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20

(72)

2 210 1301

3 777 - 1 1 803

(74)

:

(54)

(Video Phone)

(Video Conference)

, CCD

가
(sub - pixel)

; (a).

, H PSF(Point Spread Function), f

, g=Bz=Hf+n (B,H

, z

, g

, n 가 H

) ; (b). PSF(H)

가 M(f)

, (c). 가 M(f)

PSF(

H) f=Pg

PSF(P)

, (d). f=Pg=PBz=Qz PSF(P) B

Q

(f)

POCS(Projection Onto Convex Set)

가 (Nakazawa)
(Non - uniform Sample)

가 (Segmentation)
(Mapping)

n) PSF (Point Spread Function)

(a). PSF(Point Spread Function), f, z, g, H, n

(b). PSF(H) 가 M(f)

$$M(f) = \|g - Hf\|^2 + \alpha \|Cf\|^2$$

(c). 가 M(f) PSF(H)

$$H(k, \lambda) = \frac{G(k, \lambda)}{F(k, \lambda)}$$

f=Pg PSF(P)

$$P(k, \lambda) = \frac{H^*(k, \lambda)}{H^*(k, \lambda)H(k, \lambda) + C^*(k, \lambda)C(k, \lambda)}$$

(d). $f = Pg = PBz = Qz$ PSF(P) B Q (f)

1 2 , 2 1 2

1 (a i) , (A,B,C,D)

(circle) (a i) , 3x3 2

3 3 , 4 3 3

3 (a p) , (A,B,C,D,E,F,G,H,I)

(circle) (a p) , 4x4 4 3

2 3 6 ()
5 , 6 6

5 , 'x' 2 2 ,
4 3 , 2 3

2, 4, 6 가 , 9
(9bit shift) (floating point)

1 6 2 , 3 , 6 ,

PSF (spatially invariant point spread funct

ion) PSF 가 ,

f z, 1 가 g, 가

1
$$g = Bz = Hf + n$$

1 B,H,n , H
 g PSF , n 가 H
 , PSF(H) (direct inverse) PSF(H)
 2

2

$$H(k, l) = \frac{G(k, l)}{F(k, l)}$$

2 H(k,l) PSF(H) (k,l) , G(k,l) (k,l)
 , F(k,l) (k,l)
 f (under - s
 ample) PSF(H)
 0' (PSF(H)) (overshoot)가 (k,l) '
 PSF(H) 가 (regulariza
 tion image restoration)

가 M(f) 3 PSF PSF(H)

3

$$M(f) = \|g - Hf\|^2 + \alpha \|Cf\|^2$$

3

가

1 - 2 (norm) , C
 2 가 (Gaussian Filter)

3

(Gradient Operator)

4

4

$$\nabla_f M(f) = -2H^T(g - Hf) + 2\alpha C^T C f = 0$$

4 T (transpose)

5

() '1' (f)

5

$$f = \frac{H^T g}{(H^T H + C^T C)} = P g$$

5 PSF(P) $P = H^T / (H^T H + C^T C)$
(block - circulant)

, PSF(P) 6

6

$$P(k, l) = \frac{H^*(k, l)}{H^*(k, l)H(k, l) + C^*(k, l)C(k, l)}$$

6 '*' (complex - conjugate)

6 IFT (Inverse Fourier Transform) PSF(P)

PSF(P) 1 가 f 7

7

$$f = P g = P B z = Q z$$

, PSF(P) , Q

, PSF(P) (up - sampling)

가 2 3 , 가 3 4

가 2 (sub - pixel) 2 H.263
1/3 , 가 3 H.26L

가

(57)

1.

(a). PSF(Point Spread Function), f , z , g , H , n 가 H)
 $g=Bz=Hf+n$ (B,H, n 가 H) ;

(b). PSF(H) 가 $M(f)$,

(c). 가 $M(f)$ PSF(H) , $f=Pg$ PSF(P)

(d). $f=Pg=PBz=Qz$ PSF(P) B Q (f)

2.

1 , 가 $M(f)$;

$$M(f) = \|g - Hf\|^2 + \alpha \|Cf\|^2$$

(, C 2)

3.

1 , PSF(H) ;

$$H(k, l) = \frac{G(k, l)}{F(k, l)}$$

(G(k,l) (k,l) , G(k,l) (k,l)

4.

1 , PSF(P) ;

$$P(k, l) = \frac{H^*(k, l)}{H^*(k, l)H(k, l) + C^*(k, l)C(k, l)}$$

IFT(Inverse Fourier Transform)

5.

2 , '1' ,

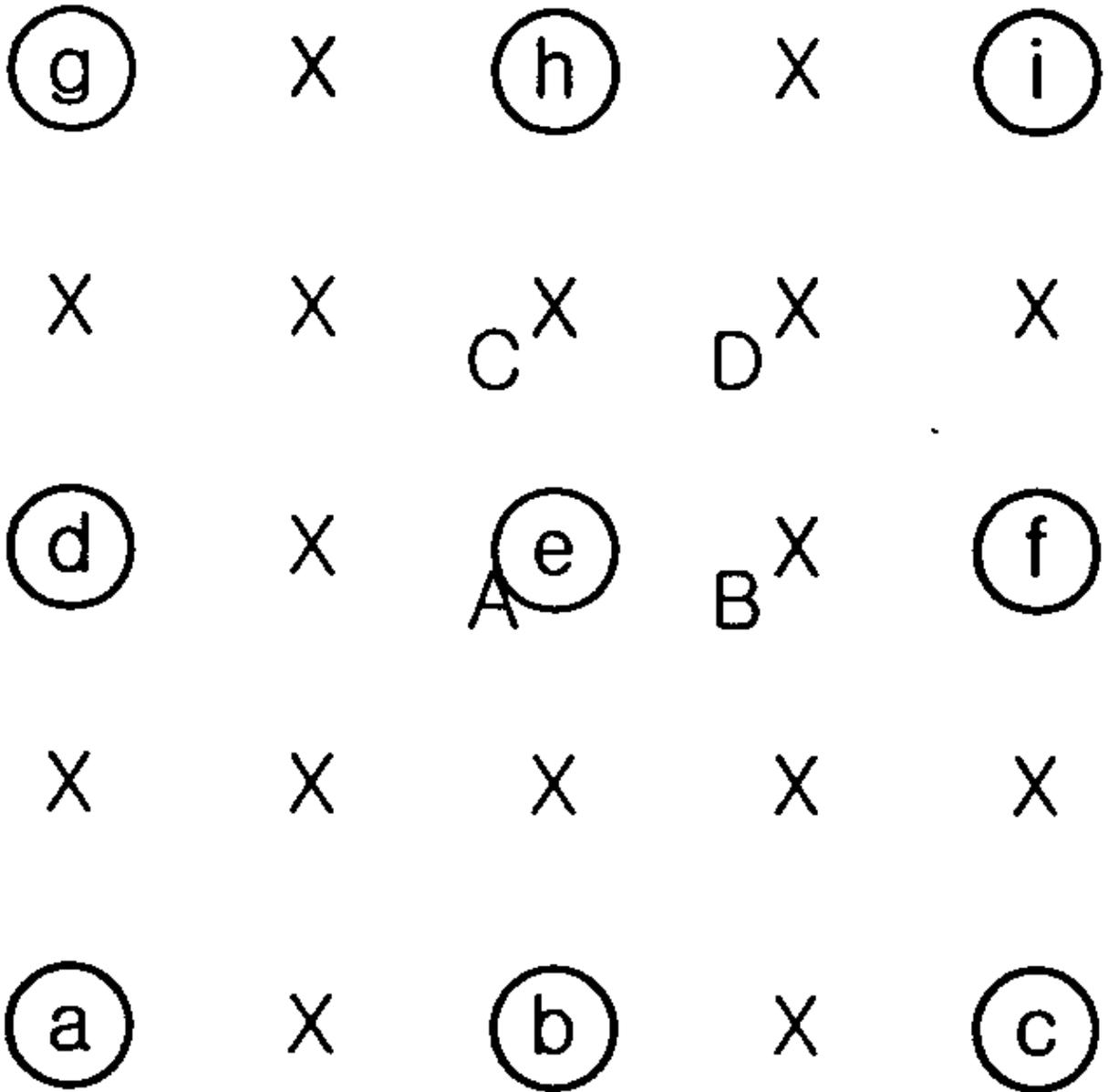
6.

1 4 , PSF(P)

7.

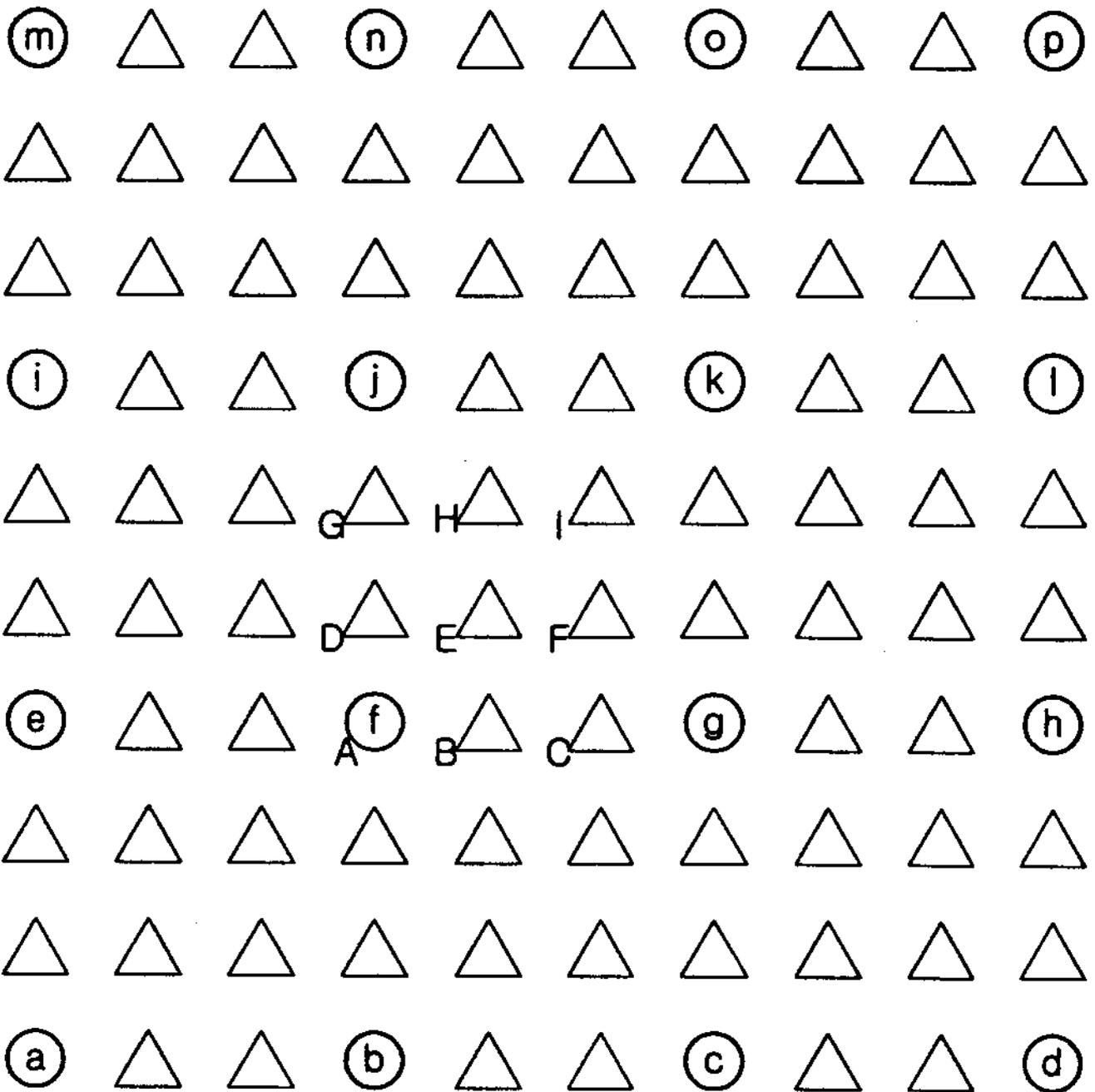
2 , 2 2 가 (Gaussian Filter)

1



2

$$\begin{bmatrix} A \\ B \\ C \\ D \end{bmatrix} = 1/512 \begin{bmatrix} 1 & 94 & -15 & 94 & 391 & -15 & -15 & -15 & -8 \\ -15 & 86 & -9 & -13 & 370 & 113 & -6 & -14 & -18 \\ -15 & -13 & -6 & 86 & 370 & -14 & 9 & 113 & -18 \\ -6 & -14 & -14 & -14 & 349 & 107 & -14 & 107 & 11 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ f \\ g \\ h \\ i \end{bmatrix}$$



4

$$\begin{bmatrix} A \\ B \\ C \\ D \\ E \\ F \\ G \\ H \\ I \end{bmatrix} = \frac{1}{512} \begin{bmatrix} -4 & 60 & -22 & 0 & 104 & 387 & -3 & 0 & -4 & 7 & -13 & 0 & 0 & 0 & 0 & 0 \\ -15 & 71 & -22 & 0 & 11 & 422 & 63 & 0 & -11 & 12 & -19 & 0 & 0 & 0 & 0 & 0 \\ -12 & 44 & 9 & -8 & -17 & 307 & 215 & -8 & -6 & 4 & -11 & -5 & 0 & 0 & 0 & 0 \\ -16 & -8 & -16 & 0 & 103 & 372 & -3 & 0 & 9 & 91 & -20 & 0 & 0 & 0 & 0 & 0 \\ -12 & -4 & -25 & 0 & 9 & 403 & 61 & 0 & -12 & 107 & -15 & 0 & 0 & 0 & 0 & 0 \\ -8 & -9 & -23 & -5 & -19 & 284 & 229 & -10 & -13 & 69 & 29 & -12 & 0 & 0 & 0 & 0 \\ -8 & -10 & -6 & 0 & 44 & 212 & -16 & 0 & 71 & 269 & -11 & 0 & -11 & -16 & -6 & 0 \\ -4 & -9 & -10 & 0 & -6 & 226 & 52 & 0 & 2 & 272 & 22 & 0 & -6 & -15 & -12 & 0 \\ -2 & -8 & -12 & -2 & -16 & 160 & 100 & -9 & -15 & 213 & 143 & -2 & -9 & -12 & -15 & -2 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \\ e \\ f \\ g \\ h \\ i \\ j \\ k \\ l \\ m \\ n \\ o \\ p \end{bmatrix}$$

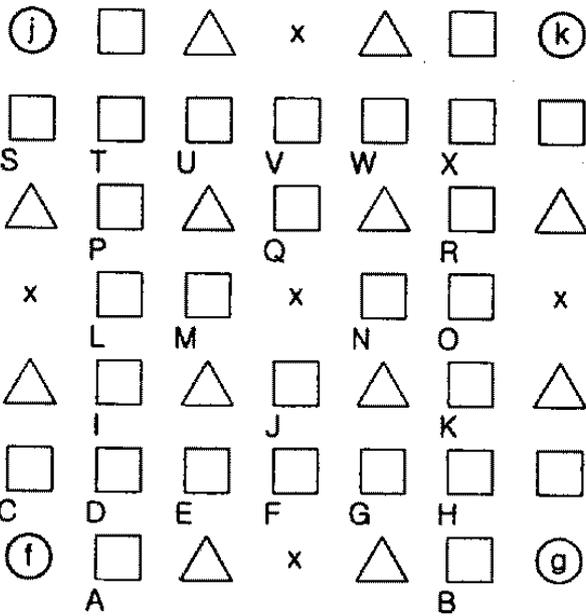
(m)

(n)

(o)

(p)

(i)



(l)

(e)

(h)

(a)

(b)

(c)

(d)

