## SEBASTIAN RASCHKA



## Introduction to Artificial Neural Networks and Deep Learning

with Applications in Python

### Introduction to Artificial Neural Networks

with Applications in Python

Sebastian Raschka

#### Draft

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This book will be available at http://leanpub.com/ann-and-deeplearning.

Please visit https://github.com/rasbt/deep-learning-book for more information, supporting material, and code examples.

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### Website

Please visit the GitHub repository to download the code examples accompanying this book and other supplementary material.

If you like the content, please consider supporting the work by buying a copy of the book on Leanpub. Also, I would appreciate hearing your opinion and feedback about the book, and if you have any questions about the contents, please don't hesitate to get in touch with me via mail@sebastianraschka.com. Happy learning!

Sebastian Raschka

### About the Author

Sebastian Raschka received his doctorate from Michigan State University developing novel computational methods in the field of computational biology. In summer 2018, he joined the University of Wisconsin–Madison as Assistant Professor of Statistics. Among others, his research activities include the development of new deep learning architectures to solve problems in the field of biometrics. Among his other works is his book "Python Machine Learning," a bestselling title at Packt and on Amazon.com, which received the ACM Best of Computing award in 2016 and was translated into many different languages, including German, Korean, Italian, traditional Chinese, simplified Chinese, Russian, Polish, and Japanese.

Sebastian is also an avid open-source contributor and likes to contribute to the scientific Python ecosystem in his free-time. If you like to find more about what Sebastian is currently up to or like to get in touch, you can find his personal website at https://sebastianraschka.com.

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### Appendix A

### Mathematical Notation Reference

This appendix provides a brief overview of the mathematical notation used throughout this book. The following appendices describe most of the corresponding concepts in more detail, and additional information is provided in the context of the applications in the main chapters.

# **DR**<sup>4</sup>**AFT**

#### A.1 Sets and Intervals

- $\mathbb{Z}$  set of integers, {..., -2, -1, 0, 1, 2, ...}
- $\mathbb{N}$  set of natural numbers,  $\{0, 1, 2, 3, ...\}$
- $\mathbb{N}^+$  set of natural numbers excluding zero,  $\{1, 2, 3, ...\}$
- $\mathbb{R}$  set of real numbers
- $\in$  element of symbol; for example,  $x \in A$  translates to "x is an element of set A"
- $\notin$  not an element of symbol
- $\varnothing$  null set, empty set
- $A \cup B$  union of two sets, A and B
- $A \cap B$  intersection of two sets, A and B
- $A \subseteq B$  A is a subset of B or included in B
- $A\Delta B$  symmetric difference between two sets A and B
- |*A*| cardinality of a set *A* (number of elements in a set *A*)
- (a, b) open interval from a to b, excluding a and b
- [a, b] closed interval from a to b, including a and b
- [a, b) half-open interval from a to b, including a but not b
- (a, b] half-open interval from a to b, including b but not a

#### A.2 Sequences

 $\sum_{i=1}^{n} x_i \quad \text{summation of an indexed variable } x_i, \text{ defined as } \sum_{i=1}^{n} x_i = x_1 + x_2 + \dots + x_n$  $\prod_{i=1}^{n} x_i \quad \text{product over an indexed variable } x_i, \text{ defined as } \prod_{i=1}^{n} x_i = x_1 \cdot x_2 \cdot \dots \cdot x_n$ 

#### A.3 Functions

1.0 I unic	
$f:A\to B$	function $f$ with domain $A$ and codomain $B$
$(g \circ f)(x)$	composition of two functions $g$ and $f$ alternative form: $g[f(x)]$
$f^{-1}(x)$	inverse of a function $f$ , such that $f(y) = x$ if $f^{-1}$ stands for $y$
x	absolute value of <i>x</i> ; for example, $ -2  = 2$
$\log_b$	base- <i>b</i> logarithm
log	natural logarithm (base- $e$ logarithm)
n!	<i>n-factorial</i> , where $0! = 1$ and $n! = n(n-1)(n-2)\cdots 2 \cdot 1$ for $n > 0$
$\binom{n}{k}$	binomial coefficient (" <i>n</i> choose <i>k</i> "); $\binom{n}{k} = \frac{n!}{k!(n-k)!}$ for $0 \le k \le n$
$rg\max f(x)$	the $x$ value that makes $f(x)$ as large as possible
$\arg\min f(x)$	the $x$ value that makes $f(x)$ as small as possible

#### A.4 Linear Algebra

- *x* scalar (lower-case italics notation)
- **x** column vector (lower-case bold notation) or  $n \times 1$ -matrix
- $\mathbf{a} \cdot \mathbf{b}$  dot product of two vectors,  $\mathbf{a}$  and  $\mathbf{b}$ ; if  $\mathbf{a}$  and  $\mathbf{b}$  are  $n \times 1$ -matrices, also written as  $\mathbf{a}^T \mathbf{b}$ ;  $\mathbf{a} \cdot \mathbf{b} = \mathbf{a}^T \mathbf{b} = \sum_i a_i b_i = a_1 b_1 + a_2 b_2 + \dots + a_n b_n$
- **X**  $m \times n$ -matrix (upper-case bold notation)
- *X* 3D-tensor (upper-case italics notation)
- $\mathbb{R}^{n} \qquad \text{real coordinate space, written as a column vector with length } n$  $\mathbf{x} = \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{n} \end{bmatrix}$

$$\mathbf{x}^{T} \qquad \text{transpose of a } n \times 1\text{-matrix}$$
$$\mathbf{x}^{T} = \begin{bmatrix} x_{1} & x_{2} & \dots & x_{n} \end{bmatrix} = \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{n} \end{bmatrix}^{T}$$

- $\begin{aligned} \|\mathbf{x}\|_p & L^p \text{ norm, vector } p\text{-norm,} \\ \|\mathbf{x}\|_p &= \left(|x_1^p| + |x_2^p| + \dots + |x_n^p|\right)^{1/p} \end{aligned}$
- $\|\mathbf{x}\|_{\infty}$   $L^{\infty}$  norm, max norm; largest absolute value of a vector  $\|\mathbf{x}\|_{\infty} = \max_{i} |x_{i}|$

$$\|\mathbf{x}\| \quad \text{vector norm, } L^2\text{-norm, } \|\mathbf{x}\| = \|\mathbf{x}\|_2$$
$$\|\mathbf{x}\| = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$

- $\mathbf{A}_{i,:}$  *i*th row of matrix  $\mathbf{A}$
- $\mathbf{A}_{:,j}$  jth column of matrix  $\mathbf{A}$

 $\mathbf{A}^{T}$  transpose of a matrix, matrix element  $\mathbf{A}_{i,j}$  becomes  $\mathbf{A}_{j,i}^{T}$ for example,  $\begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix}^{T} = \begin{bmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \end{bmatrix}$ 

 $I_n \qquad \qquad n \times n \text{ identity matrix} \\ I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ 

$\mathbf{A}^{-1}$	inverse of a matrix <b>A</b> , such that $\mathbf{A}\mathbf{A}^{-1} = \mathbf{A}^{-1}\mathbf{A} = \mathbf{I}$
$\operatorname{tr} \mathbf{A}$	trace of a matrix <b>A</b> (sum of the diagonal elements) tr $\mathbf{A} = \sum_{i=1}^{n} \mathbf{A}_{i,i}$

det **A** determinant of a matrix **A** 

$\operatorname{diag}(a_1, a_2,, a_n)$	diagonal matrix, matrix whose diagonal have the values $a_1, a_2,, a_n$ and all other elements are zero
$\mathbf{A} \odot \mathbf{B}$	Hadamard product, element-wise matrix multiplication

#### A.5 Calculus

$\lim_{x \to a} f(x)$	limit of $f(x)$ as $x$ approaches $a$
$\lim_{x \to a-} f(x)$	limit of $f(x)$ as $x$ approaches $a$ from the left
$\lim_{x \to a+} f(x)$	limit of $f(x)$ as $x$ approaches $a$ from the right
$rac{df}{dx}$	derivative of <i>f</i>
$\frac{d^n f}{dx^n}$	<i>n</i> -th derivative of <i>f</i>
$\frac{\partial f}{\partial x}$	partial derivative of $f(x, y,)$ with respect to variable $x$ , where $x$ is a scalar
$\nabla f$	gradient of a function $f : \mathbb{R}^n \to \mathbb{R}$

$$\nabla f(x_1, x_2, ..., x_n) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix}$$

 $\begin{array}{ll} \Delta f & \text{Laplacian of a function } f: \mathbb{R}^n \to \mathbb{R} \\ \Delta f = \sum\limits_{i=1}^n \frac{\partial^2 f}{\partial x_i^2} \end{array}$ 

*Hf* Hessian of a function 
$$f : \mathbb{R}^n \to \mathbb{R}$$

$$Hf = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1 \partial x_1} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_n \partial x_n} \end{bmatrix}$$

$$\frac{\partial f_j}{\partial x_i}$$

#### partial derivative of component function $f_j$ and the

variable  $x_j$ , where  $\mathbf{f} : \mathbb{R}^n \to \mathbb{R}^m$ , such that

$$\mathbf{f}(\mathbf{x}) = \begin{bmatrix} f_1(\mathbf{x}) \\ f_2(\mathbf{x}) \\ \vdots \\ f_m(\mathbf{x}) \end{bmatrix} \frac{\partial \mathbf{f}}{\partial x_i} = \begin{bmatrix} \frac{\partial f_1}{\partial x_i} \\ \frac{\partial f_2}{\partial x_i} \\ \vdots \\ \frac{\partial f_m}{\partial x_i} \end{bmatrix}$$

*D***f** Jacobian matrix of **f**.

$$D\mathbf{f} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \dots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \dots & \frac{\partial f_2}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \frac{\partial f_m}{\partial x_2} & \dots & \frac{\partial f_m}{\partial x_n} \end{bmatrix}$$

 $\int f(x)dx \quad \text{indefinite integral of } f \text{ (derivative of } F \text{) with } f : \mathbb{R} \to \mathbb{R}$  $\int_{a}^{b} f(x)dx \quad \text{definite integral of } f \text{ (derivative of } F \text{) with } f : \mathbb{R} \to \mathbb{R}$ 

#### A.6 Probability and Statistics

- $P(A \cap B)$  probability that event A and B occur
- $P(A \cup B)$  probability that event *A* or *B* occurs
- P(A | B) conditional probability of A given B
- $E(X), \mu_X$  expected value (mean) of a random variable X  $E(X) = \sum_{i=1}^{\infty} p_i x_i$  for a discrete random variable Xwith values  $x_1, x_2, \ldots$  and probabilities  $p_1, p_2, \ldots$ .  $E(X) = \int_{-\infty}^{\infty} xf(x)dx$  for a continuos random variable and probability density function f(x).
- $\bar{X}$  sample average of numerical data  $X_1, ..., X_n$  $\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$
- $\begin{array}{ll} \mathrm{var}(X), \sigma_x^2 & \mathrm{variance \ of \ a \ random \ variable \ } X \\ & \mathrm{var}(X) = E\big[(X-\mu_X)^2\big] = E(X^2) E(X)^2 \end{array}$
- $s_X^2$  sample variance of numerical data  $X_1, ..., X_n$  $s_X^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2$

std(X), $\sigma_x$	standard deviation of a random variable, square root of the variance
$s_X$	sample standard deviation, the square root of the sample variance $s_X^2$
$\operatorname{cov}(X,Y)$	covariance of two random variables X and Y cov(XY) = E[(X - E(X))(Y - E(Y))] = E(XY) - E(X)E(Y)
$s_{XY}$	sample covariance of numerical data $X_1,, X_n$ , and $Y_1,, Y_n$ $s_{XY} = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})$
$\operatorname{corr}(X,Y)$	correlation coefficient of two random variables <i>X</i> and <i>Y</i> , $\operatorname{corr}(X, Y) = \frac{\operatorname{cov}(X, Y)}{\sigma_X \sigma_Y}$
H(X)	entropy of a random variable <i>X</i> discrete: $H(X) = -\sum_{x} P(X = x) \log_{b} P(X = x)$ continuous: $H(X) = -\int_{-\infty}^{\infty} f(x) \log_{b} f(x) dx$
PMF	probability mass function of a discrete random variable, $f(x) = P(X = x)$
CDF	cumulative distribution function of a continuous random variable, $F(x) = P(X \le x)$
PDF	probability density function of a continuous random variable, $P(X \in [a,b]) = \int_{a}^{b} f(x) dx$
$X \sim D$	random variable $X$ has a distribution $D$
$\hat{ heta}$	estimator of a parameter $\theta$

 $N(x,\mu,\sigma^2)$  normal (Gaussian) distribution over x with mean  $\mu$  and variance  $\sigma^2$ 

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#### A.7 Numbers

e	Euler's number, mathematical constant approximated by 2.71828
π	"pi", mathematical constant approximated by 3.14159
$\infty$	infinity symbol
$1.234\times 10^5$	scientific notation for 123, 400
or $1.234E05$	
<	<i>less than</i> sign, for example, $x < 10$ means that x is smaller than 10
«	<i>much less than</i> sign
>	<i>greater than</i> sign, for example, $x > 10$ means that x is larger than 10
>>	<i>much greater than</i> sign
«	<i>much less than</i> sign

#### A.8 Approximation

≈	approximate equality, for instance, $e\approx 2.71828$ is the approximation of Euler's number
$f(x) \sim g(x)$	symbol to assert that the ratio of two functions approaches 1 $\lim_{x\to 0} \frac{f(x)}{g(x)} = 1$ , if <i>x</i> is small $\lim_{x\to\infty} \frac{f(x)}{g(x)} = 1$ , if <i>x</i> is large
$f(x) \propto g(x)$	the two functions $f(x)$ and $g(x)$ are proportional to each other

 $T(n) \in O(n^2) \quad \textit{big-O notation, an algorithm is asymptotically bounded by $n^2$;} \\ \text{an algorithm has an order of $n^2$ time complexity}$ 

#### A.9 Logic

- $\Rightarrow implication operator$  $for example, A \Rightarrow B translates to "if A implies B"$ or "if A then B" (or "B only if A")
- $\Leftrightarrow equality \text{ operator } (if and only if (iff)) \\ \text{for example, } A \Leftrightarrow B \text{ translates to "}A \text{ if} \\ \text{and only if } B" \text{ or "if } A \text{ then } B \text{ and if } B \text{ then } A" \\ \end{cases}$
- $\land \quad \text{logical conjunction, and} \\ \text{for example, } A \land B \text{ means "}A \text{ and } B"$
- $\vee$  logical (inclusive) disjunction, or for example,  $A \vee B$  means "A or B"
- ¬ negation, *not* for example, ¬A means "not A" or
  "if A is true then ¬A is false" and vice versa
- $\forall$  universal quantifier, means *for all* for example, " $\forall x \in \mathbb{R}, x > 1$ " translates to "for all real numbers *x*, *x* is greater than one"
- $\exists existential quantifier, means$ *there exists* $for example, "<math>\exists x \in A, f(x)$ " translates to "there is an element in set *A* for which the predicate f(x) holds true"

### Bibliography



### **Abbreviations and Terms**

**CNN** [Convolutional Neural Network]



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