(19)





### (11) **EP 2 468 932 B1**

(12)

#### **EUROPEAN PATENT SPECIFICATION**

(45) Date of publication and mention of the grant of the patent: 12.06.2013 Bulletin 2013/24 (51) Int Cl.: D01H 4/48 <sup>(2006.01)</sup> B65H 67/08 <sup>(2006.01)</sup>

D01H 15/00<sup>(2006.01)</sup>

- (21) Application number: 12160960.6
- (22) Date of filing: 08.07.2010

#### (54) Yarn end catching device and method of operating it

Garnendenaufnahmevorrichtung und Betriebsverfahren dafür

Dispositif pour attraper l'extrémité des fils et son procédé de fonctionnement

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(43)	<ul> <li>Priority: 17.08.2009 JP 2009188450</li> <li>Date of publication of application: 27.06.2012 Bulletin 2012/26</li> <li>Document number(s) of the earlier application(s) in accordance with Art. 76 EPC: 10168860.4 / 2 302 115</li> </ul>		Hansmann & Voge Patent- und Recht Maximilianstrasse 82319 Starnberg (I ) References cited: EP-A1- 2 169 096 EP-A2- 1 882 663	eser sanwälte 4b
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#### Description

#### BACKGROUND OF THE INVENTION

#### 1. Field of the Invention

**[0001]** The present invention relates to a yarn end catching device in a spinning machine and a method of operating it.

#### 2. Description of the Related Art

[0002] Patent Document 1 discloses a spinning machine. A spinning machine disclosed in Patent Document 1 includes a spinning device, a yarn feeding device, a winding device, a yarn splicing cart as main components. [0003] The yarn feeding device includes a delivery roller and a nip roller. The delivery roller is driven and rotated under a state in which yarn fed from the spinning device (spun yarn) is caught between the delivery roller and the nip roller, so that the yarn feeding device can feed the spun yarn to a winding device side.

**[0004]** The yarn splicing cart includes a yarn splicing device and a suction pipe. For a yarn splicing operation in the yarn splicing device, the suction pipe can suck and catch a yarn end which is discharged from the spinning device, and then can guide the yarn end to the yarn splicing device.

[0005] In a structure of Patent Document 1, in the yarn splicing operation which is performed when a spinning operation is started or a yarn breakage occurs, the yarn end is injected from the spinning device, and then is controlled to nip at a roller of the yarn feeding device. After the above-described operation, since the yarn can be pulled downstream while tension is being applied to the yarn by driving of the yarn feeding device, the spinning device can generate truly-twisted yarn. A leading end of the suction pipe is controlled so as to be arranged immediately downstream of the yarn feeding device, and the yarn fed downstream by such a yarn feeding device is sucked and caught through such a suction pipe. Then, the suction pipe guides the caught yarn to the yarn splicing device, and then the yarn splicing operation is performed.

**[0006]** Such kind of spinning machine is also disclosed in Patent Document 2. In a same manner as the spinning machine disclosed in Patent Document 1, a spinning machine disclosed in such Patent Document 2 includes a yarn feeding device, which can feed the yarn downstream under a state in which the yarn is caught and held by a nip roller and a delivery roller.

**[0007]** Further, in the spinning machine described in Patent Document 2, a yarn slack eliminating device (a yarn accumulating device) is arranged downstream of the yarn feeding device. The yarn slack eliminating device includes a yarn slack eliminating roller (a yarn accumulating roller) capable of winding yarn around an outer peripheral surface thereof. While the yarn slack eliminating roller is being driven and rotated, by winding yarn, which is fed continuously from a spinning device, around the outer peripheral surface thereof, the yarn slack eliminating roller temporarily accumulates the yarn. Accordingly, a yarn slackening which is generated during a yarn splicing operation can be prevented.

[Patent Document 1] Japanese Unexamined Patent Application Publication No. 2005-220483

[Patent Document 2] Japanese Unexamined Patent Application Publication No. 2004-124333

**[0008]** In these spinning machines, it is always difficult and time consuming to correctly catch and suck the yarn end after for example a yarn breakage.

**[0009]** The earlier post-published patent application EP2213773 (A1) discloses a spinning machine comprising: a spinning device that generates spun yarn by air-jet spinning and feeds the spun yarn from a spinning outlet;

<sup>20</sup> a winding device that forms a package by winding the spun yarn spun by the spinning device around a bobbin; and a yarn end catching device: The yarn end catching device comprises a suction pipe which sucks and catches a yarn end of a yarn through a suction opening, the suc-

tion pipe of the yarn end catching device comprising: a suction passage for sucking the yarn end; and a twist applying member which applies twists to the yarn sucked in the suction passage. The yarn end catching device further comprises an ejector nozzle for injecting compressed air into the suction passage such that a suction

airflow is generated.

[0010] CH 443 084 refers to a device having the function to catch the end of a spun yarn. For this purposes, the device comprises a tube and an air pipe injecting air
<sup>35</sup> in the tube such that the air flows inside the tube and the airflow is twisted on the downstream side of the air pipe. At the same time, the air injected by the air pipe causes a suction effect in that part of the tube.

#### 40 SUMMARY OF THE INVENTION

**[0011]** The present invention has been made in view of the above-described problem. It is an object of the present invention to provide a more reliable and faster

- <sup>45</sup> yarn end catching device for such spinning machines.
   [0012] According to the invention, this problem is solved with a yarn end catching device according to claim 1 or by a method of operating a yarn end catching device according to claim 8.
- <sup>50</sup> **[0013]** The subclaims describe preferable further developments of the present invention.

#### BRIEF DESCRIPTION OF THE DRAWINGS

#### <sup>55</sup> [0014]

Fig. 1 is a front view illustrating an overall structure of a spinning frame according to an embodiment of

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the present invention.

Fig. 2 is a longitudinal sectional view of the spinning frame.

Fig. 3 is a block diagram illustrating a main structure of the spinning frame.

Fig. 4 is a longitudinal sectional view of a yarn accumulating device.

Fig. 5 is an external perspective view of the yarn accumulating device.

Fig. 6 is an enlarged sectional view illustrating a structure of a leading end portion of a suction pipe. Fig. 7 is a flowchart describing the first half of a control in which a yarn portion with unstable yarn quality is unwound from a yarn accumulating roller.

Fig. 8 is a flowchart describing the last half of the control in which the yarn portion with unstable yarn quality is unwound from the yarn accumulating roller. Fig. 9 is a timing chart when the yarn portion with unstable yarn quality is unwound from the yarn accumulating roller.

Fig. 10 is a longitudinal sectional view illustrating a state in which upper yarn and lower yarn are caught by the suction pipe and a suction mouth.

Fig. 11 is a longitudinal sectional view illustrating a state in which the yarn portion with unstable yarn quality is unwound from the yarn accumulating roller.

DETAILED DESCRIPTION OF PREFERRED EMBOD-IMENTS

**[0015]** Next, by referring to the drawings, a spinning frame (a spinning machine) 1 according to an embodiment of the present invention will be described. In this specification, "upstream" and "downstream" refer to an upstream side and a downstream side in a travelling direction of a yarn during a spinning operation, respectively. Fig. 1 is a front view illustrating an overall structure of the spinning frame 1. Fig. 2 is a longitudinal sectional view of the spinning frame 1. Fig. 3 is a block diagram illustrating a main structure of the spinning frame 1.

**[0016]** The spinning frame 1 as a spinning machine illustrated in Fig. 1 includes a plurality of units (spinning units 2) arranged next to one another. The spinning frame 1 includes a yarn splicing cart 3, a blower box 80, and a motor box 5.

**[0017]** As illustrated in Fig. 1, each spinning unit 2 includes a draft device 7, a spinning device 9, a yarn accumulating device 12, and a winding device 13 as main components, which are arranged in this order from upstream to downstream. The draft device 7 is arranged near an upper end of a frame 6 of the spinning frame 1. The spinning device 9 spins a fiber bundle 8 which is fed from the draft device 7. The spun yarn 10 fed from the spinning device 9 passes through a yarn clearer 52 which will be described later, is fed by the yarn accumulating device 12, and then is wound by the winding device 13 into a package 45.

[0018] The draft device 7 drafts a sliver 15 so as to

produce the fiber bundle 8. As illustrated in Fig. 2, the draft device 7 includes four rollers, namely a back roller 16, a third roller 17, a middle roller 19 provided with an apron belt 18, and a front roller 20. As illustrated in Fig.

3, an electric motor driving such rollers(not illustrated in the drawings) is controlled by a unit controller (a control section) 60.

**[0019]** A detailed structure of the spinning device 9 is not illustrated in the drawings; however, the present embodiment adopts a pneumatic type of the spinning device

9 which applies twists to the fiber bundle 8 by whirling airflow and generates the spun yarn 10. Further, as illustrated in Fig. 3, the unit controller 60 controls generation and stoppage of the whirling airflow in the spinning device 9

**[0020]** The yarn accumulating device 12 is located downstream of the spinning device 9. The yarn accumulating device 12 includes a yarn pulling function, a yarn slack preventing function, and a tension adjusting func-

tion. The yarn pulling function is a function in which the yarn accumulating device 12 applies predetermined tension to the spun yarn 10 and pulls out the spun yarn 10 from the spinning device 9. The yarn slack preventing function is a function to accumulate the spun yarn 10

which is fed from the spinning device 9 so as to prevent a yarn slackening during a yarn splicing operation performed by the yarn splicing cart 3 (which will be described later) or the like. The tension adjusting function is a function to adjust tension in order to prevent change in tension

on a side of the winding device 13 (which will be described later) from propagating to a spinning device 9 side. As illustrated in Fig. 2, the yarn accumulating device 12 includes a yarn accumulating roller 21, a yarn hooking member (a yarn hooking section) 22, an upstream guide
 an electric motor 25, a downstream guide 26, an ac-

23, an electric motor 25, a downstream guide 26, an accumulated amount detecting sensor 27, and a yarn removing lever (a yarn removing section) 28.

[0021] The yarn hooking member 22 is capable of being engaged with (hooking) the spun yarn 10. By rotating
integrally with the yarn accumulating roller 21 under a state in which the yarn hooking member 22 is engaged with the spun yarn 10, the yarn hooking member 22 can guide the spun yarn 10 to an outer peripheral surface of the yarn accumulating roller 21.

45 [0022] The yarn accumulating roller 21 can accumulate the spun yarn 10 by winding the spun yarn 10 around the outer peripheral surface thereof. The yarn accumulating roller 21 is driven and rotated at a constant rotational speed by the electric motor 25 which is controlled 50 by the unit controller 60. In such a structure, the spun yarn 10 guided to the outer peripheral surface of the yarn accumulating roller 21 by the yarn hooking member 22 is wound around by rotation of the yarn accumulating roller 21 such that the yarn accumulating roller 21 is tight-55 ened, and pulls the spun yarn 10 located upstream of the yarn accumulating device 12. Accordingly, the spun yarn 10 can be continuously pulled out from the spinning device 9.

**[0023]** When the spun yarn 10 on the yarn accumulating roller 21 reach at least a specific amount, a contact area between the yarn accumulating roller 21 and the spun yarn 10 is increased, so that few slipping or the like is generated. Accordingly, by driving and rotating the yarn accumulating roller 21 under a state in which at least the specific amount of the spun yarn 10 is wound around the yarn accumulating roller 21, the spun yarn 10 can be pulled out from the spinning device 9 at a stable speed without generating the slipping or the like. In addition, in the following description, the specific amount of the spun yarn 10 (the yarn accumulated amount by which the slipping is no longer generated and force to pull the spun yarn 10 becomes stable) may be referred to as a minimum accumulated amount.

**[0024]** The accumulated amount sensor 27 detects an accumulated amount of the spun yarn 10 accumulated on the yarn accumulating roller 21 in a non-contact manner and transmits the detected accumulated amount of the spun yarn 10 to the unit controller 60.

**[0025]** The upstream guide 23 is located slightly upstream of the yarn accumulating roller 21. The upstream guide 23 is configured as a guiding member that appropriately guides the spun yarn 10 to the outer peripheral surface of the yarn accumulating roller 21. Further, the upstream guide 23 also functions as twist prevention which prevents twists of the spun yarn 10 propagated from the spinning device 9 from propagating downstream of the upstream guide 23.

**[0026]** The downstream guide 26 is located slightly downstream of the yarn accumulating roller 21. The downstream guide 26 restricts an orbit of the spun yarn 10 which is swung by the rotating yarn hooking member 22, and is configured as a guiding member that guides the spun yarn 10 by stabilizing a travelling route of the spun yarn 10 located downstream of the downstream guide 26.

**[0027]** The yarn removing lever 28 is arranged near an end portion of a downstream side of the yarn accumulating roller 21 and arranged upstream of the downstream guide 26. The yarn removing lever 28 is arranged so as to be capable of swinging around a swing shaft 28b.

**[0028]** The yarn clearer 52 is provided in front of the frame 6 of the spinning frame 1 and at a position between the spinning device 9 and the yarn accumulating device 12. The yarn clearer 52 monitors a thickness of the travelling spun yarn 10. When detecting a yarn defect in the spun yarn 10, the yarn clearer 52 transmits a yarn defect detection signal to the unit controller 60. A cutter 57 is arranged upstream of the yarn clearer 52. The unit controller 60 received the yarn defect detection signal, controls the cutter 57 to operate so as to cut off the spun yarn 10.

**[0029]** As illustrated in Fig. 1 and Fig. 2, the yarn splicing cart 3 includes a splicer (a yarn splicing device) 43, a suction pipe (a yarn end catching device) 44, a suction mouth 46, a pushing arm 47, and a pneumatic cylinder 49. When a yarn breakage or a yarn cut occurs in one

spinning unit 2, the yarn splicing cart 3 travels on a rail 41 fixed to the frame 6 to such a spinning unit 2, stops in front of such a spinning unit 2, and performs the yarn splicing operation. The yarn splicing operation is an operation ranging from a process in which yarn ends generated by the yarn breakage or the yarn cut are caught to a process in which the yarn ends are spliced together. Such a series of processes may be referred to as a yarn splicing operation cycle.

10 [0030] The suction pipe 44 can swing around a shaft in a vertical direction. The suction pipe 44 can suck and catch a yarn end (an upper yarn) fed from the spinning device 9, and can guide the caught yarn end to the splicer 43. A nozzle member 44a is provided at a leading end

<sup>15</sup> portion of the suction pipe 44. A detailed description on the nozzle member 44a will be made later. The suction mouth 46 can swing around the shaft in a vertical direction. The suction mouth 46 can suck and catch a yarn end (a lower yarn) from the package 45 supported by the

winding device 13, and can guide the caught yarn end to the splicer 43. Although a detailed structure on the splicer 43 is not described, by twisting both yarn ends together by whirling airflow after both yarn ends are untwisted, the splicer 43 is configured such that the upper yarn is spliced with the lower yarn.

[0031] The pushing arm 47 is arranged at a leading end portion of the pneumatic cylinder 49 provided as an actuator. By controlling the pushing arm 47 to move to an advanced position in an upward direction by driving
30 of the pneumatic cylinder 49 so as to push the yarn removing lever 28, the pushing arm 47 is configured such that the yarn removing lever 28 can be driven to an ele-

vated position. The driving of the pneumatic cylinder 49 is controlled by the unit controller 60.
35 [0032] The winding device 13 includes a cradle arm 71 which is supported so as to be capable of swinging around a currentian chaft 70. The cradle arm 71 capacity of the control of the con

around a supporting shaft 70. The cradle arm 71 can support a bobbin 48 for winding the spun yarn 10 in a manner that the bobbin 48 can be rotated.
40 [0033] The winding device 13 includes a winding drum

72 and a traverse device 75. The winding drum 72 can be driven by making contact with an outer peripheral surface of the bobbin 48 or an outer peripheral surface of the package 45 formed by winding the spun yarn 10

<sup>45</sup> around the bobbin 48. The traverse device 75 includes a traverse guide 76 which can be engaged with the spun yarn 10. In such a structure, by driving the winding drum 72 by an electric motor (not illustrated in the drawings) while reciprocating the traverse guide 76 by a driving
<sup>50</sup> means (not illustrated in the drawings), the package 45

means (not illustrated in the drawings), the package 45 making contact with the winging drum 72 is rotated, and the spun yarn 10 is wound into the package 45 while being traversed.

[0034] Next, a detailed structure of the yarn accumulating device 12 will be described by referring to Fig. 4 and Fig. 5. Fig. 4 is a longitudinal sectional view of the yarn accumulating device 12. Fig. 5 is an external perspective view of the yarn accumulating device 12.

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**[0035]** The yarn accumulating roller 21 is a roller member formed of abrasion-resistant material. The yarn accumulating roller 21 is fixed to a motor shaft 25a of the electric motor 25. Further, in the yarn accumulating roller 21, a side where the yarn hooking member 22 is provided will be referred to as a leading end and a side where the electric motor 25 is provided will be referred to as a base end. The yarn accumulating roller 21 includes a base-end taper portion 21 b, a cylindrical portion 21 c, and a leading-end taper portion 21 d arranged in this order from the base end to the leading end thereof.

**[0036]** The cylindrical portion 21c slightly tapers towards a leading end thereof, and also is flatly connected (without difference in level) with the base-end taper portion 21 b and the leading-end taper portion 21 d. A dimension of the cylindrical portion 21 c is arbitrarily determined such that at least the minimum accumulated amount of the spun yarn 10 can be accumulated. The accumulated amount sensor 27 is arranged so as to face the cylindrical portion 21c. The accumulated amount sensor 27 detects the accumulated amount of the yarn 10 wound around the yarn accumulating roller 21, and then transmits the detected accumulated amount of the yarn 10 to the unit controller 60.

[0037] Each of the base-end taper portion 21 b and the leading-end taper portion 21 d is formed in a slightly tapered shape with a larger diameter at a corresponding end surface side. On an outer peripheral surface 21 a of the yarn accumulating roller 21, the base-end taper portion 21 b smoothly moves the supplied spun yarn 10 from a larger diameter portion to a smaller diameter portion towards the cylindrical portion 21 c so as to orderly wind the spun yarn 10 around a surface of the cylindrical portion 21c. The leading-end taper portion 21d prevents a sloughing phenomenon in which the wound spun yarn 10 sloughs off all at once when unwinding the spun yarn 10 from the yarn accumulating roller 21. The leading-end taper portion 21d also has a function of sequentially rewinding the spun yarn 10 from the smaller diameter portion to the larger diameter portion at the end surface side so as to smoothly pull out the spun yarn 10.

**[0038]** As illustrated in Fig. 3 and Fig. 5, the yarn hooking member 22 located on a leading end of the yarn accumulating roller 21 is arranged coaxially with the yarn accumulating roller 21. The yarn hooking member 22 includes a flyer axis 33 and a flyer 38 fixed to a leading end of the flyer axis 33.

**[0039]** The flyer axis 33 is supported to be relatively rotatable with respect to the yarn accumulating roller 21. Meanwhile, a permanent magnet is mounted on one of the flyer axis 33 and the yarn accumulating roller 21, and a magnetic hysteresis member is mounted on the other thereof. A resistance torque is generated against rotation of the yarn hooking member 22 relative to the yarn accumulating roller 21 by such magnetic mechanisms. The yarn hooking member 22 rotates accompanying rotation of the yarn accumulating roller 21 by such magnetic mechanisms. The yarn hooking member 22 rotates accompanying rotation of the yarn accumulating roller 21 by the resistance torque. Accordingly, the yarn hooking member 22 and

the yarn accumulating roller 21 can rotate integrally. Meanwhile, when force that surpasses the resistance torque is applied to the yarn hooking member 22, the yarn hooking member 22 rotates relatively with respect to the yarn accumulating roller 21.

**[0040]** The flyer 38 is curved arbitrarily towards the outer peripheral surface 21a of the yarn accumulating roller 21, and is formed in a shape in which the flyer 38 can be engaged with the spun yarn 10 (can hook the spun yarn

10 10). Under a state in which the spun yarn 10 is not wound around on the yarn accumulating roller 21, when the flyer 38 rotates integrally with the yarn accumulating roller 21, the flyer 38 is engaged with the spun yarn 10. The spun yarn 10 engaged with the rotating flyer 38 is swung 15 around by such a flyer 38, and then is guided to and

around by such a flyer 38, and then is guided to and wound around the outer peripheral surface of the rotating yarn accumulating roller 21.

**[0041]** A state of the spun yarn 10 wound around the yarn accumulating roller 21 will be described as follows.

- That is, the spun yarn 10 passed through the upstream guide 23 is guided from a base end of the yarn accumulating roller 21 to the outer peripheral surface 21a, and then is wound around the cylindrical portion 21c a plurality of times. The spun yarn 10 pulled out from a leading end
- of the outer peripheral surface 21a, passes through the flyer 38, and then is fed downstream via the downstream guide 26.

**[0042]** As illustrated in Fig. 5, under a state in which the spun yarn 10 is wound around the yarn accumulating roller 21, when force to pull the spun yarn 10 engaged with the flyer 38 downstream is applied, force to attempt to rotate the yarn hooking member 22 so as to unwind the spun yarn 10 from a leading end portion of the yarn accumulating roller 21 is applied to the flyer 38. Accord-

- <sup>35</sup> ingly, if yarn tension at a downstream side of the yarn accumulating device 12 (yarn tension between the yarn accumulating device 12 and the winding device 13) is high enough to surpass the resistance torque (that is, at least a predetermined value of yarn tension is applied to
- 40 the spun yarn 10 engaged with the flyer 38), the yarn hooking member 22 rotates independently from the yarn accumulating roller 21. Consequently, the spun yarn 10 is gradually unwound from the leading end of the yarn accumulating roller 21 via the flyer 38.

<sup>45</sup> [0043] Meanwhile, when the yarn tension at the downstream side of the yarn accumulating device 12 is not strong enough to surpass the resistance torque, the yarn hooking member 22 rotates integrally with the yarn accumulating roller 21. In such a case, the yarn hooking

50 member 22 operates so as to prevent the spun yarn 10 from being unwound from the leading end of the rotating yarn accumulating roller 21.

[0044] As described above, when downstream tension of the spun yarn 10 increases, the yarn accumulating
device 12 operates to unwind the spun yarn 10. When the downstream tension of the spun yarn 10 decreases (when the spun yarn 10 is likely to slacken), the yarn accumulating device 12 operates to stop unwinding of

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the spun yarn 10. Accordingly, the yarn accumulating device 12 can eliminate slackening of the spun yarn 10 and apply appropriate tension to the spun yarn 10. Further, the yarn hooking member 22 operates so as to absorb change in tension applied to the spun yarn 10 between the yarn accumulating device 12 and the winding device 13 as described above. Consequently, such change in tension can be prevented from influencing the spun yarn 10 between the spinning device 9 and the yarn accumulating device 9 at a further steady speed by the yarn accumulating device 12 having the above-described structure.

**[0045]** Further, since the yarn accumulating roller 21 is driven and rotated at a predetermined speed, the spun yarn 10 is wound around at the base end of the yarn accumulating roller 21 at a predetermined speed. Accordingly, when a speed at which the spun yarn 10 is unwound from the leading end of the yarn accumulating roller 21 is faster than a speed at which the spun yarn 10 is wound around at the base end of the yarn accumulating roller 21, an accumulated amount of yarn decreases. When the spun yarn 10 is not unwound from the leading end of the yarn accumulating end of the yarn accumulating roller 21, an accumulated amount of yarn decreases.

[0046] Further, as described above, the yarn accumulating device 12 includes the yarn removing lever 28. As illustrated in Fig. 5, the yarn removing lever 28 is formed as a substantially L-shaped member having an elongate portion (an operating section 28a) arranged horizontally. A basal portion of the yarn removing lever 28 is supported by the swing shaft 28b. The yarn removing lever 28 is arranged so as to be capable of swinging vertically around the swing shaft 28b at a position between the elevated position and a lowered position. When the yarn removing lever 28 is at the lowered position, the yarn removing lever 28 does not make contact with a yarn passage of the spun yarn 10. When the yarn removing lever 28 is at the elevated position, the operating section 28a pushes up the yarn passage of the spun yarn 10 so as to remove the spun yarn 10 from the flyer 38. The yarn removing lever 28 is normally kept at the lowered position by being urged by a spring member (not illustrated in the drawings). The pneumatic cylinder 49 provided in the yarn splicing cart 3 is driven so that the yarn removing lever 28 is pushed by the pushing arm 47 and is moved up to the elevated position.

**[0047]** In the above-described structure, by moving the yarn removing lever 28 up to the elevated position, the spun yarn 10 can be removed from the yarn hooking member 22. Accordingly, since resistance force generated when the spun yarn 10 is unwound from the leading end of the yarn accumulating roller 21 (resistance torque acting on the yarn hooking member 22) stops acting on the spun yarn 10, even when yarn tension at the downstream side of the yarn accumulating roller 21 is weak, the spun yarn 10 can be unwound from the yarn accumulating roller 21. Controlling the yarn removing lever 28

to be kept at the elevated position under a state in which the spun yarn 10 is not wound around the yarn accumulating roller 21 can prevent the flyer 38 from being engaged with the spun yarn 10. Consequently, the spun yarn 10 can be prevented from being wound by the yarn

accumulating roller 21. [0048] Next, a detailed structure of the leading end portion of the suction pipe 44 provided in the yarn splicing cart 3 will be described. Fig. 6 is an enlarged sectional

<sup>10</sup> view illustrating the structure of the leading end portion of the suction pipe 44. Further, Fig. 6 illustrates a state in which the suction pipe 44 is swung and a leading end of the suction pipe 44 is located downstream of the spinning device 9.

<sup>15</sup> [0049] As illustrated in Fig. 6, the elongate nozzle member 44a is fixed to the leading end portion of the suction pipe 44. The nozzle member 44a is formed in a pipe shape. A suction passage 62 formed in a cross-sectional round shape, is formed in the nozzle member 44a.

20 One end of the suction passage 62 is connected to a suction opening 63 formed on a leading end surface of the nozzle member 44a.

**[0050]** The suction passage 62 is configured as a passage with steps which has a smaller diameter portion 64

formed in a portion near the suction opening 63 and a larger diameter portion 65 connected to the smaller diameter portion 64. Accordingly, a flow passage sectional area of the larger diameter portion 65 is larger than a flow passage sectional area of the smaller diameter portion 64. In the nozzle member 44a, a first air chamber 68 and

a second air chamber 69, which are formed in a circular shape, are formed such that the suction passage 62 is surrounded by both air chambers. The first air chamber 68 and the second air chamber 69 are connected to a
<sup>35</sup> compressed air pipe 55, and a compressed air source (not illustrated in the drawings) can supply compressed air to the first air chamber 68 and the second air chamber 68.

[0051] An ejector nozzle (a sucking section) 66 for injecting compressed air to the suction passage 62 is connected to the first air chamber 68. The ejector nozzle 66 is formed as a ring-shaped nozzle formed in a crosssectional triangular shape. A cross-sectional outline of the ejector nozzle 66 tapers towards the suction passage

<sup>45</sup> 62 arranged inside. A leading end of the ejector nozzle 66 forms an injection opening on an inner wall of the suction passage 62, and can inject air from the injection opening to the suction passage 62.

[0052] The injection opening of the ejector nozzle 66 is formed in a ring shape such that air is injected from the entire perimeter of the injection opening. The ejector nozzle 66 is arranged to slant arbitrarily so that oblique airflow directed towards a base end of the suction pipe 44 can be formed. In such a structure, by injecting air to 55 the suction passage 62 from the first air chamber 68 through the ejector nozzle 66 at a high speed, a publicly known venture effect causes pressure drop (an eject effect) to be generated. Consequently, suction airflow di-

rected towards a basal portion of the suction pipe 44 can be controlled to act on the suction opening 63. Generation and stoppage of such suction airflow are controlled by the unit controller 60.

**[0053]** The suction pipe 44 is connected to the blower box 80 via a blower duct (not illustrated in the drawings). By such a structure, different suction airflow from the suction airflow generated through the ejector nozzle 66 can be generated through the suction pipe 44.

**[0054]** A plurality of twisting nozzles (twisting sections) 67 for injecting compressed air to the suction passage 62 are connected to the second air chamber 69. The twisting nozzles 67 are placed at equally spaced intervals in the vicinity of the suction passage 62. Each twisting nozzle 67 forms an injection opening on the inner wall of the suction passage 62. Further, although for convenience in being described by the sectional view, Fig. 6 illustrates the twisting nozzle 67 such that the twisting nozzle 67 extends in a radial direction, an actual direction of the twisting nozzle 67 is a tangential direction of the round-shaped suction passage 62.

**[0055]** In such a structure, by injecting the compressed air to the suction passage 62 from the second air chamber 69 through the twisting nozzle 67, airflow is generated in the suction passage 62. Accordingly, while twists are applied to the spun yarn 10 introduced into the suction passage 62 by action of whirling airflow which is generated at the twisting nozzle 67, the spun yarn 10 is pulled into the basal portion of the suction pipe 44. Generation and stoppage of such whirling airflow are controlled by the unit controller 60.

[0056] Next, by referring to Fig. 7 through Fig. 11, a yarn processing method during the yarn splicing operation in the spinning frame 1 according to the present embodiment will be described. Fig. 7 is a flowchart describing the first half of a control in which a yarn portion with unstable yarn quality is unwound from the yarn accumulating roller 21. Fig. 8 is a flowchart describing the last half of the control in which the yarn portion with unstable yarn quality is unwound from the yarn accumulating roller 21. Fig. 9 is a timing chart when the yarn portion with unstable yarn quality is unwound from the yarn accumulating roller 21. Fig. 10 is a longitudinal sectional view illustrating a state in which the upper yarn and the lower yarn are caught by the suction pipe 44 and the suction mouth 46. Fig. 11 is a longitudinal sectional view illustrating a state in which the yarn portion with unstable yarn quality is unwound from the yarn accumulating roller 21. [0057] Further, in Fig. 9, a state in which airflow is generated through the twisting nozzle 67, the ejector nozzle 66, and the suction pipe 44, is referred to as "ON", and a state in which generation of the airflow is stopped, is referred to as "OFF". Meanwhile, a state in which the yarn removing lever 28 is elevated, is referred to as "ON", and a state in which the yarn removing lever 28 is lowered, is referred to as "OFF".

**[0058]** First, when detecting a yarn defect during a winding operation of the spun yarn 10, the yarn clearer

52 transmits the yarn defect detection signal to the unit controller 60. Immediately after receiving the yarn defect detection signal (step S101), the unit controller 60 controls the cutter 57 to cut off the spun yarn 10 and also stops operations of the draft device 7, the spinning device 9, or the like (step S102). Meanwhile, the winding device 13 still continues performing the winding operation, and the spun yarn 10 located downstream of a position at

which the spun yarn 10 was cut off, is temporarily wound
into the package 45. Accordingly, the spun yarn 10 wound around the yarn accumulating roller 21 is also wound into the package 45, which cause the spun yarn 10 on the yarn accumulating roller 21 to run out. Further, a yarn portion including the yarn defect is also wound into the
package 45 temporarily.

**[0059]** Next, the unit controller 60 transmits a control signal to the yarn splicing cart 3, and then controls the yarn splicing cart 3 to travel to the front of such a spinning unit 2 (step S103).

20 [0060] Then, the yarn splicing operation cycle starts. Specifically, the unit controller 60 controls the suction mouth 46 to swing to the vicinity of a surface of the package 45 (refer to Fig. 10) and controls the winding device 13 to rotate the package 45 backward (step S104 of Fig.

7). Accordingly, a yarn end of the lower yarn is pulled out from the outer peripheral surface of the package 45, and then the yarn end is caught by the suction mouth 46 (step S104). Further, at this point of time, by pulling out the spun yarn 10 including the yarn defect from the package
45 and sucking the spun yarn 10 including the yarn defect by suction airflow generated through the suction mouth 46, the spun yarn 10 including the yarn defect can be removed from the package 45.

[0061] Next, while rotating the package 45 backward,
the unit controller 60 swings the suction mouth 46 upward under a state in which the suction mouth 46 is sucking the lower yarn so as to guide the lower yarn to the splicer 43 (step S105). Then, when the lower yarn is guided to the splicer 43, the unit controller 60 also stops rotation
of the package 45 (step S105).

**[0062]** Before or after swinging movement of the suction mouth 46, the unit controller 60 controls the suction pipe 44 to swing to the vicinity of a downstream side of the spinning device 9 (refer to Fig. 10). Before or after

the swinging movement, the unit controller 60 controls suction airflow to be generated through the suction pipe 44 (step S106 of Fig. 7). Then, the unit controller 60 controls whirling airflow to be generated through the twisting nozzle 67 (step S107) and controls suction airflow to be generated through the ejector nozzle 66 (step S108) (refer to Fig. 9). The unit controller 60 controls the above de-

fer to Fig. 9). The unit controller 60 controls the above-described airflow to be generated, and also re-drive the spinning device 9 or the like such that the spun yarn 10 is generated.

<sup>55</sup> **[0063]** The spun yarn 10 fed herein from the spinning device 9, has been less sufficiently twisted than the spun yarn 10 in a normal state, and yarn strength of such spun yarn 10 has been decreased. Accordingly, when the spun

yarn 10 is just sucked by the suction airflow generated through the ejector nozzle 66 and the suction pipe 44, friction or the like which is generated between the spun yarn 10 and the suction opening 63 of the suction pipe 44 or between the spun yarn 10 and the inner wall of the suction passage 62 causes the spun yarn 10 to break easily, for example.

**[0064]** However, in a structure of the present embodiment, the whirling airflow generated through the twisting nozzle 67 acts such that another twists are applied to the spun yarn 10. By such another twists, the yarn strength of the spun yarn 10 can be increased and the spun yarn 10 can be sucked in the suction pipe 44. Accordingly, a yarn breakage can be prevented effectively.

**[0065]** Further, by controlling the airflow to be generated in the above-described order, the spun yarn 10 can be sucked while twists are being applied sufficiently to the spun yarn 10 in an early stage, which has been generated by the spinning device 9, by the whirling airflow. Accordingly, the spun yarn 10 is caught without fail.

**[0066]** When the suction pipe 44 catches the upper yarn, by swinging the suction pipe 44 downward while continuing sucking the spun yarn 10, the unit controller 60 pulls out the spun yarn 10 from the spinning device 9 and guides the spun yarn 10 to the splicer 43 (step S109). Further, although in a flowchart of Fig. 7, a process in which the lower yarn is caught (step S104 and step S105) is first carried out and then a process in which the upper yarn is caught (step S106 through step S109) is carried out, the flowchart just illustrates an example of operations. That is, it is possible to catch the upper yarn first and then to catch the lower yarn at the same time.

[0067] When the spun yarn 10 is guided to the splicer 43 is completed, the spun yarn 10 between the spinning device 9 and the suction pipe 44 is engaged with the flyer 38, and then starts being wound around the yarn accumulating roller 21. Meanwhile, although the winding operation performed by the winding device 13 is stopped during the yarn splicing operation, since the spun yarn 10 is fed continuously from the spinning device 9 even in such a stopped state, slackening of the spun yarn 10 is generated if the spun yarn 10 is left untouched. However, by winding the spun yarn 10 around the yarn accumulating roller 21, the slackening of the spun yarn 10 is prevented. As described above, the yarn accumulating device 12 functions as a yarn slack eliminating device during the yarn splicing operation. After this time, as an accumulated amount of yarn on the yarn accumulating roller 21 increases, force to pull the spun yarn 10 from the spinning device 9 also increases.

**[0068]** Meanwhile, as described above, until at least the minimum accumulated amount of the spun yarn 10 is accumulated on the yarn accumulating roller 21, slipping is likely to be generated between the yarn accumulating roller 21 and the spun yarn 10, and the force to pull the spun yarn 10 is unstable. Accordingly, the spun yarn 10, which has been pulled out from the spinning device 9 until a sufficient amount of the spun yarn 10 (the minimum accumulated amount of the spun yarn 10) is accumulated on the yarn accumulating roller 21, includes many portions where yarn strength is low; namely, there are many yarn portions with unstable yarn quality.

**[0069]** Further, in a conventional spinning machine, immediately after the suction pipe 44 guided a yarn end to the splicer 43, a splicing operation performed by the splicer 43 started. The splicing operation is an operation,

<sup>10</sup> in which the upper yarn and the lower yarn located at a predetermined position are cut off, untwisted, and twisted, and a plurality of the spun yarn 10 is actually twisted and spliced together. When the splicing operation is performed at the above-described timing, since there are the unstable varn portions on the varn accumulating roller.

the unstable yarn portions on the yarn accumulating roller
 21 as described above, such unstable yarn portions are
 wound into the package 45.

[0070] Then, for preventing such unstable yarn portions from being mixed into the package 45, the spinning
 frame 1 according to the present embodiment is configured as follows.

**[0071]** First, even after the upper yarn is guided to the splicer 43 by the suction pipe 44, the unit controller 60 does not start performing the splicing operation immedi-

ately. By monitoring the accumulated amount of yarn on the yarn accumulating roller 21 by the accumulated amount sensor 27, the unit controller 60 determines whether or not the accumulated amount of yarn on the yarn accumulating roller 21 reaches the minimum accumulated amount based on a monitoring result of the accumulated amount sensor 27 (step S110). When the ac-

cumulated amount sensel 27 (step 0 110). When the accumulated amount of yarn does not reach the minimum accumulated amount, by keeping the yarn removing lever 28 located at the lowered position, the spun yarn 10 is

wound by the yarn accumulating roller 21. Accordingly, the accumulated amount of yarn increases. Meanwhile, when the accumulated amount sensor 27 detects that the accumulated amount of yarn reaches at least the minimum accumulated amount, the unit controller 60 stops
the whirling airflow generated through the twisting nozzle 67 (step S111). Then, the unit controller 60 controls the pneumatic cylinder 49 to be elevated so as to move the yarn removing lever 28 up to the elevated position (step S112), and removes the spun yarn 10 from the flyer 38.

45 [0072] At this point of time, since the spun yarn 10 is subjected to drag force upward in a substantially vertical direction (in an upper side in Fig. 11) by making contact with the yarn removing lever 28, friction is generated at such a contact portion. The stronger the force to pull the 50 spun yarn 10 is, the larger such drag force is and also the higher a possibility of occurrence of a yarn breakage is. Further, when whirling airflow is generated through the suction pipe 44, since the spun yarn 10 follows such whirling airflow, suction airflow acts on the spun yarn 10 55 effectively. Accordingly, the force to pull the spun yarn 10 becomes strong. As described above, the yarn breakage may occur by elevating the yarn removing lever 28. However, in the present embodiment, by stopping the

whirling airflow generated through the suction pipe 44 before the spun yarn 10 makes contact with the yarn removing lever 28, drag force of the whirling airflow and friction force accompanying such drag force are reduced and the yarn breakage is prevented.

**[0073]** When the spun yarn 10 is removed from the flyer 38 under a state in which the yarn accumulating roller 21 rotates, the resistance force which acts so as to prevent the spun yarn 10 from unwinding from the leading end portion of the yarn accumulating roller 21, disappears. Consequently, the spun yarn 10 can be unwound from the yarn accumulating roller 21 even by weak suction force of the suction pipe 44 or the like. Accordingly, under the state illustrated in Fig. 11, the spun yarn 10 on the yarn accumulating roller 21 is unwound, and is sucked in the suction pipe 44. Therefore, the unstable spun yarn 10 on the yarn accumulating roller 21 can be removed through the suction pipe 44.

[0074] Further, when the yarn removing lever 28 is elevated, depending on how far the yarn accumulating roller 21 rotates, the slackening of the spun yarn 10 is generated at the leading end portion of the yarn accumulating roller 21. Then, when a portion with the slackening of the spun yarn 10 becomes long, the spun yarn 10 may be entangled with the flyer 38 or the like. Accordingly, it is necessary to eliminate the portion with the slackening of the spun yarn 10 immediately. However, in the present embodiment, the suction airflow is generated through the ejector nozzle 66, as well as the normal suction airflow is generated through the suction pipe 44. Consequently, strong suction action is generated. Therefore, the spun yarn 10 is sucked through the suction pipe 44 without slackening (before slackening). Meanwhile, at the base end of the yarn accumulating roller 21, the spun yarn 10 is newly wound around by rotation of the yarn accumulating roller 21. That is, since the spun yarn 10 is newly wound by the yarn accumulating roller 21 depending on how much of the spun yarn 10 the suction pipe 44 sucks, the accumulated amount of yarn is kept substantially constant.

**[0075]** Accordingly, while a state in which at least the minimum accumulated amount of the spun yarn 10 is accumulated on the yarn accumulated roller 21 is being kept, the spun yarn 10 is pulled out from the spinning device 9. Consequently, it is possible to say that the spun yarn 10 which is newly wound around at the base end of the yarn accumulating roller 21 is stable in quality. Then, while the stable spun yarn 10 is being wound around from the base end of the yarn accumulating roller 21, since the unstable spun yarn 10 is unwound from the leading end of the yarn accumulating roller 21, the spun yarn 10 on the yarn accumulating roller 21 is sequentially replaced with the stable-quality spun yarn 10.

**[0076]** In the unit controller 60, a prescribed period of time, which is required to replace all of the spun yarn 10 on the yarn accumulating roller 21 with the stable-quality spun yarn 10 after the unstable spun yarn 10 starts being unwound by elevating the yarn removing lever 28 (i.e., a

period of time which is required to remove all of the unstable-quality spun yarn 10 from the yarn accumulating roller 21), is input in advance. The unit controller 60 determines whether or not the prescribed period of time has elapsed (step S113). When the prescribed period of time has elapsed, the unit controller 60 stops the suction air-

flow generated through the ejector nozzle 66 (step S114).
The unit controller 60 controls the pneumatic cylinder 49 to lower so as to control the yarn removing lever 28 to
lower (step S114). Then, the splicing operation per-

formed by the splicer 43 starts (step S115). [0077] Further, since the flyer 38 is engaged with the spun yarn 10 by lowering the yarn removing lever 28, the spun yarn 10 is not unwound from the leading end of the

yarn accumulating roller 21. Consequently, the spun yarn
can be prevented from slackening. Furthermore, as
described above, a yarn end of the upper yarn and a yarn
end of the lower yarn are untwisted, and then are spliced
by twisting both yarn ends together. In the present embodiment at this point of time, the whirling airflow gener-

ated through the twisting nozzles 67 is stopped before the upper yarn is guided to the splice 43 (more specifically, before a yarn removing operation is performed). Accordingly, since so many twists have not been applied

to the spun yarn 10 which is guided to the splicer 43, such an untwisting operation can be performed easily.
[0078] Further, even during the splicing operation performed by the splicer 43, the suction airflow is being generated through the suction mouth 46 and the suction pipe 44 and the spun yarn 10 is being sucked by the suction airflow. Then, in the middle of the splicing operation, the unnecessary spun yarn 10 is cut off by the splicer 43, and then is sucked and removed.

[0079] Then, when the splicing operation has been completed, the unit controller 60 restarts the winding operation of the spun yarn 10 performed by the winding device 13.

[0080] As described above, the spinning frame 1 according to the present embodiment includes the spinning 40 device 9, the yarn accumulating roller 21, the yarn hooking member 22, the yarn removing lever 28, the suction pipe 44, and the unit controller 60. The spinning device 9 generates the spun yarn 10 by applying twists to the fiber bundle 8. The yarn accumulating roller 21 is ar-45 ranged downstream of the spinning device 9 and temporarily accumulates the spun yarn 10 by winding the spun yarn 10 around the outer peripheral surface thereof while rotating. The yarn hooking member 22 can make contact with the spun yarn 10 and winds the spun yarn 10 around 50 the outer peripheral surface of the yarn accumulating roller 21 by rotating integrally with the yarn accumulating roller 21 while making contact with the spun yarn 10. The yarn removing lever 28 can remove the spun yarn 10 from the yarn hooking member 22. The suction pipe 44 55 is a device for sucking and catching a yarn end of the spun yarn 10. The suction pipe 44 includes the twisting nozzle 67 that can apply twists to the caught spun yarn 10. The unit controller 60 controls the twisting nozzle 67

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[0081] That is, the spun yarn 10 immediately after the spinning device 9 has started the spinning operation is not truly twisted since a process for preventing twists from being eliminated has not been carried out at a downstream side, and yarn strength of such spun yarn is weaker than yarn strength of normal spun yarn. However, by using the above-described structure, even when the spun yarn 10 with such weak yarn strength is sucked through the suction pipe 44, such weak yarn strength can be increased and the spun yarn 10 can be sucked by an another twists applying operation performed by the twisting nozzle 67. Consequently, the suction pipe 44 can keep catching and sucking the spun yarn 10 while preventing the yarn breakage appropriately. Further, if the twisting nozzle 67 is operating when the spun yarn 10 is removed from the yarn hooking member 22, the yarn breakage may occur since resistance force (friction force) at a portion making the yarn removing lever 28 into contact with the spun yarn 10 increases by force (suction force) generated by the twisting nozzle 67. However, according to the above-described structure, since a twisting operation of the twisting nozzle 67 is stopped before the spun yarn 10 starts being unwound from the yarn accumulating roller 21, the suction pipe 44 can be prevented from catching the spun yarn 10 excessively and the yarn breakage can be prevented. Further, when an amount of the spun yarn 10 on the yarn accumulating roller 21 is not sufficient, the spun yarn 10 cannot be stably pulled out from the spinning device 9 and quality of the spun yarn 10 may become unstable. However, according to the above-described structure, by accumulating the spun yarn 10 on the varn accumulating roller 21 first, by removing the spun yarn 10 from the yarn hooking member 22, and then by sucking the spun yarn 10 in the suction pipe 44 while unwinding the spun yarn 10 from the yarn accumulating roller 21, such a unstable-quality yarn portion of the spun yarn 10 can be removed.

**[0082]** In the spinning frame 1 according to the present embodiment, the suction pipe 44 includes the ejector nozzle 66 that can generate suction airflow directed towards a downstream side in a sucking direction. The ejector nozzle 66 is provided near the twisting nozzle 67. When the suction pipe 44 catches the spun yarn 10, the unit controller 60 controls the suction airflow to be generated through the ejector nozzle 66.

**[0083]** Accordingly, even when the suction opening 63 of the suction pipe 44 is away from the spun yarn 10 that should be sucked, by using the suction airflow generated through the ejector nozzle 66, the spun yarn 10 can be easily caught and sucked through the suction pipe 44.

**[0084]** Further, in the spinning frame 1 according to the present embodiment, while the spun yarn 10 is being

removed from the yarn hooking member 22 by the yarn removing lever 28, the control section 60 controls the suction airflow to be generated through the ejector nozzle 66.

<sup>5</sup> **[0085]** That is, when the suction airflow generated through the ejector nozzle 66 stops while the spun yarn 10 is being removed from the yarn hooking member 22, a speed at which the spun yarn 10 is sucked decreases. Accordingly, when a speed at which the spun yarn 10 is

<sup>10</sup> unwound is fast, the speed at which the spun yarn 10 is sucked through the suction pipe 44 does not catch up with the speed the spun yarn 10 is unwound. Consequently, the spun yarn 10 unwound from the yarn accumulating roller 21 may slacken. In this case, the slack-

ened spun yarn 10 is entangled with the flyer 38 or the like on the yarn accumulating roller 21. However, in the above-described structure, the spun yarn 10 is sucked through the suction pipe 44 before slackening by using the suction airflow generated through the ejector nozzle
66. Accordingly, entanglement of the spun yarn 10 can be prevented.

**[0086]** Further, the spinning frame 1 according to the present embodiment includes the splicer 43 that splices a yarn end of the spun yarn 10 at an upstream side with

<sup>25</sup> a yarn end of the spun yarn 10 at a downstream side.
The suction pipe 44 catches a yarn end of the spun yarn 10 and guides the yarn end to the splicer 43.

**[0087]** Accordingly, errors caused by the yarn breakage during the yarn splicing operation in the splicer 43 can be decreased, and operation efficiency in the spinning frame 1 can be improved.

**[0088]** Further, in the spinning frame 1 according to the present embodiment, the control section 60 stops the twisting operation of the twisting nozzle 67 before the splicer 43 starts the splicing operation.

[0089] Accordingly, since the twisting operation of the twisting nozzle 67 is stopped and then the splicing operation is performed, an influence of twists applied by the twisting nozzle 67 does not affect a portion where the plurality of the spun yarn 10 is spliced together. Therefore, the splicer 43 can eliminate twists of the spun yarn 10 and splice the plurality of the spun yarn 10 together easily.

**[0090]** While a preferred embodiment of the present invention has been described as above, the above-described structure can also be modified as follows, for example.

[0091] Although in the above-described embodiment, the yarn processing method applied during the yarn splic<sup>50</sup> ing operation when the yarn defect is detected has been described, a yarn processing method of the present invention can be applied not only when the yarn splicing operation is performed but also when the spun yarn 10 starts being wound around the yarn accumulating roller

<sup>55</sup> 21. For example, even when a doffing operation for changing the bobbin 48 is performed since the package 45 turns into a fully-wound package, the unstable spun yarn 10 can be discarded from the yarn accumulating

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roller 21 by the yarn processing method of the present invention.

**[0092]** Although the yarn removing lever 28 as a yarn removing section has a structure in which the yarn removing lever 28 swings around a shaft, a structure provided to the yarn removing lever 28 is not limited to the structure in which the yarn removing lever 28 swings around a shaft. For example, a structure in which the spun yarn 10 is removed from the yarn removing member 22 by controlling the yarn removing lever 28 to move back and forth in a parallel direction, may be provided.

**[0093]** Further, in place of a structure in which a dedicated member is provided as the yarn removing section, a structure in which the downstream guide 26 is arranged so as to be capable of moving forward and backward and the spun yarn 10 is removed from the yarn hooking member 22 by moving the downstream guide 26 forward, may be provided, for example.

**[0094]** In the above-described embodiment, although the yarn splicing cart 3, the pushing arm 47, and the pneumatic cylinder 49 are provided as a means that drives the yarn removing lever 28, a structure in which each spinning unit 2 drives the yarn removing lever 28 may be provided, for example. Further, in place of the pneumatic cylinder 49, for example, a structure in which an appropriate structure such as a rack and pinion mechanism or a cam mechanism moves the yarn removing lever 28, may be provided.

**[0095]** Further, in place of a structure in which the yarn splicing cart 3 performs the yarn splicing operation, each spinning unit 2 may include a structure for performing the yarn splicing operation.

**[0096]** A method of applying torque to between the yarn hooking member 22 and the yarn accumulating roller 21 is not limited to magnetic means as described <sup>35</sup> above. For example, friction force or an electromagnetic means may be provided.

**[0097]** A structure in which one ejector nozzle 66 and one twisting nozzle 67 are arranged, can be changed into a structure in which at least two ejector nozzle 66 and at least two twisting nozzle 67 are arranged, for example.

**[0098]** A position of the ejector nozzle 66 can be changed such that the ejector nozzle 66 is arranged at a suction opening 63 side of the twisting nozzle 67 (at an upstream side in a sucking direction).

#### Claims

 A yarn end catching device in a spinning machine, with a suction pipe (44) which sucks and catches a yarn end of a yarn (10) through a suction opening (63), the suction pipe (44) of the yarn end catching device comprising:

a suction passage (62) for sucking the yarn end; and

a twist applying member (67) which applies twists to the yarn sucked in the suction passage (62), **characterized in that** 

the yarn end catching device comprises an ejector nozzle (66) injecting compressed air into the suction passage (62) such that a suction airflow is generated, wherein

the suction pipe (44) is connected to a blower box (80) via a blower duct such that the suction pipe (44) is configured to generate another suction airflow different to the suction airflow generated by the ejector nozzle (66)

- 2. The yarn end catching device according to claim 1, characterized in that the twist applying member (67) is a twist applying nozzle (67) that forms whirling airflow in the suction passage (62) by injecting compressed air.
- 20 3. The yarn end catching device according to claim 2, characterized in that the suction passage (62) includes a first section (64) connected to the suction opening (63) and a second section (65) connected to a downstream side end of the first section (64) in a suction direction,

a cross-sectional area of a flow channel of the second section (65) is greater than a cross-sectional area of a flow channel of the first section (64), and an injection hole of the twist applying nozzle (67) is formed in the second section (65).

- 4. The yarn end catching device according to claim 2 or claim 3, characterized in that the ejector nozzle (66) injects compressed air towards a downstream side in the suction direction in the suction passage (62), and characterized in that in the suction direction, the twist applying nozzle (67) is arranged between the suction opening (63) and the ejector nozzle (66).
- 5. A spinning machine comprising:

a spinning device (9) that generates spun yarn by air-jet spinning and feeds the spun yarn from a spinning outlet (9a); and
a winding device (13) that forms a package by winding the spun yarn spun by the spinning device (9) around a bobbin,
characterized in that
spinning machine further comprises a yarn end catching device (44) according to any one of claim 1 through claim 4, wherein
the yarn end catching device (44) can directly suck the spun yarn fed from the spinning outlet

6. The spinning machine according to claim 5, characterized by further comprising a yarn splicing device

(9a) into the suction passage (62).

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(43) which splices spun yarn at the spinning device(9) and spun yarn at the package,

**characterized in that** the yarn end catching device (44) catches a yarn end of the spun yarn fed from the spinning device (9) and guides the yarn end to the yarn splicing device (43).

7. The spinning machine according to claim 5, **characterized by** further comprising a doffing device (61) which removes a fully-wound package from the winding device (13) and replaces with an empty bobbin so that the spun yarn can be wound around the empty bobbin,

**characterized in that** the yarn end catching device (44) catches a yarn end of the spun yarn fed from the spinning device (9) and guides the yarn end to the empty bobbin.

Method of operating a yarn end catching device in a spinning machine, with a suction pipe (44) which <sup>20</sup> sucks and catches a yarn end of a yarn (10) through a suction opening (63), the suction pipe (44) of the yarn end catching device comprising:

A suction passage (62) for sucking the yarn end <sup>25</sup> and a twist applying member (67) which twists the yarn sucked in the suction passage (62), **characterized in that** an ejector nozzle (66) injects compressed air into the suction passage (62) such that a suction airflow is generated, and <sup>30</sup> the suction pipe (44) generates another suction airflow different to the suction airflow generated by the ejector nozzle (66) .

**9.** Method according to claim 8, **characterized in that** <sup>35</sup> in the beginning of a splicing operation, when the yarn end is to be caught, as a first step, suction air is sucked through the suction pipe (44), then, as a second step, a twisting air flow is send through the twist applying member (67); and, <sup>40</sup>

as a third step, suction air is sucked through the ejector nozzle (66).

#### Patentansprüche

 Garnendefangeinrichtung in einer Spinnmaschine, mit einem Saugrohr (44), welches ein Garnende eines Garns (10) durch eine Saugöffnung (63) ansaugt und fängt, welches Saugrohr (44) der Garnendefangeinrichtung enthält:

> einen Saugkanal (62) zum Ansaugen des Garnendes; und

ein Drallgeberelement (67), das dem in den Saugkanal (62) angesaugten Garn einen Drall verleiht, **dadurch gekennzeichnet, dass** die Garnendefangeinrichtung eine Auswerfdüse (66) aufweist, die Druckluft in den Saugkanal (62) einbläst, so dass ein Saugluftstrom erzeugt wird, wobei

das Saugrohr (44) über einen Gebläsekanal mit einem Gebläsekasten (80) verbunden ist, so dass das Saugrohr (44) dafür konfiguriert ist, einen weiteren Saugluftstrom zu erzeugen, der von dem durch die Auswerfdüse (66) erzeugten Saugluftstrom verschieden ist.

- 2. Garnendefangeinrichtung nach Anspruch 1, dadurch gekennzeichnet, dass das Drallgeberelement (67) eine Drallgeberdüse (67) ist, die durch Einblasen von Druckluft einen Wirbelluftstrom in dem Saugkanal (62) bildet.
- 3. Garnendefangeinrichtung nach Anspruch 2, dadurch gekennzeichnet, dass der Saugkanal (62) einen ersten, mit der Saugöffnung (63) verbundenen Abschnitt (64) und einen zweiten, mit einem stromabwärtsseitigen Ende des ersten Abschnitts (64) in einer Saugrichtung verbundenen Abschnitt (65) enthält,

eine Querschnittsfläche eines Durchflusskanals des zweiten Abschnitts (65) größer ist als eine Querschnittsfläche eines Durchflusskanals des ersten Abschnitts (64), und

eine Einblasöffnung der Drallgeberdüse (67) in dem zweiten Abschnitt (65) gebildet ist.

- Garnendefangeinrichtung nach Anspruch 2 oder Anspruch 3, dadurch gekennzeichnet, dass die Auswerfdüse (66) Druckluft zu einer in Saugrichtung stromabwärts liegenden Seite gerichtet in den Saugkanal (62) einbläst, und dadurch gekennzeichnet, dass in der Saugrichtung die Drallgeberdüse (67) zwischen der Saugöffnung (63) und der Auswerfdüse (66) angeordnet ist.
- 5. Spinnmaschine, enthaltend:

eine Spinneinrichtung (9), die durch Luftspinnen Spinnfasergarn erzeugt und das Spinnfasergarn aus einem Spinnauslass (9a) zuliefert; und eine Spuleinrichtung (13), die durch Aufspulen des Spinnfasergarns von der Spinneinrichtung (9) um eine Spulhülse eine Auflaufspule bildet, **dadurch gekennzeichnet, dass** 

die Spinnmaschine ferner eine Garnendefangeinrichtung (44) gemäß einem beliebigen der Ansprüche 1 bis 4 enthält, wobei die Garnendefangeinrichtung (44) das von dem Spinnauslass (9a) zugelieferte Garn direkt in den Saugkanal (62) ansaugen kann.

 Spinnmaschine nach Anspruch 5, gekennzeichnet dadurch, dass sie ferner eine Garnspleißeinrichtung (43) aufweist, welche Spinnfasergarn an der

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Spinneinrichtung (9) und Spinnfasergarn an der Auflaufspule spleißt,

**dadurch gekennzeichnet, dass** die Garnendefangeinrichtung (44) ein Garnende des von der Spinneinrichtung (9) zugelieferten Spinnfasergarns fängt und das Garnende zu der Garnspleißeinrichtung (43) führt.

- 7. Spinnmaschine nach Anspruch 5, gekennzeichnet dadurch, dass sie ferner eine Abnehmeinrichtung <sup>10</sup> (61) aufweist, die eine voll bewickelte Auflaufspule von der Spuleinrichtung (13) entfernt und durch eine leere Spulhülse ersetzt, so dass das Spinnfasergarn um die leere Spulhülse gewickelt werden kann, dadurch gekennzeichnet, dass die Garnende-<sup>15</sup> fangeinrichtung (44) ein Garnende des von der Spinneinrichtung (9) zugelieferten Spinnfasergarns fängt und das Garnende zu der leeren Spulhülse führt.
- Verfahren für den Betrieb einer Garnendefangeinrichtung in einer Spinnmaschine, mit einem Saugrohr (44), welches ein Garnende eines Garns (10) durch eine Ansaugöffnung (63) ansaugt, wobei das Saugrohr (44) der Garnendefangeinrichtung enthält:

einen Saugkanal (62) zum Ansaugen des Garnendes und ein Drallgeberelement (67), welches dem in den Saugkanal (62) angesaugten Garn einen Drall verleiht,

dadurch gekennzeichnet, dass eine Auswerfdüse (66) Druckluft in den Saugkanal (62) einbläst, so dass ein Saugluftstrom erzeugt wird, und

das Saugrohr (44) einen weiteren Saugluftstrom <sup>35</sup>
erzeugt, der von dem durch die Auswerfdüse
(66) erzeugten Saugluftstrom verschieden ist.

9. Verfahren nach Anspruch 8, dadurch gekennzeichnet, dass am Beginn eines Spleißvorgangs, wenn das Garnende gefangen werden soll, als ein erster Schritt Saugluft durch das Saugrohr (44) gesaugt wird, dann, als ein zweiter Schritt, ein drehender Luftstrom durch das Drallgeberelement (67) geschickt wird; und

als ein dritter Schritt Saugluft durch die Auswerfdüse (66) gesaugt wird.

#### Revendications

 Dispositif de capture d'extrémité de fil dans une machine de filage, avec un tuyau d'aspiration (44) qui aspire et attrape une extrémité de fil d'un fil (10) à travers une ouverture d'aspiration (63), le tuyau d'aspiration (44) du dispositif de capture d'extrémité de fil comprenant : un passage d'aspiration (62) pour aspirer l'extrémité de fil ; et

un élément d'application de torsion (67) qui applique des torsions au fil aspiré dans le passage d'aspiration (62), **caractérisé en ce que** 

le dispositif de capture d'extrémité de fil comprend une buse d'éjecteur (66) injectant de l'air comprimé dans le passage d'aspiration (62) de sorte qu'un flux d'air d'aspiration est produit, dans lequel

le tuyau d'aspiration (44) est relié à une boîte de soufflage (80) via un conduit de soufflage de sorte que le tuyau d'aspiration (44) est configuré pour produire un autre flux d'air d'aspiration différent du flux d'air d'aspiration produit par la buse d'éjecteur (66).

- Dispositif de capture d'extrémité de fil selon la revendication 1, caractérisé en ce que l'élément d'application de torsion (67) est une buse d'application de torsion (67) qui forme un flux d'air tourbillonnant dans le passage d'aspiration (62) en injectant de l'air comprimé.
- Dispositif de capture d'extrémité de fil selon la revendication 2, caractérisé en ce que le passage d'aspiration (62) inclut une première section (64) reliée à l'ouverture d'aspiration (63) et une seconde section (65) reliée à une extrémité côté aval de la première section (64) dans un sens d'aspiration, une surface en coupe transversale d'un canal d'écoulement de la seconde section (65) est supérieure à une surface en coupe transversale d'un canal d'écoulement de la première section (64), et un trou d'injection de la buse d'application de torsion (67) est formé dans la seconde section (65).
  - 4. Dispositif de capture d'extrémité de fil selon la revendication 2 ou la revendication 3, caractérisé en ce que la buse d'éjecteur (66) injecte de l'air comprimé vers un côté aval dans le sens d'aspiration dans le passage d'aspiration (62), et caractérisé en ce que dans le sens d'aspiration, la buse d'application de torsion (67) est agencée entre l'ouverture d'aspiration (63) et la buse d'éjecteur (66).
  - 5. Machine de filage comprenant :

un dispositif de filage (9) qui produit un filé par filage à jet d'air et amène le filé à partir d'une sortie de filage (9a) ; et un dispositif d'enroulement (13) qui forme un rouleau en enroulant le filé, filé par le dispositif de filage (9) autour d'une bobine,

#### caractérisé en ce que

la machine de filage comprend en outre un dispositif de capture d'extrémité de fil (44) selon l'une quelconque des revendications 1 à 4, dans

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laquelle

le dispositif de capture d'extrémité de fil (44) peut directement aspirer le filé amené en provenance de la sortie de filage (9a) dans le passage d'aspiration (62).

- 6. Machine de filage selon la revendication 5, caractérisée en ce qu'elle comprend en outre un dispositif d'épissage de fil (43) qui épisse un filé au niveau du dispositif de filage (9) et un filé au niveau du rouleau, caractérisée en ce que le dispositif de capture d'extrémité de fil (44) attrape une extrémité de fil du filé amené en provenance du dispositif de filage (9) et guide l'extrémité de fil vers le dispositif d'épissage de fil (43).
- Machine de filage selon la revendication 5, caractérisée en ce qu'elle comprend en outre un dispositif de changement de rouleaux (61) qui enlève un rouleau entièrement enroulé du dispositif d'enroulement 20 (13) et le remplace par une bobine vide de sorte que le filé peut être enroulé autour de la bobine vide, caractérisée en ce que le dispositif de capture d'extrémité de fil (44) attrape une extrémité de fil du filé amené en provenance du dispositif de filage (9) et 25 guide l'extrémité de fil vers la bobine vide.
- Procédé de mise en oeuvre d'un dispositif de capture d'extrémité de fil dans une machine de filage, avec un tuyau d'aspiration (44) qui aspire et attrape une 30 extrémité de fil d'un fil (10) à travers une ouverture d'aspiration (63), le tuyau d'aspiration (44) du dispositif de capture d'extrémité de fil comprenant :

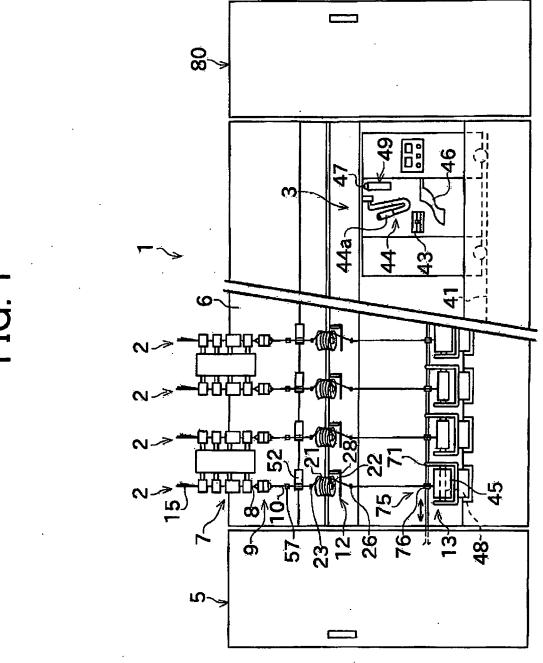
un passage d'aspiration (62) pour aspirer l'ex- <sup>35</sup> trémité de fil et un élément d'application de torsion (67) qui tord le fil aspiré dans le passage d'aspiration (62),

**caractérisé en ce qu'**une buse d'éjecteur (66) injecte de l'air comprimé dans le passage d'aspiration (62) de sorte qu'un flux d'air d'aspiration est produit, et

le tuyau d'aspiration (44) produit un autre flux d'air d'aspiration différent du flux d'air d'aspiration produit par la buse d'éjecteur (66).

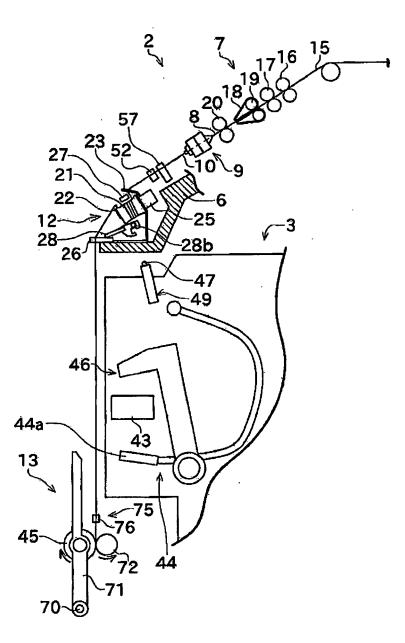
 Procédé selon la revendication 8, caractérisé en ce qu'au début d'une opération d'épissage, quand l'extrémité de fil doit être attrapée, en tant que première étape, de l'air d'aspiration est aspiré à travers le tuyau d'aspiration (44), ensuite, en tant que deuxième étape, un flux d'air de torsion est envoyé à travers l'élément d'application de torsion (67) ; et, en tant que troisième étape, de l'air d'aspiration est aspiré à travers la buse d'éjecteur (66).

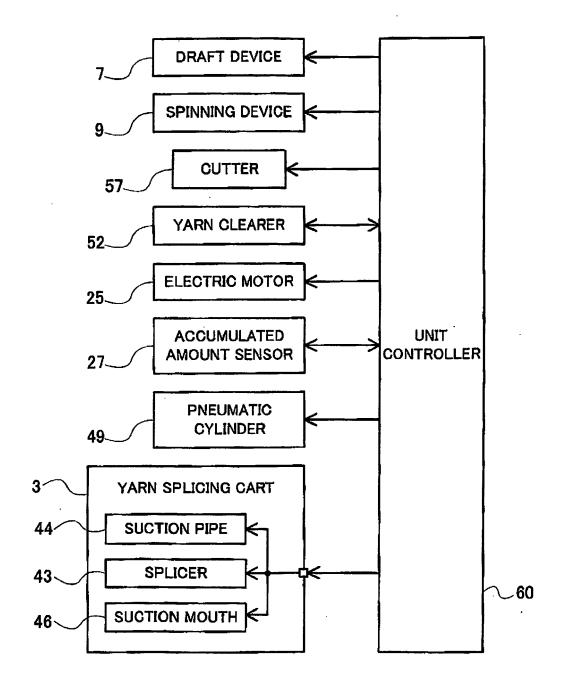
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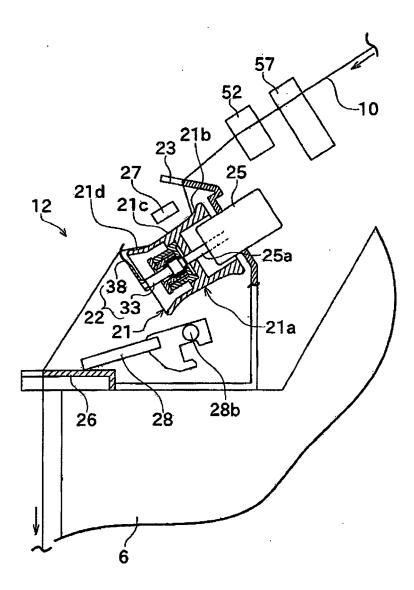


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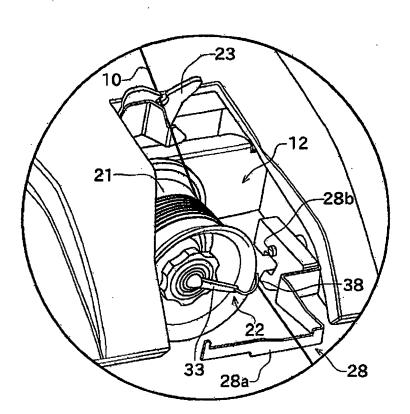


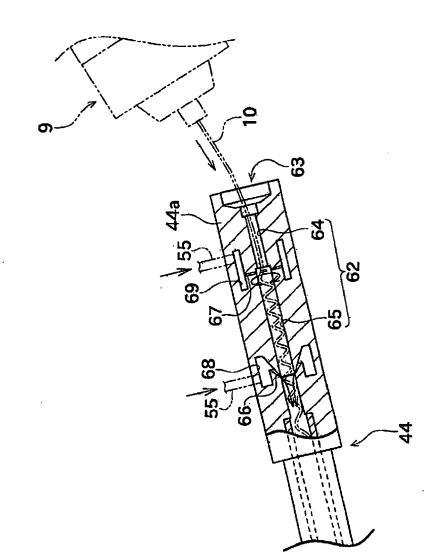


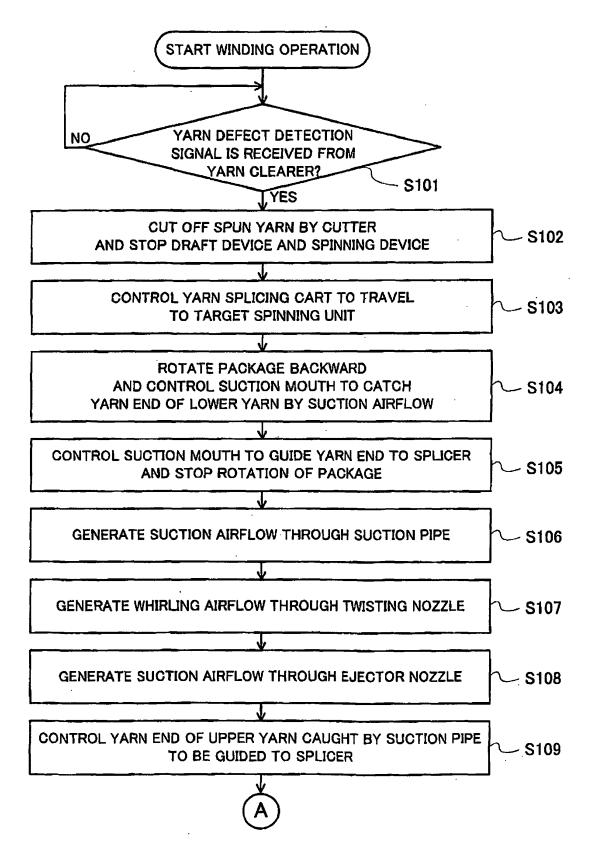
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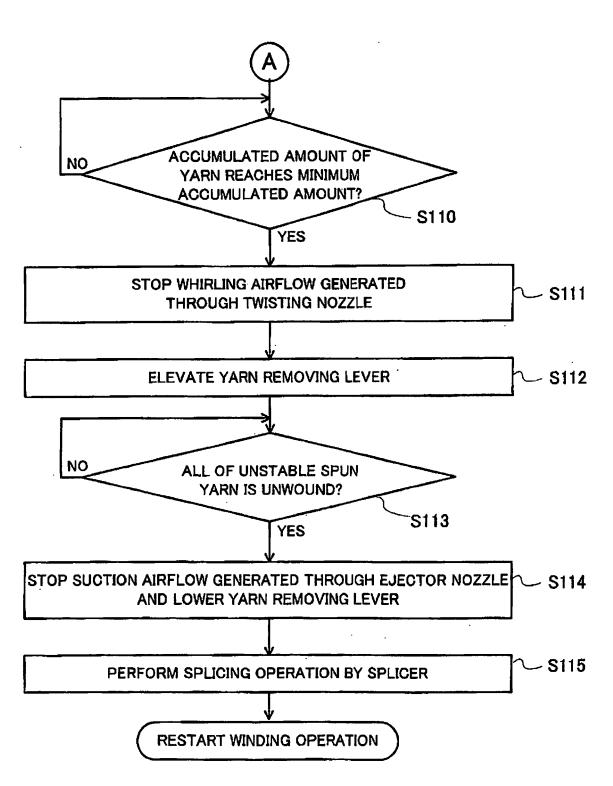
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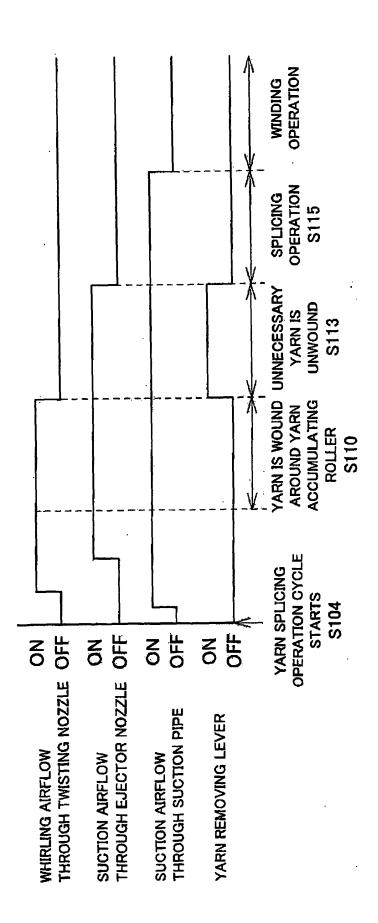






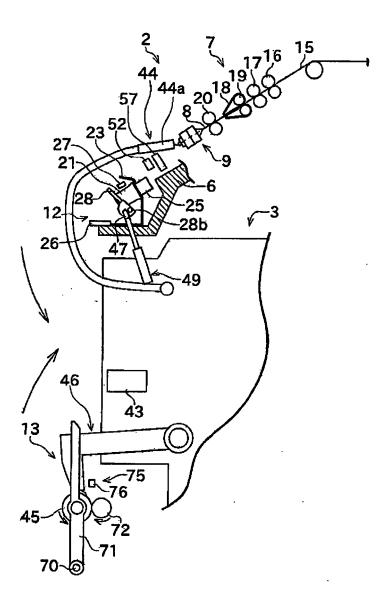




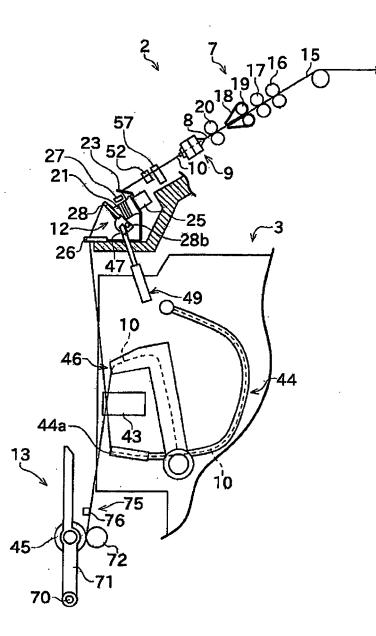




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#### **REFERENCES CITED IN THE DESCRIPTION**

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