



Systems Engineering in Venus Satellite

How to benefit from system engineering process in designing a microsatellite

Jacob Herscovitz
Venus Project Manager
RAFAEL - Israel

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Presentation Contents

- Introduction of the Venus program
- Description of the synthesis step of the Systems Engineering Process (SEP)
- Example of synthesis in Venus Program:
 - Solar panels and Thrusters configuration
- Conclusions

Presentation goal:

 To demonstrate the applicability of SEP and Conceptual design (preliminary design) in context of spacecraft and space mission engineering.



VENUS Satellite

A joint CNES - ISA scientific program

Satellite developed by RAFAEL - IAI Joint Venture

A low-cost, LEO micro-satellite, for dual missions:

- Multispectral earth imaging
- Electrical propulsion system demonstration

Launch scheduled for 2008

Venus Program

Vegetation and Environment New µSatellite

- A Joint Israeli (ISA Via IAI and RAFAEL) French (CNES) Program
- Dual missions:
 - Scientific Mission: A research demonstrator mission for the GMES program (Global Monitoring for Environment and Security), dedicated to monitoring vegetation and water quality – using a Multi-Spectral camera
 - Technological Mission: Validation of the Israeli Hall Effect Thruster (IHET) and demonstration of its mission enhancement capabilities:
 - · Orbit maintenance,
 - LEO to LEO orbit transfer

Enabling imaging mission in a high drag environment.

Venus platform based on IMPS design of IAI

- Estimated launch weight: 230 kg
- Launch in 2009
- Planned lifetime of 4½ years













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Venus Mission VM1 VM2 IOT VM1a (Orbit Transfer) VM1aS IMAGING Oct. 15 VM1aT IHET VM1b VM3 **Nov. 14 IHET** VM3a VM3aS Launch **IMAGING** Oct. 15 VM3aT IHET **Imaging** VM3b mission **Disposal Nov. 14** IHET mission

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VM1 Mission Characteristics

- Orbit: near polar, sun-synchronous, earth repeating
- Altitude: 720 km
- Inclination: 98.27°
- Revisit time: two days (29 revolutions)
- Equator crossing time: 10:30 AM, descending mode
- Mission start & duration: June 2009, for ~4.25 years
- Imaging:
 - Swath: 27.56 km
 - Spatial resolution: 5.3 m
 - Number of spectral bands: 12 (VIS-NIR)
 - Tilting capability: +/-30° across and along track
 - Radiometric resolution: 10 bits

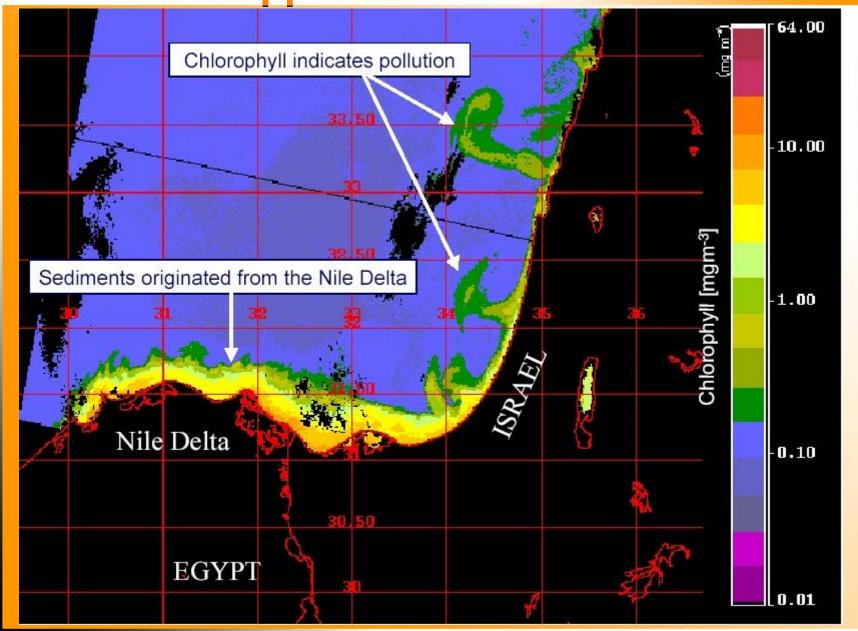
Monitoring of Temporal Dynamics

Crop evolution as seen by the SPOT constellation every month

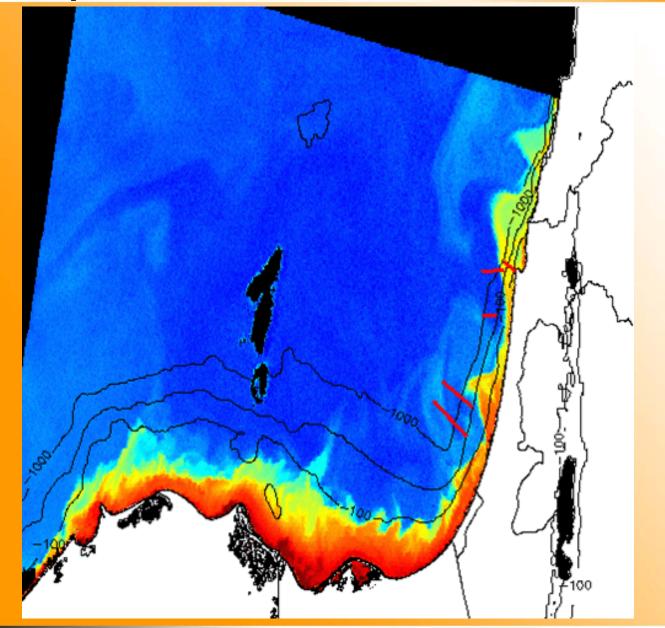


After compositing procedures for eliminating clouds, VENµS will provide images with improved spectral information every 10 days

Coastal Zone Applications

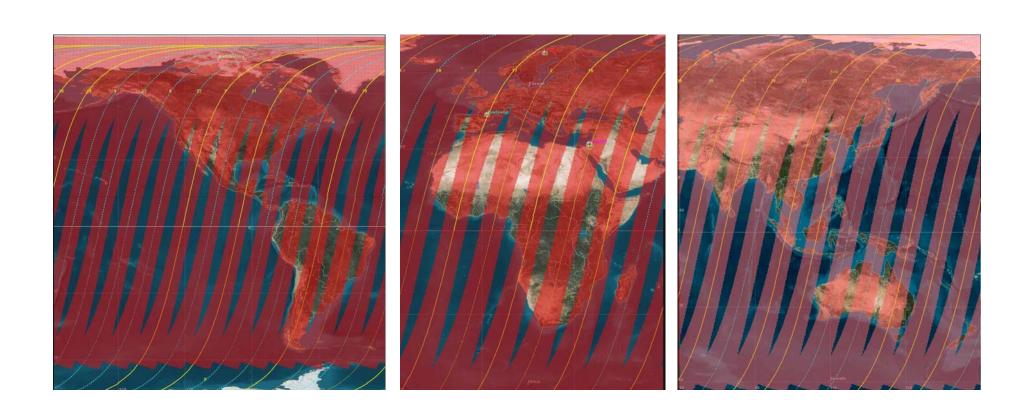


Pollution Dispersion – 11 – 25, June 2001

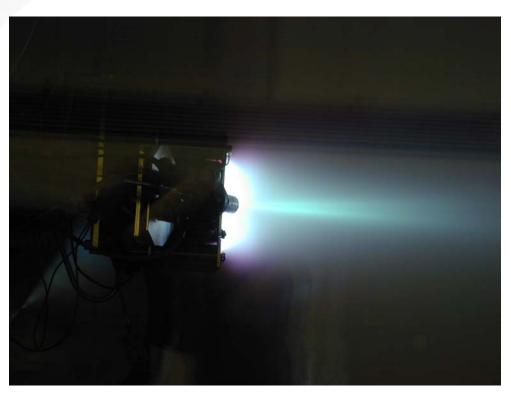




VM1 Imaging Access



IHET-300W





Isp @ 300W: >1300s

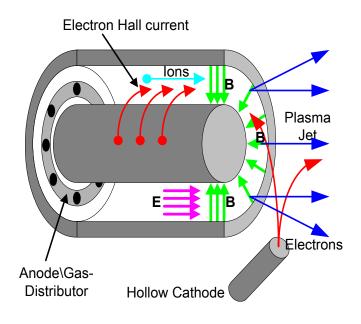
Thrust @ 300W: ≥15mN

Total Impulse: >50 KNs



Thruster operating principles

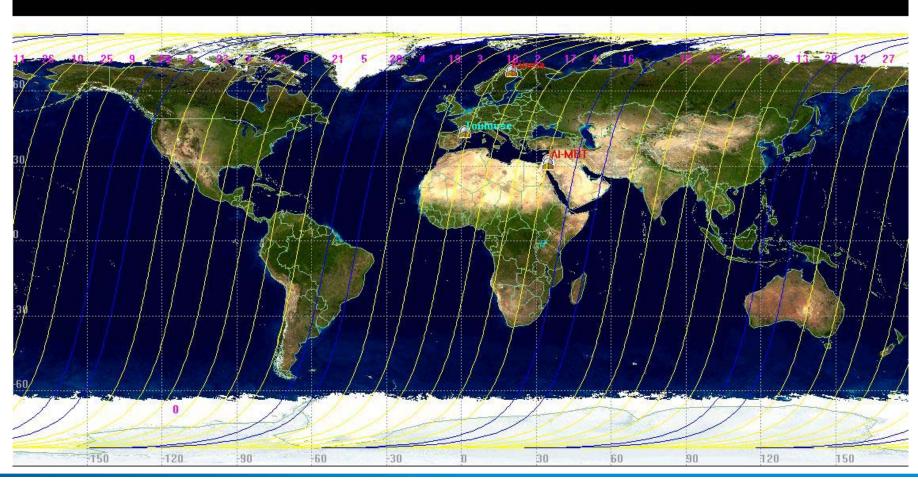
- Xe gas directed through distribution channel (Anode)
- Electrons emitted from cathode, collide with Xe atoms, and ionizing them.
- Induced magnet field, spiral ions movement in the thruster channel.
- Electric field accelerates ions out of the channel.
- Ions neutralization at exit by electrons from the cathode.





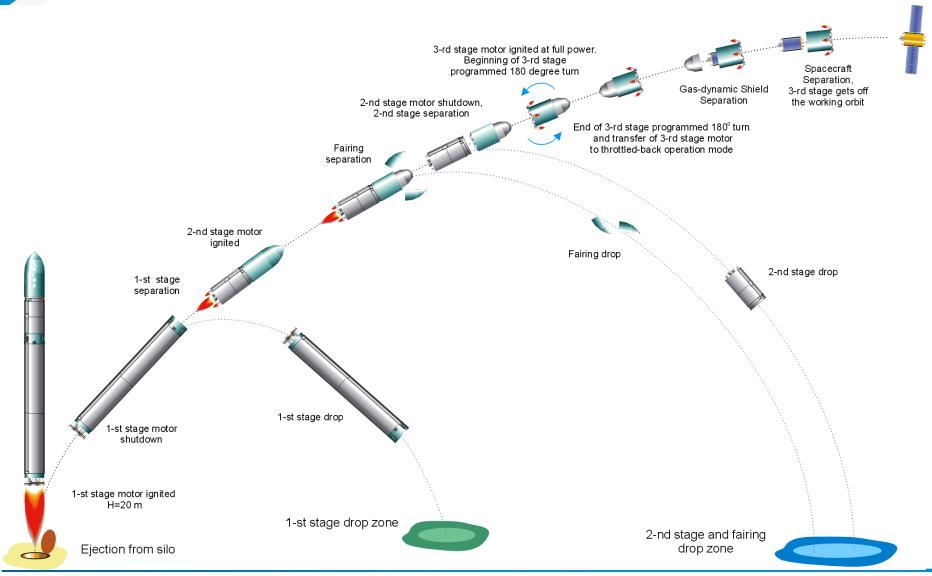
VM3 Combined Scientific and Technological Missions

Imaging orbits in Yellow, IHET orbits in blue





Venus Launch



Venus – System of Systems

Space segment – Venus satellite:

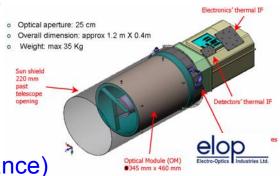
- Venus platform (IAI & Rafael, Israel)
- Venus Super Spectral Camera (ELOP, Israel)
- Israeli Hall Effect Thruster- IHET (Rafael, Israe
- Launch segment DNEPR (Kosmotras, Russia & Ukraine)

Ground segment:

- Command and control center (MBT, Israel)
- X-band receiving station (Kiruna, Sweden)
- Image processing center (CNES Toulouse, France)
- Technological Mission Center (Rafael, Israel)

Orbits and Missions

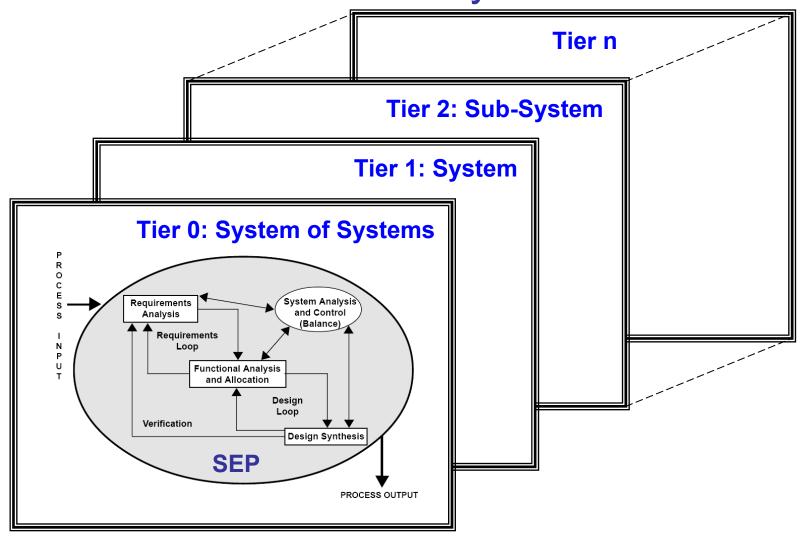
- Scientific mission: Multispectral imaging for agriculture, vegetation and water quality
- Technological mission: Validation of IHET and mission enhancement demonstration
- Orbits: Initial orbit (720km), LEO to LEO transfer and Final orbit (410km)





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SEP (Systems Engineering Process)
Performed in System Tiers





Example of synthesis in Venus Program:

Solar Panels and IHET Architecture for Venus Satellite



Define the Design Problems:

Main Functional Requirements:

- Provide power:
 - 350W for IHET
 - 150W for platform,

for maximum duration (Required: > 20 mins, Desired: ~60 mins)

- Provide maneuverability in orbit
- Provide propulsion redundancy
- Provide camera protection from ATOX

Constraints:

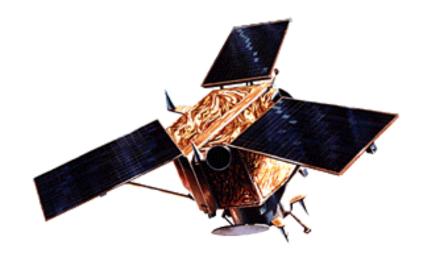
- Venus orbits: Sun-Synchronous, descending node @ 10:30
- Restricted maneuvers of "ROLL" about thrust vector.

Define Solar Panels and IHET geometric placement architecture on the Venus satellite (orientation of panels to IHET and satellite platform).



Possible Solutions to Solar Panels Problem



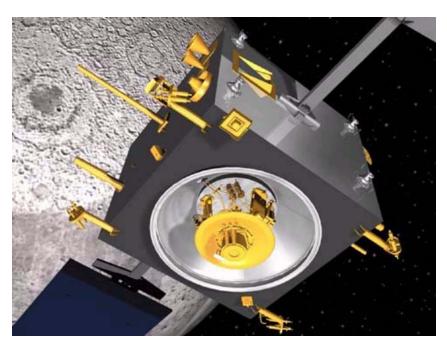


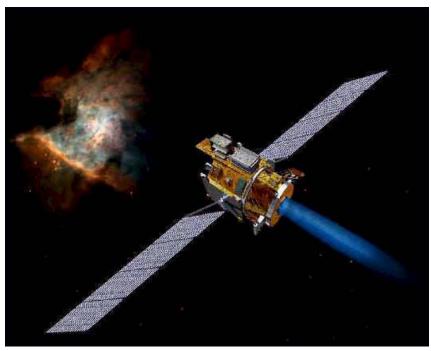
IAI-MBT "Ofeq"

Lockheed Martin "Ikonos"



Possible Solutions to IHET Problem



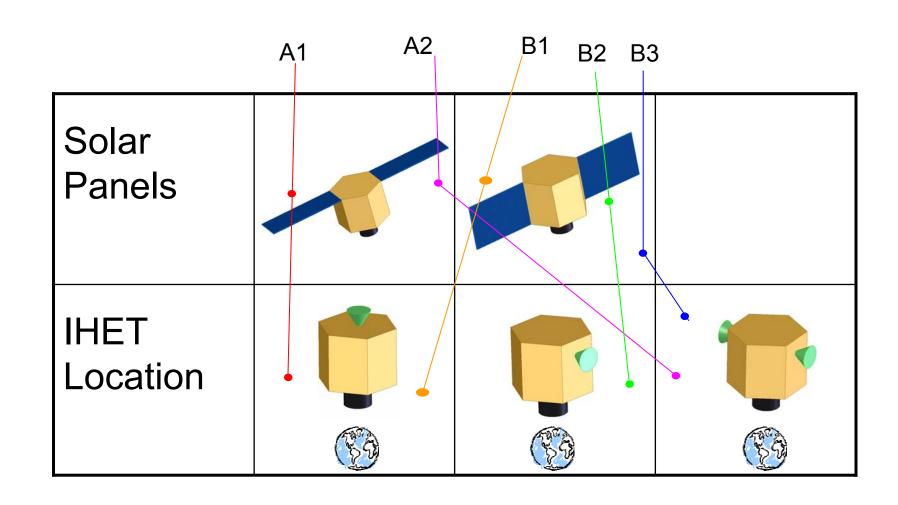


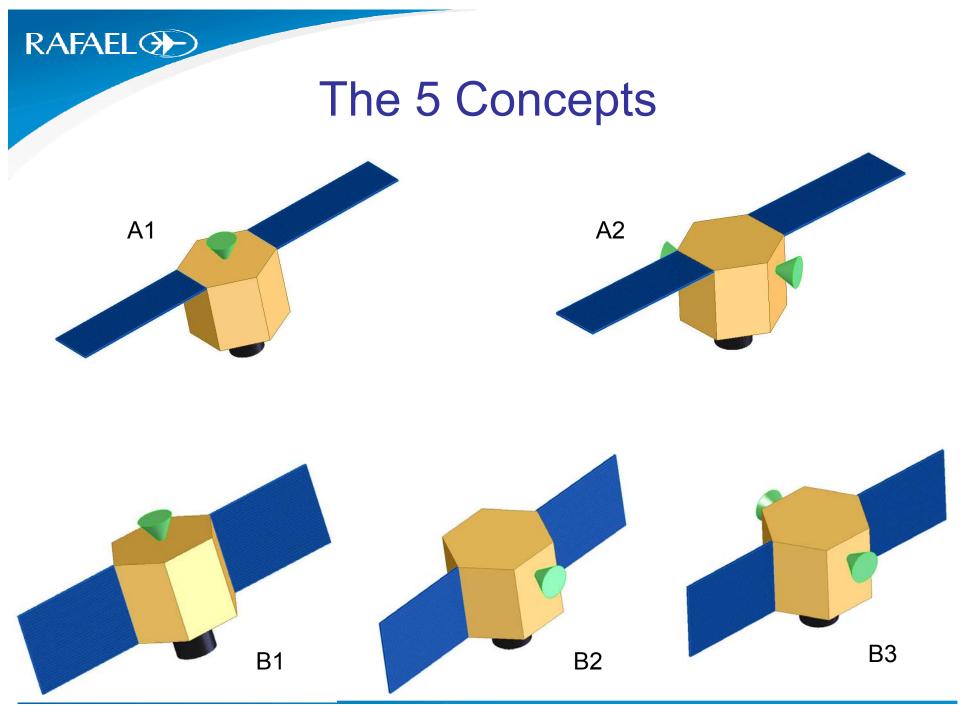
ESA "Smart1"

NASA & JPL "Deep Space 1"

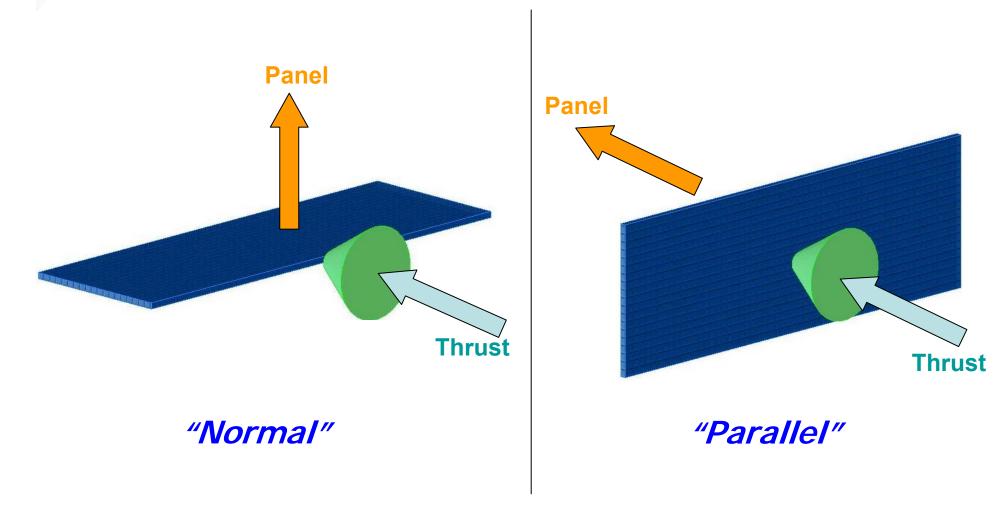


Panels & IHET configuration

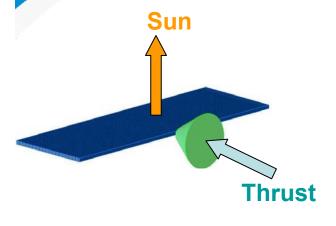




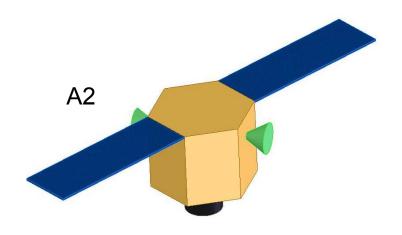
Basic Solar Panel and IHET Architecture Alternatives

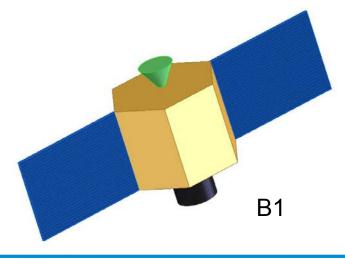


Alternatives "Normal"

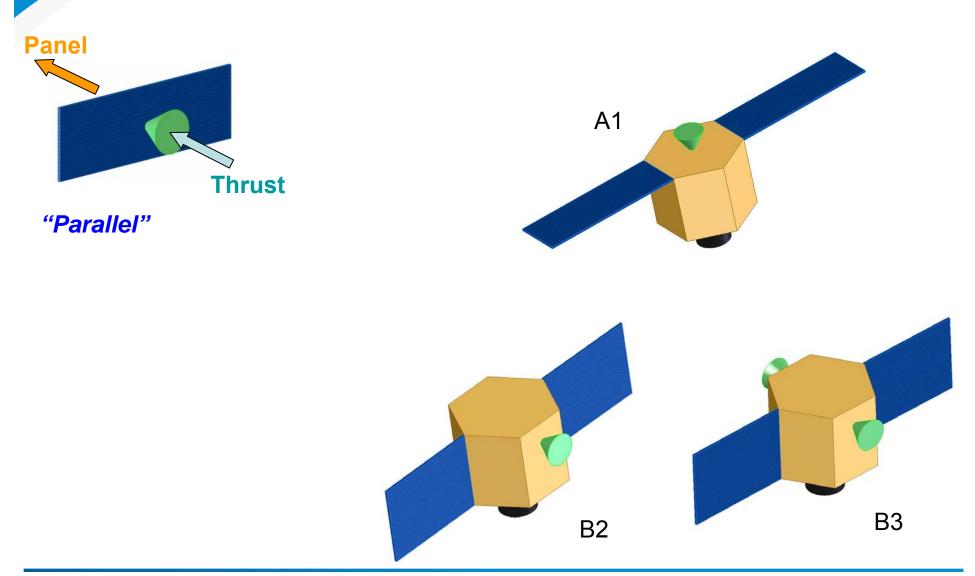


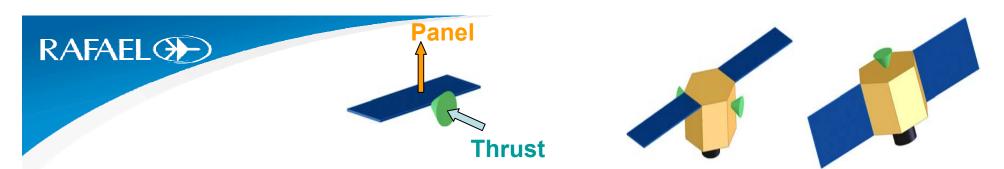




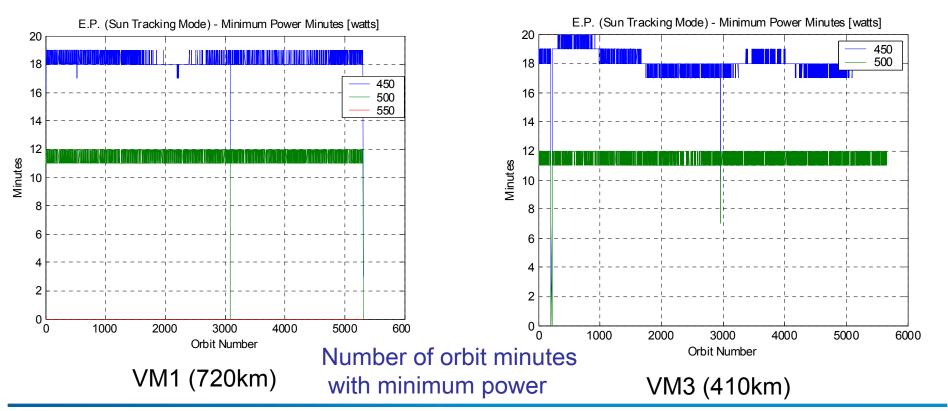


Alternatives "Parallel"



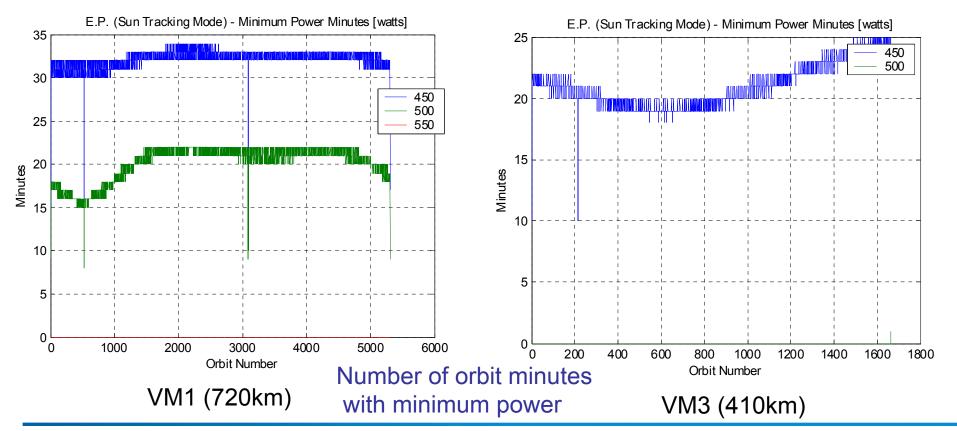


Power Generation Analysis for Solar Panels – IHET Architecture "Normal"





Power Generation Analysis for Solar Panels – IHET Architecture "Parallel"



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Drag Consideration

Computations for VM3 @ Altitude: 410 km

Satellite mass: 150 kg

Panels area: 2.5 m²

Satellite body area: 1 m²

Assume Solar-Max conditions (*)

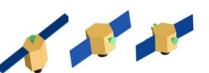
(year 2010)

	Concept	1	1	1	F	
IHET Operation	Area [m ²]	3.5	1	1	3.5	3.5
	Drag [mN]	1.46	0.42	0.42	1.46	1.46
Imaging Operation	Area [m ²]	1	1	3.5	3.5	3.5
	Drag [mN]	0.42	0.42	1.46	1.46	1.46



Drag Results Analysis

Drag impulse of one orbit (Altitude = 410km, Orbit period = 92 min):



- For concepts A1, B2, B3 (A = $3.5m^2$): 8.1 Ns
- For concepts A2, B1, $(A = 1m^2)$: 2.3 Ns



 Typical IHET impulse (13mN for 20 min.) operation: 15.6 Ns



Evaluation Criteria

- IHET operation minutes / orbit (for 500W consumption in 720km and 410km orbits)
- Need for Camera Cover
- ΔV flexibility Capability of ± ΔV for orbit maneuvering
- Heritage usage of legacy components
- Integration complexity IHET and satellite integration effort due to modularity and coupling
- VM1 (2 years) specific:
 - N/A
- VM3 (3rd year) specific:
 - Drag during Imaging and IHET operation
 - Enough IHET power during orbits for orbit maintenance

Concepts Evaluation

	Concept			-		
Criteria		A1	A2	B1	B2	B3
Drag (1) [mN]	Imaging	0.42	0.42	1.46	1.46	1.46
	IHET	1.46	0.42	0.42	1.46	1.46
500W minutes	s / orbit ⁽²⁾	15 - 22	11	11	15 - 22	15 - 22
Camera Cove	r	Must	Optional	Must	Optional	Optional
		-ΔV @ dawn			-ΔV @ dawn	±ΔV @ dawn
ΔV flexibility		+∆V @ dusk	±ΔV @ noon	±ΔV @ noon	+∆V @ dusk	±∆V @ dusk
Heritage		New	New	Existing	Existing	Existing
Integration Co	omplexity (4)	Low	Moderate	Low	Moderate	Mederate

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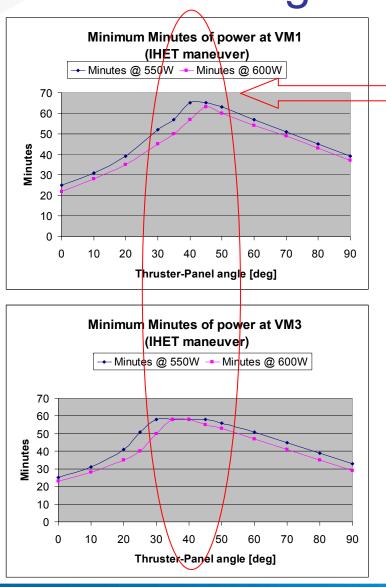
Concept Selection

					,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
Criteria	Weight	A1	A2	B1	B2	B3
Drag Considerations	10		1	0	-2	-2
Power Production Capability	25	D	-2	-2	0	0
Camera Risk (Need for camera cover)	20	A = T	3	0	3	3
ΔV flexibility (maneuverability)	25		-2	-2	0	3
Heritage Design (Solar Panels)	15	М	0	2	2	2
IHET Integration Complexity	5		-2	0	-2	-2
Total	100	0	-40	-70	60	135
						181 //

Pairs Comparison	Grade
Much better than datum	3
Better than datum	2
Slightly better than datum	1
Same as datum	0
Slightly worse than datum	-1
Worse than datum	-2
Much worse than datum	-3

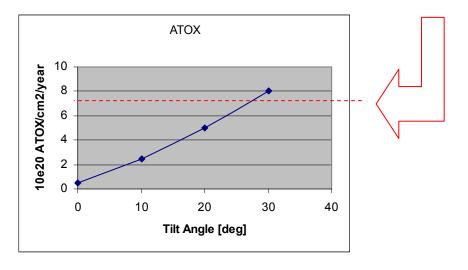


Design Improvements



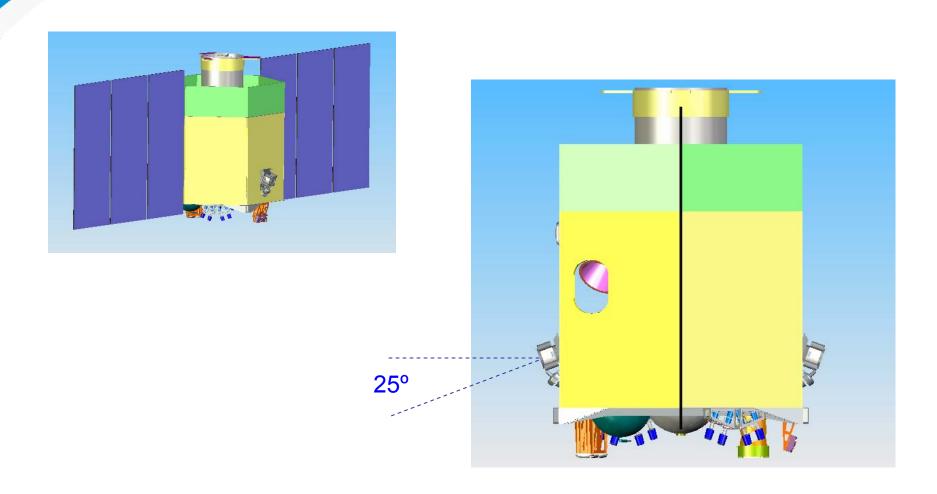
Optimal power

Camera Tolerance: 7.3 10²⁰ ATOX/m²/Y





Final IHET Configuration





Conclusions

- System of systems design process can benefit from applying the SEP starting from the initial conceptual design phase
- SEP and synthesis tools are easily applicable to the first tiers of system engineering, as they are to the detailed design tiers
- The applicability of SEP and Conceptual design (preliminary design) was demonstrated in the context of spacecraft and space mission engineering
- Using quantitative synthesis methods can produce a reasonable and rational design



Thank You

Jacob Herscovitz
Space systems Directorate
RAFAEL
jacobh@rafael.co.il

Contributed to work presented in this presentation:

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- David Reiner Propulsion Section Head, Rafael
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