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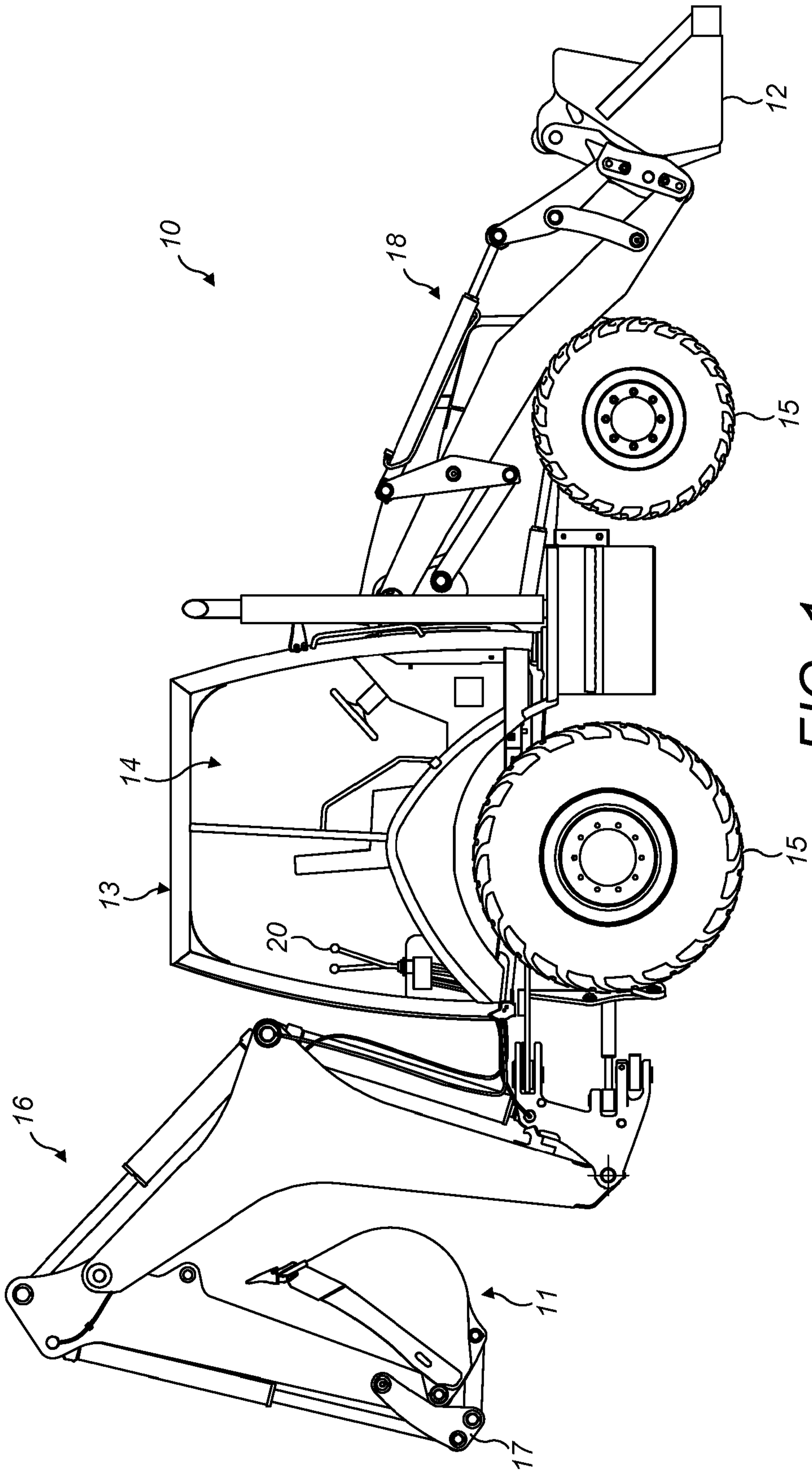


FIG. 1

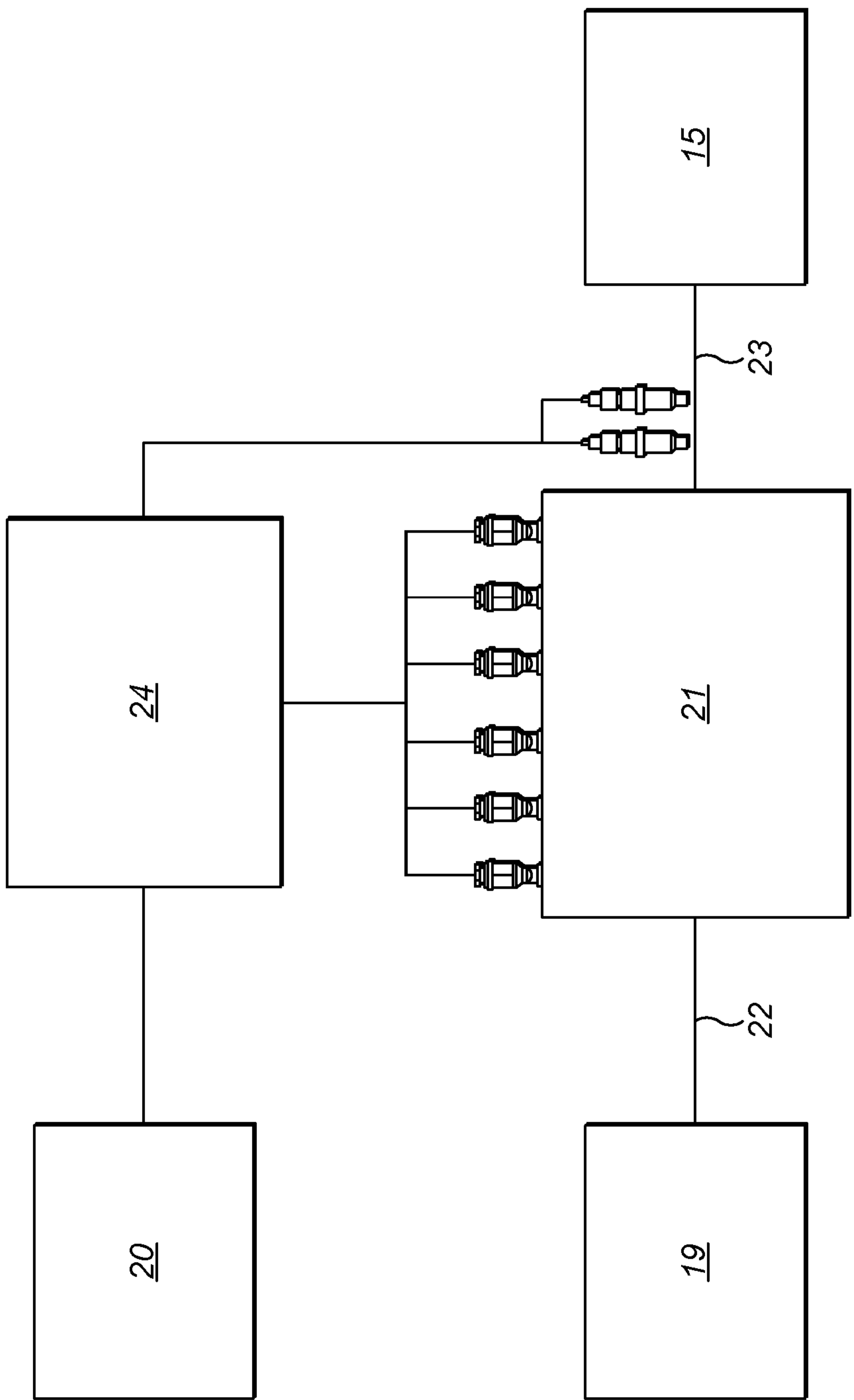
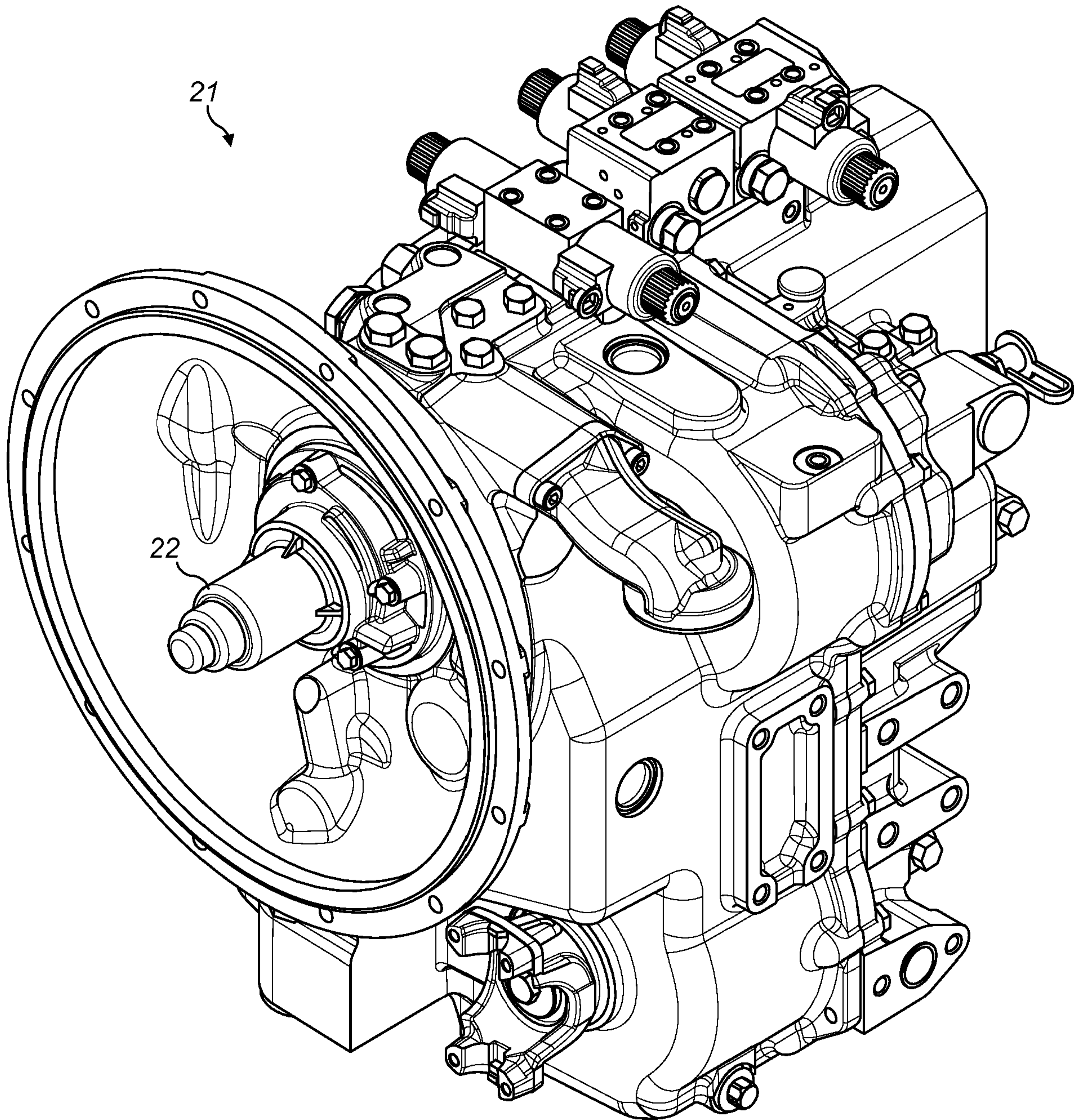
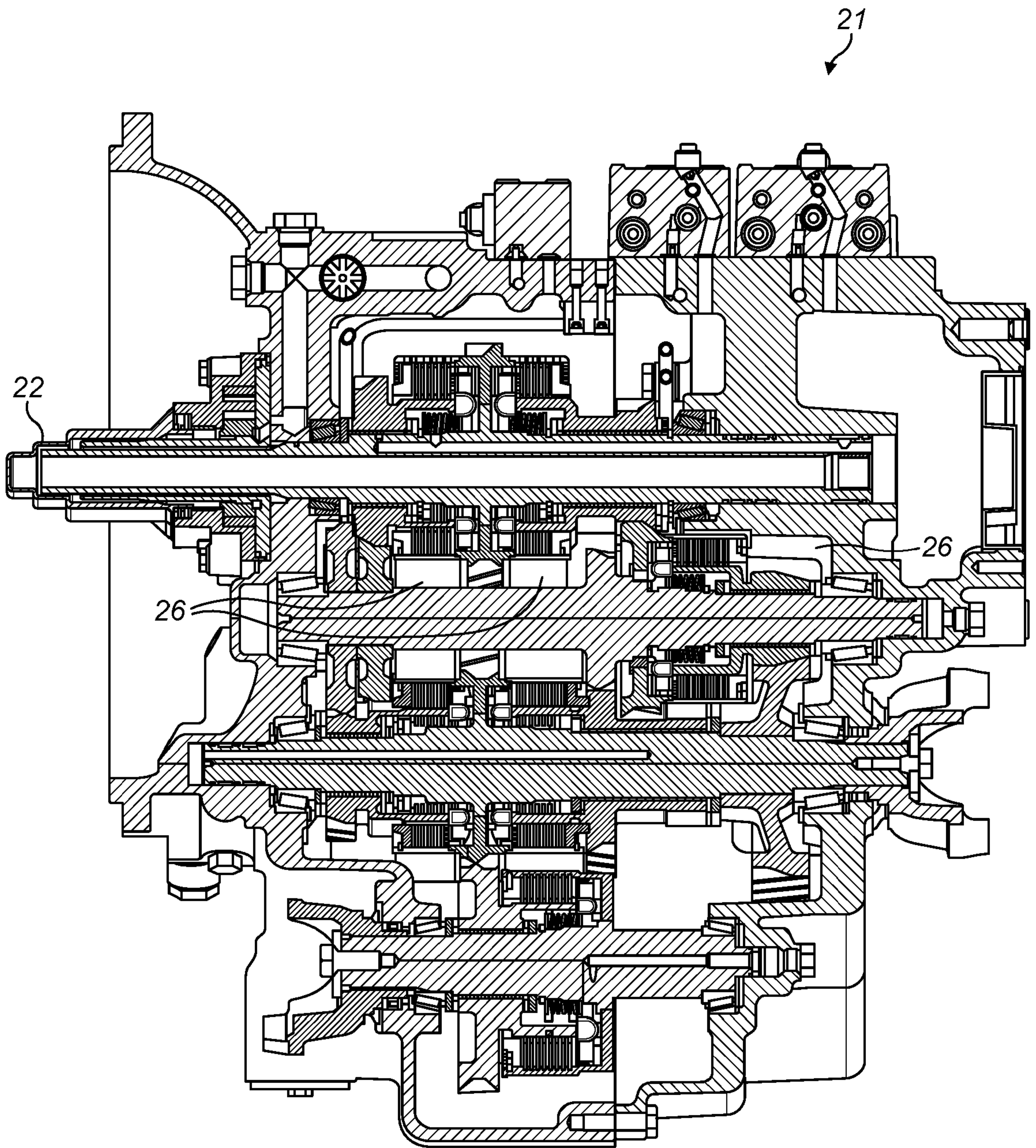


FIG. 2

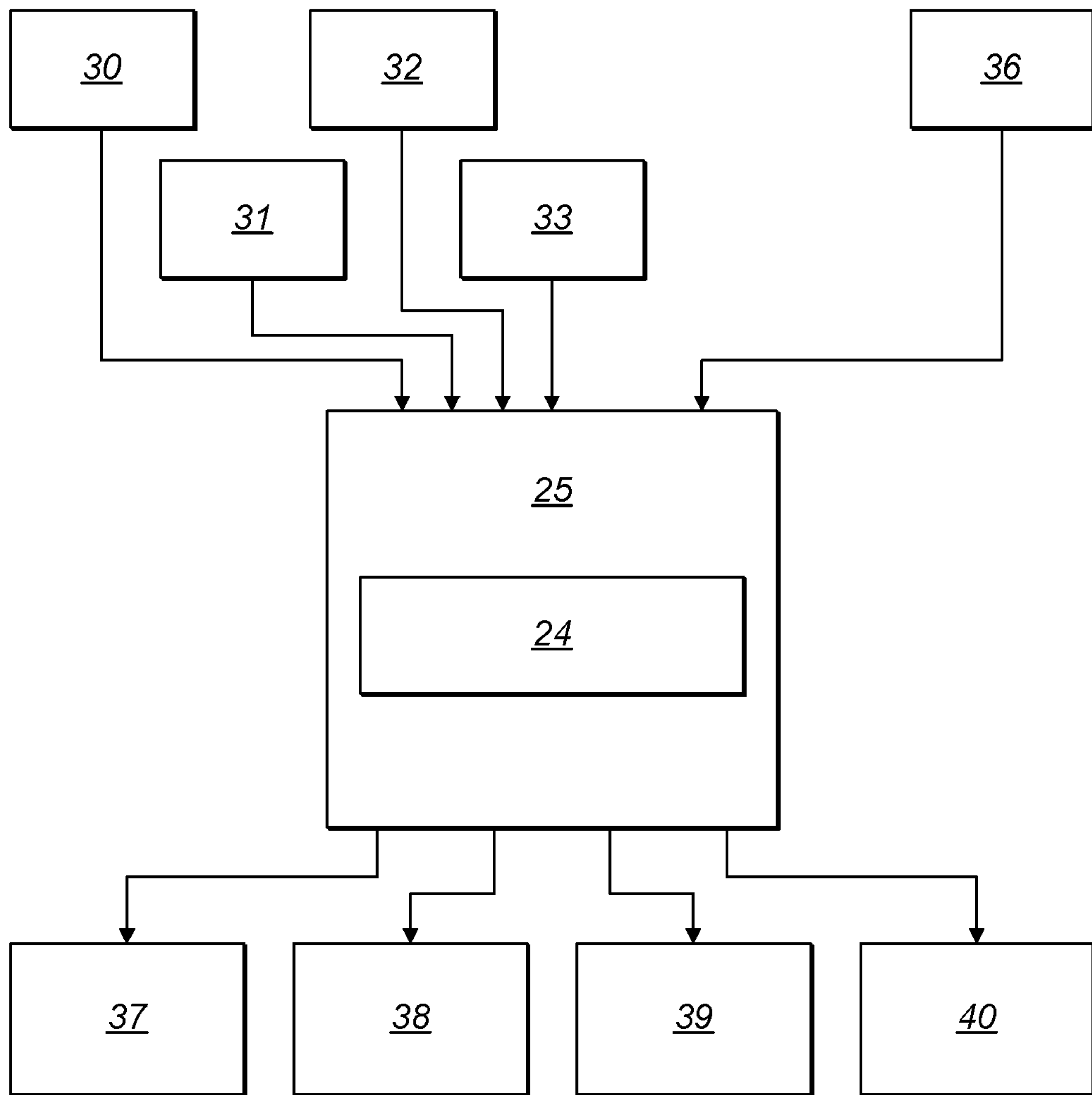


**FIG. 3**





**FIG. 4**



**FIG. 5**

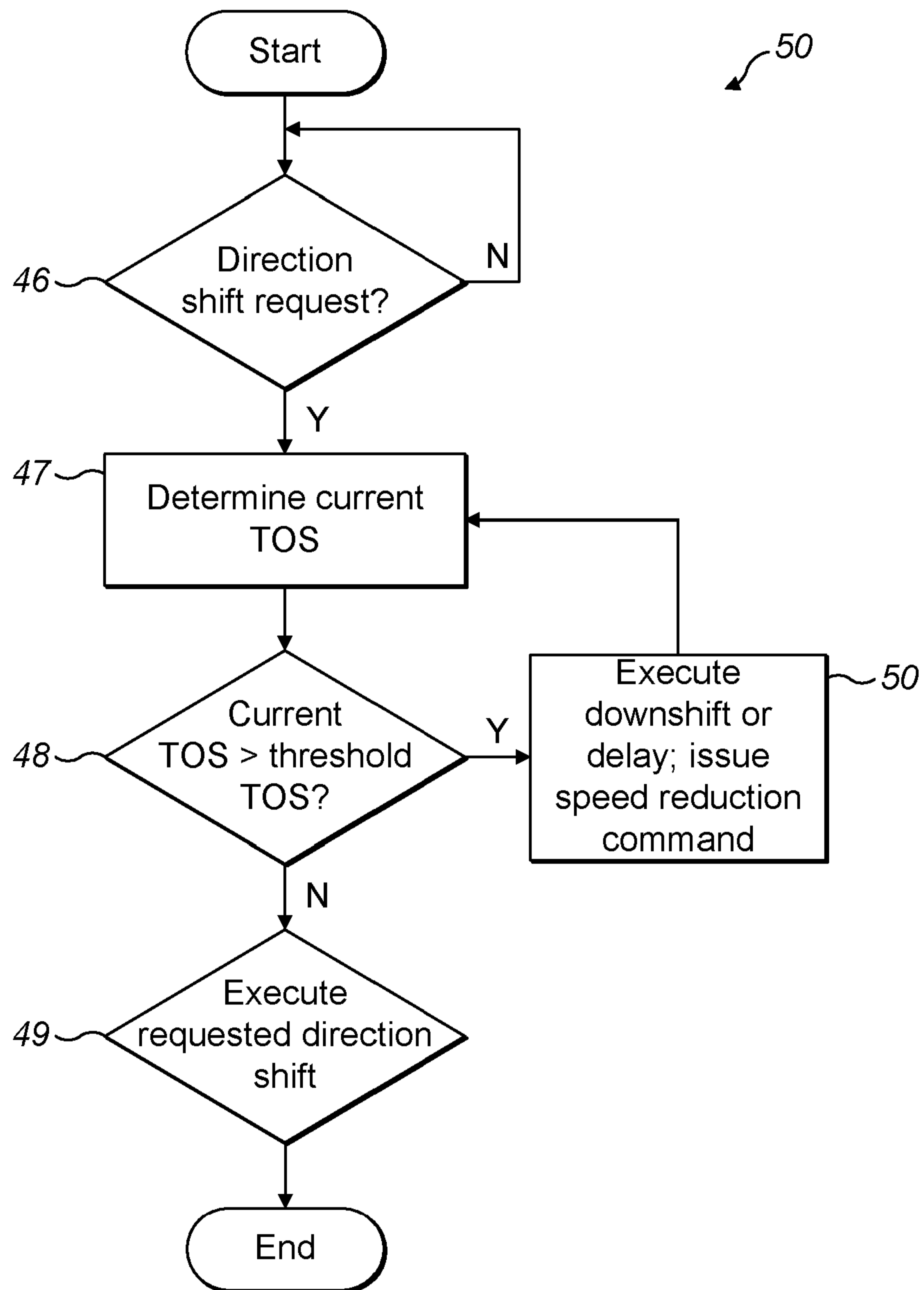


FIG. 6

Initial gear when direction shift is requested	Transmission output speed when direction shift is requested	Shift control logic shift
Forward to reverse		
3F	≤1000 (Threshold to allow the direction shift)	3F-3R
3F	1010 (greater than 1000) Once TOS ≤1000	3F-2F 2F-2R
2F	≤1000	2F-2R
2F	1010 Once TOS ≤1000	2F 2F-2R
4F	≤1000	4F-3R
4F	1010 Once TOS ≤1000	4F-3R-2F 2F-2R
Reverse to forward		
3R	≤1000 (Threshold to allow the direction shift)	3R-3F
3R	1010 Once TOS ≤1000	3R-2R 2R-2F
2R	≤1000	2R-2F
2R	1010 Once TOS ≤1000	2R 2R-2F

**FIG. 7**



## DIRECTIONAL SHIFT CONTROL IN VEHICLES

### Technical Field

The present disclosure relates to a method of controlling gear selection in a transmission of a vehicle in response to a directional shift requested by an operator and to a control system for controlling gear selection to manage directional shifts in vehicles.

### Background

Many vehicles, such as work machines, mining equipment and other work vehicles may include a powershift transmission coupled to a power source, such as an internal combustion engine or an electric motor, in order to provide more flexible use of the power output of the power source. The transmission for such a vehicle typically comprises a plurality of speed and direction changing clutches, and a plurality of transmission gears, wherein combinations of pairs of direction and speed changing clutches effectively recruit transmission gears to provide a plurality of transmission gear ratios. The transmission may provide not only a number of gears having gear ratios that enable the work machine to travel at a relatively wide range of speeds or conditions that might be impractical without a transmission, but also for a change of vehicle direction between forward and reverse. Some transmissions are configured to change gears automatically in order to improve ease of operation of the vehicle through its speed range.

The direction of vehicle travel may be selectable by an operator via a suitable control device, such as a joystick. Operator selected direction shifts, to change the direction of travel while the vehicle is moving, are common especially with vehicles such as backhoe loaders and forklifts. Operators may decelerate during a change of direction by selecting the drive direction opposite to that of travel. Although some direction changing shifts may be acceptable, certain shifts, for example high speed direction changing shifts from high speed transmission gears in one direction to low speed transmission gears in a reverse direction, may be undesirable as they may cause damage to one or both of the proposed incoming speed and direction changing clutches when engaged.

During a transmission shift, energy is transmitted to the clutch plates and the amount of energy is proportional to the speed differential of the clutch plates. In a high speed direction shift, the clutch plates are rotating in opposite directions with a high speed differential before engagement. Therefore, in the time it takes for the clutch to fully lock up, a large amount of energy may be transmitted to the clutch plates, being converted from kinetic

energy to heat energy due to friction. The increased energy requirement may cause increases in the heat generated at the transmission clutches during the velocity change, and can result in premature clutch failure when the clutch temperature repeatedly exceeds the material durability limits of the clutch components. Similar issues can arise when the vehicle accelerates and clutches cause the vehicle to upshift and when the vehicle decelerates and clutches maintain the current gear or downshift for engine braking. In some powershift transmissions, the incoming direction changing clutch is often most prone to damage during high speed direction changing shifts as much of the energy of the vehicle is effectively absorbed by the direction changing clutch during such a shift.

10

One option to mitigate this behaviour is to raise a warning, but this may still allow the potential damage to occur. Another option is to inhibit a direction shift. Inhibiting a shift includes holding the original gear but limiting engine speed to slow the machine or selecting neutral to slow the vehicle. Inhibiting a shift may be problematic as the vehicle's behaviour may not be as the operator expects. Where the operator expects a rapid deceleration, if only a moderate or no deceleration is realised, this may lead to degradation of control or the need to employ inconvenient stopping mechanisms, such as dropping work tools or employing the parking brake.

15

Thus, there is a need for a control strategy to slow the vehicle down to a speed where a transmission direction shift is appropriate and hence prevent the transmission damage whilst maintaining vehicle control.

20

US9689490B2 describes a method for velocity change gear selection and shift execution for a motor grader, including a method for controlling directional shift gear selection. When the rotational speed of the transmission output shaft is greater than a predetermined limit, the transmission is prevented from shifting directly to a reverse gear. Instead, the transmission initially downshifts to a lower forward gear (e.g. from 4F to 3F) and a retarding force is applied to slow the work machine until the rotational speed of the transmission output shaft is less than the predetermined maximum velocity limit. When the speed is less than the predetermined limit, the directional shift is completed by shifting the transmission to a lower reverse gear (e.g. from 3F to 1R). This is a combinational direction shift, i.e. there is a direction and gear number change. In some cases the direction shift is prohibited until the operator slows the machine to below the predetermined speed.

30

35



However this control strategy may not be suitable for all types of machines and all types of transmission systems.

### Summary

5 The present disclosure therefore provides a method of controlling gear selection in a transmission of a vehicle, said vehicle having a power unit and an automatic transmission, said transmission having a plurality of first direction gears configured to move the vehicle in a first direction and a plurality of second direction gears configured to move the vehicle in a second direction which is opposite to the first direction, the method comprising the steps of:

10 determining a direction shift request by a vehicle operator to move the vehicle from the first to the second direction when the transmission is in an initial first direction gear;

determining a current transmission output speed;

comparing the current transmission output speed with a predetermined direction shift threshold transmission output speed; and

15 if the current transmission output speed is less than or equal to the predetermined direction shift threshold transmission output speed, causing the transmission to execute a direction shift from the initial first direction gear to the same second direction gear, or a next highest second direction gear if there is no second direction gear which corresponds to the initial first direction gear, and

20 if the current transmission output speed is greater than the predetermined direction shift threshold transmission output speed, the transmission is caused to execute one or more downshifts from the initial first direction gear to a secondary first direction gear which is the lowest gear which has a predetermined downshift inhibit threshold which is greater than the current transmission output speed, each

25 downshift being to the next highest first direction gear sequentially, and

when the current transmission output speed slows to less than or equal to the predetermined direction shift threshold transmission output speed, and if the direction shift request is still active, the transmission is caused to execute a

30 direction shift from the secondary first direction gear to the same second direction gear, or a next highest second direction gear if there is no second direction gear which corresponds to the secondary first direction gear.

The present disclosure further provides a control system for controlling gear selection in a transmission of a vehicle, said vehicle having a power unit and an indirect drive automatic

transmission, said transmission having a plurality of first direction gears configured to move the vehicle in a first direction and a plurality of second direction gears configured to move the vehicle in a second direction which is opposite to the first direction, said control system configured to;

5 evaluate direction control signals to determine when a direction shift request is made by a vehicle operator to move the vehicle from the first to the second direction when the transmission is in an initial first direction gear;

determine a current transmission output speed;

10 compare the current transmission output speed with a predetermined direction shift threshold transmission output speed; and

15 if the current transmission output speed is less than or equal to the predetermined direction shift threshold transmission output speed, generate a transmission direction shift signal to cause the transmission to execute a direction shift from the initial first direction gear to the same second direction gear, or a next highest second direction gear if there is no second direction gear which corresponds to the initial first direction gear, and

20 if the current transmission output speed is greater than the predetermined direction shift threshold transmission output speed, the control system is further configured to generate a downshift signal to cause the transmission to execute one or more downshifts from the initial first direction gear to a secondary first direction gear which is the lowest gear which has a predetermined downshift inhibit threshold which is greater than the current transmission output speed, each downshift being to the next highest first direction gear sequentially, and

25 when the current transmission output speed slows to less than or equal to the predetermined direction shift threshold transmission output speed, and if the direction shift request is still active, to generate a direction shift signal which causes the transmission to execute a direction shift from the secondary first direction gear to the same second direction gear, or a next highest second direction gear if there is no second direction gear which corresponds to the secondary first direction gear.

30

The present disclosure further provides a vehicle comprising:

a power unit;

an indirect drive automatic transmission, said transmission having a plurality of first direction gears configured to move the vehicle in a first direction and a plurality of second



direction gears configured to move the vehicle in a second direction which is opposite to the first direction;

an operator actuated input direction control configured to generate direction control signals;

5 at least one transmission output speed sensor configured to measure current speed of the transmission output and generate a transmission output speed signal; and

the above-mentioned control system as operatively connected to the power unit, transmission, input direction control, at least one transmission output speed sensor.

## 10 **Brief Description of the Drawings**

Aspects of the present disclosure are described below, by way of example only, with reference to the following drawings, in which:

15 Figure 1 is a side elevation of a backhoe loader, being a vehicle suitable for implementing the method and control system of the present disclosure;

Figure 2 is a schematic diagram of a power train comprising a transmission control system for implementing the method of the present disclosure;

Figure 3 is pictorial representation of a transmission system for the vehicle of Figure 1;

20 Figure 4 is a cross section representation of the transmission system of Figure 3;

Figure 5 is a schematic diagram of a machine control system comprising the transmission control system of Figure 2 and associated control components;

Figure 6 is a flow diagram illustrating a gear selection routine according to the method of the present disclosure; and

5 Figure 7 is a table of data for an exemplary directional shifting control logic implemented by the transmission control system of Figure 2.

### Detailed Description

Figure 1 illustrates an example of a vehicle 10, in this case a backhoe loader, which is  
10 suitable to implement the method and control system of the present disclosure. The vehicle 10 may, however, be another type of vehicle or work machine. The vehicle 10 may comprise a main unit 13 having an operator cabin 14 for an operator and a power unit 19 (not shown in Figure 1), such as an internal combustion engine, for providing power to ground engaging means 15, such as tracks or wheels. The vehicle 10 may comprise a first  
15 implement 11, in this example a bucket, and a first arm arrangement 16 (a backhoe) to which the first implement 11 may be connected via a known coupling arrangement 17. The vehicle 10 may also comprise a second implement 12, in this example also a bucket, attached to the main unit 13 via a second arm arrangement 18. The first and second arm arrangements 16, 18 and the first and second implements 11, 12 may be manoeuvred by  
20 means of a suitable hydraulic system as is known in the art. Vehicles 10 suitable for implementing the method of the present disclosure may have any alternate configurations comprising some or no arms, implements and/or attachments depending on the intended use and function of the vehicle 10.

25 The ground engaging means 15 may be powered by an automatic transmission 21 (see Figures 2 to 4) operatively connected between the power unit 19 and the ground engaging means 15. A rotating power unit output shaft (not shown) may extend from the power unit 19 and may be connected to a transmission input shaft 22 directly, by a torque converter, or by another indirect drive connection as is known in the art. Alternatively, the  
30 transmission 21 may be a direct drive system, which may require the system to be calibrated differently than for an indirect drive system. A transmission output shaft 23 may be connected to the ground engaging means 15 by way of a final drive or the like (not shown). The transmission 21 may be a constant mesh transmission as illustrated, or another type of transmission. As is known in the art, the transmission 21 may comprise a  
35 series of gears that are selectively engaged by a combination of clutches 26 and brakes. The clutches 26 may comprise a plurality of speed changing clutches and direction



changing clutches. Although not described in detail, combinations of direction and speed changing clutches effectively provide a plurality of transmission gears which control the transmission of power between the power unit 19 and the ground engaging means 15. The transmission gears may be provided to move the vehicle 10 in a first (usually) forward direction and a second (usually reverse) direction. The transmission 21 may therefore have a plurality of first direction transmission gears, which may be forward transmission gears (for example 1F, 2F, 3F, 4F), and second direction transmission gears, which may be reverse transmission gears (for example 1R, 2R, 3R). A suitable shift control 20, such as a joystick or switch arrangement, may be provided in the operator cabin 14 to enable the operator to select a desired direction of travel of the vehicle 10, i.e. forward, neutral or reverse, and thereby acts as an input direction control 31. The shift control 20 may also enable the operator to request a gear upshift or downshift, thereby acting as an input gear control 32. The latter function may, however, be provided by a separate device, such a switch. A suitable input speed control 30, such as a gas pedal or accelerator, may also be provided in the operator cabin 14 to enable the operator to regulate the speed of the vehicle 10.

The transmission 21 may be electronically coupled to a transmission control system 24, which may electronically control operation of the transmission 21 at least by controlling the engagement and disengagement of the clutches 26. The clutches 26 may be hydraulically actuated clutches 26, which are disposed in a hydraulic circuit and are each operable to engage in a known manner in response to an actuating flow of pressurised hydraulic fluid thereto. The transmission control system 24 may comprise an on/off clutch control system which, during each gear shift, controls the requisite speed and direction clutches 26. The clutches 26 may be controlled by means of a solenoid valve arrangement comprising a solenoid corresponding to each clutch 26. Actuation of a solenoid, for example on receipt of a suitable control signal thereto, may cause the solenoid to direct an actuating flow of pressurised hydraulic fluid to its respective clutch 26.

In the event of either a requested upshift or downshift in the forward/reverse direction, the on/off control mechanism effects the engagement of the oncoming speed clutch 26, by switching the associated solenoid on, and disengagement of the corresponding off going speed clutch 26, by switching the associated solenoid off. Where a direction shift is selected, the corresponding speed and direction clutch 26 is engaged and disengaged in a similar manner. Such on/off control mechanisms are known in the art. Alternatively, the

transmission system may have other types of clutch control, such as electronic clutch pressure control.

5 Although the physical configuration of the transmission control system 24 is not illustrated, it may comprise a plurality of conventional electronic components, analogue-to-digital converters, input-output devices, solenoid drivers, electronic circuitry, and one or more processors. It is to be understood that the one or more processors may comprise one or more microprocessors, controllers, or any other suitable computing devices, resource, hardware, software, or embedded logic. The transmission control system 24 may comprise  
10 memory in the processors, main memory, and/or hard disk drives, which carry a set of non-transient machine readable instructions or software/code which when executed by the one or more processors, causes the transmission control system 24, to operate the gear selection routine 45 in a manner as described herein.

15 The transmission control system 24 may comprise a plurality of components or modules which correspond to the functional tasks to be performed thereby. In this regard, "module" in the specification will be understood to include an identifiable portion of code, computational or executable instructions, data, or computational object to achieve a particular function, operation, processing, or procedure. It follows that a module need not  
20 be implemented in software; a module may be implemented in software, optionally hardware, or a combination of software and hardware. Further, the modules need not necessarily be consolidated into one system, but may be spread across a plurality of other devices and systems to provide the functionality described herein. In one example embodiment, the one or more processors, executing the aforementioned machine readable  
25 instructions or software/code, may effectively provide the modules, or the functionality thereof, as described herein.

As an alternative, the transmission control system 24 may be an analog or electromechanical device.

30

The transmission control system 24 may be part of the main machine control system 25 (as shown in Figure 5) which controls other functions of the vehicle 10. The machine control system 25 may be of any suitable known type and may comprise an engine control unit (ECU) or the like. The machine control system may comprise a memory, which may store  
35 instructions or algorithms in the form of data, and a processing unit, which may be configured to perform operations based upon the instructions. The memory may comprise



any suitable computer-accessible or non-transitory storage medium for storing computer program instructions, such as RAM, SDRAM, DDR SDRAM, RDRAM, SRAM, ROM, magnetic media, optical media and the like. The processing unit may comprise any suitable processor capable of executing memory-stored instructions, such as a microprocessor, uniprocessor, a multiprocessor and the like. Alternatively, the transmission control system 24 may be an independent control unit connected electronically to the machine control system 25.

The machine control system 25 may be electronically connected to control elements of the vehicle 10 as well as various input devices, for commanding the operation of the vehicle 10 and monitoring its performance. The machine control system 25 may be connected to a plurality of input devices detecting operator input which provide demand signals to the machine control system 25, that may include:-

- the input speed control 30, which generates a speed control signal;
- the input direction control 31, which generates a direction control signal; and
- the input gear control 32, which generates a gear selection signal.

The machine control system 25 may also be electronically connected to a plurality of sensing devices which provide sensor signals with values indicating real-time operating conditions of the vehicle 10. The sensors may include:-

- at least one transmission output speed sensor 33 connected to the output shaft 23, that transmits a transmission output speed signal with values indicating the rotational transmission output speed (TOS) of the transmission output shaft 23; and
- an oil temperature sensor 36, such as a thermocouple disposed within the transmission housing or other drivetrain component, that may transmit an oil temperature sensor signal a value corresponding to the oil temperature. Although the control strategy described herein may not make use of oil temperature values, temperature has a notable effect on transmission oil and may prevent or allow certain modes of operation. Thus they may be employed in a modified version of the strategy.

The machine control system 25 may also be electrically connected to output devices to which control signals are transmitted and from which control signals may be received by the machine control system 25. The output devices may include:-

- an engine throttle 37 that may control the speed of the power unit 19;
- one or more clutch actuators 38 that may control the transmission clutches 26 (via the transmission control system 24) to switch between the available gears;
- 5 - a brake actuator or actuators 39 that may cause hydraulic fluid to flow to braking devices to engage and reduce the speed of the vehicle 10; and
- other retarding device actuators 40 that may be selectively operated to reduce the TOS. Although the example of the control strategy described herein may not make use of brake and retarding systems, they may be employed in a modified strategy.

10

The transmission control system 24 may be programmed to execute a gear selection routine 45 in response to a direction shift requested by the operator via the input direction control 31. The gear selection routine 45 may comprise a logic which is based on a control strategy designed to prevent engine/transmission damage and assist operator control of the vehicle 10. The logic may ensure that the vehicle 10 is moving at an appropriate speed before a direction shift is executed. Thus the gear selection routine 45 may initially inhibit the requested direction shift. Where a requested direction shift is not executed immediately, the gear selection routine 45 may be designed to execute one or more sequential downshifts from the initial gear (i.e. the gear at the time the direction shift is requested) to a secondary gear in the same direction of vehicle travel to assist in the deceleration of the vehicle 10. The gear selection routine 45 may also, under certain conditions, maintain the initial gear and may execute an engine speed reduction command which also assists in the deceleration of the vehicle 10, The direction shift may then only be executed when the vehicle 10 is moving at the appropriate speed and the opposite direction gear selected may be that which matches the current vehicle speed. Thus the same opposite direction gear may be selected as the initial or secondary gear. The logic uses the current TOS, as measured by the transmission output speed sensor 33, and compares this with a predetermined direction shift threshold TOS programmed into the transmission control system 24.

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The direction shift threshold TOS for a vehicle 10 may be based on a maximum amount of energy that is expended to change the direction of the vehicle 10 without exceeding an operational limit of a component of the vehicle 10, such as the transmission 21 and the transmission clutches 26. The direction shift threshold TOS may be pre-programmed into the transmission control system 24. The direction shift threshold TOS may be empirically derived from test data for the vehicle 10, and may be derived using power and energy

35



analysis to determine the direction shift TOS limits which the clutches 26 may take without incurring damage. Different configurations of vehicles 10 and transmissions 21 may have different direction shift threshold TOS's.

- 5 The machine control system 25 and/or the transmission control system 24 may further be programmed with predetermined downshift inhibit threshold TOS's for each downshift (i.e. to a same direction gear). These may prevent the transmission 21 from downshifting to a lower gear that would risk over speeding of the power unit 19.
- 10 Figure 6 illustrates one embodiment of the control logic of the gear selection routine 45 for use in the vehicle 10 described herein according to the method of the present disclosure. The gear selection routine 45 may begin at block 46, when a direction shift request is made by the operator from forward to reverse or vice versa. The transmission control system 24 may continuously evaluate the value of the direction control signal from the input direction  
15 control 31 and will determine that a direction shift request has been made when the direction control signal value changes from the current travel direction of the vehicle 10 (the first direction) to the opposite direction (the second direction). If a direction shift request is determined, by a change in the direction control signal, control may pass to block 47.
- 20 At block 47 the transmission control system 24 may determine the current TOS based on the measurements made by the transmission output speed sensor 33.
- At block 48 the transmission control system 24 may compare the current TOS with the direction shift threshold TOS for the requested direction shift.
- 25 If the current TOS is equal to or less than the direction shift threshold TOS, control may pass to block 49, where the transmission direction shift signal may be generated to the transmission 21 which may cause it to execute the requested direction shift to same gear in the second direction (known as a straight directional shift). If there is no same gear in the  
30 opposite direction (for example if there are 4 forward gears and 3 reverse gears and the direction shift is from 4F) the shift may be made to the next highest gear in the other direction (in the foregoing example to 3R).
- 35 If the current TOS is greater than the direction shift threshold TOS, control may pass to block 50. At block 50, the gear selection routine 45 may inhibit the direction shift and may generate one or more transmission downshift signals to the transmission 21 to execute one

or more sequential downshifts to a lower gear in the first direction (hereinafter referred to as a secondary gear), or maintain the initial gear, until the current TOS drops to or below the direction shift threshold TOS. A change in gear due to the downshift may cause engine braking to reduce the speed of the vehicle 10 and therefore the TOS. The gear selection routine 45 may alternatively, or in addition, issue an engine speed reduction signal to reduce the engine speed (i.e. the speed of the power unit 19). The machine control system 25 may override the engine throttle 37 on receipt of such an engine speed reduction signal. Where the commanded engine speed is lower than the actual engine speed, the machine control system 25 may limit the supply of fuel to the power unit 19, so that the power unit 19 may be turned by the transmission 21. This means that the transmission 21 may expend energy to turn the power unit 19, which may reduce its speed. The engine speed reduction command may be limited so that there is no positive torque provided by the power unit 19. Retardation may also be provided by pumping losses of the power unit 19 and parasitic loads on the power unit 19 and the vehicle 10. The lower gear (and torque converter characteristics) may act to back drive the power unit 19 to the highest appropriate speed against these losses to maximise the retardation effect. The gear selection routine 45 may select the lowest gear in the first direction which has a downshift inhibit threshold TOS which is greater than the current TOS and may cause the transmission 21 to downshift sequentially to that gear. That gear may then be maintained until the current TOS drops to, or below, the direction shift threshold TOS.

If the initial gear has a downshift inhibit threshold TOS which is greater than the current TOS, the gear selection routine 45 may maintain the initial gear and wait for the current TOS to drop to or below the direction shift threshold TOS generating the transmission direction shift signal.

Control may then pass to block 49 and, if the operator is still requesting the direction shift, i.e. the direction shift request is still active, a transmission direction shift signal may be generated to the transmission 21 which may cause a direction shift to be executed to the same gear in the second direction (or the next highest in the event of there being no corresponding gear in the second direction).

### **Industrial Applicability**

The method of the present disclosure which executes the gear selection routine 45 is particularly suitable for a vehicle which uses an on/off clutch control system such as a backhoe loader, although it can be applied to other types of vehicles operating other types of



clutch control. This method may be effective in limiting transmission damage as a result of heat energy dissipation to the clutches from high speed directional shifts and may therefore mitigate degradation and premature failure of the transmission clutches. The logic used in the gear selection routine 45 may control the TOS by means of downward shifts in the same direction to slow the vehicle 10 to a speed where a straight direction shift to reverse the direction of travel may not cause transmission damage. The method does not attempt to impose any time constraint on the direction shift, only on the speed. Time based control strategies may suffer from a lack of feedback from the system. By using speed, the strategy may respond faster or slower, depending on the system and may provide better performance and protection.

Examples of the logic steps performed in the gear selection routine 45 as executed by the transmission control system 24 are given in the table of Figure 7. This will now be described in more detail based on an exemplary transmission 21 having four forward transmission gears 1F, 2F, 3F, 4F and three reverse transmission gears 1R, 2R, 3R and a direction shift threshold TOS of 1000rpm. The downshift inhibit threshold TOS's for this example may be as shown in the table below.

Downshift	Downshift inhibit threshold TOS
4F-3F	1345
3F-2F	1020
2F-1F	717
2R-1R	717
3R-2R	1345

It should be noted that the table shown in Figure 7 does not refer to 1F or 1R as an initial gear for a direction shift. This may be because, in this embodiment, the current TOS may not reach a damaging speed in these gears. Furthermore 1F or 1R may be avoided in the downshift strategy of the gear selection routine 45 to prevent too much torque passing through the transmission, which may be more torque than expected by the operator. Alternatively the vehicle 10 may be travelling too fast, which may cause damage to 1R/1F if the gear was suddenly reduced. This may be a separate control strategy to prevent the power unit 19 from over speeding. The control strategy of the present disclosure may be

designed to interact with other control strategies which the transmission control system 24 and/or machine control system 25 are programmed to implement.

5 If the initial gear (i.e. the gear when the direction shift is requested) is 3F and the current TOS is equal to or below the direction shift threshold TOS of 1000rpm, the gear selection routine 45 may generate a transmission direction shift signal which causes the transmission 21 to immediately execute the direction shift to 3R (i.e. the direction shift is executed to the same gear in the other direction). However, if the current TOS is over 1000rpm, say 1010rpm, the gear selection routine 45 may initially inhibit the direction shift  
10 (by not generating a generate a transmission direction shift signal) and may generate a transmission downshift signal to cause the transmission 21 to execute a downshift to the next lowest gear 2F in the same direction (i.e. a secondary gear). The gear selection routine 45 may also generate an engine speed reduction signal to reduce the engine speed. A reduction in engine speed and/or a lower gear may retard the speed of the  
15 vehicle 10 and reduce the current TOS. Unfavourable grades, payloads, frictional effects, lack of engine power may be variables which also help the vehicle 10 to slow naturally. When the current TOS falls to or below 1000rpm, and the operator is still requesting a direction shift, the gear selection routine 45 may generate a transmission direction shift signal to cause the transmission 21 to execute the direction shift to 2R (i.e. the direction  
20 shift is executed to the same gear in the second direction).

The gear selection routine 45 may not select 1F as a secondary gear for a further downshift, as the downshift inhibit threshold TOS for a 2F-1F downshift in this example is 717rpm, which is below the direction shift threshold TOS of 1000rpm for a 2F-2R direction  
25 shift. The same applies in reverse (i.e. selecting 1R). This may apply to each of the following examples.

If the initial gear is 2F and the current TOS is equal to or below the direction shift threshold TOS of 1000rpm, the gear selection routine 45 may generate a transmission direction shift  
30 signal which immediately causes the transmission 21 to execute a direction shift to 2R (i.e. the direction shift is executed to the same gear in the second direction). However, if the current TOS is over the 1000rpm, the gear selection routine 45 may initially inhibit the direction change by maintaining the initial gear 2F generate an engine speed reduction signal to reduce the engine speed. When the current TOS falls to or below 1000rpm, the  
35 gear selection routine 45 may generate a transmission direction shift signal which causes



the transmission 21 to execute the direction shift to 2R (i.e. the direction shift is executed to the same gear in the second direction).

If the initial gear is 4F and the current TOS is equal to or below the direction shift threshold TOS of 1000rpm, the gear selection routine 45 may generate a transmission direction shift signal to cause the transmission 21 to immediately execute the direction shift to 3R (i.e. the next highest reverse gear as there is no 4R in this example). However, if the current TOS is over 1000rpm, for example at 1010rpm, the gear selection routine 45 may initially inhibit the direction shift and may generate a transmission direction shift signal to cause the transmission 21 to execute a first downshift 3F as a first secondary gear in the same direction, then a second downshift to 2F as a second secondary gear. The gear selection routine 45 may also generate an engine speed reduction signal to reduce the engine speed. When the current TOS subsequently falls to or below 1000rpm, the gear selection routine 45 may generate a transmission direction shift signal to cause the transmission 21 to execute the direction shift to 2R (i.e. the direction shift is executed to the same gear in the second direction).

If the direction shift is requested when the initial gear is 4F and the current TOS, for example 1050rpm, only a first downshift from 4F-3F may be performed as the current TOS is higher than the downshift threshold TOS for a 3F-2F (i.e. 1020rpm). 3F may therefore be the secondary gear which will remain selected until the current TOS subsequently falls to or below 1000rpm, at which point the gear selection routine 45 may generate a transmission direction shift signal to cause the transmission 21 to execute the direction shift to 3R (i.e. the direction shift is executed to the same gear in the other direction). In this case, 2F may or may not be selected when the current TOS is between 1000rpm and 1020rpm, depending on calibration.

If the initial gear is 3R and the current TOS is equal to or below the direction shift threshold TOS of 1000rpm, the gear selection routine 45 may generate a transmission direction shift signal to cause the transmission 21 to execute the direction shift to 3F (i.e. the direction shift is executed to the same gear in the other direction). However, if the current TOS is over 1000rpm, for example at 1010rpm, the gear selection routine 45 may initially inhibit the direction shift and may generate a transmission direction shift signal to cause the transmission 21 to execute a downshift to 2R, which is the secondary gear in the same direction. The gear selection routine 45 may also cause generate an engine speed reduction signal to reduce the engine speed. When the current TOS falls to or below

1000rpm, the gear selection routine 45 may generate a transmission direction shift signal to cause the transmission 21 to execute the direction shift to 2F (i.e. the direction shift is executed to the same gear in the second direction).

- 5 If the initial gear is 2R and the current TOS is equal to or below the direction shift threshold TOS of 1000rpm, the gear selection routine 45 may generate a transmission direction shift signal to cause the transmission 21 to execute the direction shift to 2F (i.e. the direction shift is executed to the same gear in the other direction). However, if the current TOS is over 1000rpm, the gear selection routine 45 may initially inhibit the direction shift and
- 10 maintain the initial gear 2R and generate an engine speed reduction signal to reduce the engine speed. When the current TOS falls to or below 1000rpm, the transmission control system 24 may generate a transmission direction shift signal to cause the transmission 21 to execute the direction shift to 2F (i.e. the direction shift is executed to the same gear in the second direction).



## CLAIMS:

1. A method of controlling gear selection in a transmission of a vehicle, said vehicle having a power unit and an automatic transmission, said transmission having a plurality of first direction gears configured to move the vehicle in a first direction and a plurality of second direction gears configured to move the vehicle in a second direction which is opposite to the first direction, the method comprising the steps of:

determining a direction shift request by a vehicle operator to move the vehicle from the first to the second direction when the transmission is in an initial first direction gear;

determining a current transmission output speed;

comparing the current transmission output speed with a predetermined direction shift threshold transmission output speed; and

if the current transmission output speed is less than or equal to the predetermined direction shift threshold transmission output speed, causing the transmission to execute a direction shift from the initial first direction gear to the same second direction gear, or a next highest second direction gear if there is no second direction gear which corresponds to the initial first direction gear, and

if the current transmission output speed is greater than the predetermined direction shift threshold transmission output speed, the transmission is caused to execute one or more downshifts from the initial first direction gear to a secondary first direction gear which is the lowest gear which has a predetermined downshift inhibit threshold which is greater than the current transmission output speed, each downshift being to the next highest first direction gear sequentially, and

when the current transmission output speed slows to less than or equal to the predetermined direction shift threshold transmission output speed, and if the direction shift request is still active, the transmission is caused to execute a direction shift from the secondary first direction gear to the same second direction gear, or a next highest second direction gear if there is no second direction gear which corresponds to the secondary first direction gear.

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2. The method as claimed in claim 1 wherein:

if the initial first direction gear is the lowest gear which has a predetermined downshift inhibit threshold which is greater than the current transmission output speed, the initial first direction gear is maintained, and

when the current transmission output speed slows to less than or equal to the predetermined direction shift threshold transmission output speed, and if the direction shift request is still active, the transmission is caused to execute a direction shift from the initial

first direction gear to the same second direction gear, or a next highest second direction gear if there is no second direction gear which corresponds to the initial first direction gear.

3. The method as claimed in any one of the preceding claims, comprising the further  
5 step of executing an engine speed reduction signal to reduce a speed of the power unit.

4. A control system for controlling gear selection in a transmission of a vehicle, said  
vehicle having a power unit and an indirect drive automatic transmission, said transmission  
having a plurality of first direction gears configured to move the vehicle in a first direction  
10 and a plurality of second direction gears configured to move the vehicle in a second  
direction which is opposite to the first direction, said control system configured to;

evaluate direction control signals to determine when a direction shift request is  
made by a vehicle operator to move the vehicle from the first to the second direction when  
the transmission is in an initial first direction gear;

15 determine a current transmission output speed;

compare the current transmission output speed with a predetermined direction shift  
threshold transmission output speed; and

20 if the current transmission output speed is less than or equal to the  
predetermined direction shift threshold transmission output speed, generate a  
transmission direction shift signal to cause the transmission to execute a direction  
shift from the initial first direction gear to the same second direction gear, or a next  
highest second direction gear if there is no second direction gear which  
corresponds to the initial first direction gear, and

25 if the current transmission output speed is greater than the predetermined direction  
shift threshold transmission output speed, the control system is further configured to  
generate a downshift signal to cause the transmission to execute one or more downshifts  
from the initial first direction gear to a secondary first direction gear which is the lowest gear  
which has a predetermined downshift inhibit threshold which is greater than the current  
transmission output speed, each downshift being to the next highest first direction gear  
30 sequentially, and

when the current transmission output speed slows to less than or equal to the  
predetermined direction shift threshold transmission output speed, and if the direction shift  
request is still active, to generate a direction shift signal which causes the transmission to  
execute a direction shift from the secondary first direction gear to the same second  
35 direction gear, or a next highest second direction gear if there is no second direction gear  
which corresponds to the secondary first direction gear.

5. The control system as claimed in claim 4, wherein:



if the initial first direction gear is the lowest gear which has a predetermined downshift inhibit threshold which is greater than the current transmission output speed, the control system is configured to maintain the initial first direction gear, and when the current transmission output speed slows to less than or equal to the predetermined direction shift threshold transmission output speed, and if the direction shift request is still active, generate a direction shift signal which causes the transmission to execute a direction shift from the initial first direction gear to the same second direction gear, or a next highest second direction gear if there is no second direction gear which corresponds to the initial first direction gear.

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6. The control system as claimed in claim 4 or claim 5, wherein the control system is configured to generate an engine speed reduction signal.

7. A vehicle comprising:

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a power unit;

an indirect drive automatic transmission, said transmission having a plurality of first direction gears configured to move the vehicle in a first direction and a plurality of second direction gears configured to move the vehicle in a second direction which is opposite to the first direction;

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an operator actuated input direction control configured to generate direction control signals;

at least one transmission output speed sensor configured to measure current speed of the transmission output and generate a transmission output speed signal; and

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the control system as claimed in any one of claims 4 to 6 operatively connected to the power unit, transmission, input direction control, at least one transmission output speed sensor.