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Section 29

AUSTRALIA  
PATENTS ACT 1990

**PATENT REQUEST: STANDARD PATENT**

We Linden Fabricating and Engineering (Prince George) Ltd, being the person identified below as the Applicant, request the grant of a patent to the person identified below as the Nominated Person, for an invention described in the accompanying standard complete specification.

Full application details follow.

Applicant: Linden Fabricating and Engineering (Prince George) Ltd

Address: 9368 Milwaukee Way, B.C.R. Industrial Site, Prince George, British Columbia, Canada, V2N 2K8

Nominated Person: Linden Fabricating and Engineering (Prince George) Ltd

Address: 9368 Milwaukee Way, B.C.R. Industrial Site, Prince George, British Columbia, Canada, V2N 2K8

Invention Title: Ending Apparatus and Method

Names of actual inventors: Bruno Lindenblatt and Gary Larsen

Address for service in Australia:  
C/- R K MADDERN & ASSOCIATES, 345 King William Street,  
Adelaide, South Australia, Australia

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BASIC CONVENTION APPLICATION(S) DETAILS			
Application Number	Country	Country Code	Date of Application
07/757686	United States	US	11/9/91

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DATED this 9th day of September, 1992.

LINDEN FABRICATING AND  
ENGINEERING (PRINCE GEORGE) LTD  
By its Patent Attorneys  
R K MADDERN & ASSOCIATES

  
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R S CATT

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PATENTS ACT 1990

**NOTICE OF ENTITLEMENT**

We Linden Fabricating and Engineering (Prince George) Ltd  
of 9368 Milwaukee Way, B.C.R. Industrial Site, Prince George,  
British Columbia, Canada, V2N 2K8

being the applicant in respect of Application No. ,  
state the following:-

1. The person nominated for the grant of the patent:  
has entitlement from the actual inventors. The applicant  
is the assignee of the actual inventors.
2. The person nominated for the grant of the patent:  
has entitlement from the applicants of the basic  
application listed on the patent request form.

The basic application listed on the request form:  
is the first application made in a Convention country in  
respect of the invention.

DATED this 9th day of September 1992.

LINDEN FABRICATING AND  
ENGINEERING (PRINCE GEORGE) LTD  
By its Patent Attorneys  
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(19) AUSTRALIAN PATENT OFFICE (10) Acceptance No. 648731

(Modified Examination)

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ENDING APPARATUS AND METHOD
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757686 11.09.91 US UNITED STATES OF AMERICA
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- (71) Applicant(s)  
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- (74) Attorney or Agent  
R K MADDERN & ASSOCIATES , 345 King William Street, ADELAIDE SA 5000
- (57) Claim

1. An ending apparatus for positioning elongate objects comprising, in combination:

object singulating means for separating a plurality of elongate objects in an inlet area into single objects while moving the objects in a first direction to an outlet area;

object support means intermediate said inlet and outlet area for supporting a separated, single elongate object adapted to move said elongate object in a second direction toward reference surface means independently of the object's movement in said first direction on said singulating device;

said reference surface means stopping movement of said elongate object to establish a pre-determined position for said elongate object; and

cutting means positionable with respect to said reference surface means to cut said object into pre-determined lengths.

12. A method for positioning a plurality of elongate objects comprising the steps of:

moving the objects in a first direction between an inlet area and an outlet area;

separating the elongate objects into discrete objects while moving the objects in said first direction; and

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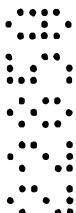
aligning each individual elongate object with respect to a pre-determined reference position by movement in a second direction independent of movement in said first direction.

AUSTRALIA  
PATENTS ACT 1990

COMPLETE SPECIFICATION

FOR A STANDARD PATENT

*ORIGINAL*



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Name of Applicant: Linden Fabricating and Engineering (Prince  
George) Ltd

Actual Inventors: Bruno Lindenblatt and Gary Larsen

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William Street, Adelaide, South  
Australia, Australia

Invention title: Ending Apparatus and Method

The following statement is a full description of this  
invention, including the best method of performing it known to  
us.

ENDING APPARATUS AND METHOD

FIELD OF THE INVENTION

This invention relates to an ending apparatus and  
5 method for positioning of an object with respect to a  
reference surface, and is particularly suited for  
separating and ending elongate objects such as logs.

BACKGROUND OF THE INVENTION

In sawmills, the handling and processing of logs in  
10 an efficient manner is of vital importance. Equipment  
for separating large groups of raw logs into individual  
logs is often the first step in processing. The  
separated logs are then transported to an ending  
apparatus that positions each log relative to a reference  
15 surface so that the log is in a pre-determined position  
for future processing operations. This ending process is  
vital in such operations as cutting the log into pre-  
determined lengths. It is generally necessary to  
separate groups of logs into single logs in order to  
20 accomplish the ending process accurately.

Currently, the separating and ending process is  
carried out by different machinery. For example, a  
separating or singulating device as disclosed in Canadian  
Patent 1,277,682 issued on December 11, 1990 to Interlog  
25 AB is used to separate groups of logs into individual  
logs. Once separated, the logs are transported to a  
ending apparatus for positioning in a second totally  
separate operation.

In a sawmill, movement of raw materials between  
30 equipment takes time which affects the overall efficiency  
and throughput through the mill. As well, each

additional piece of equipment represents a significant capital expense.

Therefore, there is a general need for equipment that will reduce overall processing time by handling logs  
5 more efficiently and reducing the need for expensive equipment.

SUMMARY OF THE INVENTION

The present invention provides an ending apparatus that separates logs and performs an ending operation.  
10 Combining these two functions in a single apparatus eliminates the need for separate, expensive singulating equipment and ending equipment. Processing time is also reduced as the transportation period between equipment is eliminated.

15 Accordingly, the present invention provides an ending apparatus for positioning elongate objects comprising, in combination:

object singulating means for separating a plurality of elongate objects in an inlet area into single objects  
20 while moving the objects in a first direction to an outlet area; and

object support means intermediate said inlet and outlet area for supporting a separated, single elongate object adapted to move said elongate object in a second  
25 direction toward reference surface means independently of the object's movement in said first direction on said singulating device;

said reference surface means stopping movement of said elongate object to establish a pre-determined  
30 position for said elongate object.

The apparatus of the present invention provides a relatively compact piece of equipment that saves space within a sawmill. In addition, the compact nature of the present apparatus allows for adjacent positioning of a close-coupled breakdown or handling device such as a cutting machine for cutting the logs into pre-determined lengths.

In a further aspect, the present invention provides a method for positioning a plurality of elongate objects comprising the steps of:

moving the objects in a first direction between an inlet area and an outlet area;

separating the elongate objects into discrete objects while moving the objects in said first direction; and

aligning each individual elongate object with respect to a pre-determined reference position by movement in a second direction independent of movement in said first direction.

BRIEF DESCRIPTION OF THE DRAWINGS

Aspects of the present invention are illustrated, merely by way of example, in the accompanying drawings in which:

Figure 1 is a plan view of an ending apparatus according to the present invention; and

Figure 2 is an elevation view with cut away section taken along line 2-2 of Figure 1.

DESCRIPTION OF THE PREFERRED EMBODIMENTS



Referring to Figure 1, a preferred embodiment of the present invention is illustrated in plan view. The device comprises, in combination, object singulating means in the form of singulating device 10 and object support means in the form of a plurality of rollers 12. In the following description, logs will be used as examples of articles to be processed, it being understood that the apparatus of the present invention is capable of handling any elongate object.

10 Singulating device 10 is preferably of the construction described in Canadian Patent 1,277,682 issued December 11, 1990 to Interlog AB. The device comprises a series of pairs of spaced, parallel log support surfaces 14. As best shown in Figure 2, each log support surface 14 comprises an essentially rigid plate member having an upper surface 16 formed into a series of steps 18 separated by inclined portions 19 which are generally parallel to each other. Steps 18 and their adjacent inclined portions 19 define a series of V-shaped pockets 20 along support surface 14 adapted to retain individual logs. Log support surfaces 14 extend generally between a log inlet area 21 and a log outlet area 22. Inlet area 21 retains a plurality of logs arranged in generally parallel fashion in a stack. Outlet area 22 can be provided with a conveyor belt (not shown) for removing logs after handling by the apparatus of the present invention.

Between pairs of fixed log support surfaces 14 are provided movable feeding surfaces 24 that are also formed into a step pattern that generally corresponds to the step pattern of the log support surface 14. The steps of feeding surface 24 are separated by essentially parallel planar sections 28. The overall length of each feeding surface 24 is shorter than the length of the log support surfaces 14 to allow for back and forth motion of

the feeding surface between pairs of log support surfaces in a first direction as indicated by arrow 30. The motion is such that steps 18 and 26 remain parallel and inclined portions 19 remain parallel with planar sections 28.

Feeding surface 24 are mounted to a support framework 32 to allow for the necessary back and forth motion. Referring to Figure 2, log support surfaces 14 are rigidly mounted to a series of horizontal beams 34 that are in turn connected to uprights 36 extending from a base frame 38. Each log support surface 14 includes wheeled supports 40 that engage and support the underside of feeding surface 24. Feeding surfaces 24 are moved back and forth by driving means in the form of hydraulic cylinder 42 mounted between upright 36 adjacent the inlet area 21 and the underside of a step 26. By retracting and extending cylinder 42, the feeding surface 24 is movable between a lower position illustrated by solid lines and an upper position illustrated by dashed lines in Figure 2. Note that the various feeding surfaces 24 are joined by connecting members 44 so that a single hydraulic cylinder 44 can drive a plurality of feeding surfaces.

Movement of feeding surfaces 24 between log support surfaces 14 causes individual logs to be driven up the inclined portions 19 of the log support surfaces. As feeding surfaces 24 are advanced upwardly, each step 26 in combination with inclined portion 19 of the log support surface forms a movable pocket that advances a single log held within the pocket up the apparatus along inclined portion 19. When step 26 of the feeding surface reaches the next log support surface step 18, the log rolls down step 18 and into stationary pocket 20 of the log support surface due to gravity. Step 18 holds the log in place as feeding surfaces 24 are retreated

downwardly. When the feeding surfaces 24 are advanced upwardly in the next cycle, the log will be pushed onto the next stationary pocket by the movable pocket created by the advancing step 26 and the inclined portion 19 of the support surface 14. In this manner, logs are moved in stages between inlet area 21 and outlet area 22 and separated into individual logs. Feeding surface planar sections 28 are formed with large openings 29 that permit bark and other waste material to fall through the apparatus so that it does not interfere with separating operations.

The spacing between log support surfaces 14 and feeding surfaces 24 is selected such that each step 26 projects above inclined portion 19 a distance sufficient to receive a single log in the moving pocket that is formed.

Referring to Figure 1, log support surfaces 14 are arranged in paired groups with spacing between groups. This spacing permits rollers 12 to be mounted between groups of support surfaces intermediate inlet and outlet areas 21 and 22, respectively, in order to perform the ending function of the present apparatus. Rollers 12 are hour-glass rollers arranged along the longitudinal axis of a log. At least one of the rollers 12 is provided with driving means in the form of a motor 50 driving a belt 52.

As best shown in Figure 2, rollers 12 are positioned between log support surfaces 14 such that a log being deposited within an upper stationary pocket 20 will also rest on the rollers. Sensing means are provided that detect whenever a log comes to rest atop rollers 12. The sensing means stop hydraulic cylinders 42 moving feeding surfaces 24 and activate motor 50 to rotate at least one of the rollers 12. The rollers cause a supported log to

move in a second direction, indicated by arrow 58 in Figure 1, toward a reference surface 60. Generally, the second direction of log travel for ending purposes will be perpendicular to the first direction of log travel for singulating purposes.

Reference surface 60 is a rigidly mounted surface that stops movement of the log in the second direction thereby establishing a pre-determined position for the log. A further sensor to detect alignment of the log can be used to stop movement of the rollers and resume movement of the singulating device in the first direction so that the aligned log is moved toward outlet area 22.

Once the log has been aligned into a pre-determined position efficient handling and processing of the log is possible with less wastage of material.

The ending apparatus of the present invention can optionally be provided with cutting means positionable with respect to reference surface 60 to cut an aligned log into pre-determined lengths. In the illustrated embodiment, cutting means in the form of circular saw blades 62 are provided. As best shown in Figure 2, saw blades 62 are mounted above outlet area 22 for pivotable movement about point 66 into and out of the path of logs being transported on the singulating apparatus. The saw blades swing down into the path of the log after the log has been aligned against reference surface 60. The cutting blades are positioned to swing between the log support plates 14.

Although the present invention has been described in some detail by way of example for purposes of clarity and understanding, it will be apparent that certain changes and modifications may be practised within the scope of the appended claims.

The claims defining the invention are as follows:

1. An ending apparatus for positioning elongate objects comprising, in combination:

object singulating means for separating a plurality of elongate objects in an inlet area into single objects while moving the objects in a first direction to an outlet area;

object support means intermediate said inlet and outlet area for supporting a separated, single elongate object adapted to move said elongate object in a second direction toward reference surface means independently of the object's movement in said first direction on said singulating device;

said reference surface means stopping movement of said elongate object to establish a pre-determined position for said elongate object; and

cutting means positionable with respect to said reference surface means to cut said object into pre-determined lengths.

2. Apparatus as claimed in claim 1 in which said object support means comprises:

a plurality of rollers to receive an individual elongate object;

drive means to rotate at least one of said rollers to move said elongate object toward said reference surface means in said second direction.

3. Apparatus as claimed in claim 2 in which said rollers are arranged at spaced intervals along a path corresponding to said second direction and the longitudinal axis of one of said elongate objects.

4. Apparatus as claimed in claim 1 in which said first and second directions are perpendicular.

5. Apparatus as claimed in claim 1 in which said cutting means comprises at least one cutting member insertable into the path of said individual elongate object while moving in



said first direction to cut said object into pre-determined lengths.

5 6. Apparatus as claimed in claim 5 in which said cutting member is mounted adjacent said outlet area for pivotable movement into and out of the path of said elongate objects.

10 7. Apparatus as claimed in claim 5 in which said cutting member comprises a rotary saw blade.

8. Apparatus as claimed in claim 1 in which said reference surface means comprises a fixed surface positioned to abut the end of an elongate object.

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9. Apparatus as claimed in claim 1 including first sensing means to determine when an object is positioned on said object support means, said first sensing means stopping movement of said object in said first direction and actuating said object support means to initiate movement of said object in said second direction, and second sensing means to determine when an object has reached said reference surface means, said second sensing means stopping movement of said object in said second direction and resuming movement of said object in said first direction.

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10. Apparatus as claimed in claim 1 in which said object singulating means comprises:

spaced and parallel object support surfaces extending between said inlet and outlet areas having a step-like configuration defining a series of stationary object retaining pockets along said support surfaces;

a movable feeding surface between said spaced support surfaces having a corresponding step-like configuration;

35 drive means to move said feeding surface back and forth between said spaced object support surfaces;

said movable feeding surface being positioned with respect to said object support surfaces such that <sup>said</sup> step-like configuration of said movable feeding surface moving between said object supporting surfaces define a series of movable

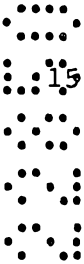


pockets that transport objects along said supporting surfaces to said stationary pockets, said movable and stationary pockets being dimensioned to accept only one object at a time such that movement of said objects between pockets by said feeding surface tends to separate groups of objects in said inlet area into single objects for delivery to said outlet area.

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11. Apparatus as claimed in claim 10 in which there are a plurality of paired object support surfaces each with an associated feeding surface arranged in spaced, parallel configuration, said object support means being mounted between object support surfaces adjacent a stationary pocket.

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12. A method for positioning a plurality of elongate objects comprising the steps of:

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moving the objects in a first direction between an inlet area and an outlet area;

separating the elongate objects into discrete objects while moving the objects in said first direction; and

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aligning each individual elongate object with respect to a pre-determined reference position by movement in a second direction independent of movement in said first direction.



13. A method as claimed in claim 12 including the additional step of:

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cutting said positioned objects into one of more pre-determined lengths.



14. A method as claimed in claim 12 in which the step of aligning each individual elongate object involves:

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sensing the presence of each individual object; stopping movement of said object in said first direction;

moving said object in said second direction to stop at a reference surface; and

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resuming movement of said positioned object in said first direction.



15. A method as claimed in claim 13 in which cutting of said objects comprises the additional steps of:

sensing the presence of said positioned object;

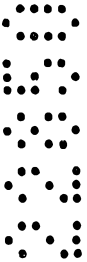
actuating a cutting member to cut through said

5 positioned object while moving in said first direction.

16. A method as claimed in claim 12 in which said separating step is accomplished by a step feeder.

Dated this 15th day of December 1993.

LINDEN FABRICATING AND  
ENGINEERING (PRINCE GEORGE) LTD  
By its Patent Attorneys  
R K MADDERN & ASSOCIATES

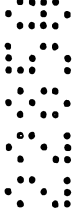




ABSTRACT

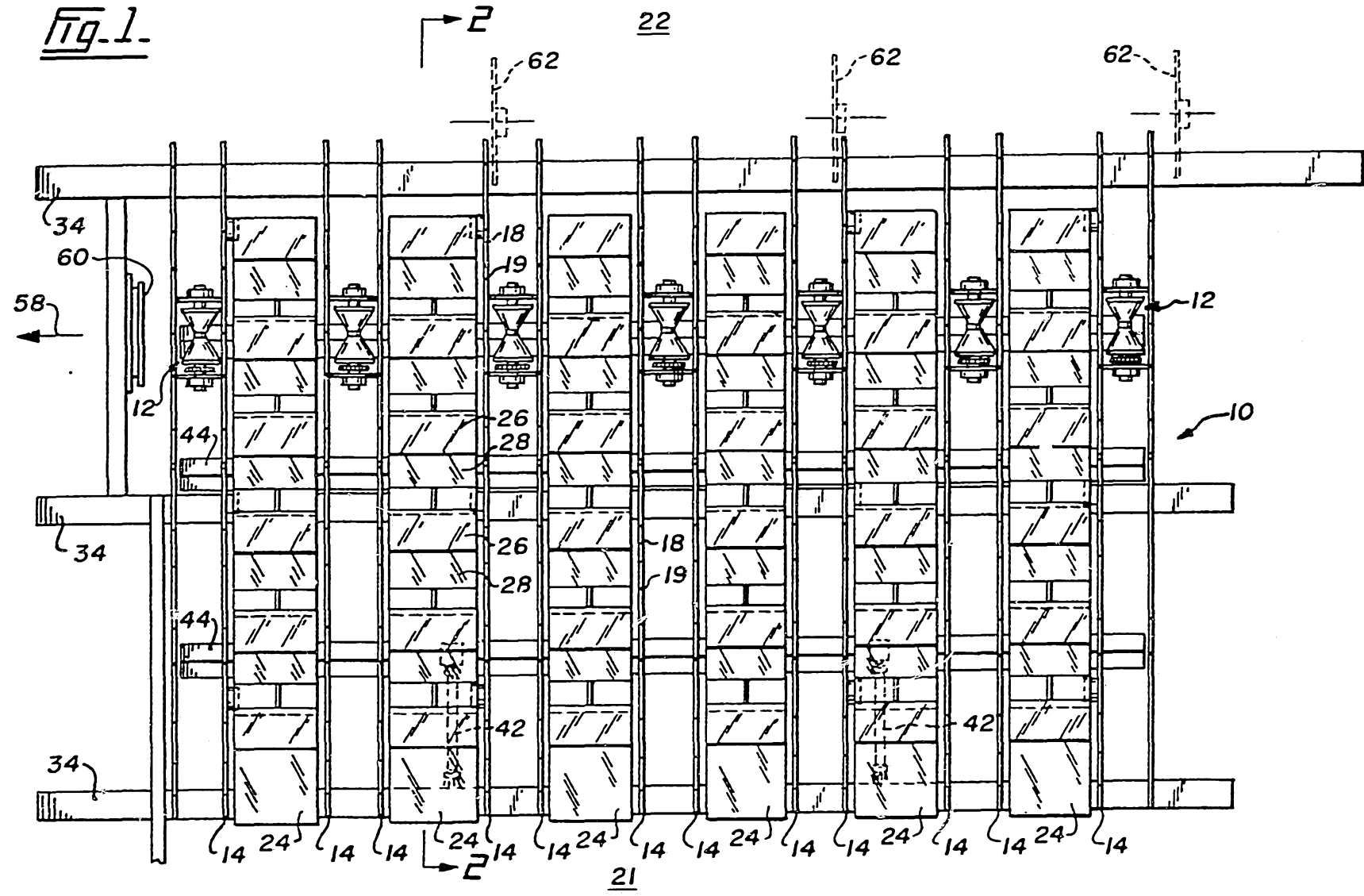
An ending apparatus for positioning elongate objects comprising, in combination, object singulating equipment (10) for separating a plurality of elongate objects in an inlet area into single objects while moving the objects in a first direction to an outlet area, and object support rollers (12) intermediate the inlet and outlet area for supporting a separated, single elongate object. The object support rollers (12) are adapted to move the elongate object in a second direction toward a reference surface (60) independently of the object's movement in the first direction on the singulating device (10). The reference surface (60) stops movement of the elongate object to establish a pre-determined position for the elongate object. Establishing the position of the object permits more efficient handling during further processing.

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Fig. 1.



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Fig. 2.

