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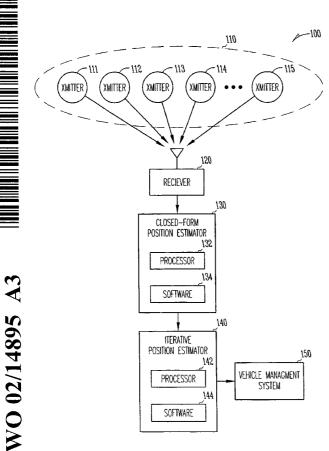
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[Continued on next page]

(54) Title: SYSTEM, METHOD, AND SOFTWARE FOR NON-ITERATIVE POSITION ESTIMATION USING RANGE MEA-**SUREMENTS** 



(57) Abstract: The typical global positioning system (GPS) estimates the three-dimensional, global position of a radio receiver and associated vehicle, such as an aircraft, using the range measurements between the radio receiver and a set of earth-orbiting satellite transmitters. Estimating the position of the receiver from these range measurements generally entails using an iterative calculation process, which computes a series of position estimates, with each successive estimate converging with increasing accuracy toward the actual receiver position. This iterative approach, however, is not only time consuming, but sometimes fails to converge toward the actual receiver position. Though others have tried to solve these problems, their approaches either fail to consistently converge on a single solution or give multiple solutions. Accordingly, the inventors devised, among other things, new non-iterative methods, for using range measurements to estimate position. One exemplary position-estimation method entails receiving a set of two or more range measurements; defining an error function based on the set of range measurements, with the error function having only one local minimum; and then determining a position estimate based the one local minimum of the error function. This and other exemplary embodiments of the invention promise to reduce the time for computing position estimates.



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### INTERNATIONAL SEARCH REPORT

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### B. FIELDS SEARCHED

 $\begin{array}{ll} \text{Minimum documentation searched (classification system followed by classification symbols)} \\ \text{IPC 7} & \text{G01S} \end{array}$ 

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EPO-Internal, WPI Data, PAJ, INSPEC

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X Fur	ther documents are listed in the continuation of box C.	χ Patent family members are	e listed in annex.
° Special c	ategories of cited documents :	"T" later document published after t	he international filing date
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	document but published on or after the international	"X" document of particular relevance	
"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another		cannot be considered novel or involve an inventive step when	the document is taken alone
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II ational Application No
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