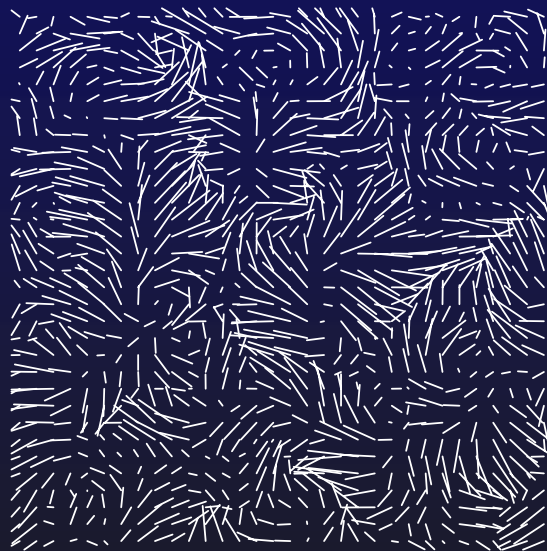
Gradient

Projection Step

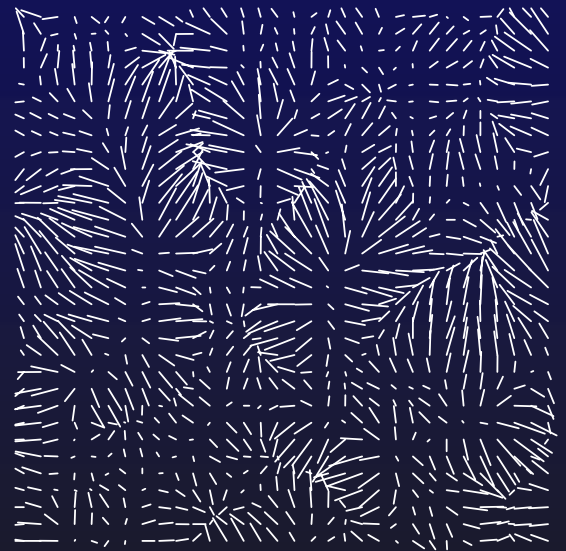
Subtract Gradient Field



=



-



Mass Conserving

Any Field

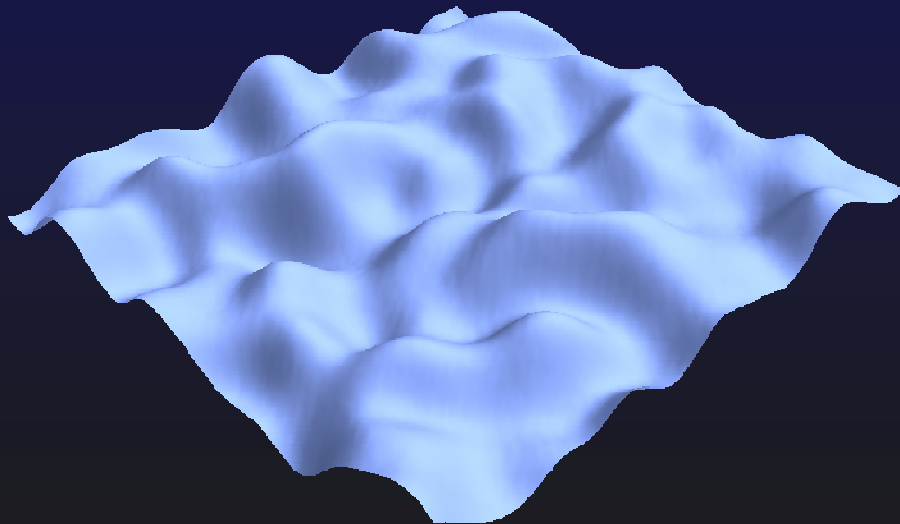
Gradient

Projection Step

Gradient: Direction of steepest Descent of a height field.

$$G_x[i, j] = 0.5 * (p[i+1, j] - p[i-1, j]) / h$$

$$G_y[i, j] = 0.5 * (p[i, j+1] - p[i, j-1]) / h$$



$p[i, j]$

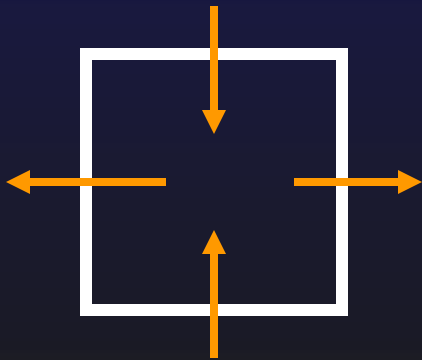
Projection Step

Height Field satisfies a Poisson Equation

$$4*p[i,j]-p[i+1,j]+p[i-1,j]+p[i,j+1]+p[i,j-1] = \text{div}[i,j]$$

$$\text{div}[i,j] = -0.5*h*(u[i+1,j]-u[i-1,j]+v[i,j+1]-v[i,j-1])$$

Ideally div is zero: Flow IN = Flow OUT

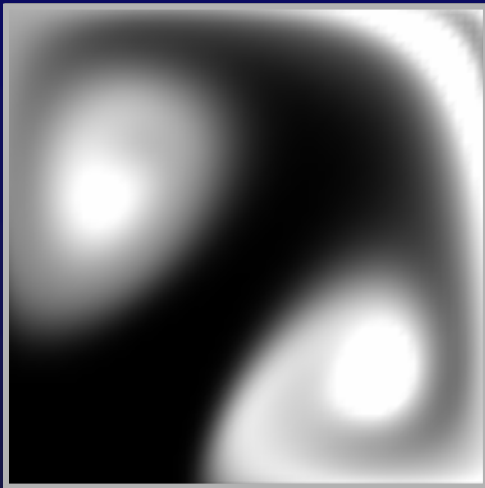


Reuse linear solver of the diffusion step

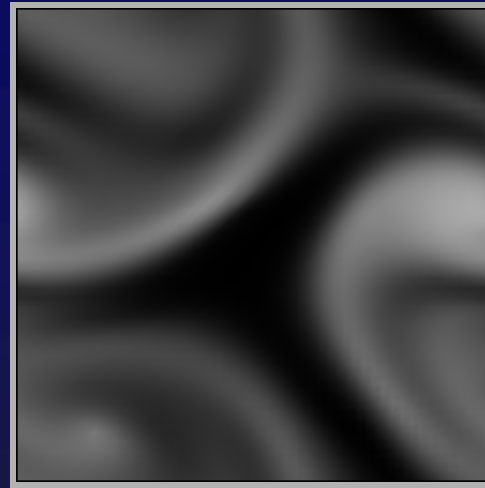
Projection Step

```
void project ( float * u, float * v, float * div, float * p )
{
    int i, j;
    // compute divergence
    for ( i=1 ; i<=N ; i++ ) {
        for ( j=1 ; j<=N ; j++ ) {
            div[i,j] = -0.5*h*(u[i+1,j]-u[i-1,j]+v[i,j+1]-v[i,j-1]);
            p[i,j] = 0.0;
        }
    }
    set_bnd ( 0, div ); set_bnd ( 0, p );
    // solve Poisson equation
    lin_solve ( p, div, 1, 4 );
    // subtract gradient field
    for ( i=1 ; i<=N ; i++ ) {
        for ( j=1 ; j<=N ; j++ ) {
            u[i,j] -= 0.5*(p[i+1,j]-p[i-1,j])/h;
            v[i,j] -= 0.5*(p[i,j+1]-p[i,j-1])/h;
        }
    }
}
```

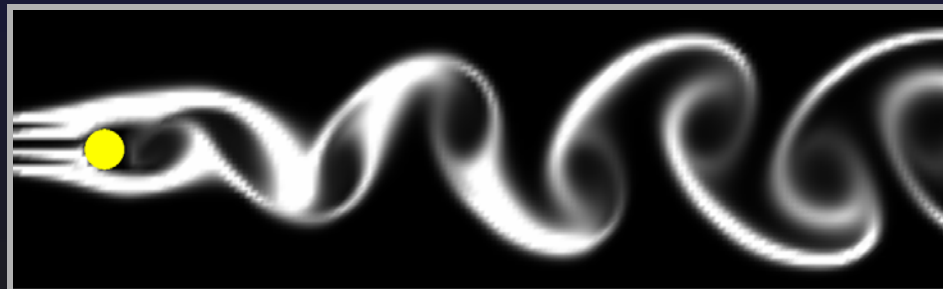
Boundaries



Fixed Walls



Periodic



Inflow + internal

Boundaries



Add another layer around the grid

Boundaries

	0.5	0.1	0.2	
	0.4	0.2	0.0	
	0.2	0.1	0.0	

Densities: simply copy over values

Boundaries

0.0	0.5	0.1	0.2	0.0
-0.5	0.5	0.1	0.2	-0.2
-0.4	0.4	0.2	0.0	-0.0
-0.2	0.2	0.1	0.0	-0.0
0.0	0.2	0.1	0.0	0.0

U-velocity: zero on vertical boundaries

Boundaries

0.0	-0.5	-0.1	-0.2	0.0
0.5	0.5	0.1	0.2	0.2
0.4	0.4	0.2	0.0	0.0
0.2	0.2	0.1	0.0	0.0
0.0	-0.2	-0.1	-0.0	0.0

V-velocity: zero on horizontal boundaries

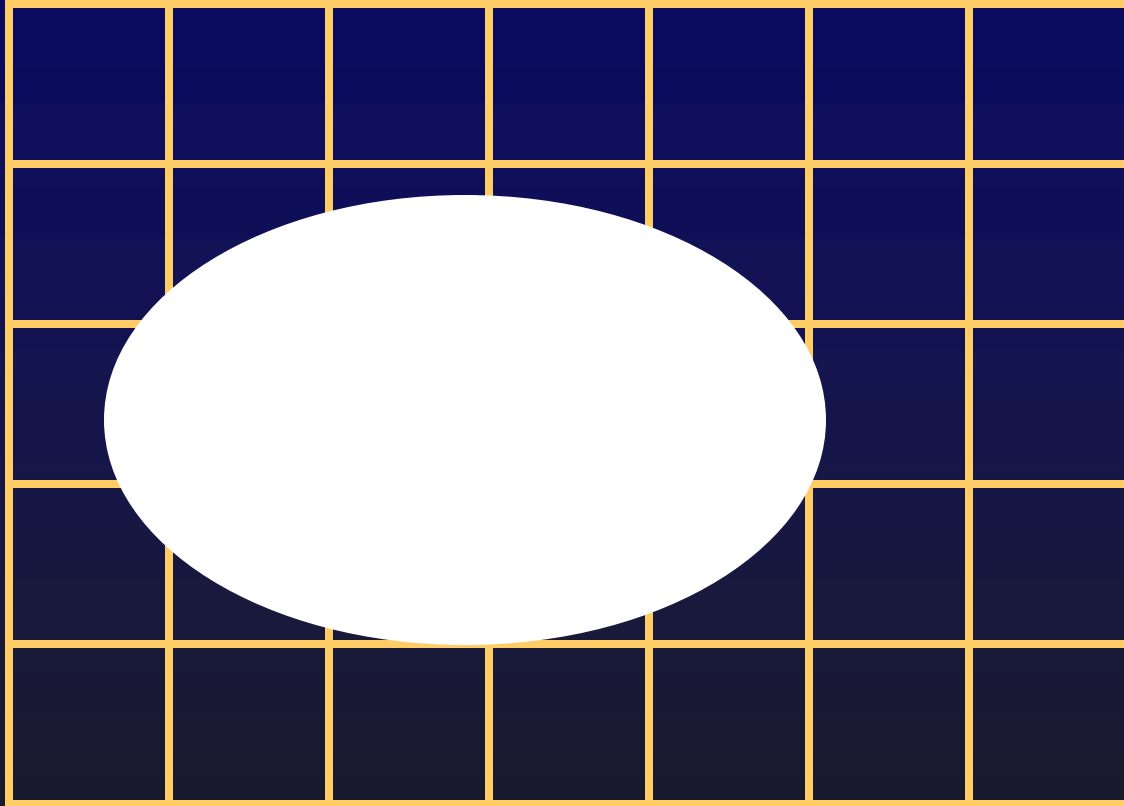
Boundaries

```
void set_bnd ( int b, float * x )
{
    int i;

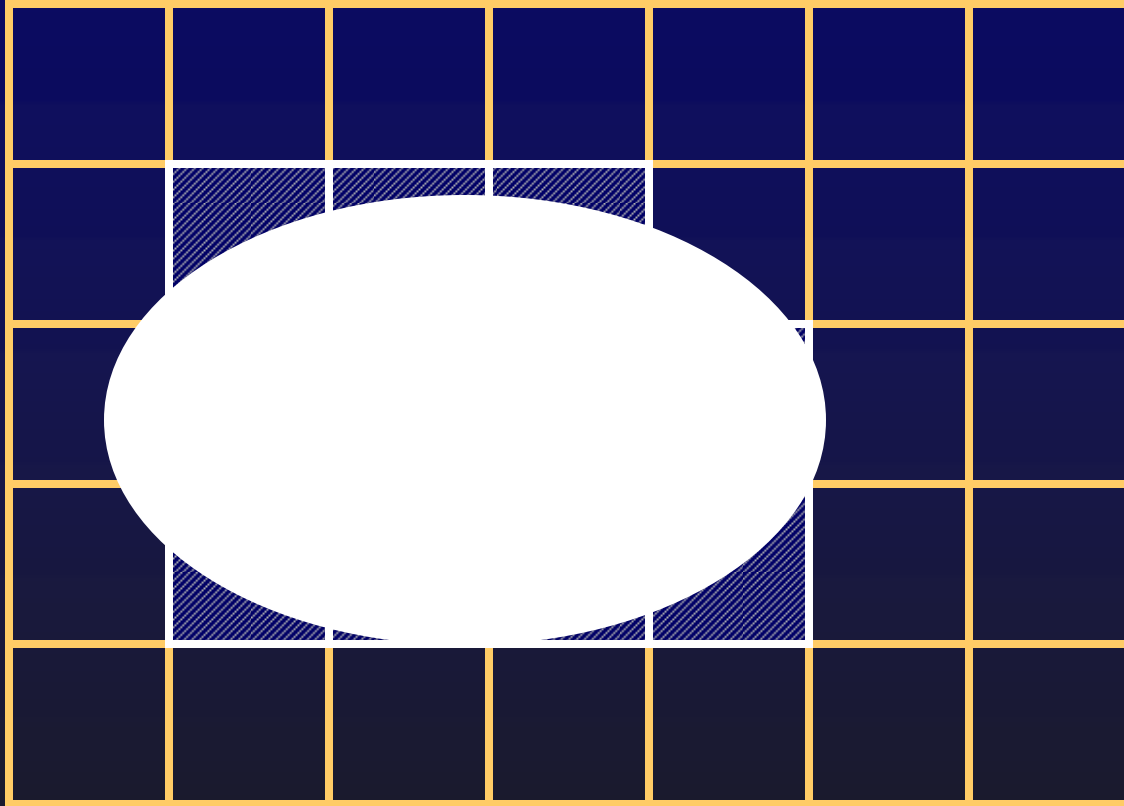
    for ( i=1 ; i<=N ; i++ ) {
        x[0 ,i ] = b==1 ? -x[1,i] : x[1,i];
        x[N+1,i ] = b==1 ? -x[N,i] : x[N,i];
        x[i ,0 ] = b==2 ? -x[i,1] : x[i,1];
        x[i ,N+1] = b==2 ? -x[i,N] : x[i,N];
    }
    x[0 ,0 ] = 0.5*(x[1,0 ]+x[0 ,1]);
    x[0 ,N+1] = 0.5*(x[1,N+1]+x[0 ,N]);
    x[N+1,0 ] = 0.5*(x[N,0 ]+x[N+1,1]);
    x[N+1,N+1] = 0.5*(x[N,N+1]+x[N+1,N]);
}
```

Call after every update of the grids

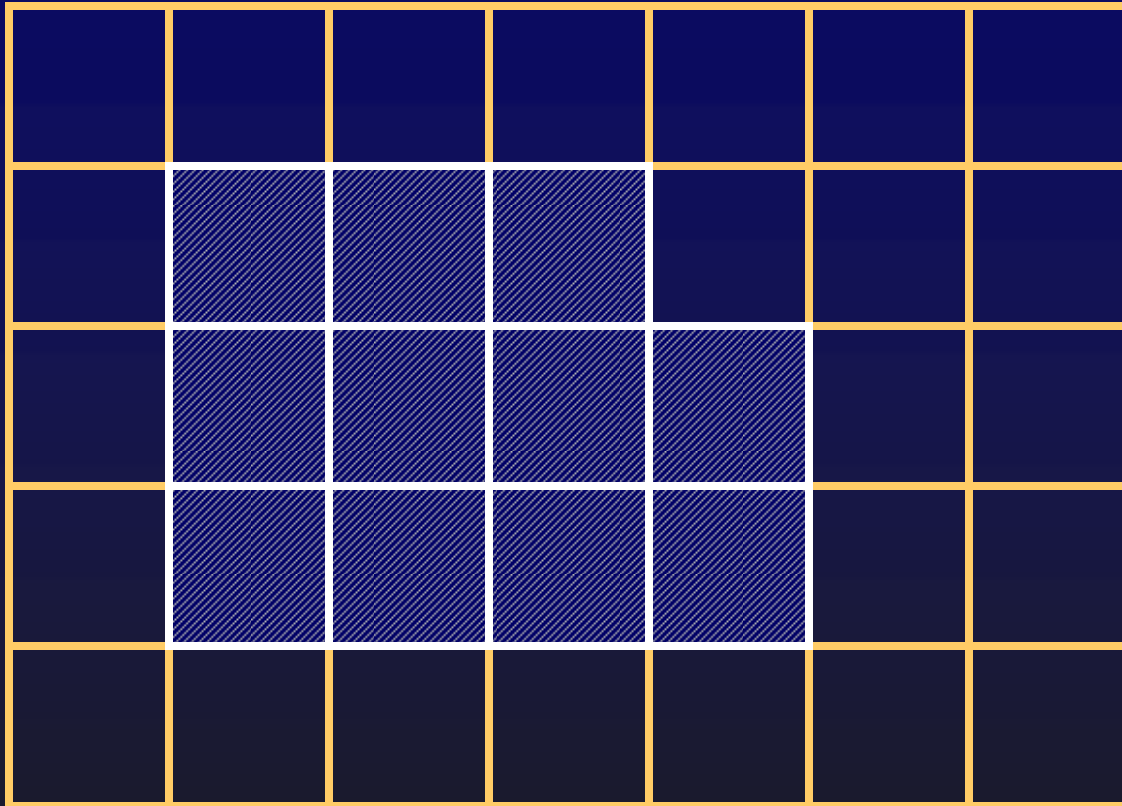
Internal Boundaries



Internal Boundaries



Internal Boundaries



Internal Boundaries

0.0	0.0	0.5	0.1	0.2	0.1	0.3
0.4				0.3	0.2	0.5
0.6					0.5	0.6
0.5					0.8	0.7
0.5	0.1	0.2	0.1	0.2	0.7	0.9

For density

Internal Boundaries

0.0	0.0	0.5	0.1	0.2	0.1	0.3
0.4	0.2	0.5	0.2	0.3	0.2	0.5
0.6	0.6	0.0	0.0	0.4	0.5	0.6
0.5	0.2	0.2	0.1	0.5	0.8	0.7
0.5	0.1	0.2	0.1	0.2	0.7	0.9

For density

The Code

Entire solver in 100 lines of
(readable) C-code...

```

#define IX(i,j) ((i)+(N+2)*(j))
#define SWAP(x0,x) {float * tmp=x0;x0=x;x=tmp;}
#define FOR_EACH_CELL for ( i=1 ; i<=N ; i++ ) {\
                for ( j=1 ; j<=N ; j++ ) {
#define END_FOR }}

```

```

void add_source(int N, float *x, float *s, float dt)
{
    int i, size=(N+2)*(N+2);
    for ( i=0 ; i<size ; i++ ) x[i] += dt*s[i];
}

```

```

void set_bnd(int N, int b, float *x)
{
    int i;

    for ( i=1 ; i<=N ; i++ ) {
        x[IX(0 ,i)] = b==1 ? -x[IX(1,i)] : x[IX(1,i)];
        x[IX(N+1,i)] = b==1 ? -x[IX(N,i)] : x[IX(N,i)];
        x[IX(i,0 )] = b==2 ? -x[IX(i,1)] : x[IX(i,1)];
        x[IX(i,N+1)] = b==2 ? -x[IX(i,N)] : x[IX(i,N)];
    }
    x[IX(0 ,0 )] = 0.5f*(x[IX(1,0 )]+x[IX(0 ,1)]);
    x[IX(0 ,N+1)] = 0.5f*(x[IX(1,N+1)]+x[IX(0 ,N)]);
    x[IX(N+1,0 )] = 0.5f*(x[IX(N,0 )]+x[IX(N+1,1)]);
    x[IX(N+1,N+1)] = 0.5f*(x[IX(N,N+1)]+x[IX(N+1,N)]);
}

```

```

void lin_solve(int N, int b, float *x, float *x0,
float a, float c)
{
    int i, j, n;

    for ( n=0 ; n<20 ; n++ ) {
        FOR_EACH_CELL
            x[IX(i,j)] = (x0[IX(i,j)]+a*(x[IX(i-1,j)]+
                x[IX(i+1,j)]+x[IX(i,j-1)]+x[IX(i,j+1)]))/c;
        END_FOR
        set_bnd ( N, b, x );
    }
}

```

```

void diffuse(int N, int b, float *x, float *x0,
float diff, float dt)
{
    float a=dt*diff*N*N;
    lin_solve ( N, b, x, x0, a, 1+4*a );
}

```

```

void advect(int N, int b, float *d, float *d0, float *u, float *v, float dt)
{
    int i, j, i0, j0, i1, j1;
    float x, y, s0, t0, s1, t1, dt0;

    dt0 = dt*N;
    FOR_EACH_CELL
        x = i-dt0*u[IX(i,j)]; y = j-dt0*v[IX(i,j)];
        if (x<0.5f) x=0.5f; if (x>N+0.5f) x=N+0.5f; i0=(int)x; i1=i0+1;
        if (y<0.5f) y=0.5f; if (y>N+0.5f) y=N+0.5f; j0=(int)y; j1=j0+1;
        s1 = x-i0; s0 = 1-s1; t1 = y-j0; t0 = 1-t1;
        d[IX(i,j)] = s0*(t0*d0[IX(i0,j0)]+t1*d0[IX(i0,j1)])+
            s1*(t0*d0[IX(i1,j0)]+t1*d0[IX(i1,j1)]);
    END_FOR
    set_bnd ( N, b, d );
}

```

```

void project(int N, float * u, float * v, float * p, float * div)
{
    int i, j;

    FOR_EACH_CELL
        div[IX(i,j)] = -0.5f*(u[IX(i+1,j)]-u[IX(i-1,j)]+v[IX(i,j+1)]-v[IX(i,j-1)])/N;
        p[IX(i,j)] = 0;
    END_FOR
    set_bnd ( N, 0, div ); set_bnd ( N, 0, p );

    lin_solve ( N, 0, p, div, 1, 4 );

    FOR_EACH_CELL
        u[IX(i,j)] -= 0.5f*N*(p[IX(i+1,j)]-p[IX(i-1,j)]);
        v[IX(i,j)] -= 0.5f*N*(p[IX(i,j+1)]-p[IX(i,j-1)]);
    END_FOR
    set_bnd ( N, 1, u ); set_bnd ( N, 2, v );
}

```

```

void dens_step(int N, float *x, float *x0, float *u, float *v, float diff, float dt)
{
    add_source ( N, x, x0, dt );
    SWAP ( x0, x ); diffuse ( N, 0, x, x0, diff, dt );
    SWAP ( x0, x ); advect ( N, 0, x, x0, u, v, dt );
}

```

```

void vel_step(int N, float *u, float *v, float *u0, float *v0, float visc, float dt)
{
    add_source ( N, u, u0, dt ); add_source ( N, v, v0, dt );
    SWAP ( u0, u ); diffuse ( N, 1, u, u0, visc, dt );
    SWAP ( v0, v ); diffuse ( N, 2, v, v0, visc, dt );
    project ( N, u, v, u0, v0 );
    SWAP ( u0, u ); SWAP ( v0, v );
    advect ( N, 1, u, u0, u0, v0, dt ); advect ( N, 2, v, v0, u0, v0, dt );
    project ( N, u, v, u0, v0 );
}

```


Guide to the Litterature

(Computational Fluid Dynamics)

Diffusion Step -- Implicit Methods

- Any standard text in numerical methods

Advection Step -- Semi-Lagrangian

- Courant et al., *Comm. Pure & App. Math.*, 1952.
- Weather Forecasting
- Rediscovered many times...

Projection Step -- Projection Methods

- Chorin, *Math. Comput.*, 1969.

Guide to the Litterature

(Computer Graphics)

Vortex Blob – Restricted to 2D

- Upson & Yaeger, Proc. *SIGGRAPH*, 1986.
- Gamito et al., *Eurographics*, 1995.

Explicit Finite Differences -- Unstable

- Foster & Metaxas, *GMIP*, 1996.
- Foster & Metaxas, Proc. *SIGGRAPH*, 1997.
- Chen et al., *IEEE CG&A*, 1997.

Implicit—Semi-Lagrangian -- Stable

- Stam, Proc. *SIGGRAPH*, 1999.

Fedkiw's Group at Stanford

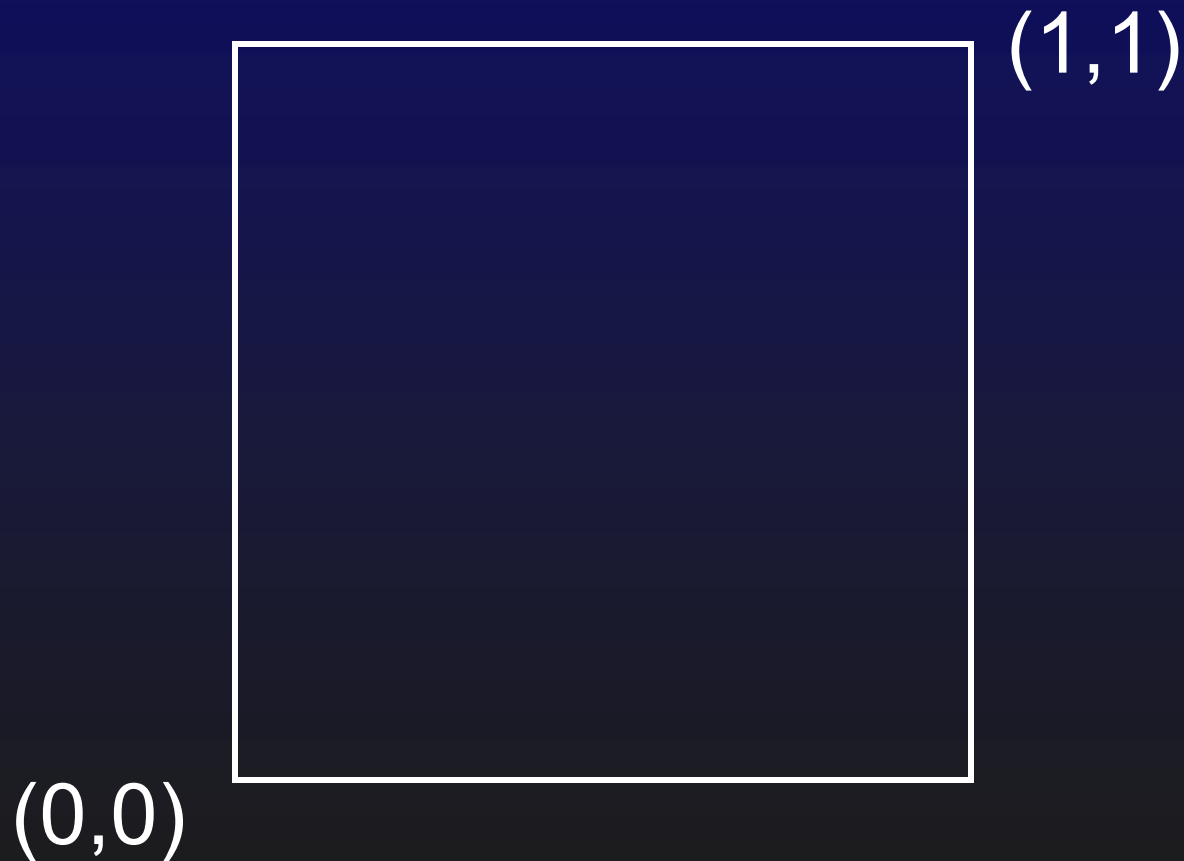
Demo

Show 2D Demos



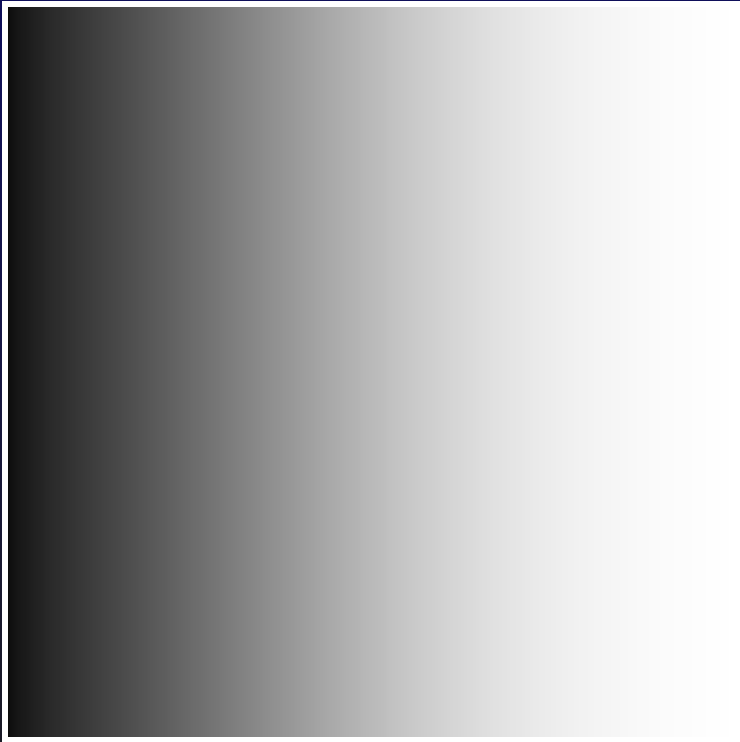
Liquid Textures

Animate texture coordinates

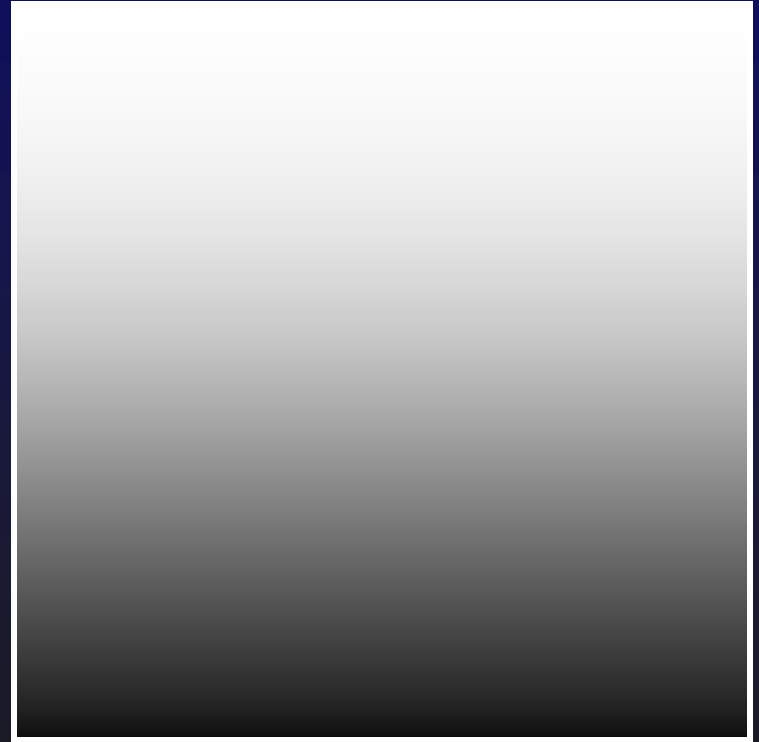


Liquid Textures

Treat texture coordinate as a density

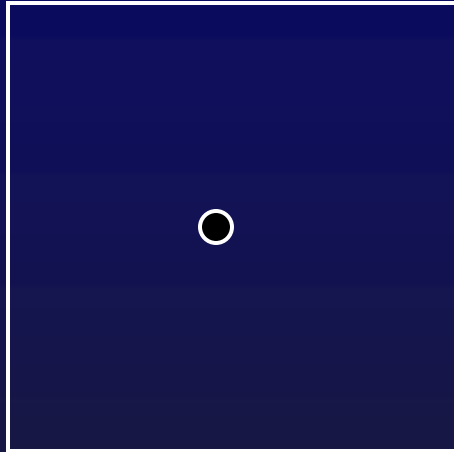


U-coordinate

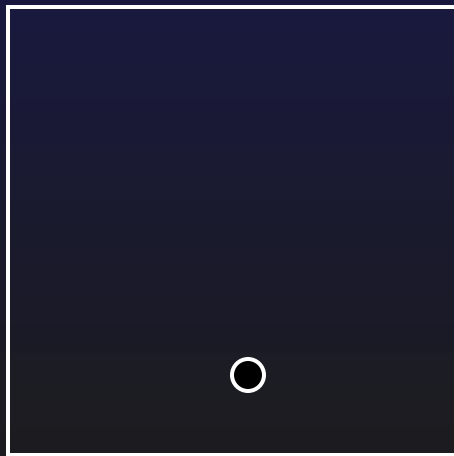


V-coordinate

Liquid Textures



(0.5,0.5)

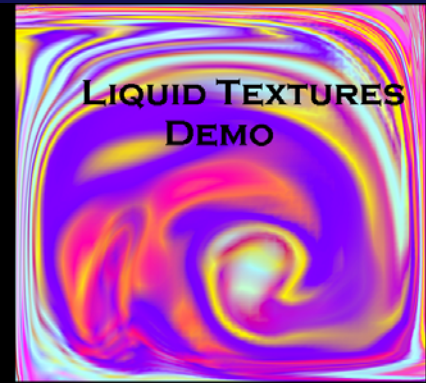


(0.2,0.52)

Liquid Textures

```
void tex_step ()  
{  
    SWAP(u_tex,u0_tex); SWAP(v_tex,v0_tex);  
    advect(u_tex,u0_tex,u,v);  
    advect(v_tex,v0_tex,u,v);  
}
```

Demo

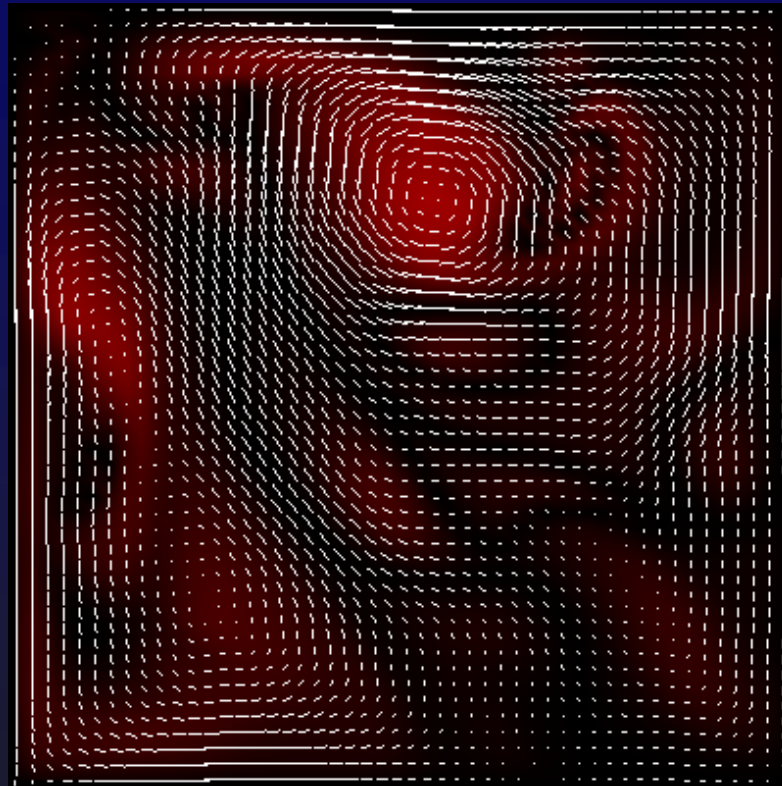


Vorticity Confinement

Technique to defeat dissipation

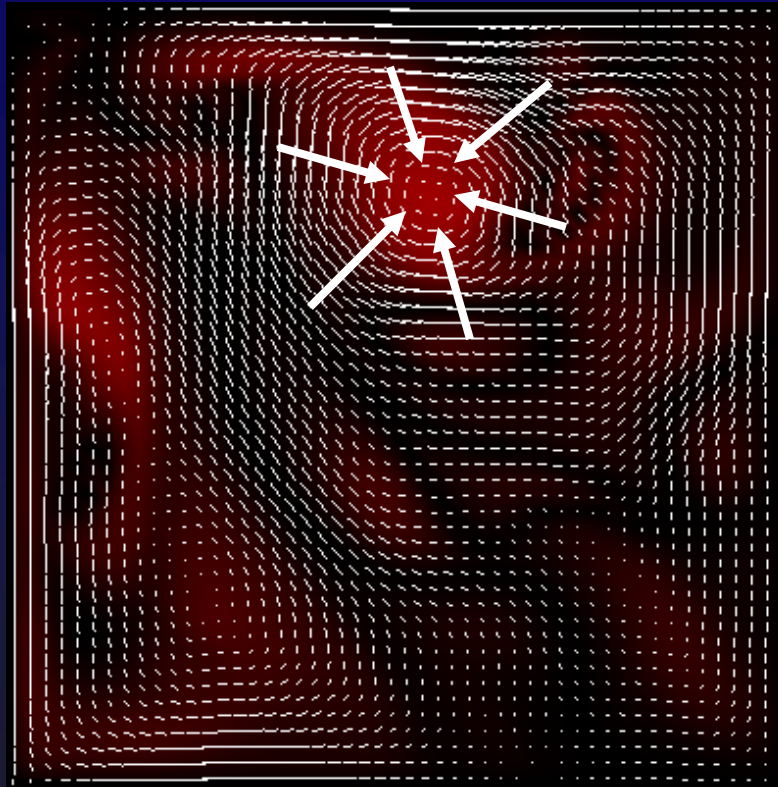
- Steinhoff, *Physics of Fluids*, 1994.
- Fedkiw, Stam & Jensen, *SIGGRAPH*, 2001.

Vorticity Confinement



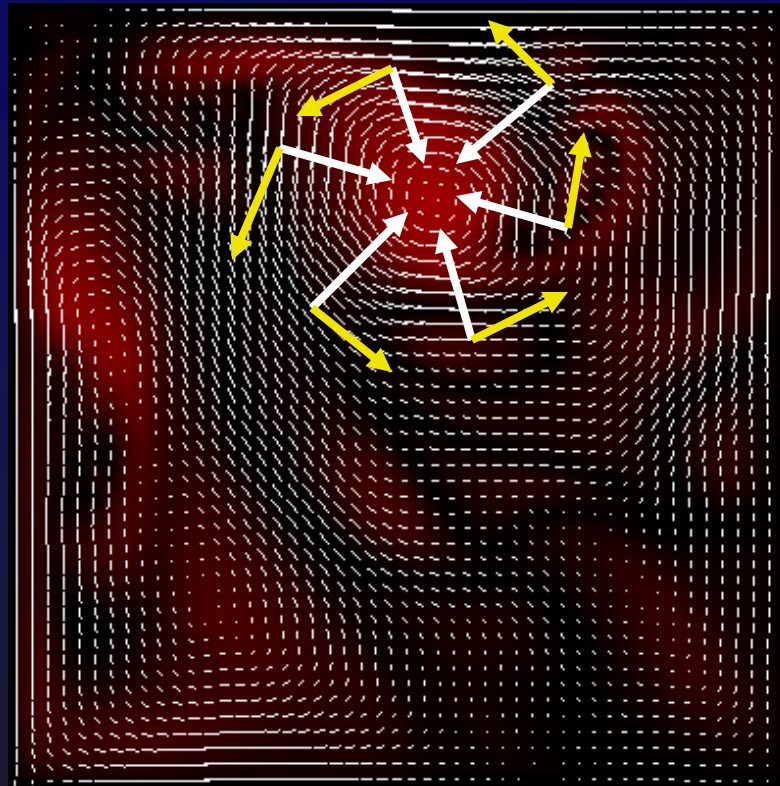
$$\omega = \nabla \times \mathbf{u}$$

Vorticity Confinement



Compute gradient of vorticity

Vorticity Confinement



Add force perpendicular to the gradient

Demo

Vorticity Confinement Demo

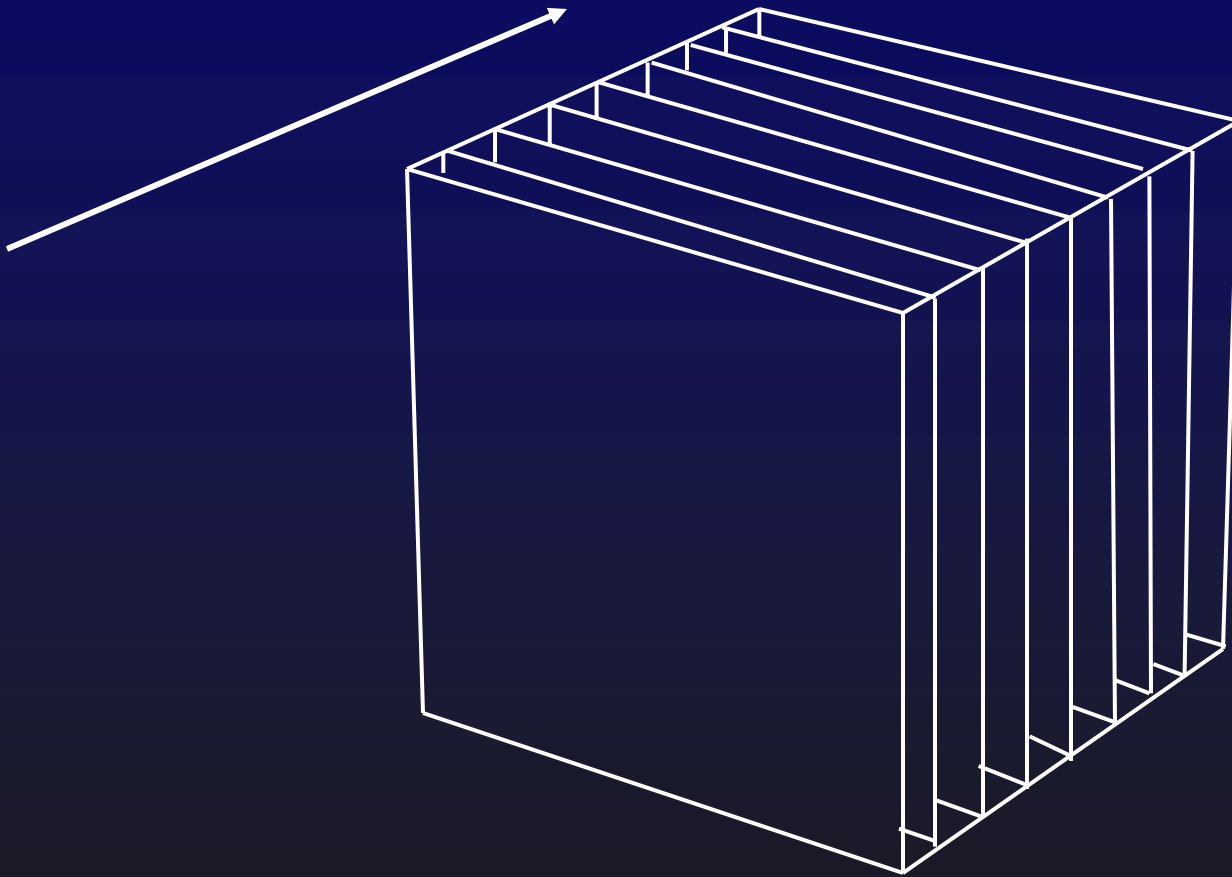
3D Solver

```
for ( i=1 ; i<=N ; i++ ) {  
    for ( j=1 ; j<=N ; j++ ) {  
        density[i,j] = ...  
    }  
}
```

Becomes...

```
for ( i=1 ; i<=N ; i++ ) {  
    for ( j=1 ; j<=N ; j++ ) {  
        for ( k=1 ; k<=N ; k++ ) {  
            density[i,j,k] = ...  
        }  
    }  
}
```

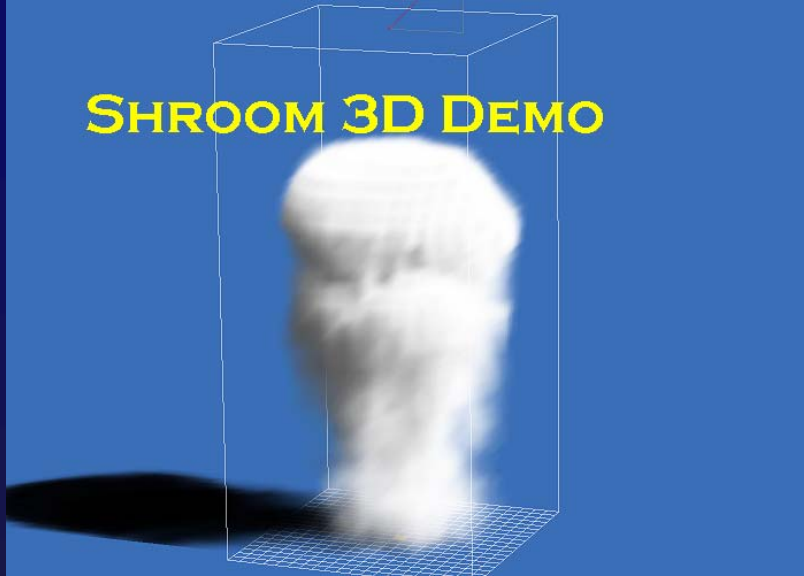
3D Solver



Volume render density

Demo

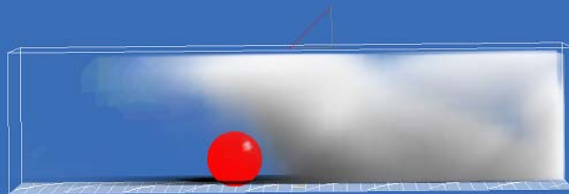
SHROOM 3D DEMO



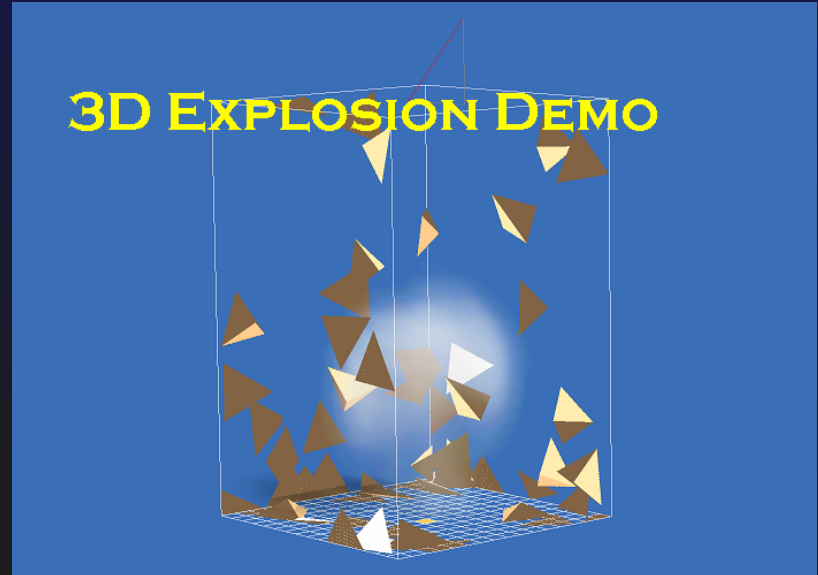
3D FALLING BALL DEMO



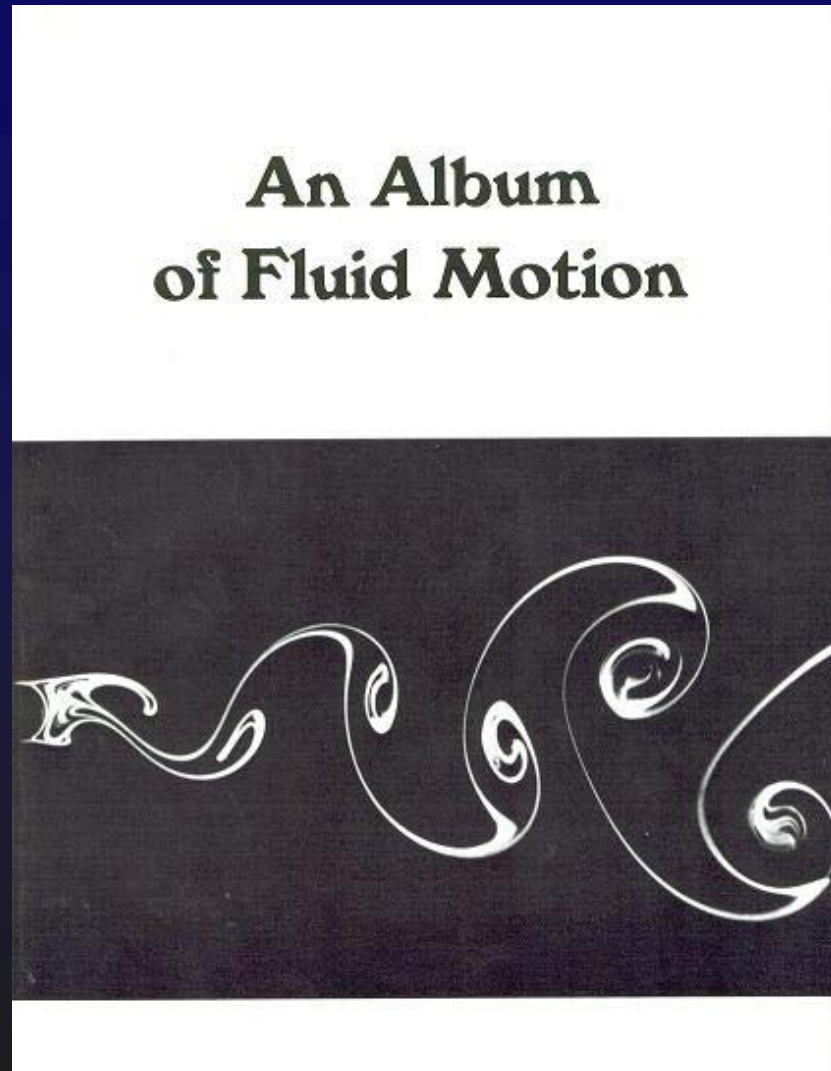
3D ROLLING BALL DEMO



3D EXPLOSION DEMO

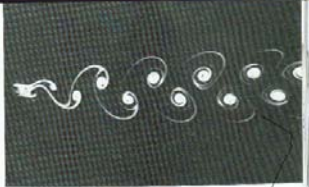


An Album Of Fluid Motion

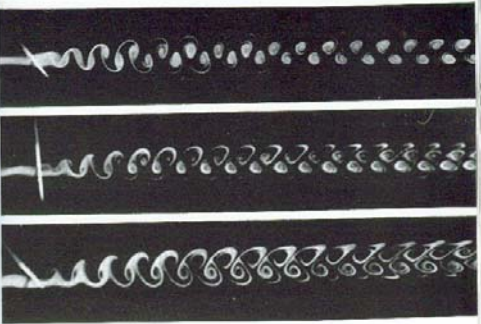


An Album Of Fluid Motion


86. Kármán vortex street behind a circular cylinder at $R=105$. The initially spreading wake shows opposite development and the two parallel rows of staggered vortices that von Kármán's classical theory shows to be stable when the ratio of width to streamwise spacing is 0.28. Strahlkäden are shown by electrochromic progression in water. Photograph by Isidore Tsolis.



87. Smoke at various levels in a vortex street. A smoke filament in air shows, at a Reynolds number of 80, both wave layers (top photograph), only one wave layer (middle), and the irrotational flow below the wake (bottom). Zehnlebach 1909.




88. Kármán vortices in absolute motion. Here the camera moves with the vortices rather than the cylinder. The straining pattern closely resembles the inviscid one calculated by von Kármán. The flow is visualized by particles floating on water. (Photograph by R. Wille, from Wolt 1973. Reprinted, with permission, from the Annual Review of Fluid Mechanics, Volume 5, © 1973 by Annual Reviews Inc.)



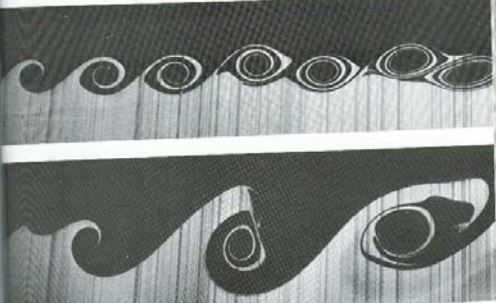
57

Von Karmann

145. Kelvin-Helmholtz instability of stratified shear flow. A long rectangular tube, initially horizontal, is filled with water above colored brine. The fluids are allowed to diffuse for about an hour, and the tube then quickly tilted six degrees, setting the fluids into motion. The brine acquires uniformly down the slope, while the water above similarly acquires up the slope. Sinusoidal instability of the interface occurs after a few seconds, and has here grown rudimentarily into regular spiral rolls. Thorpe 1973.



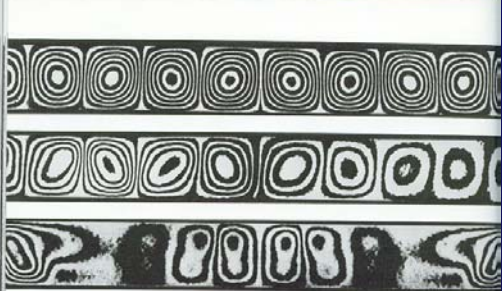
146. Kelvin-Helmholtz instability of superposed streams. The upper stream of water is moving to the right faster than the lower one, which contains dye that becomes visible (illustration) by a vertical sheet of laser light. The faster stream is perturbed sinusoidally at the most unstable frequency in the upper photograph, and at half that frequency in the lower one so that the motion locks into the subharmonic. Photograph by F. A. Kamen, F. E. Dowling & A. Rohde.




85

Kelvin-Helmholtz

139. Buoyancy-driven convection rolls. Differential interferograms show side views of convective instability of silicone oil in a rectangular box of relative dimensions 0.641 heated from below. At the top is the classical Rayleigh-Bénard situation; uniform heating produces rolls parallel to the shorter side. In the middle photograph the temperature difference and hence the amplitude of motion increase from right to left. At the bottom, the box is rotating about a vertical axis. Coull & Kosbar; 1979, Coull 1982.



108. Buoyant thermals rising from a heated surface. Mushroom-shaped plumes rise periodically above a heated copper plate. They are made visible by an electrochemical technique using chloro blue. The heating rate is higher in the photograph at the right. Sparrow, Flair & Chidambaram 1970.

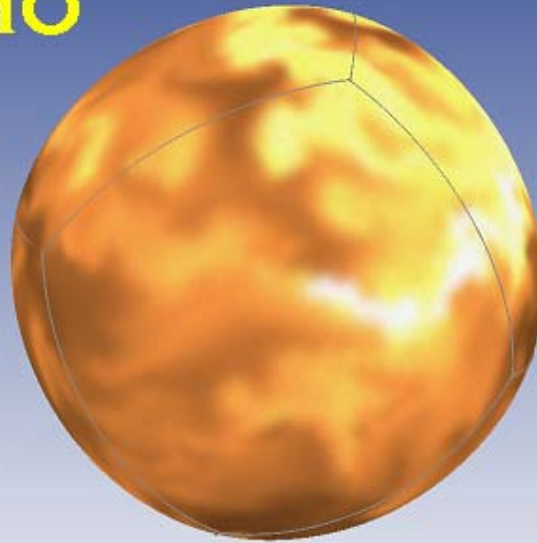


63

Rayleigh-Benard

Flows on Surfaces

CATMULL-CLARK FLUID DEMO



Fluids on PDAs

Fixed point math:

8 bits

8 bits

```
#define freal short // 16 bits
```

```
#define X1 (1<<8)
```

```
#define I2X(i) ((i)<<8)
```

```
#define X2I(x) ((x)>>8)
```

```
#define F2X(f) ((f)*X1)
```

```
#define X2F(x) ((float)(x)/(float)X1)
```

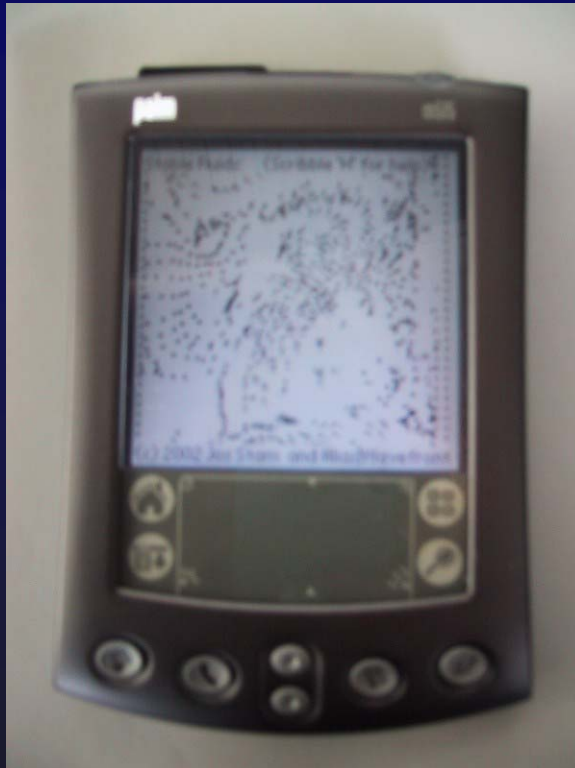
```
#define XM(x,y) ((freal)((long)(x)*(long)(y))>>8)
```

```
#define XD(x,y) ((freal)((long)(x)<<8)/(long)(y))
```

```
x = a*(b/c)
```

```
x = XM(a,XD(b,c))
```

Fluids on PDAs



Palm



PocketPC

MAYA Fluid Effects

Fluid Solver now available
in Maya 4.5 Unlimited

Download the screensaver

<http://www.aliaswavefront.com>

MAYA Fluid Effects



Future Work

- Real-Time Water
- Out of the box
- Smart Texture Maps
- (...)

