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(71) Applicant(s):
Robert Bosch GmbH
(Incorporated in the Federal Republic of Germany)
Postfach 30 02 20, Wernerstrasse 1,
D-70442 Stuttgart,
Federal Republic of Germany

(72) Inventor(s):
Jamie Moreno

(74) Agent and/or Address for Service:
A A Thornton & Co
235 High Holborn, LONDON, WC1V 7LE,
United Kingdom

(54) Abstract Title: Drive apparatus for a reciprocating tool

(57) A reciprocating saw (10, fig 1) comprises a housing (12, fig 1), a drive shaft 46 rotatably mounted in the housing, and a motor (20, fig 1) in the housing for driving the drive shaft. An elongate plunger 28 is located in the housing for reciprocating motion, and is driven by a wobble plate interface structure (72, 76, fig 5) and pivotally supported in a front bushing 112 in a manner permitting the plunger to rotate about an axis of rotation aligned with a longitudinal axis of the plunger. The plunger has a front end portion 80 for attaching a tool, and an enlarged rear end spherical portion 94. A counterweight assembly 32 is provided that includes a movable counterweight 98 and a drive arm (156, fig 3) for moving the counterweight located in the housing. The counterweight has an opening 96 for receiving the plunger, where the opening has at least cylindrical side wall portions that are sized and configured to support the rear end spherical portion of the plunger as the plunger and counterweight move relative to one another. First and second wobble plate assemblies 42, 44 are operatively connected to the drive shaft for engaging the plunger and the counterweight respectively.

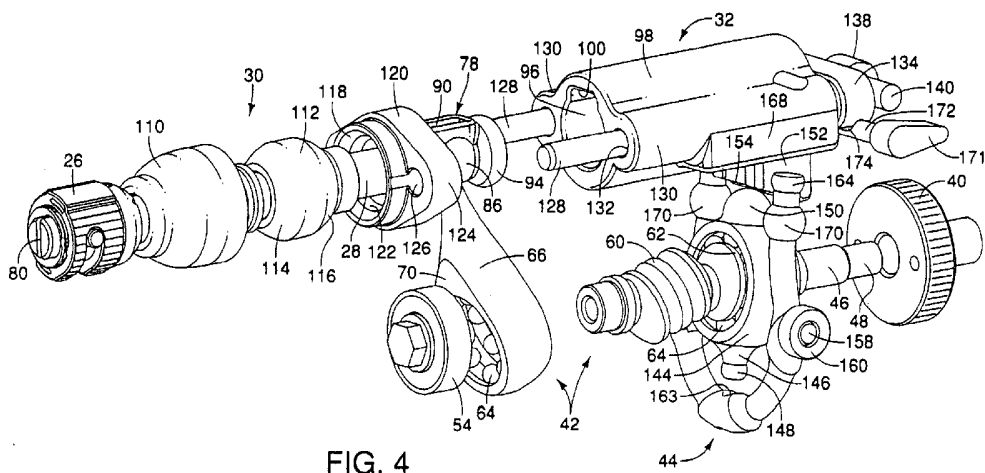


FIG. 4

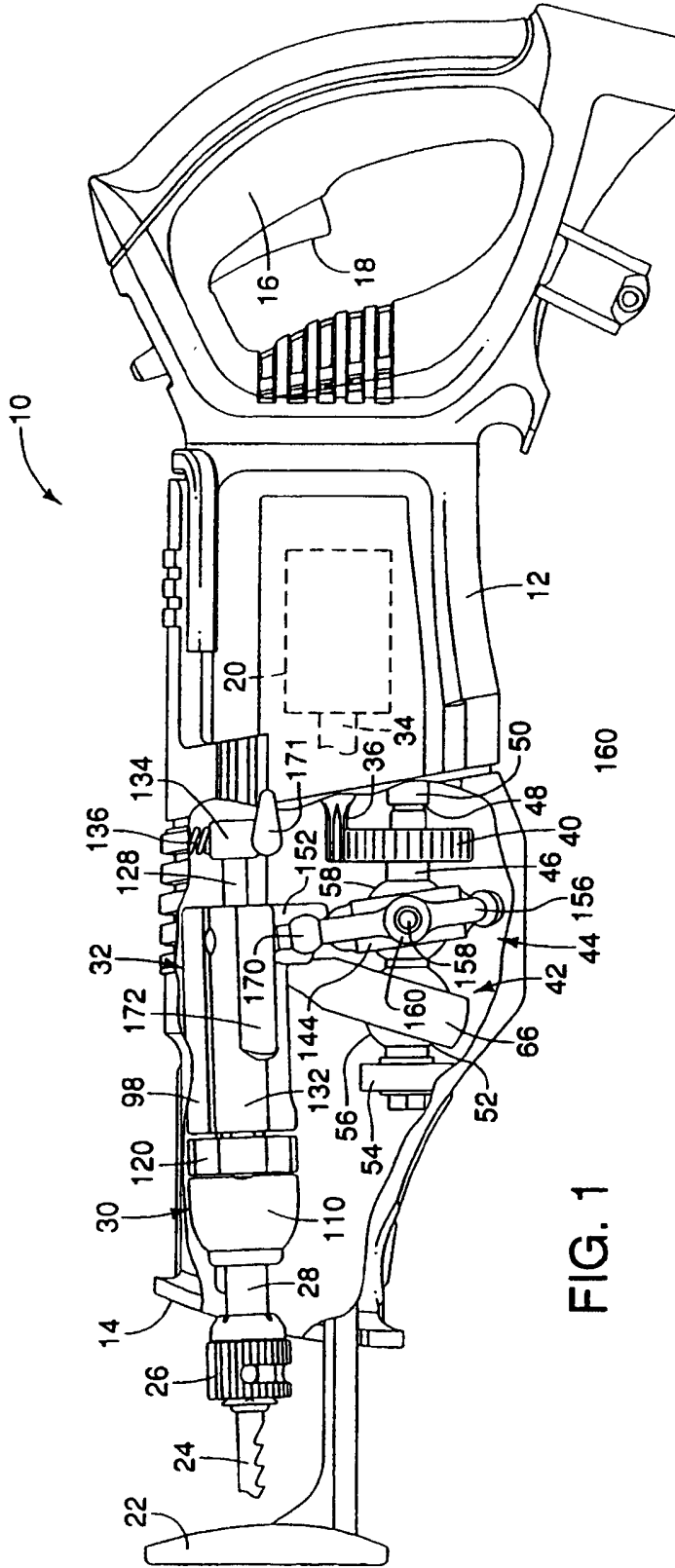


FIG. 1

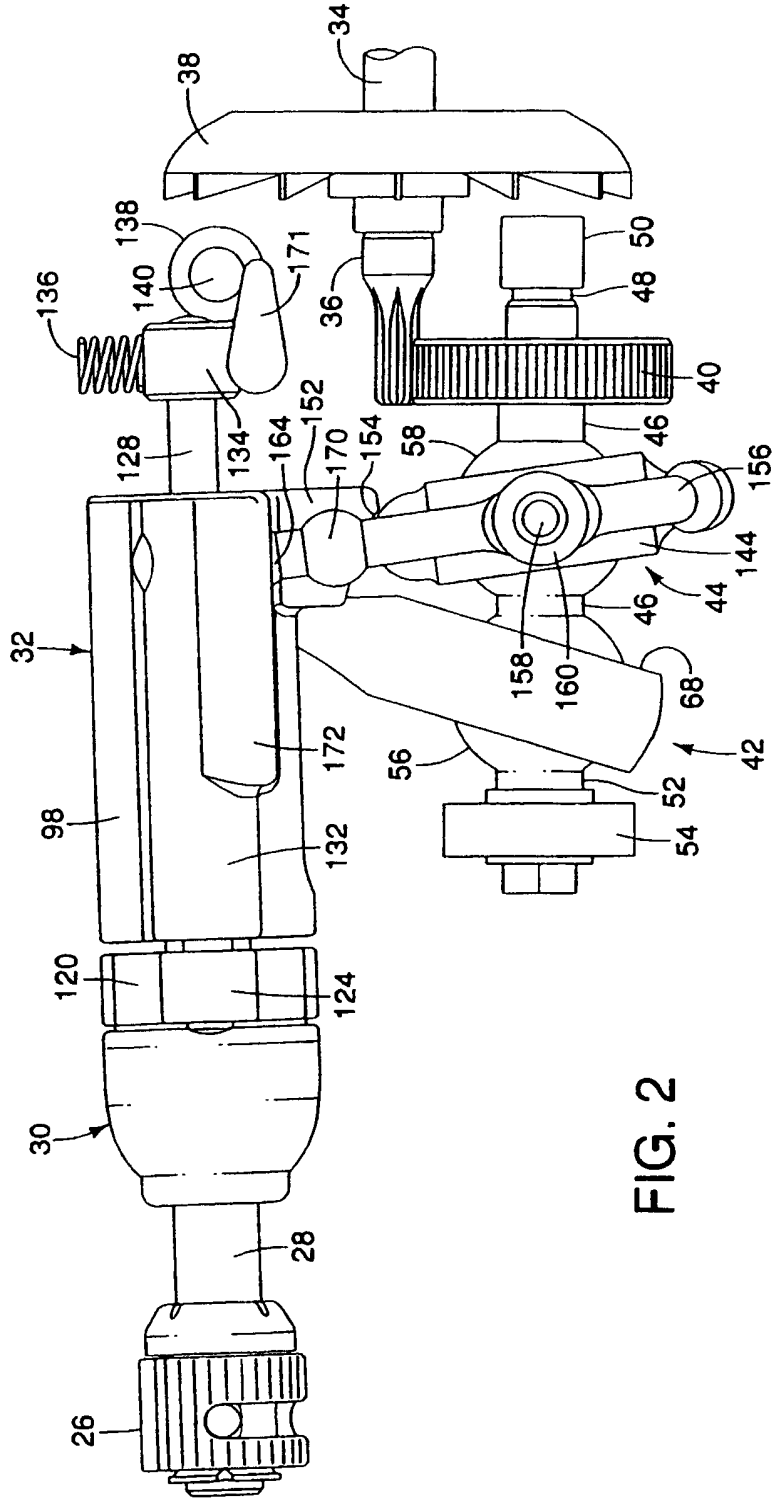


FIG. 2

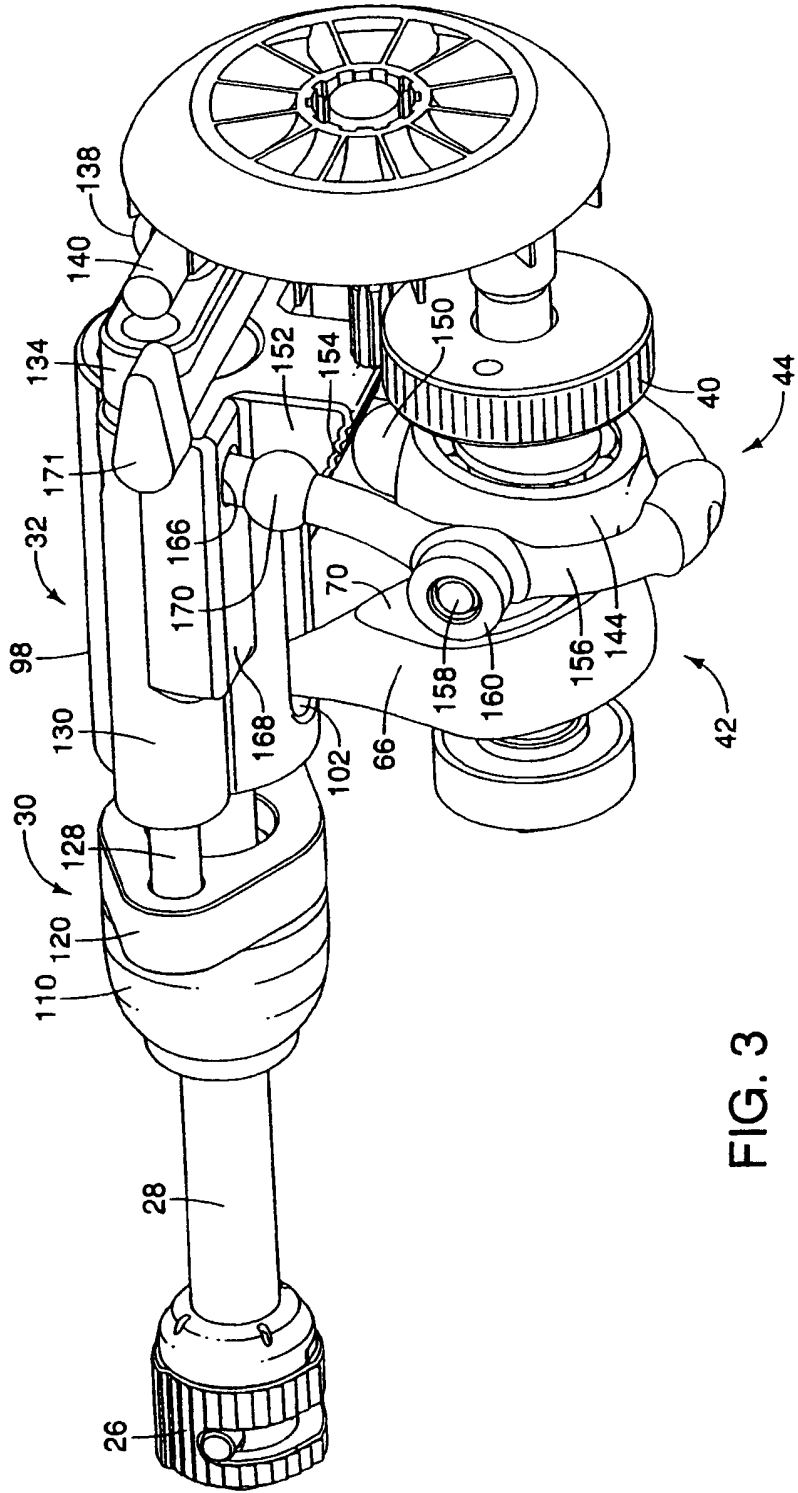


FIG. 3

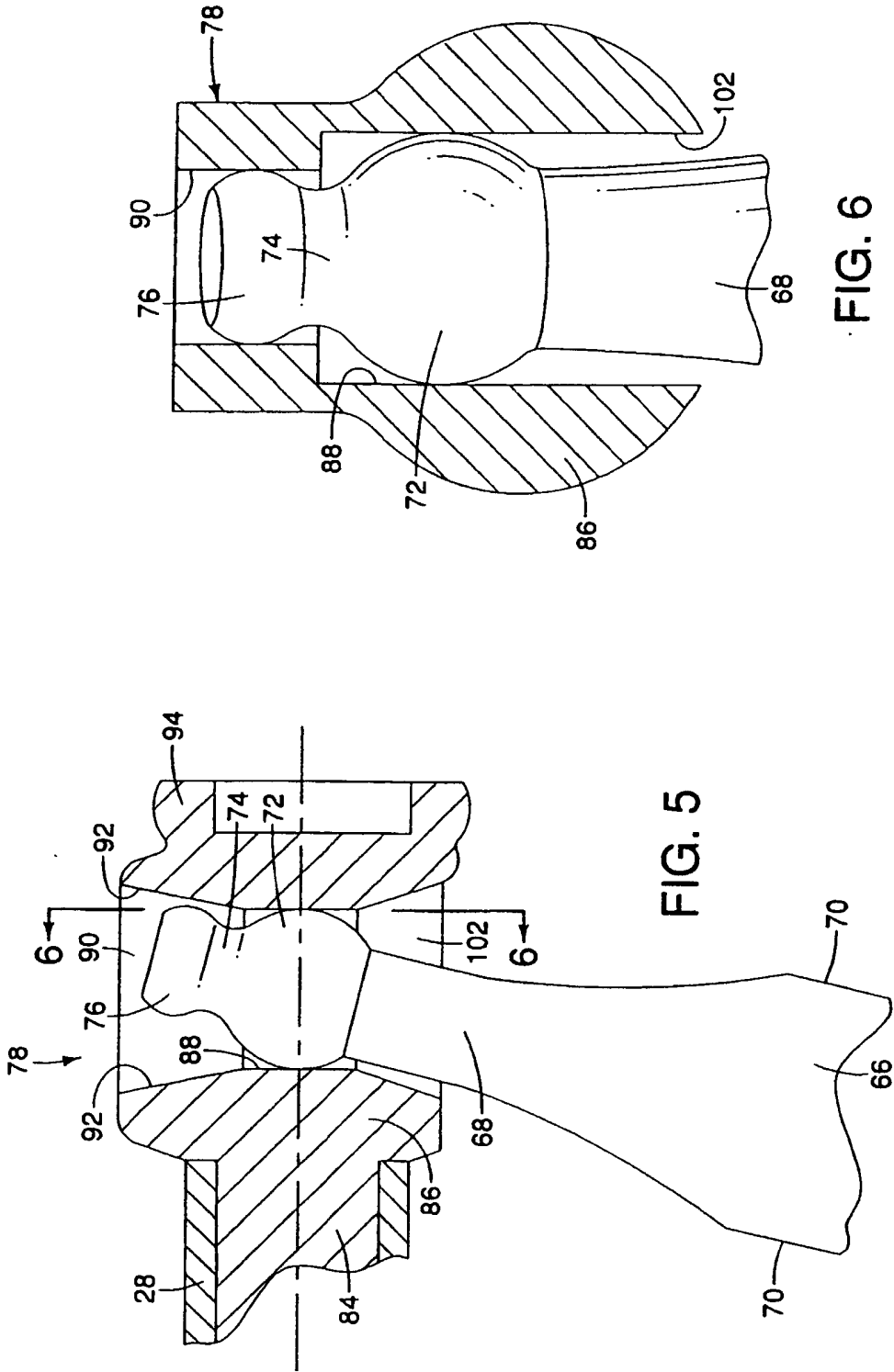


FIG. 6

FIG. 5

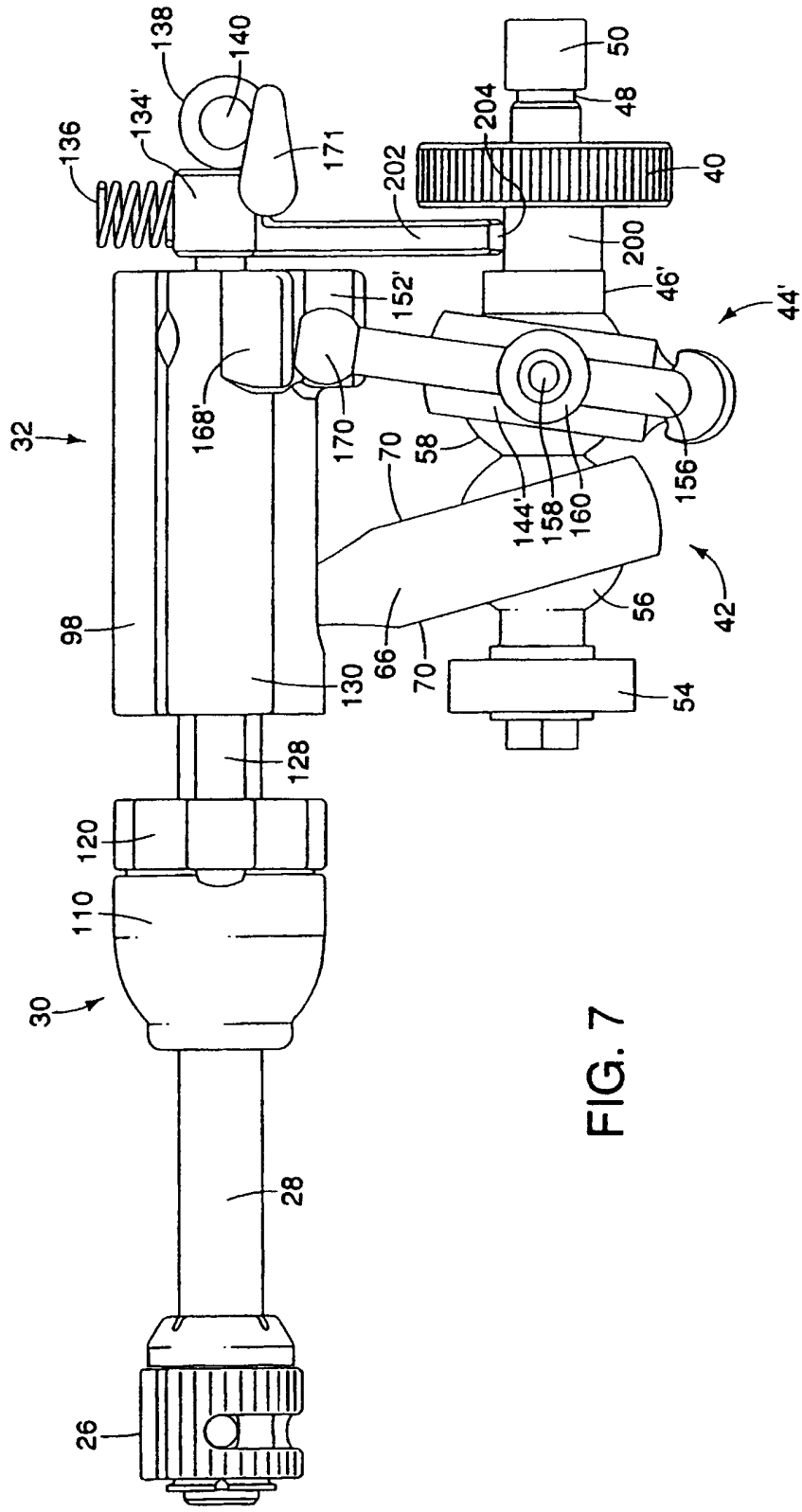


FIG. 7

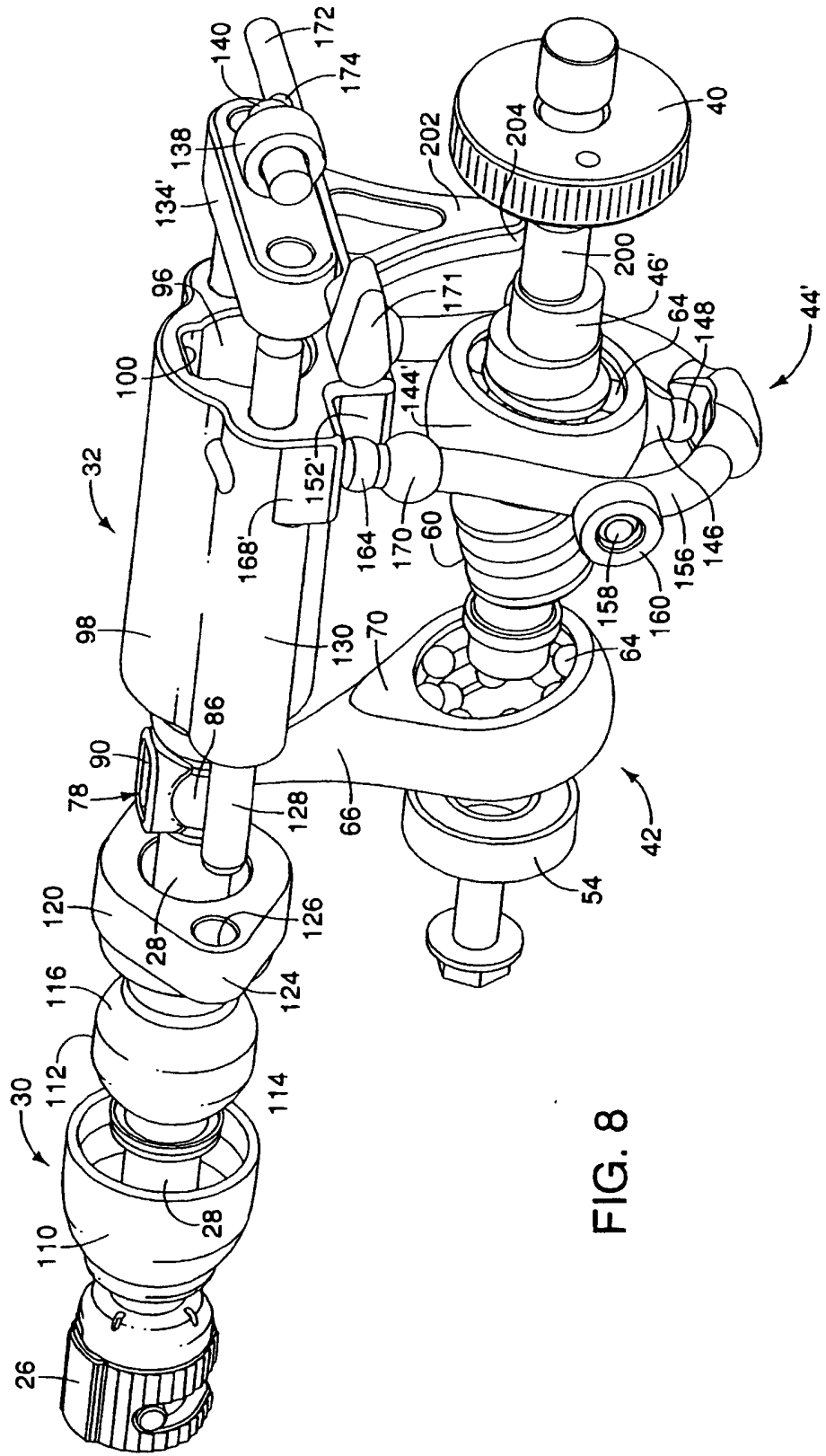


FIG. 8

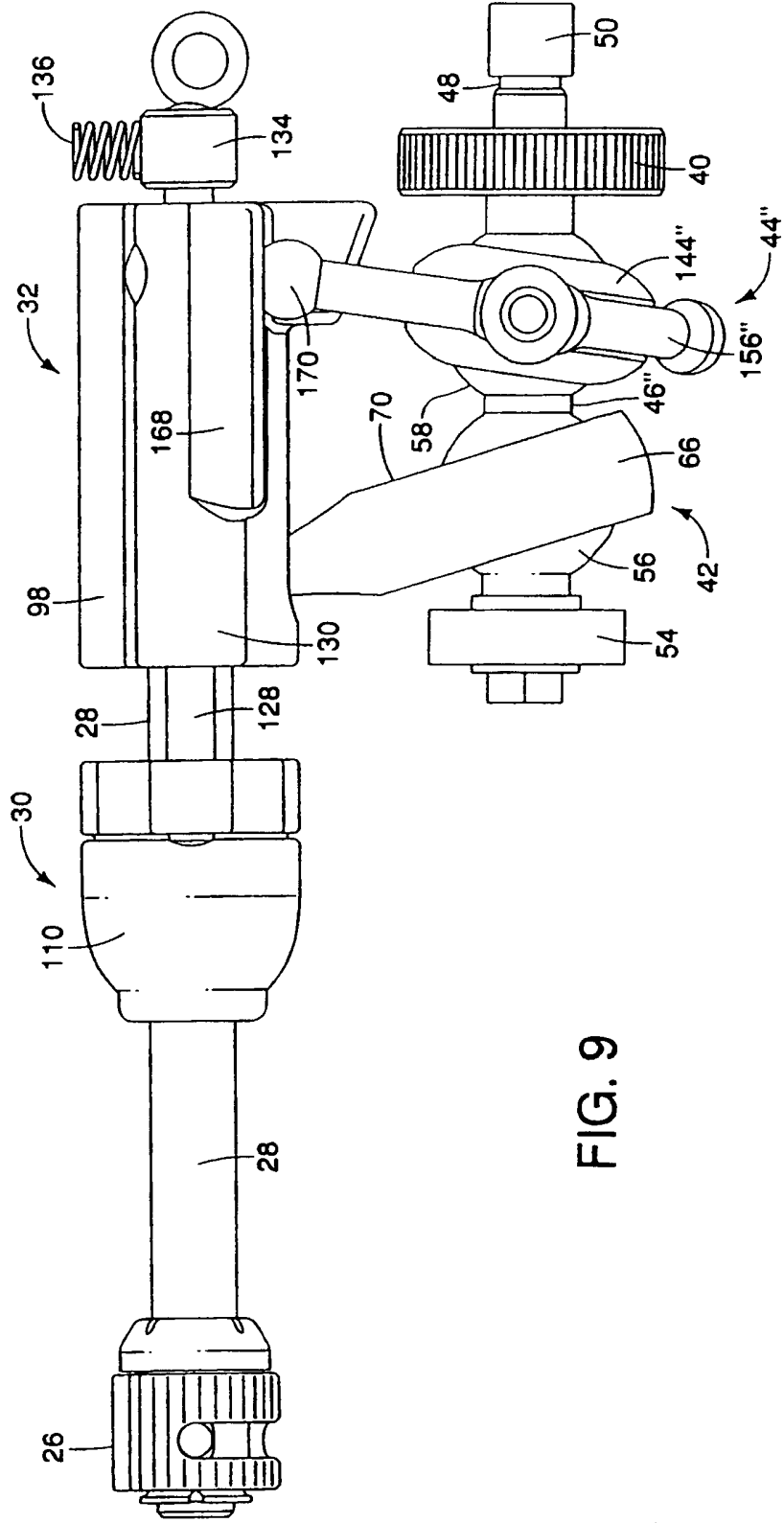


FIG. 9

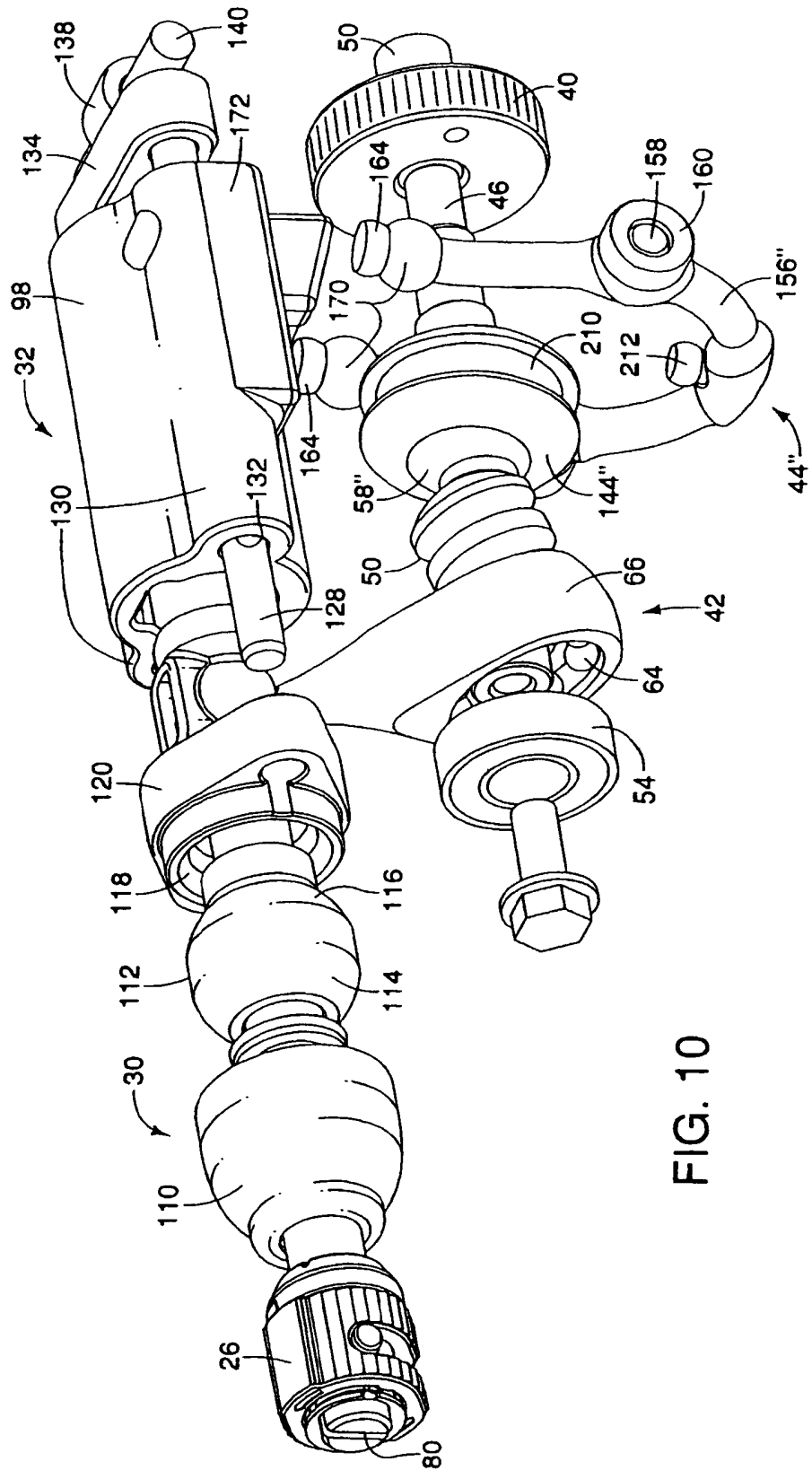


FIG. 10

1 A DRIVE MECHANISM FOR A RECIPROCATING TOOL

2 BACKGROUND OF THE INVENTION

3 The present invention generally relates to power hand tools, and more
4 particularly, to power reciprocating tools.

5 Reciprocating tools that are motor driven, such as saber saws, larger
6 reciprocating saws and the like are usually driven by electric motors that have a rotating
7 output shaft. The rotating motion must be translated into reciprocating motion for
8 moving a saw blade or the like in a reciprocating manner. While various types of
9 mechanisms have been known in the art for translating the rotation motion into
10 reciprocating motion, one common type of motion conversation mechanism is known as
11 a wobble plate drive. A wobble plate drive shaft is typically connected to the motor
12 through a gear arrangement to reduce the speed of rotation of the motor output shaft and
13 the wobble plate drive causes a wobble arm to reciprocate in a path that is parallel to the
14 motion of the saw blade or the like. The blade of a reciprocating saw is mounted in a
15 blade clamping mechanism that is located at the end of a plunger, the other end of which
16 is operatively connected to a wobble arm.

SUMMARY OF THE INVENTION

1 Embodiments of a reciprocating drive apparatus are disclosed which
2 comprise a housing, a drive shaft rotatably mounted in the housing, a motor in the
3 housing for driving the drive shaft, an elongated plunger located in the housing for
4 reciprocating motion, the plunger being driven by a wobble plate interface structure and
5 pivotally supported in a front bushing and in a manner permitting the plunger to rotate
6 about an axis of rotation aligned with the longitudinal axis of the plunger, the plunger
7 having a front end portion for attaching a tool, and an enlarged rear end spherical portion,
8 a counterweight assembly including a movable counterweight and a drive arm for moving
9 the counterweight located in the housing, the counterweight having an opening for
10 receiving the plunger, wherein the opening has at least cylindrical side wall portions that
11 are sized and configured to support the rear end spherical portion of the plunger as the
12 plunger and counterweight move relative to one another, a first wobble plate assembly
13 operatively connected to the drive shaft and having a first wobble plate interface structure
14 for engaging and reciprocating the plunger in the front bushing and the counterweight;
15 and a second wobble plate assembly operatively connected to the drive shaft and having a
16 second wobble plate interface structure for engaging the drive arm of the counterweight
17 assembly.

1 in a blade clamping mechanism 26 that is mounted at the end of an elongated plunger,
2 indicated generally at 28, which is slideable in a front bushing assembly, indicated
3 generally at 30 and in a counterweight assembly indicated generally at 32. As shown in
4 FIGS. 1 and 2, the motor 20 has an output shaft 34 with a pinion gear 36 and fan member
5 38 operatively attached to the shaft 34, with the gear 36 engaging a larger gear 40 that is
6 connected to a two wobble plate assemblies, indicated generally at 42 and 44, which
7 respectively drive the plunger 28 and counterweight assembly 32 in a reciprocating
8 manner and in an opposite direction relative to one another as the gear 38 drives the
9 wobble shaft assemblies 42 and 44.

10 More particularly, the wobble shaft assemblies 42 and 44 have a drive shaft
11 indicated generally at 46, to which the gear 40 is attached. The shaft has an end portion
12 48 that is supported in a ball bearing 50 or the like and its opposite end 52 supported in
13 another ball bearing 54 that is mounted in the housing 12. It should be understood that
14 the manner in which the motor 20, gears 36 and 40 as well as the shaft 46 are mounted in
15 the housing 12 is not in and of itself part of the present invention and the manner in
16 which the housing 12 is constructed and the rotating parts are supported is well known to
17 those of ordinary skill in the art.

18 With regard to the wobble plate assemblies 42 and 44, and referring to
19 FIGS. 1-4, the shaft 46 has two spaced apart enlarged portions 56 and 58, each of which
20 has generally cylindrical shaped portions 60 and 62 (see FIG. 4) that are oriented at an

1 acute angle relative to the axis of the shaft 46 and ball bearings 64 (see FIG. 4) are
2 provided to permit the arms of wobble plate assemblies 42 and 44 to move in a left and
3 right direction relative to the cylindrical portions 60 and 62 as the shaft 46 is rotated
4 during operation.

5 More particularly, as the shaft 46 is rotated, the angular orientation of the
6 cylindrical portion 60 changes, and an arm 66 of the wobble plate assembly 42 is moved
7 in a reciprocating manner, i.e., to the left as shown in FIGS. 3 and 4, and to the right as
8 shown in FIGS. 1 and 2. As is shown in FIGS. 1-6, the arm 66 has generally flat sides 70
9 that extend from the bottom upwardly which then merges into a curved outer end member
10 68 that reduces in size and becomes circular shaped in cross-section. It then merges with
11 a first ball-type interface 72 that in turn merges into a transition portion 74 that in turn
12 merges into a second ball-type interface 76. The interfaces 72 and 76 have a generally
13 spherical form, albeit truncated, and they are sized to fit within cooperative structure of a
14 receiver member 78 that is preferably attached to the inner end of the plunger 28. It
15 should be understood that these ball-type interface portions do not need to be strictly
16 spherical but are desirably generally near-spherically shaped so that point contact is made
17 between these interfaces and the receiver member 78 of the plunger 28.

18 Referring to FIGS. 4, 5 and 6, the plunger 28 has a left outer end solid
19 generally cylindrical portion that has a vertical slot 80 (see FIG. 4) in which the shank
20 end of the blade 24 may be inserted. The end also has an aperture (not shown) in which a

1 pin 82 of the blade clamping mechanism 26 may be attached. At the opposite end of the
2 plunger 28 is the receiver member 78 that has a cylindrical extension 84 that is sized to
3 closely fit within the interior of the plunger 28 and which is also preferably braised to
4 securely hold the two components together inasmuch as extreme forces are applied to the
5 plunger 28 during operation. Alternatively, the receiver member 78 may be formed with
6 the plunger 28 as a single integral structure.

7 The receiver member 78 has a main body 86 that has a circular opening 88
8 that merges into an elongated slot 90, the lengthwise direction of which is oriented in the
9 same direction as the axis of the plunger 28 as shown in FIGS. 4 and 5. The ends of the
10 slot 90 are flared outwardly as shown at 92 to accommodate the reciprocating motion that
11 is caused by the elongated arm 66 and particularly the ball-type interfaces 72 and 76 that
12 are positioned in the opening 88 and slot 90, respectively. As shown in FIGS. 5 and 6,
13 the first ball-type interface 72 is positioned in the opening 88 with the outside of the
14 interface being generally in a point contact with the sidewall of the opening 88. The
15 second ball-type interface 76 also rides in the slot 90, and as is also shown in FIGS. 5 and
16 6, the diameter of the interface 76 is only slightly smaller than the width of the slot 90
17 and thereby effectively prevents the plunger 28 from rotating out of its generally vertical
18 plane of movement.

19 Because of the preferably spherical-shaped configuration of the interfaces
20 72 and 76 being positioned in the respective opening 88 and slot 90, each of which have

1 straight wall surfaces that are contacted, there is only point contact between the interfaces
2 and the sidewalls during the entire movement of the elongated wobble arm 66. This point
3 contact results in the advantages of reduced wear between the interfaces and the receiver
4 member 78 and less heat being generated during operation. Also, because of the
5 curvature of the ball interface portions with the vertical walls being contacted, there is
6 only point contact at all times, regardless of the tolerances and clearances between the
7 parts. It is also preferred that grease be applied to the receiver member 78 to further
8 reduce friction between the ball-type interfaces and the receiver member 78.

9 The receiver member 78 has a spherical rear end portion 94 that is
10 configured to fit within and slide in an opening 96 in a counterweight body 98 of the
11 counterweight assembly 44. The opening 96 also has an enlarged generally rectangular
12 recess portion 100 that is sized to enable the top portion of the main body 86 of the
13 receiver member 78 to fit within the opening 96 and recess 100 during reciprocating
14 movement of the plunger 28 and receiver member 78 relative to the counterweight body
15 98 which also is driven in a reciprocating manner. The bottom of the receiver member 78
16 has an axial slot 102 that is sized to permit non-contacting movement of the arm 66 with
17 the receiver member 78. The use of the spherical end portion 94 does not require critical
18 tolerances of the outside diameter relative to the counterweight body opening 96 and
19 therefore reduces manufacturing costs.

1 From the foregoing, it should be understood that the wobble plate assembly
2 42 drives the plunger 28 in a reciprocating manner and thereby causes the blade 24 to be
3 moved in a cutting action. The plunger 28 slides in the front bushing assembly 30 that
4 comprises a spherical cover plate 110 that is mounted in the housing 12 and has an
5 opening in which the plunger is located. The plunger is supported near the nose portion
6 14 of the saw 10 by a front spherical bushing 112 (best shown in FIG. 4) that has a front
7 spherical surface portion 114 that engages a complementary interior spherical surface in
8 the spherical cover plate 110. The front spherical bushing 112 also has a rear spherical
9 surface 116 that engages a complementary spherical surface 118 that is provided in a
10 front rod support bracket 120 that is retained in a stationary position by suitable structure
11 of the housing 12.

12 Thus, the spherical bushing 112 is captured between the spherical cover
13 plate 110 and the front rod support bracket 120, both of which contain semi-spherical
14 sections that allow the bushing 112 to be freely rotationally movable which permits self-
15 alignment of the plunger 28 in the spherical bushing 112. As previously described, the
16 opposite ends of the plunger has the receiver member 78 which has the spherical bushing
17 section 94 supported in the opening 96 of the counterweight body 98. The front spherical
18 bushing 112 acts as a pivot point that enables the right end portion of the plunger 28 to be
19 moved up and down a slight distance which can similarly cause an attached blade to be
20 moved in an orbital path as it is reciprocated during operation. Such minor vertical

1 movement of the right end of the plunger, including the receiver member 78 can be made
2 relative to the arm 66 of the wobble plate assembly 42 because the interfaces 72 and 76
3 located on the end of the wobble plate arm 66 can be moved a slight vertical distance
4 relative to the receiver member 78 without detrimentally affecting the operation of the
5 saw 10.

6 The front rod support bracket 120 has a central opening 122 through which
7 the plunger 28 can pass and it has a pair of side flange extensions 124 located on opposite
8 sides thereof, each of which has an opening for receiving one of a pair of rods 128. The
9 rods 128 are provided to support the counterweight body 98 in a sliding relationship. In
10 this regard, the counterweight body 98 has side extensions 130 on opposite sides thereof
11 with openings 132 that extend the entire length of the extension and are sized to receive
12 the rods 128. The opposite ends of the rods 128 are secured in a rear support bracket 134.
13 A spring 136 is interposed between an inside surface of the housing 12 and the top of the
14 rear support bracket 134 (see FIG. 1) for imparting a downward biasing force on the
15 bracket 134. While the spring 136 is only shown in FIGS. 1, 2, 7 and 9, it should be
16 understood that it is provided in all of the embodiments of the present invention.

17 From the foregoing, it should be understood that the counterweight
18 assembly has the counterweight body 98 that is reciprocated along the rods 128 and the
19 rods are supported in the front by the front rod support bracket and in the rear by the rear
20 support bracket 134 and these brackets are generally floating in the housing and pivot

1 about the front bushing assembly 30 as previously described. The spring 136 is provided
2 to bias the rear support bracket 134 toward its downward position. A rubber or other
3 resilient roller 138 is mounted on a shaft 140 that is secured by the housing 12 and
4 positioned adjacent to the end surface of the rear support bracket 134 to apply a holding
5 force to the bracket 134 during operation. The roller 138 preferably rotates on the shaft
6 140 and permits the bracket 134 to move up and down during desired orbital action.

7 The reciprocating mechanism is designed and configured to move the
8 plunger 28 and counterweight assembly 32 in a manner to create an orbital movement of
9 the blade which improves the cutting performance of the saw and to also reduce the
10 vibration of the saw during operation.

11 To reduce the vibration that is generated by reciprocal saws, the
12 counterweight assembly 32 is reciprocated simultaneously with the reciprocation of the
13 plunger 28. It is done in a manner whereby the direction of movement of the
14 counterweight assembly 32 is opposite that of the plunger 28 which tends to balance the
15 forces that are produced during operation. The size of the counterweight assembly 32 is
16 determined to create the same amount of force that is generated by the plunger and its
17 associated moving parts so that the forces in opposite directions tend to neutralize one
18 another. While the wobble plate assembly 42 drives the plunger and its associated parts,
19 the counterweight assembly 32 is driven by the counterweight wobble plate assembly 44,
20 and both wobble plate assemblies are driven by the same drive shaft 46.

1 The counterweight wobble plate assembly 44 comprises an interface
2 structure 144 that rides on the cylindrical portion 62 of the drive shaft 46. The interface
3 structure 144 completely surrounds the drive shaft 46 and has a lower extension 146 with
4 a spherical drive ball 148 and an upper generally spherical extension 150 which is
5 positioned to engage a lower extension 152 of the counterweight body 98. More
6 particularly, the extension 152 has a ramped surface 154 with transverse corrugations or
7 steps (best shown in FIG. 3) which create an impact insertion of the blade 24 into
8 material that is being cut by the saw 10. As the counterweight wobble plate assembly 44
9 operates during rotation of the drive shaft 46, the interface structure 144 will move so that
10 the ball 150 will ride up and down the ramp surface 154 and cause the counterweight and
11 therefore the right end of the plunger 28 to move up and down and cause an orbiting
12 movement of the blade 24.

13 The interface structure 144 drives a generally U-shaped drive arm 156 that
14 has a pair of spherical side extensions 158 that are retained in cylindrical bushings 160
15 that are fixed by suitable structure to the inside of the housing 12 as is known to those of
16 ordinary skill in the art. Thus, there are pivot points on opposite sides of the U-shaped
17 drive arm 156 and the spherical drive ball 148 fits within a cylindrical recess 162 in the
18 bottom of the drive arm 156. The upper ends of the U-shaped drive arm have truncated
19 spherical balls 164 which fit within openings 166 which are provided in a lower side
20 extension 168 on each side of the counterweight body 98. The balls 164 are

1 approximately the size of the openings 166 and they similarly have generally point to
2 point contact between the ball and the opening during operation.

3 Each of the arms also preferably include an enlarged spherical portion 170
4 which is larger than the opening 166 and which balance the counterweight body 98 so
5 that neither of the balls 164 penetrate too deeply into the opening 166 in the lower
6 extension 168 which could interfere with the point to point contact between the drive arm
7 ends and the cylindrical surface of the openings 166. It should also be understood that
8 during the vertical movement of the counterweight body 98 caused by the ratcheting
9 action of the ball 150 contacting the ramp surface 154 of the counterweight body 98, the
10 balls 164 of the drive arm 156 will increase and decrease their penetration into the
11 openings 166. However, the amount of movement is controlled by the design and
12 configuration of these cooperating components so that there is no possibility that the balls
13 164 can separate from the openings 166.

14 The orbital action can be selectively turned on and off by use of a lever 171
15 that is connected to a rod 172 that has a notch 174 in it that extends the length of the
16 support bracket 134 as is best shown in FIG. 4. The lever 171 is shown in a generally
17 horizontal position with the notch being oriented so that it is open upwardly which
18 permits the rear support bracket 134 to be pushed downwardly against the bottom of the
19 notch 174. The rod 172 is pivotally supported in suitable structure of the housing 12 with

1 the lever 171 extending outwardly through the wall of the housing 12 so that it is
2 available to an operator for the purpose of turning the orbital action on and off.

3 If the lever 171 is rotated 90° in either direction, the rear support bracket
4 134 will be elevated to the elevation of the rod 172 that would exist were the notch 174
5 not present and in this position, the action of the spherical ball 150 against the inclined
6 surface 154 will have no orbital effect because the ball will not be in any appreciable
7 contact with the ramp surface to cause upward movement of the counterweight body 98
8 during operation of the saw 10.

9 The embodiment shown in FIGS. 1-6 has an advantage of providing an
10 orbital movement of the blade with a ratcheting action which can provide improved
11 cutting performance. The design of the mechanism also reduces vibration and friction.
12 The reduced friction is a result of the self-alignment system that has the front spherical
13 bushing 112 providing a freedom of movement by permitting rotation of the plunger 28
14 as well as pivoting movement in both the vertical and horizontal directions which enables
15 the plunger to be aligned in a manner that reduces friction.

16 Also, the reduction in vibration is a result of the counterweight mass having
17 a center of gravity that is very close to the axis of the plunger. The rear portion of the
18 plunger 28 is supported by the spherical portion 94 of the receiver member 78 which is
19 free to slide inside the counterweight. The effective orbit arm comprises the spherical
20 cover plate 110, the front and rear support brackets 120 and 134 as well as the rods 128

1 and counterweight body 98. The orbit arm is maintained in a forward position by the
2 roller 138 and is biased in the downward position by the spring 136.

3 A second preferred embodiment of the present invention is shown in FIGS.
4 7 and 8 and will not be described in detail except insofar as it has modified or additional
5 features and structure compared to the embodiment of FIGS. 1-6. Therefore, where
6 components have reference numbers that are the same as has been shown and described
7 in the first preferred embodiment of FIGS. 1-6, the structure and function will be
8 substantially similar to the previously described first preferred embodiment. To the
9 extent that components are modified relative to the components shown in FIGS. 1-6, they
10 will carry a prime or double prime designation to indicate they are modified and where
11 necessary or appropriate, the description of the modified component will be provided.
12 New and different aspects of the alternative embodiments will carry reference numbers
13 beginning with the number 200.

14 Turning now to FIG. 7, the drive shaft 46' is modified so that it has a
15 smooth cam shaped portion 200 that is off-centered relative to the axis of the drive shaft
16 46'. Also, the rear support bracket 134' has a downward extension 202 which has a
17 generally V-shaped configuration as shown in FIG. 8, and which has a lower end 204 that
18 contacts the cam surface 200 of the drive shaft 46'. In this configuration, the interface
19 structure 144' does not have a spherical ball at its upper portion (like ball 150 in FIG. 3)
20 and the lower extension 152' does not have a ramped surface. The orbital action is

1 therefore a result of the lower extension 202 acting as a cam follower for providing the
2 orbital action of the blade 24. It should be appreciated that the cam follower follows the
3 smooth cam surface 200 and therefore this embodiment does not produce a ratcheting
4 orbital action as was the case with regard to the embodiment shown in FIGS. 1-6. The
5 lever 171 is operable to selectively turn the orbital action on and off in this embodiment.

6 In the third preferred embodiment shown in FIGS. 9 and 10, a less
7 expensive to manufacture counterweight wobble plate assembly 44" is provided which
8 dispenses with internal ball bearings and has a simplified interface structure 144" that has
9 an external circumferential groove 210 that cooperates with a ball 212 provided on the
10 drive arm 156" for driving the counterweight 32. It should be understood that the
11 interface structure 144" can be formed with the drive shaft 46" or it could also be
12 provided with a ball bearing construction so that it could rotate relative to the enlarged
13 portion 58" of the drive shaft 46". This embodiment also does not have orbital action
14 capability and therefore the lever 171 is not present.

15 While various embodiments of the present invention have been shown and
16 described, it should be understood that other modifications, substitutions and alternatives
17 are apparent to one of ordinary skill in the art. Such modifications, substitutions and
18 alternatives can be made without departing from the spirit and scope of the invention,
19 which should be determined from the appended claims.

20 Various features of the invention are set forth in the following claims.

WHAT IS CLAIMED IS:

- 1 1. A reciprocating saw, comprising;
2 a housing;
3 a drive shaft rotatably mounted in said housing;
4 a motor in the housing for driving said drive shaft;
5 an elongated plunger located in said housing for reciprocating motion, said
6 plunger being driven by a wobble plate interface structure and pivotally supported in a
7 front bushing and in a manner permitting said plunger to rotate about an axis of rotation
8 aligned with the longitudinal axis of said plunger, said plunger having a front end portion
9 for attaching a tool, and an enlarged rear end spherical portion;
10 a counterweight assembly including a movable counterweight and a drive arm for
11 moving said counterweight located in said housing, said counterweight having an
12 opening for receiving said plunger, wherein said opening has at least cylindrical side wall
13 portions that are sized and configured to support said rear end spherical portion of said
14 plunger as said plunger and counterweight move relative to one another;
15 a first wobble plate assembly operatively connected to said drive shaft and having
16 a first wobble plate interface structure for engaging and reciprocating said plunger in said
17 front bushing and said counterweight; and

1 a second wobble plate assembly operatively connected to said drive shaft and
2 having a second wobble plate interface structure for engaging said drive arm of said
3 counterweight assembly.

4 2. A reciprocating saw as defined in claim 1 wherein said first and second
5 wobble plate assemblies are configured so that their respective interface structures move
6 in opposite directions during operation.

7 3. A reciprocating saw as defined in claim 1 wherein said counterweight
8 assembly comprises a pair of spaced apart parallel rods mounted in front and rear rod
9 support brackets, said counterweight having extensions on opposite sides thereof with
10 apertures in which said rods are located, said counterweight being slidable on said rods
11 during operation.

12 4. A reciprocating saw as defined in claim 3 wherein said drive arm has a
13 generally U-shaped configuration wherein the bottom portion of the arm extends around
14 said drive shaft and the upper end portions engage said side extensions of said
15 counterweight, the arm being pivotable about pivot connections that are generally
16 midway between the top and bottom of said U-shaped arm and on an axis that extends
17 generally through said drive shaft.

18 5. A reciprocating saw as defined in claim 4 wherein said front and rear
19 brackets and rods of said counterweight assembly are configured to be vertically
20 pivotable around said front bushing and rotatable and slidable about said plunger.

1 6. A reciprocating saw as defined in claim 1 wherein said counterweight has
2 an inclined ramp portion extending downwardly toward said second wobble interface
3 structure, and said second wobble interface structure further comprises an upper
4 extension with a generally spherical end portion for engaging said ramp portion, said
5 second wobble plate assembly driving said arm and said counterweight in a reciprocating
6 manner during operation, and said spherical end portion of said upper extension engaging
7 said ramp portion and causing said rear end portion of said plunger to pivot around said
8 front bushing.

9 7. A reciprocating saw as defined in claim 6 wherein said ramp portion has a
10 transverse corrugated surface for imparting impact forces on a tool attached to said saw.

11 8. A reciprocating saw as defined in claim 4 wherein each of said side
12 extensions have a recess with a cylindrical portion having a predetermined diameter for
13 receiving one of the upper end portions of said arm, said end portions having a generally
14 spherical shape and a diameter slightly smaller than said predetermined diameter so that
15 said end portions make generally point contact with said cylindrical portion of said
16 recesses.

17 9. A reciprocating drive apparatus, comprising;
18 a housing;
19 a drive shaft rotatably mounted in said housing;

1 an elongated plunger located in said housing for reciprocating motion, said
2 plunger being supported in a spherical front bushing that permits rotational and pivotal
3 movement during reciprocating motion, said plunger having a front end portion for
4 attaching a tool, and an enlarged rear end spherical portion;

5 a counterweight assembly including a movable counterweight and a drive arm for
6 moving said counterweight located in said housing, said counterweight having an
7 opening for receiving said plunger, wherein said opening is sized and configured to
8 support said rear end spherical portion of said plunger as said plunger and counterweight
9 move relative to one another;

10 a first wobble plate assembly operatively connected to said drive shaft and having
11 a first wobble plate interface structure for engaging and reciprocating said plunger in said
12 front bushing and said counterweight; and

13 a second wobble plate assembly operatively connected to said drive shaft and
14 having a second wobble plate interface structure for engaging said drive arm of said
15 counterweight assembly;

16 said first and second wobble plate assemblies being configured so that their
17 respective interface structures move in opposite directions during operation.

18 10. A drive apparatus for a reciprocating tool that has a housing, a motor with
19 an output shaft in the housing, said apparatus comprising;

20 a rotatable drive shaft operatively connected to the motor output shaft;

1 an elongated reciprocating plunger having a forward portion supported in said
2 housing in a spherical bushing that permits rotational and pivotal movement and an
3 enlarged rear end spherical portion supported in a bore of a reciprocating counterweight,
4 said counterweight being supported in the housing in a manner to permit said rotational
5 and pivotal movement of said plunger;

6 first and second wobble plate assemblies operatively connected to said drive shaft
7 configured to respectively drive said plunger and counterweight in opposite directions
8 during operation.

9 11. A reciprocating drive apparatus comprising;

10 a housing;

11 a drive shaft rotatably mounted in said housing;

12 an elongated plunger located in said housing for reciprocating motion, said
13 plunger having a rear end portion configured to engage a wobble plate interface structure
14 and a front end portion for attaching a tool, said plunger having a spherical portion
15 adjacent the rear end thereof;

16 a front bushing positioned in said housing for retaining said front end portion in a
17 manner whereby said plunger is not restrained from rotating about a first axis of rotation;

18 a counterweight assembly positioned in said housing for receiving said rear end
19 portion of said elongated plunger and including a movable counterweight and a drive arm
20 for moving said counterweight, said counterweight having at least cylindrical side wall

1 portions that are sized and configured to support said spherical portion of said plunger as
2 said plunger and counterweight move relative to one another;

3 a first wobble plate assembly operatively connected to said drive shaft and having
4 an elongated arm with a first wobble plate interface structure for engaging said rear end
5 portion of said plunger and reciprocating said plunger in said front bushing and said
6 counterweight; and

7 a second wobble plate assembly operatively connected to said drive shaft and
8 having a second wobble plate interface structure for engaging said drive arm of said
9 counterweight assembly.

10 12. Apparatus as defined in claim 11 wherein said counterweight assembly
11 comprises a pair of spaced apart parallel rods mounted in front and rear rod support
12 brackets, said counterweight having extensions on opposite sides thereof with apertures
13 in which said rods are located, said counterweight being slidable on said rods during
14 operation.

15 13. Apparatus as defined in claim 12 wherein said drive arm has a generally U-
16 shaped configuration wherein the bottom portion of the arm extends around said drive
17 shaft and the upper end portions engage said side extensions of said counterweight, the
18 arm being pivotable about pivot connections that are generally midway between the top
19 and bottom of said U-shaped arm and on an axis that extends generally through said drive
20 shaft.

1 14. Apparatus as defined in claim 13 wherein said pivot connections connect
2 said drive arm to said second wobble plate assembly about its effective pivot axis, said
3 second wobble plate interface engaging the bottom of said U-shaped arm.

4 15. Apparatus as defined in claim 14 wherein each of said pivot connections
5 comprise a generally cylindrical receiving structure on one of said arm and second
6 wobble plate assembly in which a generally spherical extension from the other of said
7 arm and second wobble plate assembly is inserted.

8 16. Apparatus as defined in claim 12 wherein said front and rear brackets and
9 rods of said counterweight assembly are configured to be vertically pivotable around said
10 front bushing and rotatable and slidable about said plunger.

11 17. Apparatus as defined in claim 16 further comprising a member mounted in
12 said housing and bearing on said rear support bracket to limit movement of said rods,
13 front and rear brackets away from said front bushing.

14 18. Apparatus as defined in claim 17 wherein said member comprises a
15 resilient roller mounted for rotation on a generally horizontal shaft attached to said
16 housing.

17 19. Apparatus as defined in claim 16 further comprising a spring positioned in
18 said housing for applying a downward force on said rear bracket

19 20. Apparatus as defined in claim 13 wherein each of said side extensions have
20 a recess with a cylindrical portion having a predetermined diameter for receiving one of

1 the upper end portions of said arm, said end portions having a generally spherical shape
2 and a diameter slightly smaller than said predetermined diameter so that said end portions
3 make generally point contact with said cylindrical portion of said recesses.

4 21. Apparatus as defined in claim 20 wherein said arms have larger spherical
5 portions adjacent end portions, said larger spherical portions engaging said side
6 extensions to substantially prevent rotation of said counterweight assembly about said
7 plunger

8 22. Apparatus as defined in claim 12 wherein said second wobble interface
9 structure comprises a lower extension with a generally spherical end portion for engaging
10 a generally cylindrical portion of a recess in the bottom of said U-shaped arm, said
11 second wobble plate assembly driving said arm and said counterweight in a reciprocating
12 manner during operation.

13 23. Apparatus as defined in claim 12 wherein said counterweight has an
14 inclined ramp portion extending downwardly toward said second wobble interface
15 structure, and said second wobble interface structure further comprises an upper
16 extension with a generally spherical end portion for engaging said ramp portion, said
17 second wobble plate assembly driving said arm and said counterweight in a reciprocating
18 manner during operation, and said spherical end portion of said upper extension engaging
19 said ramp portion and causing said rear end portion of said plunger to pivot around said
20 front bushing.

1 24. Apparatus as defined in claim 23 further comprising a lever for selectively
2 raising said rear end portion of said plunger to disengaging said spherical end portion
3 from said ramp portion.

4 25. Apparatus as defined in claim 11 wherein said first and second wobble
5 plate assemblies are configured so that their respective interface structures move in
6 opposite directions during operation.

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Claims searched: 1 to 25

Date of search: 28 April 2008

**Patents Act 1977
Corrected Search Report under Section 17**

Documents considered to be relevant:

Category	Relevant to claims	Identity of document and passage or figure of particular relevance
A	-	EP1593448 A1 (BLACK & DECKER) See especially counterweight 27.
A	-	EP1156902 A1 (MILWAUKEE) See especially counterweight 26.

Categories:

X Document indicating lack of novelty or inventive step	A Document indicating technological background and/or state of the art.
Y Document indicating lack of inventive step if combined with one or more other documents of same category.	P Document published on or after the declared priority date but before the filing date of this invention.
& Member of the same patent family	E Patent document published on or after, but with priority date earlier than, the filing date of this application.

Field of Search:

Search of GB, EP, WO & US patent documents classified in the following areas of the UKC^X:

Worldwide search of patent documents classified in the following areas of the IPC

B23B; B24B; B25D; B27B

The following online and other databases have been used in the preparation of this search report

Online: WPI, EPODOC

International Classification:

Subclass	Subgroup	Valid From
B23D	0051/16	01/01/2006