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(54) **APPARATUS AND METHODS FOR MANUFACTURING OPERATIONS**

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(57) **ABSTRACT**

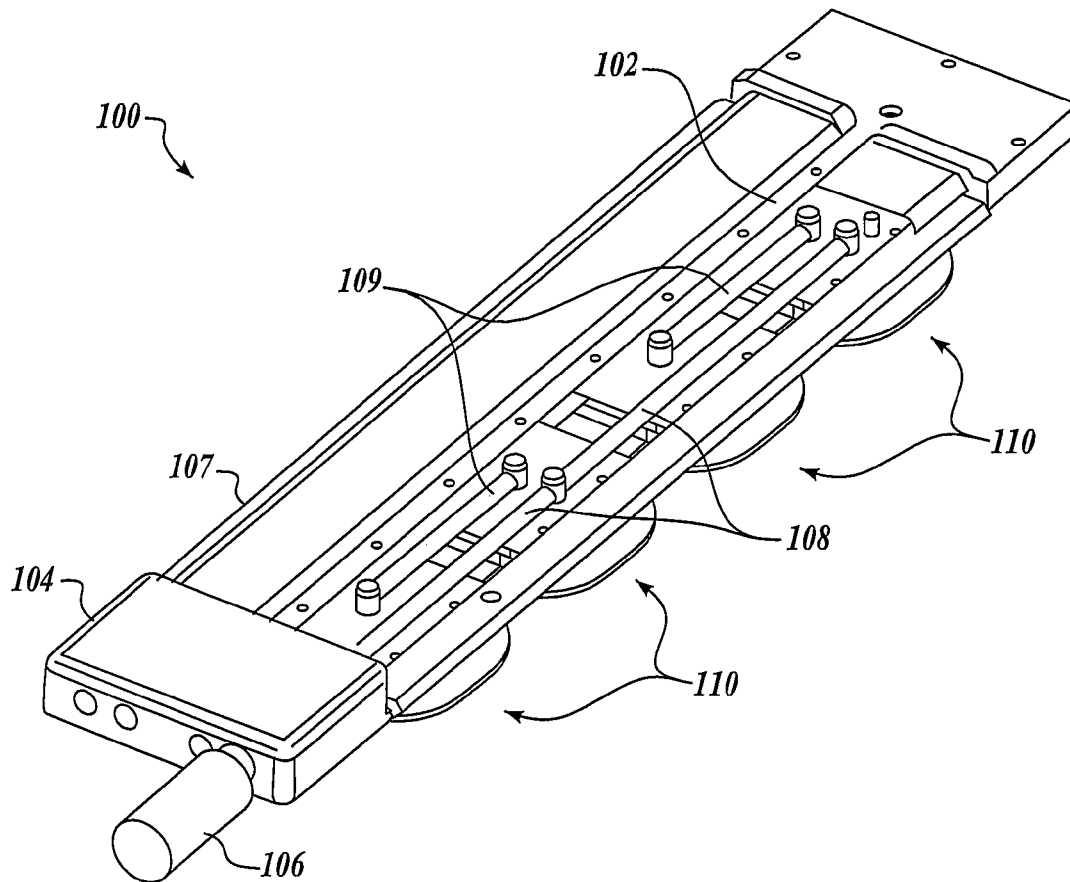
(21) Appl. No.: **12/145,662**

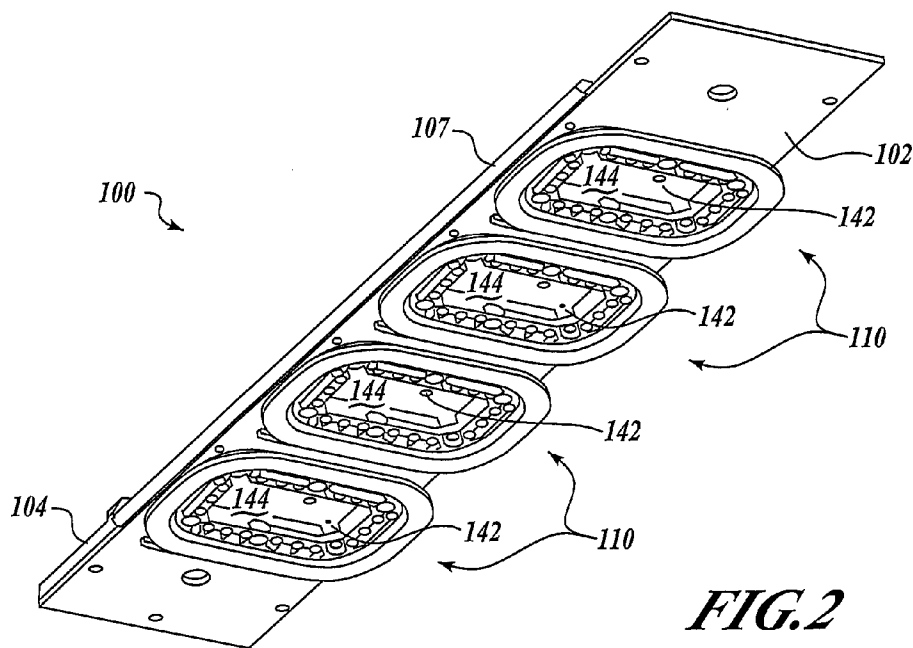
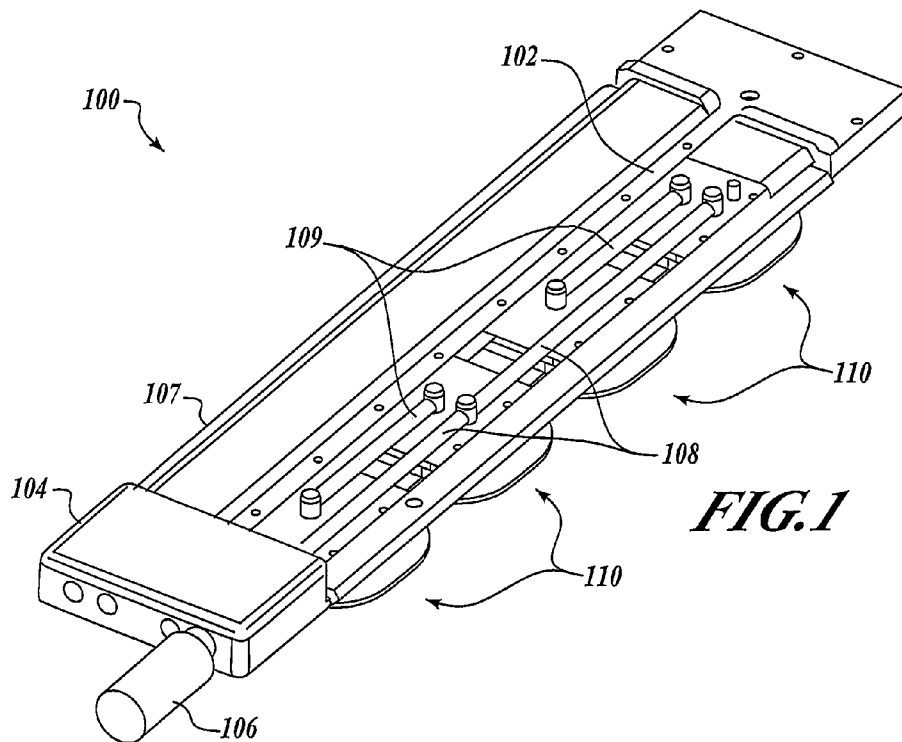
(22) Filed: **Jun. 25, 2008**

Techniques of performing a manufacturing operation on a workpiece are disclosed. In one embodiment, a method includes forming an indexing hole in the workpiece. A coordinating pin may be installed into the indexing hole, the coordinating pin including a quantum of indexing information. A sensor may be positioned proximate the coordinating pin. The quantum of indexing information may be sensed with a sensor. A manufacturing operation may be performed on the workpiece based at least partially on the quantum of indexing information.

Related U.S. Application Data

(62) Division of application No. 10/903,713, filed on Jul. 30, 2004, now Pat. No. 7,406,758.





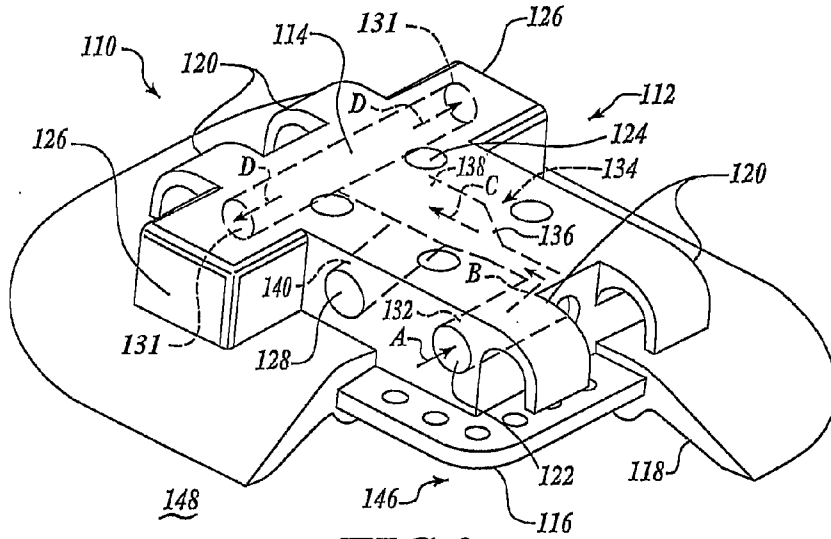


FIG. 3

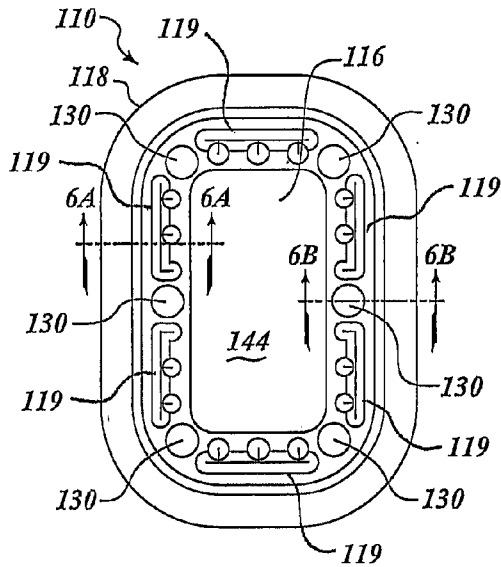


FIG. 4

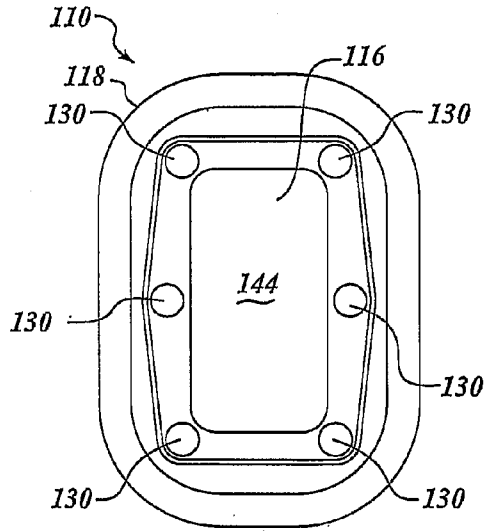


FIG. 5

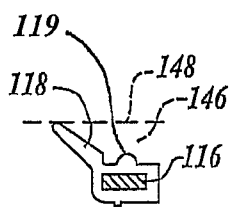


FIG. 6A

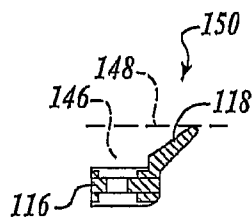


FIG. 6B

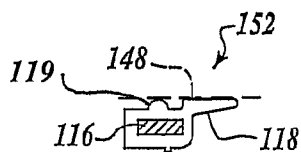


FIG. 6C

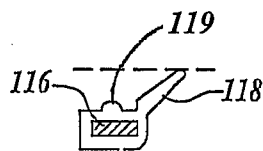


FIG. 6D

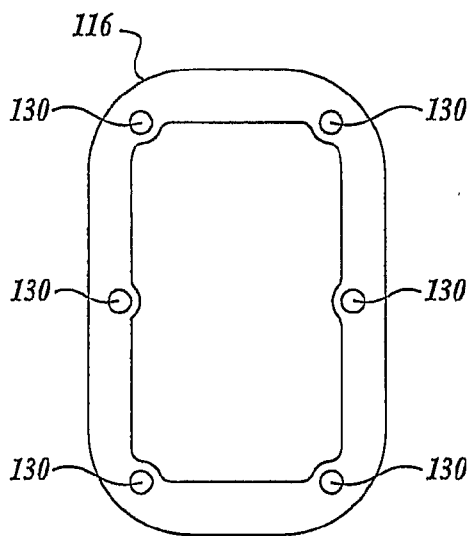


FIG. 7

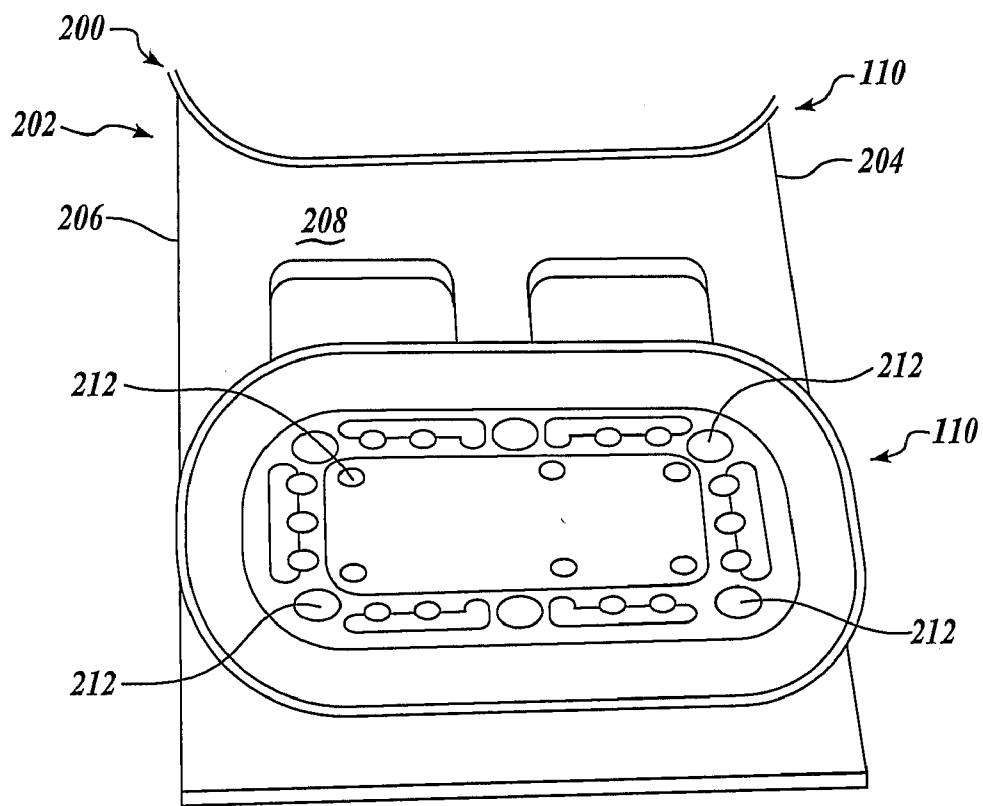


FIG. 8

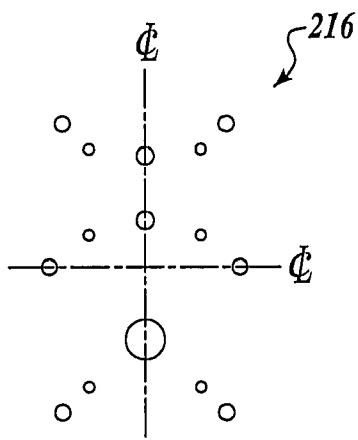


FIG. 9

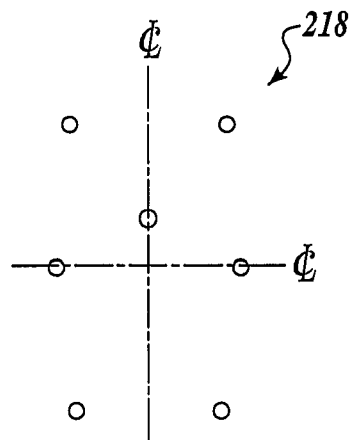


FIG. 10

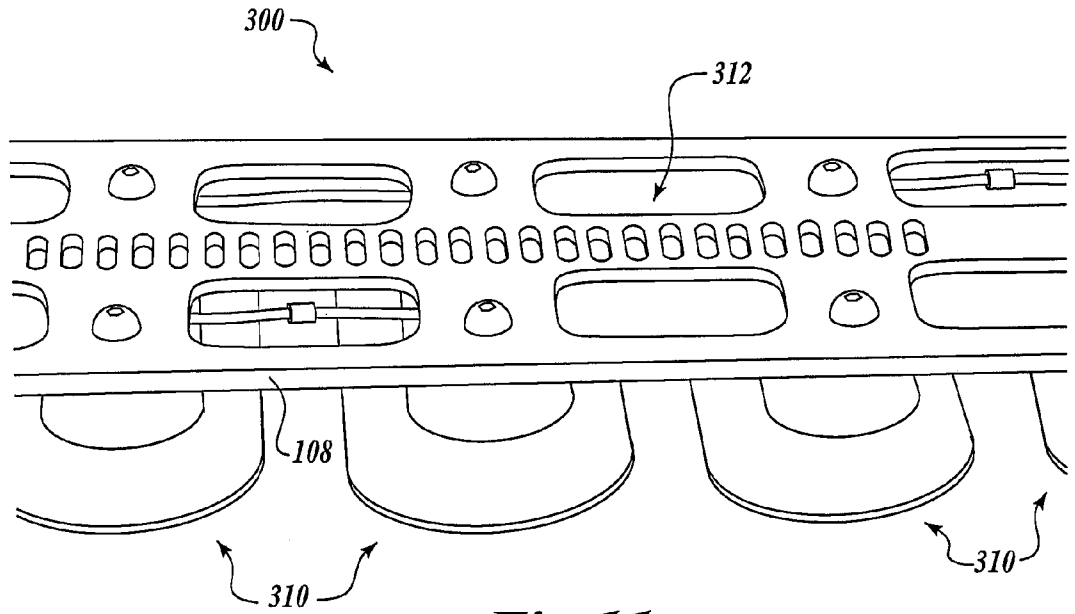


Fig. 11

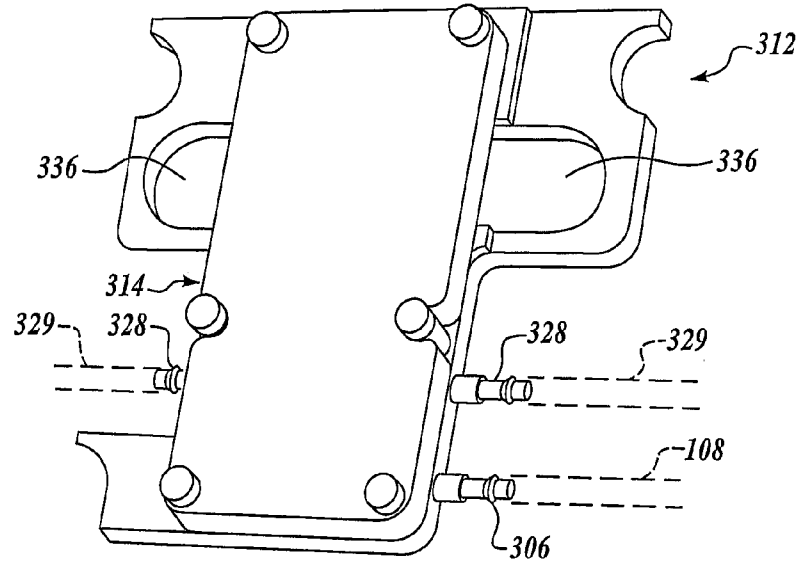


Fig. 12

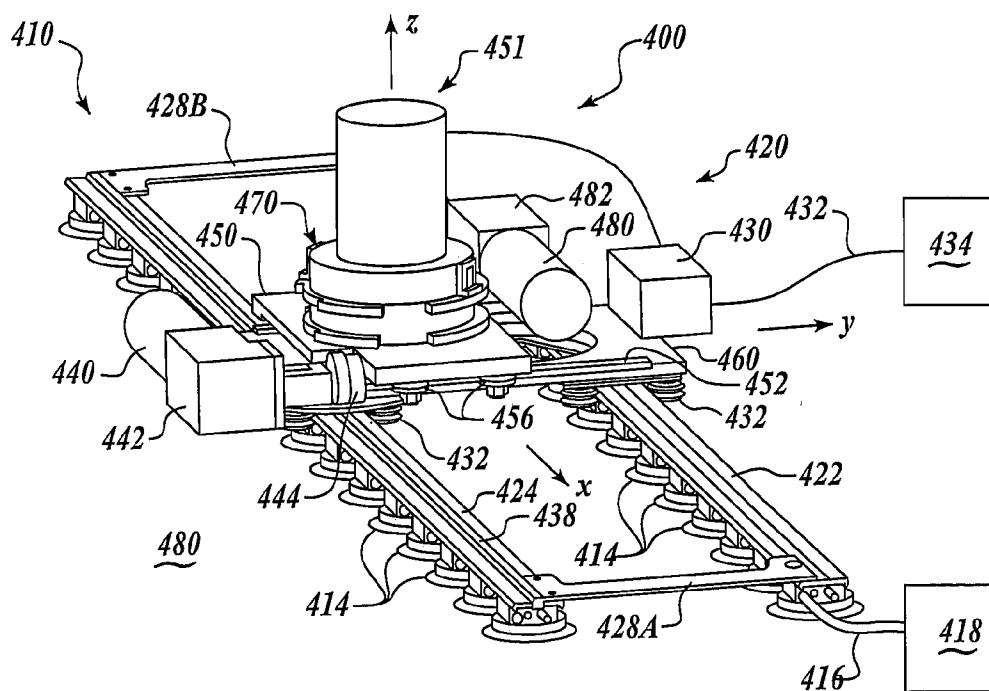


Fig. 13

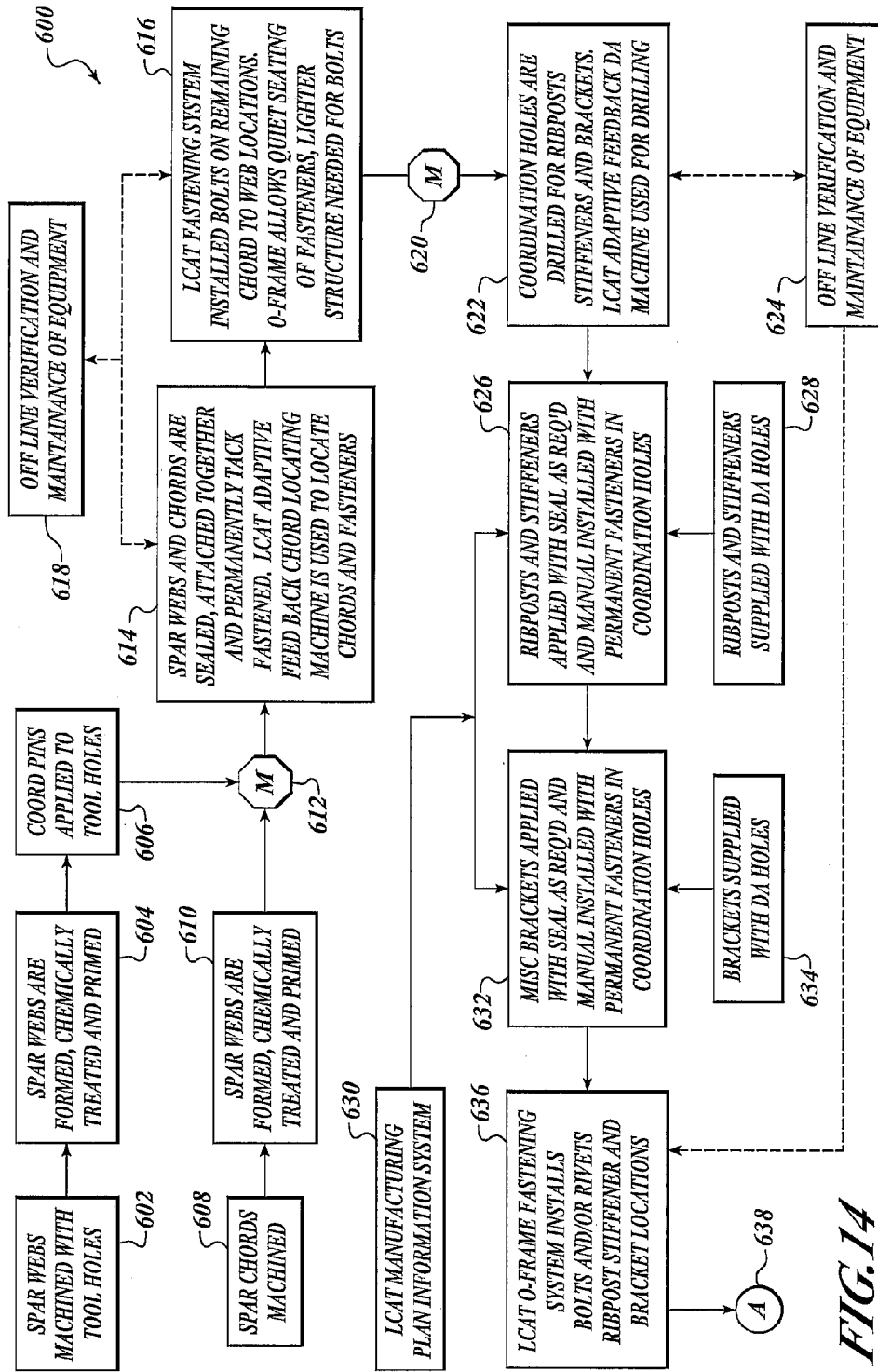


FIG. 14

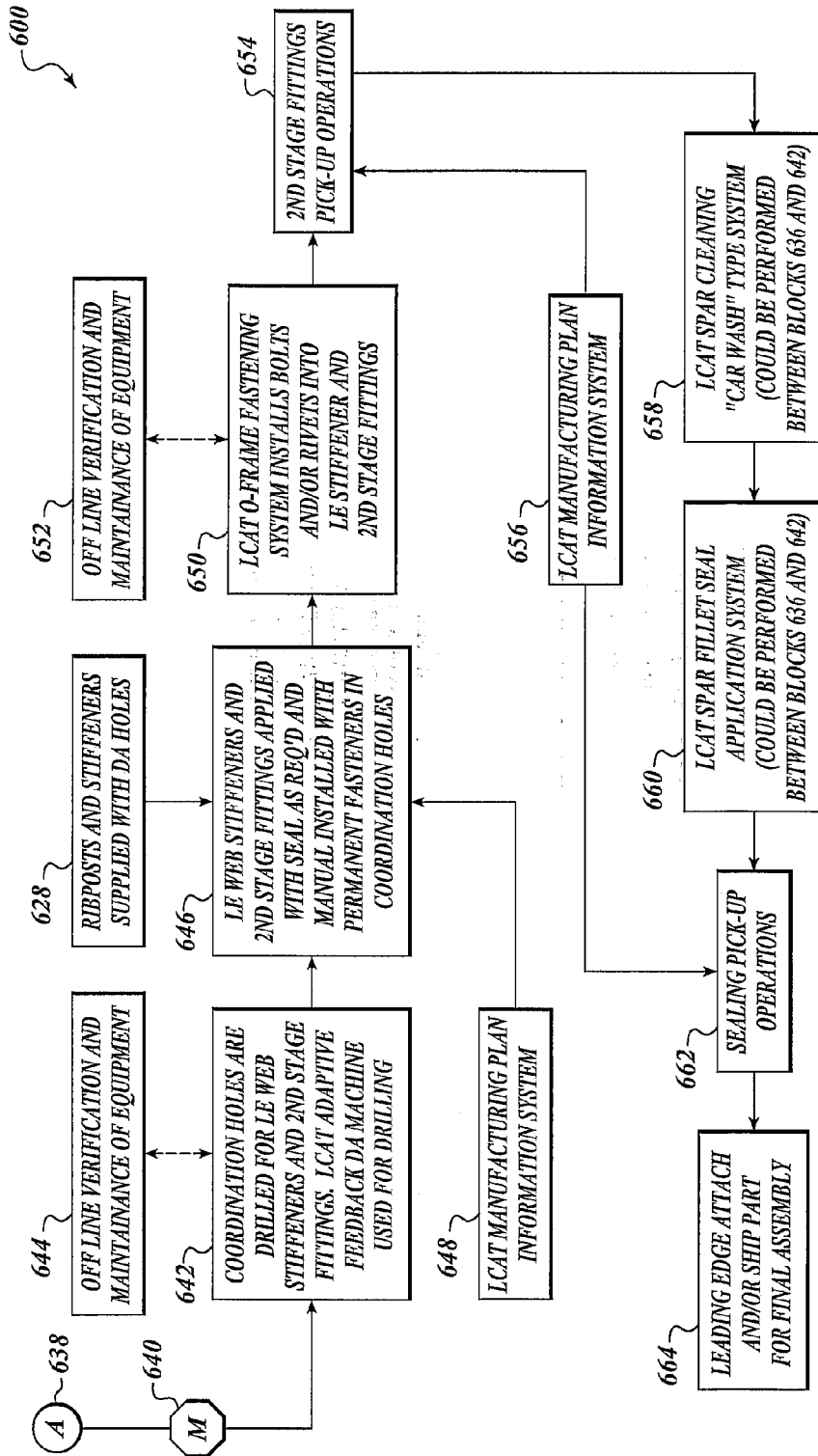
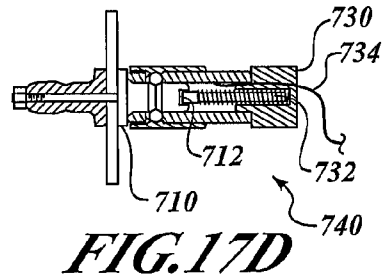
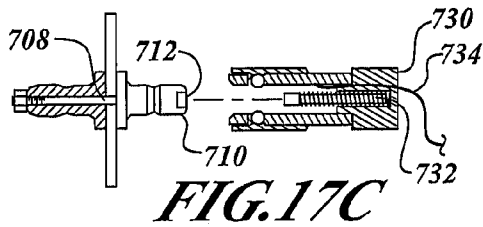
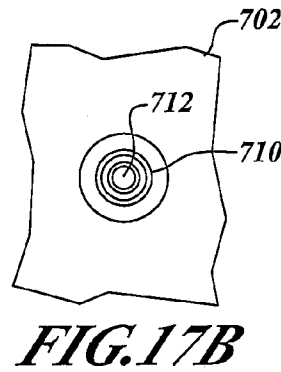
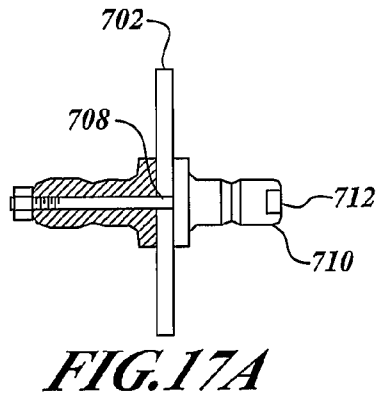
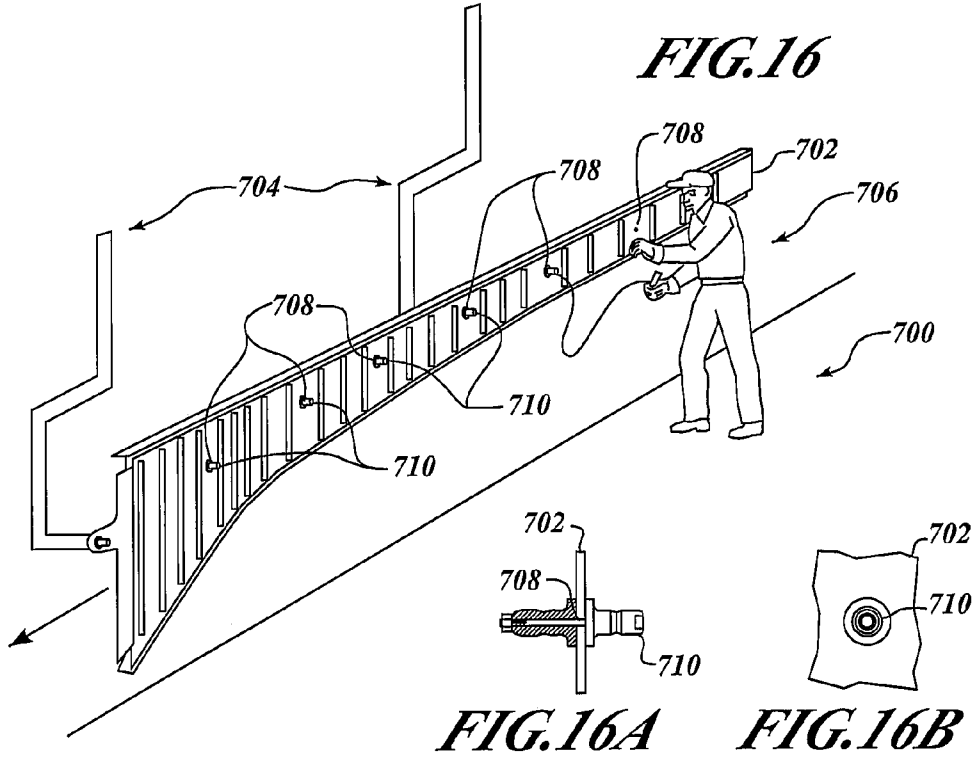


FIG.15



APPARATUS AND METHODS FOR MANUFACTURING OPERATIONS

CROSS REFERENCE TO RELATED APPLICATIONS

[0001] This patent application is a divisional application of co-pending, commonly-owned U.S. patent application Ser. No. 10/903,713 entitled "Apparatus and Methods for Manufacturing Operations" filed on Jul. 30, 2004, which claims priority from U.S. Provisional Application Ser. No. 60/500,863, filed Sep. 5, 2003, which applications are incorporated herein by reference.

TECHNICAL FIELD

[0002] The present disclosure relates to apparatus and methods for manufacturing operations, and more specifically, to manufacturing operations employing vacuum devices, and to manufacturing operations that employ an indexing system based on pin locations.

BACKGROUND

[0003] Manufacturing operations in many fields typically require accurate positioning of manufacturing tools over a workpiece. The manufacturing environment and the structural details of the workpiece often make it difficult to properly position the manufacturing tool relative to the workpiece to achieve the desired manufacturing operation with the necessary degree of accuracy. This is particularly true in the field of aircraft manufacturing, wherein a large number of manufacturing operations are typically needed on a variety of contoured surfaces. Similar difficulties may be encountered, for example, in the manufacture of ships, railcars, missiles, sheet metal buildings, and other similar structures.

[0004] It is known that a support assembly that supports a manufacturing tool may be temporarily attached to a surface of the workpiece in order to facilitate manufacturing operations on the workpiece. Some conventional support assemblies utilize one or more elongated rails equipped with vacuum cup assemblies for temporarily attaching the support assembly to the workpiece, including, for example, those assemblies generally disclosed in U.S. Pat. No. 6,467,385 B1 issued to Buttrick et al., and U.S. Pat. No. 6,210,084 B1 issued to Banks et al. In such conventional support assemblies, the rails may be coupled to the workpiece using the vacuum cup assemblies over a desired section of the workpiece, and then a manufacturing tool may be mounted on a carriage that is moveable along the rails. The carriage may then be traversed along the rails in a manual or automated fashion, and the desired manufacturing operations may be performed.

[0005] Vacuum for the vacuum cup assemblies of such conventional support assemblies is typically generated externally from the point-of-use, such as by a vacuum pump or other suitable source. The vacuum is then routed to each vacuum cup assembly by one or more vacuum lines. In order to isolate one vacuum circuit from another it is usually necessary to run separate, multiple lines to each vacuum cup assembly, or incorporate a valve network to isolate one line from another. Because the pressure differential along the length of each vacuum line is at most one atmosphere, care must be taken to avoid line losses which may degrade the degree of vacuum provided to the vacuum cup assemblies. One conventional approach to solving this line-loss problem

is to provide a portable vacuum pump that may be transported along with the vacuum assembly in order to reduce the lengths of the vacuum lines between the vacuum pump and the vacuum cup assemblies.

[0006] Traditional hard tooling and indexing systems for large-scale manufacturing operations typically involve the construction of large, "monument like" equipment that provides support and indexing during manufacturing operations on a workpiece. Such structures are typically very expensive to design, build, and maintain. For example, the tooling for a new airplane manufacturing operation may comprise a substantial percentage of the initial investment cost of the manufacturing facilities needed to produce the aircraft.

[0007] Although desirable results have been achieved using the prior art manufacturing methods and apparatus, there is still room for improvement. Namely, it may yet be possible to improve the operating efficiency, cost, and performance of such manufacturing operations.

SUMMARY

[0008] The present disclosure is directed to methods for manufacturing operations, and more specifically, to manufacturing operations employing vacuum devices, and to manufacturing operations that employ an indexing system based on pin locations. Methods in accordance with the present disclosure may advantageously improve the efficiency, throughput, and accuracy of manufacturing operations on a workpiece.

[0009] In one embodiment, a method includes forming an indexing hole in the workpiece. A coordinating pin may be installed into the indexing hole, the coordinating pin including a quantum of indexing information. A sensor may be positioned proximate the coordinating pin. The quantum of indexing information may be sensed with a sensor. A manufacturing operation may be performed on the workpiece based at least partially on the quantum of indexing information.

BRIEF DESCRIPTION OF THE DRAWINGS

[0010] The preferred and alternative embodiments of the present disclosure are described in detail below with reference to the following drawings.

[0011] FIG. 1 is an upper isometric view of a vacuum support assembly having a plurality of vacuum cup assemblies in accordance with an embodiment of the disclosure;

[0012] FIG. 2 is a lower isometric view of the vacuum support assembly of FIG. 1;

[0013] FIG. 3 is an upper isometric, partial cross-sectional view of a vacuum cup assembly in accordance with an embodiment of the disclosure;

[0014] FIG. 4 is a top elevational view of a retaining plate and a sealing member of the vacuum cup assembly of FIG. 3;

[0015] FIG. 5 is a bottom elevational view of the retaining plate and the sealing member of FIG. 4;

[0016] FIGS. 6A-D show partial cross-sectional views of the retaining plate and the sealing member of FIG. 4;

[0017] FIG. 7 is a top elevational view of a retaining plate of the vacuum cup assembly of FIG. 4;

[0018] FIG. 8 is a lower isometric view of a rail assembly including a plurality of vacuum cup assemblies in accordance with an alternate embodiment of the disclosure;

[0019] FIG. 9 is a schematic view of a first hole pattern in a rail member in accordance with an embodiment of the disclosure;

[0020] FIG. 10 is a schematic view of a second hole pattern in a rail member in accordance with an embodiment of the disclosure;

[0021] FIG. 11 is an upper isometric view of a rail assembly including a plurality of vacuum cup assemblies in accordance with another embodiment of the disclosure;

[0022] FIG. 12 is an isometric view of a vacuum generator of FIG. 11;

[0023] FIG. 13 is an isometric view of a representative manufacturing assembly in accordance with yet another embodiment of the disclosure;

[0024] FIG. 14 is a flow chart of a first portion of a manufacturing process in accordance with an embodiment of the disclosure;

[0025] FIG. 15 is a flow chart of a second portion of a manufacturing process in accordance with an embodiment of the disclosure;

[0026] FIG. 16 is an isometric view of a manufacturing operation in accordance with yet another embodiment of the disclosure; and

[0027] FIGS. 16A, 16B and 17A-17D show enlarged, partial cross-sectional and end elevational views of a coordinate pin of FIG. 16, and a coordinate pin reader, in accordance with another embodiment of the disclosure.

DETAILED DESCRIPTION

[0028] The present disclosure relates to apparatus and methods for manufacturing operations, and more specifically, to manufacturing operations employing vacuum devices, and to manufacturing operations that employ an indexing system based on pin locations. Many specific details of certain embodiments of the disclosure are set forth in the following description and in FIGS. 1-17 to provide a thorough understanding of such embodiments. One skilled in the art, however, will understand that the present disclosure may have additional embodiments, or that the present disclosure may be practiced without several of the details described in the following description.

[0029] FIGS. 1 and 2 are upper and lower isometric views, respectively, of a vacuum support assembly 100 having a plurality of vacuum cup assemblies 110 in accordance with an embodiment of the disclosure. In this embodiment, the vacuum support assembly 100 includes a rack 102 to which the vacuum cup assemblies 110 are attached. An intake manifold 104 having an intake port 106 is mounted at a first end of the rack 102. A cover (or muffler) 107 extends along the length of the rack 102, as described more fully below. An air supply line 108 extends from the manifold 104 to one or more of the vacuum cup assemblies 110. Similarly, vacuum lines 109 extend between adjacent vacuum cup assemblies 110.

[0030] FIG. 3 is an upper isometric, partial cross-sectional view of a vacuum cup assembly 110 in accordance with an embodiment of the disclosure. In this embodiment, the vacuum cup assembly 110 includes a vacuum generator 112 having a housing 114 with a retaining plate 116 coupled to a sealing member 118. The housing 114 includes a pair of tube clips 120 extending from opposing ends thereof, and a plurality of attachment holes 124 (four shown) are disposed in the housing 114 to facilitate the attachment of the housing 114 to the rack 102 (e.g. by bolts or other suitable attachment members). An air supply port 122 is disposed in the housing 114 and is fluidly coupled to a high pressure portion 132 of an internal flow duct 134 (shown in phantom lines) disposed through the housing 114. In this embodiment, the high pres-

sure portion 132 of the internal flow duct 134 leads to a venturi portion 136, and then to a low pressure portion 138. Finally, the internal flow duct 134 exits the housing 114 at a pair of exhaust ports 131 (shown in phantom lines). The housing 114 includes a pair of outwardly-depending exhaust mufflers 126 that at least partially shroud the air exhaust ports 131. Finally, an auxiliary vacuum port 128 is disposed in the housing 114 and is coupled by an auxiliary flow duct 140 (shown in phantom lines) to the low pressure portion 138 of the internal flow duct 114.

[0031] It will be appreciated that any suitable fluid medium may be used to operate the vacuum cup assemblies 110, and that the present disclosure is not limited to air as the operating fluid medium. For the sake of simplicity, however, throughout the following description, the term air will be used to refer to the operating fluid medium.

[0032] FIGS. 4 and 5 are top and bottom elevational views, respectively, of the retaining plate 116 and the sealing member 118 of the vacuum cup assembly 110 of FIG. 3. FIG. 6 shows various partial cross-sectional views of the retaining plate 116 and the sealing member 118 of FIG. 4. FIG. 7 is a top elevational view of the retaining plate 116 of FIG. 4. As best shown in FIGS. 5 and 7, a plurality of coupling apertures 130 are disposed through the retaining plate 116 for coupling the retaining plate 116 (and the sealing member 118) to the housing 114 using fasteners (not shown).

[0033] In operation, a source of pressurized air is coupled to the intake port 106 of the vacuum support assembly 110. The pressurized air passed into the intake manifold 104 and then through the air line 108 to one or more of the vacuum cup assemblies 110. At the vacuum cup assembly 110, the pressurized air enters the air supply port 122 of the vacuum generator 112 (see arrow A) and passes through the high pressure portion 132 (see arrow B) of the internal flow duct 134. The pressurized air then expands through the venturi portion 136 and into the low pressure portion 138 (see arrow C) of the internal flow duct 134. The expanded air is exhausted from the internal flow duct 134 via the exhaust ports 130 (see arrows D) into the surrounding environment.

[0034] As best shown in FIG. 2, one or more vacuum ports 142 are disposed in a bottom surface 144 of the vacuum generator 112 and provide fluid communication between the low pressure portion 138 of the internal flow duct 134 and a suction chamber 146 formed between the vacuum cup assembly 110 and a workpiece 148 (see FIG. 3). As the pressurized air is expanded through the venturi portion 136, the low pressure portion 138, the exhaust ducts 130, and the suction chamber 146 formed between the vacuum cup assembly 110 and the workpiece 148 is exhausted (i.e. the pressure within the suction chamber 146 drops). As shown in FIG. 6, the sealing member 118 is flexible and bends from an initial non-deflected position 150 (FIG. 6(B)) prior to the reduction of pressure within the suction chamber 146, to a deflected position 152 (FIG. 6(C)) substantially in alignment with a foot 119 as the pressure within the suction chamber 146 is reduced and the vacuum cup assembly 110 is drawn closer to the workpiece 148. Thus, the plurality of vacuum cup assemblies 110 adhere to the workpiece 148 and support the vacuum support assembly 100 in a desired position on the workpiece 148.

[0035] It will be appreciated that a variety of different vacuum generator 112 configurations may be conceived, and that the vacuum generator is not limited to the particular configuration described above and shown in the accompany-

ing figures. It will also be appreciated that the vacuum generator may be at least partially fabricated from known, conventional vacuum generators **112**, including, for example, those vacuum generators offered as model number X5 vacuum generators by PIAB, Inc. of Hingham, Mass.

[0036] The vacuum cup assemblies **110** may provide several advantages over prior art vacuum cup assemblies. For example, because the vacuum cup assemblies **110** rely on pressurized air which is used to form the necessary pressure drop within the suction chamber **146** locally at each vacuum cup assembly **110**, the vacuum support assembly **100** is far less sensitive to pressure losses than prior art assemblies. In contrast to such prior art assemblies, in which the maximum pressure differential along a vacuum line leading from a vacuum source to each vacuum cup assembly is one atmosphere (at most), in the vacuum support apparatus **100**, the pressure differential along the air lines **108** leading to the vacuum cup assemblies **110** can be far greater than one atmosphere. Thus, the energy that can be transferred from the point of generation to the point of use through a given size of tube is far greater in embodiments of the present disclosure than in prior art assemblies. As a result, in positive pressure systems in accordance with the present disclosure, because the necessary vacuum can be generated at the vacuum cup assembly more efficiently than in the prior art vacuum-based systems, the apparatus in accordance with the present disclosure may operate more efficiently than comparable prior art systems. Also, because of the improved operational efficiencies, embodiments of the present disclosure may utilize relatively smaller, less bulky components (e.g. smaller diameter tubes), enabling vacuum support assemblies **100** in accordance with the present disclosure to be used in a wider variety of applications.

[0037] Furthermore, embodiments of vacuum support assemblies may be more robust and reliable in comparison with alternate, prior art vacuum support assemblies. Since the vacuum cup assemblies rely on pressurized air, and since the pressure differential within the air supply system for the pressurized air may greatly exceed one atmosphere, embodiments of the present disclosure may be far less sensitive to leakage and failure of a particular system component (e.g. a sealing member of a vacuum cup assembly). Thus, even in the event that one vacuum usage point (e.g. a vacuum cup assembly) becomes disabled, the reduced pressures within the suction chambers of the other vacuum cup assemblies **110** may remain relatively unaffected, and the vacuum support assembly **100** may continue to operate.

[0038] In addition, embodiments of the present disclosure advantageously eliminate the need for portable vacuum sources to accompany the vacuum support assembly, relying instead on more commonly-available sources of pressurized air. Thus, embodiments of the present disclosure may provide improved accessibility and ease of use in comparison with alternate, prior art assemblies.

[0039] It will be appreciated that a wide variety of support assemblies and manufacturing assemblies may be conceived that incorporate embodiments of apparatus in accordance with the present disclosure. Some embodiments of the present disclosure may advantageously use an integrated assembly of a vacuum cup, vacuum pump/generator, manifold, muffler and mounting system all-in-one. In alternate embodiments, this may be accomplished by using, for example, off-the-shelf components integrated into a common housing, or the generator and muffler may be physically fabricated into the back-

shell/housing of the vacuum cup. This compact and common design can easily be mounted and plumbed in many different configurations for various applications. In further embodiments, two or more vacuum cup assemblies **110** can share common a vacuum generator **112** and/or supply pressure line **108** to improve reliability, reduced flow requirements, assembly time and tubing lines.

[0040] For example, one possible embodiment is shown in FIG. **8**, which provides a lower isometric view of a rail assembly **200** including a plurality of vacuum cup assemblies **110** in accordance with an alternate embodiment of the disclosure. In this embodiment, the rail assembly **200** includes a rail member **202** having first and second edges **204**, **206**. As described, for example, in the above-referenced U.S. Pat. No. 6,467,385 B1 issued to Buttrick et al., and U.S. Pat. No. 6,210,084 B1 issued to Banks et al., which patents are incorporated herein by reference, a manufacturing tool may be operatively coupled to at least one of the first and second edges **204**, **206** of the rail member **202** for performing manufacturing operations on the workpiece **148**.

[0041] With continue reference to FIG. **8**, the plurality of vacuum cup assemblies **110** are coupled directly to a lower surface **208** of the rail member **202** by fasteners **212** passing through the coupling apertures **130** (FIG. **7**). The air lines **108** may extend along an upper surface **214** (not visible in FIG. **8**) of the rail member **202**, and may provide the necessary flow of pressurized air to the vacuum generators **112** of the vacuum cup assemblies **110** via air holes formed in the rail member **202**. FIGS. **9** and **10** are schematic views of first and second hole patterns **216**, **218**, respectively, that may be formed in the rail member **202** for this purpose. Thus, the above-described advantages of embodiments of the present disclosure may be achieved in a rail assembly **200** as shown in FIGS. **8** through **10**.

[0042] FIG. **11** is an upper isometric view of a rail assembly **300** including a plurality of vacuum cup assemblies **310** in accordance with another embodiment of the disclosure. In this embodiment, the vacuum cup assemblies **310** are coupled to a lower surface **308** of a rail member **302**, and a vacuum generator **312** is disposed between and operatively coupled to a pair of adjacent vacuum cup assemblies **310**. The air line **108** is coupled to the vacuum generator **312** and extends along the lower surface **308** of the rail member **302** (i.e. the same surface upon which the vacuum cup assemblies **310** are attached), thereby advantageously leaving the upper surface free from obstructions to facilitate the movement of manufacturing tools or carriage assemblies along the upper surface of the rail member **302**.

[0043] FIG. **12** is an isometric view of the vacuum generator **312** of FIG. **11**. In this embodiment, the air line **108** is coupled to the intake port **306** so that pressurized air passes through the internal flow duct **334** disposed within the housing **314**. A pair of vacuum ports **328** are fluidly coupled to the internal flow duct **334** (e.g. to the venturi portion **336** or the low pressure portion **338**), and are in turn coupled to vacuum lines **329** which lead to the suction chamber **346** of each of the adjacent vacuum cup assemblies **310**. As in the embodiment described above, the pressurized air exits the internal flow duct **334** via the exhaust apertures **330**, which are at least partially shrouded by the shrouds **336**. The above-noted advantages of embodiments of the present disclosure may thereby be achieved in a rail assembly **300** wherein a single

vacuum generator **312** creates a reduced pressure (or vacuum) for a pair of adjacent vacuum assemblies as shown in FIGS. **11** and **12**.

[0044] It will be appreciated that various additional embodiments of manufacturing apparatus incorporating one or more aspects of the present disclosure may be conceived in accordance with the present disclosure. Such apparatus may range from automated, computer controlled manufacturing apparatus, to relatively-simple manually-operated apparatus, and even to relatively simple, manually-driven apparatus. Representative manufacturing assemblies which may incorporate apparatus in accordance with the present disclosure include, but are not limited to, those manufacturing assemblies generally described in U.S. Pat. No. 4,850,763 issued to Jack et al., as well as the exemplary manufacturing assemblies disclosed in co-pending, commonly owned U.S. patent application Ser. No. 10/016,524 entitled "Flexible Track Drilling Machine" filed Dec. 10, 2001, co-pending, commonly-owned U.S. patent application Ser. No. 10/606,402 entitled "Apparatus and Methods for Servo-Controlled Manufacturing Operations" filed Jun. 25, 2003, co-pending, commonly-owned U.S. patent application Ser. No. 10/606,443 entitled "Methods and Apparatus for Counter-Balance Assisted Manufacturing Operations" filed Jun. 25, 2003, co-pending, commonly-owned U.S. patent application Ser. No. 10/606,472 entitled "Methods and Apparatus for Manufacturing Operations Using Opposing-Force Support Systems" filed Jun. 25, 2003, and co-pending, commonly-owned U.S. patent application Ser. No. 10/606,473 entitled "Apparatus and Methods for Manufacturing Operations Using Non-Contact Position Sensing" filed Jun. 25, 2003, which patents and patent applications are hereby incorporated by reference.

[0045] FIG. **13** is an isometric view of a representative manufacturing assembly **400** in accordance with yet another embodiment of the disclosure. In this embodiment, the manufacturing assembly **400** includes a track assembly **410** controllably attachable to a workpiece **130**, and a carriage assembly **420** moveably coupled to the track assembly **410**. A secondary controller **430** is mounted on the carriage assembly **420** and is operatively coupled to a primary controller **434**. At least one of the secondary controller **430** and the primary controller **434** may also be coupled to a manufacturing tool **451** mounted on the carriage assembly **420**.

[0046] As further shown in FIG. **13**, the track assembly **410** may include first and second rails **422**, **424**, each rail **422**, **424** being equipped with a plurality of vacuum cup assemblies **414** in accordance with one or more embodiments of the present disclosure. The vacuum cup assemblies **414** are fluidly coupled to a supply line **416** leading to a source of pressurized fluid **418**, such as a pump or the like, such that a reduced pressure may be formed in the suction chambers of the vacuum cup assemblies **414** as described above to secure the track assembly **410** to the workpiece **480**.

[0047] The rails **422**, **424** may be connected by one or more connecting members **428**, and may be adapted to bend, twist, and flex to adjust to the contours of the workpiece **130**. The carriage assembly **420** may translate along the rails **422**, **424** by virtue of rollers **432** that are mounted on an x-axis carriage **460** of the carriage assembly **420** and engaged with the rails **422**, **424**. In a particular embodiment, each rail **422**, **424** may have a V-shaped edge engaged by the rollers **32**, and the rollers **32** may include V-shaped grooves that receive the V-shaped edges of the rails **422**, **424**. In another embodiment, the x-axis carriage **460** may be adapted to flex and twist as

needed (i.e. as dictated by the contour of the workpiece **130**) as the carriage assembly **420** traverses the rails **422**, **422** to allow a limited degree of relative movement to occur between the x-axis carriage **430** and the rollers **432**. Consequently, a reference axis of the carriage assembly **420** (in the illustrated embodiment, a z-axis normal to the plane of the x-axis carriage **460**) may be maintained substantially normal to the workpiece **130** at any position of the carriage assembly **420** along the rails **422**, **424**.

[0048] As further shown in FIG. **13**, a rack **438** for a rack and pinion arrangement is mounted along the rail **424**. A first motor **440** and associated first gearbox **442** is mounted on the carriage assembly **420**. An output shaft from the first gearbox **442** has a first pinion gear **444** mounted thereon which engages the rack **438** on the rail **424**. Thus, rotation of the first pinion gear **444** by the first motor **440** drives the carriage assembly **420** along the rails **422**, **424**.

[0049] With continued reference to FIG. **13**, the carriage assembly **420** further includes a y-axis carriage **450** slideably mounted atop the x-axis carriage **460** so that the y-axis carriage **450** can slide back and forth along a y-axis direction perpendicular to the x-axis direction. More particularly, rails **452**, **454** are affixed to the opposite edges of the x-axis carriage **460**, and rollers **456** are mounted on the y-axis carriage **450** for engaging the rails **452**, **454**. A rack **458** for a rack and pinion arrangement is affixed to the x-axis carriage **460** along the rail **454**. A second motor **480** and associated second gearbox **482** are mounted on the y-axis carriage **450** and drive a second pinion gear (not shown) that engages the rack **458** to drive the y-axis carriage **450** in the y-axis direction. Additional aspects of the manufacturing assembly **400** are described in the above-referenced co-pending, commonly owned U.S. patent application Ser. No. 10/016,524 entitled "Flexible Track Drilling Machine" filed Dec. 10, 2001, previously incorporated by reference herein.

[0050] In operation, the manufacturing assembly **400** may be mounted onto the workpiece **130** by providing a flow of pressurized fluid medium from the source **418** to the vacuum cup assemblies **414** in a manner as described above. The carriage assembly **420** may then be moved to a desired position over the workpiece **130**. Specifically, at least one of the primary and secondary controllers **434**, **430** may transmit control signals to the first drive motor **440** to drive the carriage assembly **420** along the track assembly **410**, and may also transmit control signals to the second drive motor **480** to adjust the position of the y-axis carriage **450** be coupled to the carriage assembly **420** by, for example, a clamp ring **470** or other suitable structure that provides access to the workpiece **130** for the manufacturing tool **451**.

[0051] It should also be understood that the various operations of the manufacturing assembly **400** may be accomplished in an automated or semi-automated manner using computerized numerically-controlled (CNC) methods and algorithms. Alternately, the various operations of the manufacturing assembly **400** may be performed manually or partially-manually by an operator, such as, for example, by having the operator provide manual control inputs to the primary and/or secondary controllers **434**, **430**, or by temporarily disabling or neutralizing the above-referenced motors and drive assemblies to permit manual movement. In a particular aspect, at least one of the primary and secondary controllers **434**, **430** includes a CNC control system. It may also be noted that manufacturing assemblies in accordance with the present disclosure, including the manufacturing assembly **400**

described above, may be operated in combination with a wide variety of manufacturing tools **451**, including but not limited to, drilling devices, riveters, mechanical and electromagnetic dent pullers, welders, wrenches, clamps, sanders, nailers, screw guns, or virtually any other desired type of manufacturing tools or measuring instruments.

[0052] FIGS. **14** and **15** are flow charts of first and second portions, respectively, of a manufacturing process **600** that uses coordinate or “smart” pins in accordance with another embodiment of the disclosure. In this particular embodiment, the manufacturing process **600** is adapted for manufacture of wing spar of an aircraft wing assembly. It will be appreciated, however, that the manufacturing process **600** may alternately be adapted for the manufacture of any desired article of manufacture, and that embodiments of methods in accordance with the disclosure are not limited solely to the manufacture of a wing spar.

[0053] As shown in FIG. **14**, the manufacturing process **600** may begin with the formation of tool holes in one or more spar webs at a block **602**. The spar webs may then be at least one of formed, chemically treated, and primed at a block **604**. At a block **606**, one or more coordinate pins are applied (or installed) into the tool holes. As described more fully below, the coordinate pins (or smart pins) may remain installed in the tool holes throughout one or more subsequent actions of the manufacturing process **600**, and may advantageously be used by one or more pieces of manufacturing equipment throughout the manufacturing process **600**. The coordinate pins may, for example, be used to monitor spar growth, to locate spar features, to locate fasteners, to position sealant application machinery, to position automated wash and dry equipment, to obtain manufacturing plan information, or for any other suitable process or activity. At a block **608**, the spar chords are machined, and at a block **610**, the spar chords are at least one of formed, chemically treated, and primed. At a block **612**, measurements of the spar are performed for quality control, and one or more of the blocks **602** through **608** may be repeated as necessary.

[0054] With continued reference to FIG. **14**, at a block **614**, the spar webs and chords are sealed, attached together, and permanently coupled (e.g. tack fastened), and a chord locating device may be used to locate the chords and fasteners. A fastening system may install bolts on remaining chord and web locations at a block **616**. In a particular embodiment, an O-frame may be suitably employed to allow for quiet sealing of fasteners, and a lighter structure which may be suitable for bolts. An offline verification and maintenance of equipment may be performed at a block **618**. Again, measurements of the spar may be performed at a block **620**, and one or more previous steps may be repeated as needed.

[0055] Next, at a block **622**, one or more coordinate holes may be drilled for ribposts, stiffeners, brackets, or other components. In one embodiment, a Low Cost Automation Technology (LCAT) adaptive feedback Determinant Assembly (DA) machine is used for these drilling operations. As used in this patent application, a DA machine is a machine that uses matching part-to-part features (e.g. holes, etc.) to assemble a product accurately versus using traditional locating jigs or special tools. At a block **624**, an offline verification and maintenance of equipment may be performed. The ribposts and stiffeners may be sealed as required, and installed (e.g. manually) using permanent fasteners in corresponding coordination holes at a block **626**. The ribposts and stiffeners may be provided with DA holes at a block **628**. Relevant information

regarding the manufacturing operation **600** may be transmitted to a manufacturing plan information system at a block **630**. Similarly, at a block **632**, one or more miscellaneous brackets may be sealed as required, and installed (e.g. manually) using permanent fasteners in corresponding coordination holes, and at a block **634**, the brackets may be provided with DA holes. At a block **636**, a fastening system installs fasteners at appropriate ribpost, stiffener, and bracket locations. Information from the offline verification and maintenance of equipment at the block **624** may be received into the block **636** for this purpose. In a particular embodiment, for example, an LCAT O-frame fastening system installs bolts and/or rivets during the block **636**. The manufacturing process **600** continues at a block **638**.

[0056] Referring now to FIG. **15**, measurements of the wing spar may be performed at a block **640**, and one or more previous steps may be repeated as needed. At a block **642**, coordination holes may be formed for leading edge (LE) web stiffeners and second stage fittings. As described above, in one representative embodiment, an LCAT adaptive feedback DA machine is used for this purpose. Information may be transmitted to or received from an offline verification and maintenance of equipment at a block **644** (or from the block **624**). Then, using the web stiffeners from the block **628**, the web stiffeners and second stage fittings are sealed as required, and permanent fasteners installed in the coordination holes, at a block **646**. At a block **648**, information from the manufacturing plan information system may be provided to the block **646**.

[0057] As further shown in FIG. **15**, fasteners may be installed into the LE stiffeners and second stage fittings at a block **650**. Again, information may be transmitted to or received from an offline verification and maintenance of equipment at a block **652** (or from the block **624**). The second stage fittings pick-up operations are performed at a block **654**. Again, at a block **656**, information from the manufacturing plan information system may be provided to the block **654**. A spar cleaning is performed at a block **658**. In one particular embodiment, the cleaning may be a “car wash” type of cleaning. At a block **660**, the spar fillet is sealed (e.g. with an application system). Sealing pick-up operations are performed at a block **662**. Information may be provided at the block **662** from the manufacturing plan information system (block **656**). Finally, at a block **664**, at least one of a leading edge attachment and a shipping of the part for final assembly is performed.

[0058] FIG. **16** is an isometric view of a manufacturing operation **700** in accordance with yet another embodiment of the disclosure. In this embodiment, a workpiece **702** (e.g. a wing spar) is being carried by handling equipment **704** while an operator **706** manually applies a plurality of coordinate pins (or smart pins or smart buttons) **710** into a corresponding plurality of holes **708** in the workpiece **702**. The holes **708** may be formed by any desired method, including, for example, Determinant Spar Assembly Cell (DSAC), Automated Spar Assembly Tool (ASAT), robot, milling machine, or any other suitable drilling device or method. The coordinate pins **710** may be installed in specific tool hole locations. In one embodiment, the coordinate pins **710** are so-called “quick disconnect” pins. In a particular embodiment, the coordinate pins **710** can include industry-standard HSK type machine tool holders to improve dimensional accuracy. Other suitable types of coordinate pin systems could also be used.

[0059] It may be noted that each of the coordinate pins 710 installed in the workpiece 702 may be individualized and may contain highly specific characteristics or identification information that is unique to the specified location of each respective coordinate pin 710. Therefore, placement of the coordinate pins 710 into the workpiece 702 may be checked and certified, for example, by a second operator or quality assurance inspector (not shown). The coordinate pins 710 may be kept in a precision equipment box and color-coded, or otherwise marked, for placement in a specific hole location 708. Also, upon completion of manufacturing operations on the workpiece 702, the coordinate pins 710 may be removeable and reusable for similar manufacturing operations on subsequent workpieces 702. For example, a process for installing the coordinate pins 710 could start by assigning a box containing a set of unique coordinate pins 710 to a specific workpiece 702 (e.g. a front wing spar Part No. IGW-200 for a Model 777 aircraft commercially-available from The Boeing Company of Chicago, Ill.). The coordinate pins 710 may be designated for their respective index hole 708 in the workpiece 702 by, for example, color coding of the pins, or cross-referencing numbers that are affixed or stamped on the pins, or any other suitable means. The operator 706 select the correct box of coordinate pins 710 to install for the respective workpiece 702, and then install each coordinate pin 710 into its corresponding index hole 708.

[0060] FIG. 17 shows enlarged, partial cross-sectional and end elevational views of a coordinate pin 710 of FIG. 16, and a coordinate pin reader 730, in accordance with another embodiment of the disclosure. As shown in FIG. 17, the coordinate pin 710 may include an identifier 712 containing identification information that may be useful in the performance of one or more actions of the manufacturing process 600 (FIGS. 14 and 15). In one embodiment, for example, the identifier 712 may be embedded within a tip portion of the coordinate pin 710. In an engaged position 740, the pin reader 730 may be engaged with the coordinate pin 710 so that a receiving member 732 of the pin reader 730 engages with the identifier 712 and receives the identification information contained therein. The identification information may be transmitted via a conductive lead 734 to a data acquisition system (not shown), a controller, a manufacturing plan information system, or other suitable data analysis and storage system.

[0061] In one particular embodiment, the identifier 712 may be a sensor that is embedded into the coordinate pin 710. A number of different types of contact and non-contact sensors are commercially-available that may be used for this purpose. For example, in one exemplary embodiment, a sensor known as a "smart button" available from Dallas Semiconductor, Inc. of Dallas, Tex. may be employed that is about the size of a typical watch battery and has a unique character string identifier that is embedded in a microchip. Each smart button is robust and costs only a few dollars. A smart button reader 730 can read the smart button's unique identifier by simply touching the surface of the smart button. An electrical micro voltage potential between the reader 730 and the button 710 provides the power source to read the button 710. Once the smart buttons 710 are installed then multiple pieces of manufacturing equipment can hook up to any of the coordinate pin locations and read the unique character string identifier for that location. The manufacturing system can then automatically look up the unique character identifier in a table, and may cross-reference the workpiece information for that location.

[0062] For example, in one representative embodiment, a piece of automated drilling equipment, such as the manufacturing assembly 400 described above and shown in FIG. 13, may be attached to the coordinate pin 710. The drilling equipment may include a pin reader 730 (e.g. in its secondary controller 430 or its manufacturing tool 451), and may download the identification information of the coordinate pin 710 to, for example, the primary controller 434. The primary controller 434 may perform the table look up on the identification information. The identification information may be cross-referenced to the workpiece of interest, and other various details about the manufacturing operation (e.g. airplane model, structure, station number, and data sets for that location). The primary controller 434 may then formulate one or more control signals to the carriage assembly 420 or the manufacturing tool 451 accordingly.

[0063] The identification information in the coordinate pin 710 may advantageously allow unique identification of each index hole 708 location so that manufacturing equipment will be better able to know where and what assembly operations are to be performed on the workpiece 702. For example, in the representative manufacturing process 600 shown in FIGS. 14 and 15, the coordinate pins 710 may be installed, for example, in the block 606. Subsequently, the coordinate pins 710 may be employed during various operations and sub-processes of the manufacturing process 600, including, for example, for monitoring spar growth, for locating spar features, to position sealant application machinery, to position washing and drying equipment, to obtain manufacturing plan information, and during any other suitable operation or sub-process. More specifically, in the manufacturing process 600 shown in FIGS. 14 and 15, the coordinate pins 710 may be used in numerous processes and sub-processes, including, for example, in blocks 614 through 624, in block 630, in blocks 636 and 642, in block 650, and in blocks 656 through 660.

[0064] Furthermore, the coordinate pins 710 may remain in the workpiece 702 as the workpiece 702 progresses beyond the manufacturing process 600. In a particular embodiment, for example, the coordinate pins 710 remain in the wing spar 702 after a spar assembly process and into a wing majors assembly process. The wing majors assembly process may use the coordinate pins for the same or similar purposes and uses as during the manufacturing process 600. When manufacturing operations are complete, the coordinate pins 710 may be finally removed and recycled for the next workpiece 702. Thus, the coordinate pins 710 may advantageously establish a common index throughout a production process.

[0065] Embodiments of apparatus and methods that include indexing in accordance with the teachings of the present disclosure may allow a dramatic reduction or elimination of at least some of the traditional tools and traditional "monument like" equipment involved in conventional manufacturing processes. Embodiments of methods and apparatus disclosed herein may be relatively lower cost, relatively simple, and relatively flexible and adaptable in comparison with prior art manufacturing apparatus and methods. Traditional hard tooling and indexing systems are relatively more expensive to design, build, and maintain in comparison with the inventive indexing apparatus and methods disclosed herein. Since tooling for large manufacturing operations, such as a new airplane, typically comprises a substantial percentage of the capital investment needed to begin manu-

facturing operations, the cost savings attributable to apparatus and methods in accordance with the present disclosure may be substantial.

[0066] It will also be appreciated that apparatus and methods in accordance with the present disclosure may also provide other advantages over prior art manufacturing apparatus and methods. For example, embodiments of the present disclosure may allow index locations to be identified relatively quickly, and may provide a convenient method for configuration control in automated processing operations. Also, embodiments of the present disclosure may provide a method for communicating key manufacturing instructions throughout the manufacturing process at relatively low cost and high reliability. Embodiments of the present disclosure may also provide a method of "mistake proofing" manufacturing operations to reduce or eliminate manufacturing errors.

[0067] While specific embodiments of the disclosure have been illustrated and described herein, as noted above, many changes can be made without departing from the spirit and scope of the disclosure. Accordingly, the scope of the disclosure should not be limited by the disclosure of the specific embodiments set forth above. Instead, the disclosure should be determined entirely by reference to the claims that follow.

What is claimed is:

1. A method of performing a manufacturing operation on a workpiece, comprising:

- forming an indexing hole in the workpiece;
- installing a coordinating pin into the indexing hole, the coordinating pin including a quantum of indexing information;
- positioning a sensor proximate the coordinating pin;
- sensing the quantum of indexing information with the sensor; and
- performing a manufacturing operation on the workpiece based at least partially on the quantum of indexing information.

2. The method of claim 1, wherein installing a coordinating pin into the indexing hole includes installing a coordinating pin having a microchip embedded therein.

3. The method of claim 1, wherein installing a coordinating pin having a quantum of indexing information includes installing a coordinating pin having a unique character string identifier.

4. The method of claim 1, wherein positioning a sensor proximate the coordinating pin includes positioning a sensor at least partially over an end portion of the coordinating pin.

5. The method of claim 1, wherein sensing the quantum of indexing information with the sensor includes contacting the sensor to the coordinating pin.

6. The method of claim 1, wherein performing a manufacturing operation on the workpiece includes performing a drilling operation at the desired location on the workpiece.

7. The method of claim 1, wherein performing a manufacturing operation on the workpiece includes at least one of monitoring workpiece growth, locating workpiece features,

positioning sealant application machinery, positioning washing and drying equipment, and obtaining manufacturing plan information.

8. The method of claim 1, further comprising transmitting the quantum of indexing information to a controller.

9. The method of claim 1, further comprising moving a position of a manufacturing tool relative to the workpiece.

10. The method of claim 1, wherein moving a position of a manufacturing tool relative to the workpiece includes moving a position of a manufacturing tool based on the quantum of indexing information.

11. The method of claim 1, wherein moving a position of a manufacturing tool relative to the workpiece includes traversing a carriage assembly along an elongated rail member based on the quantum of indexing information.

12. A method of performing a manufacturing operation on a workpiece, comprising:

- forming an indexing hole in the workpiece;
- installing a coordinating pin into the indexing hole, the coordinating pin including a quantum of indexing information;
- positioning a sensor proximate the coordinating pin;
- sensing the quantum of indexing information with the sensor;
- performing a manufacturing operation on the workpiece based at least partially on the quantum of indexing information;
- transmitting the quantum of indexing information to a controller; and
- moving a position of a manufacturing tool relative to the workpiece.

13. The method of claim 12, wherein installing a coordinating pin into the indexing hole includes installing a coordinating pin having a microchip embedded therein.

14. The method of claim 12, wherein installing a coordinating pin having a quantum of indexing information includes installing a coordinating pin having a unique character string identifier.

15. The method of claim 12, wherein positioning a sensor proximate the coordinating pin includes positioning a sensor at least partially over an end portion of the coordinating pin.

16. The method of claim 12, wherein sensing the quantum of indexing information with the sensor includes contacting the sensor to the coordinating pin.

17. The method of claim 12, wherein performing a manufacturing operation on the workpiece includes performing a drilling operation at the desired location on the workpiece.

18. The method of claim 12, wherein performing a manufacturing operation on the workpiece includes at least one of monitoring workpiece growth, locating workpiece features, positioning sealant application machinery, positioning washing and drying equipment, and obtaining manufacturing plan information.

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