

Open Source: <https://github.com/microsoft/tutel>

# Tutel: Adaptive Mixture-of-Experts at Scale

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# Mixture-of-Experts (MoE)

- **Dense Model:**

Scale Solutions: ZeRO / Model Parallel / ..

*data* ↑ *param* ↑ *device* ↑ → *local mem* ↑ *net* ↑

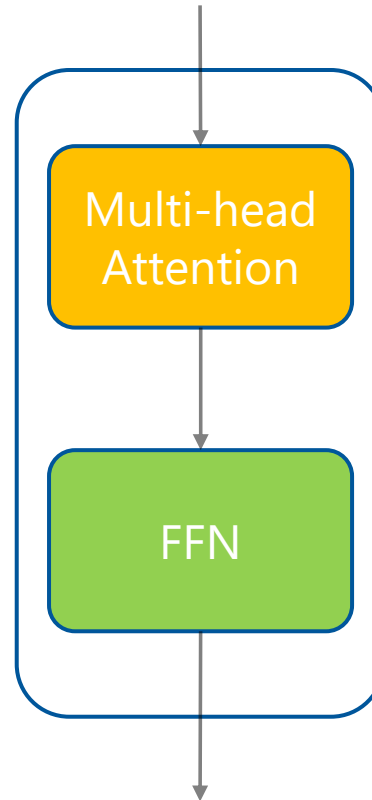
- **MoE based Model:**

“Key to unlock **Exa-scale** Training”

*data* ↑ *param* ↑ *device* ↑ → *local mem* (-) *net* (-)

“sub-linear” scaling

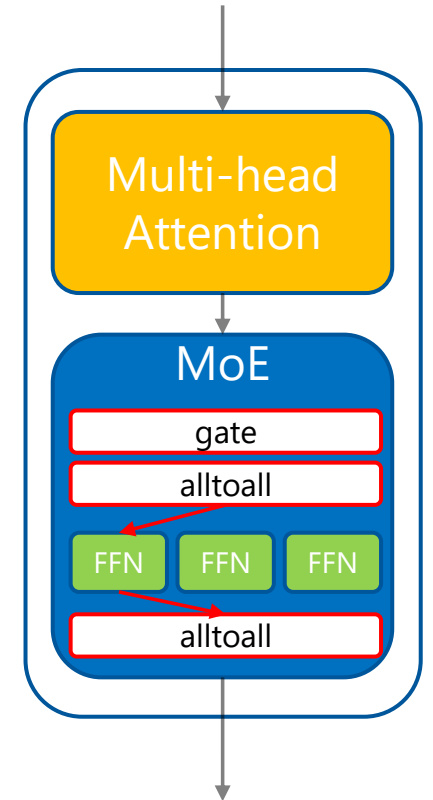
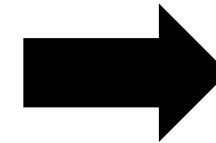
*Transformer (Dense)*



**Total Parameters:**

|FFN|

*Transformer (MoE)*



|FFN| × expert\_count

# Mixture-of-Experts (MoE)

## ① Decide Expert ID:

$$F_{\text{gating}}(\text{input}_x) \rightarrow \text{expert\_id}$$

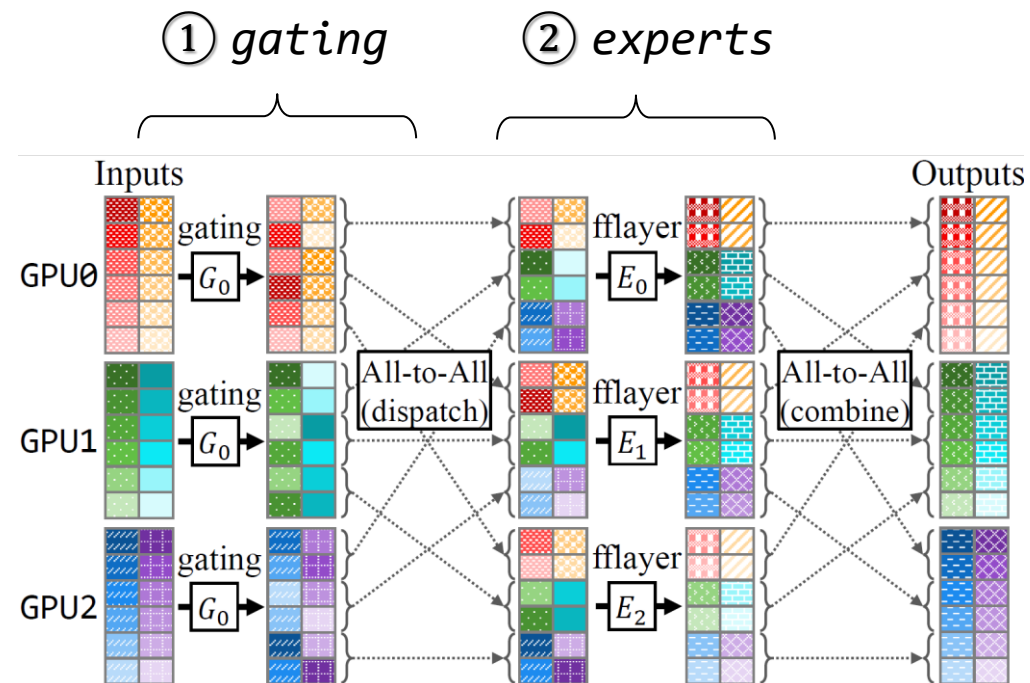
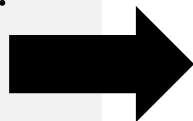
## ② Train With Target Expert ID:

$$\text{output} = \text{FFN}_{\text{expert\_id}}(\text{input}_x)$$

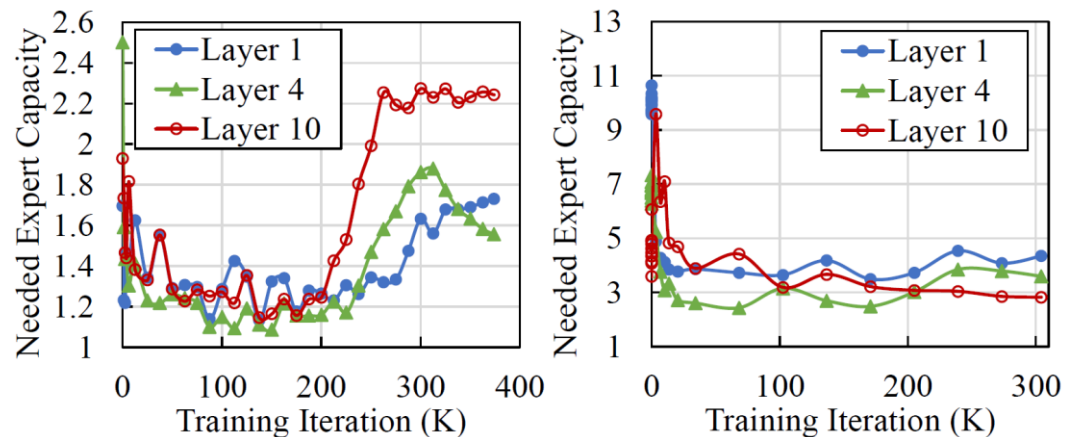
$F_{\text{gating}}$  is trainable, so:

the dispatch from "Inputs  $\rightarrow$  Experts":

- ***dynamically changed***
- ***potentially imbalanced***



Internal MoE layer Data Flow



Imbalance States by Training Iterations

SwinV2-MoE tiny (left) and base (right)

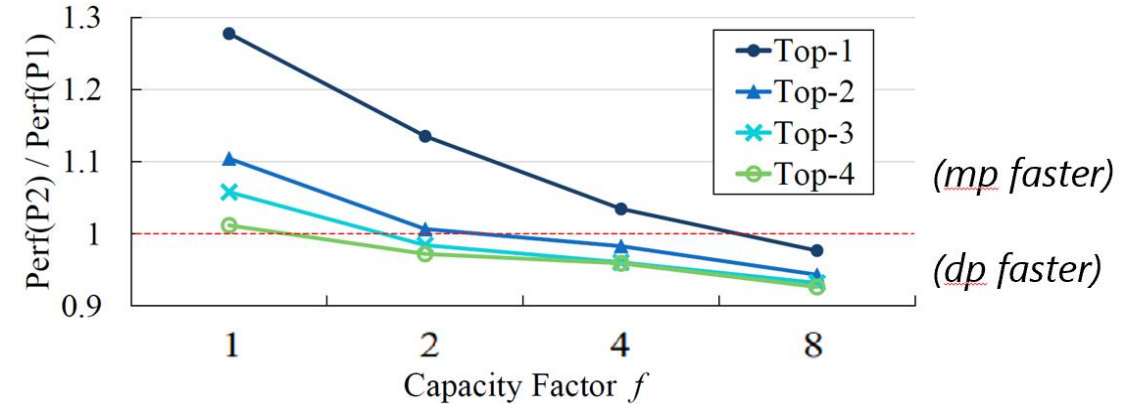
# Static Parallelism for Dynamic MoE

Static parallelism cannot satisfy all efficient preferences from **dynamic** workload

**Hard to Change Parallelism:** Normal parallel solutions are not compatible to switch.

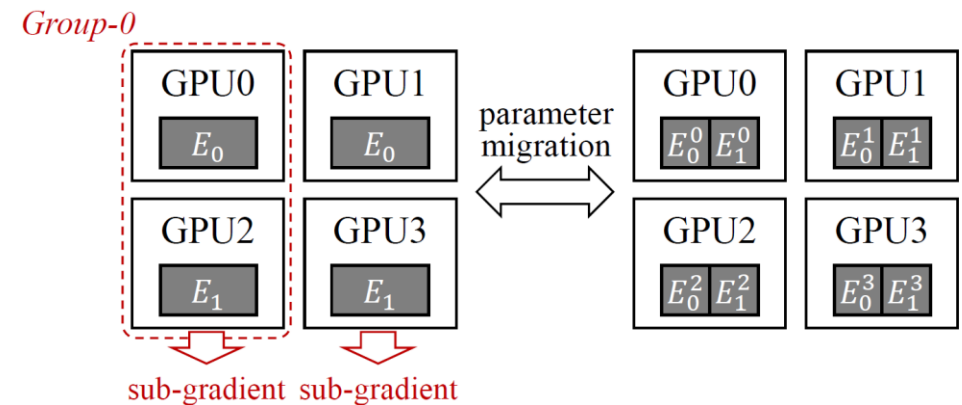
- Overhead of **parameter** migration
- Different **input** layout, **gradient** update, etc..

*Tensor parallelism is not the only factor deserved to change in dynamic workload.*



## Parallelism Efficiency on Different Capacities

(P1: Data Parallel P2: Model Parallel)



Existing data ↔ model parallelism for MoE

# Tutel Design

*- Adaptive MoE at Scale*



# Switchable Parallelism

One MoE  $\rightarrow$  Multi-path Parallelism:

$$P_1(+)\ P_2(-) \leftrightarrow P_1(-)\ P_2(+)$$

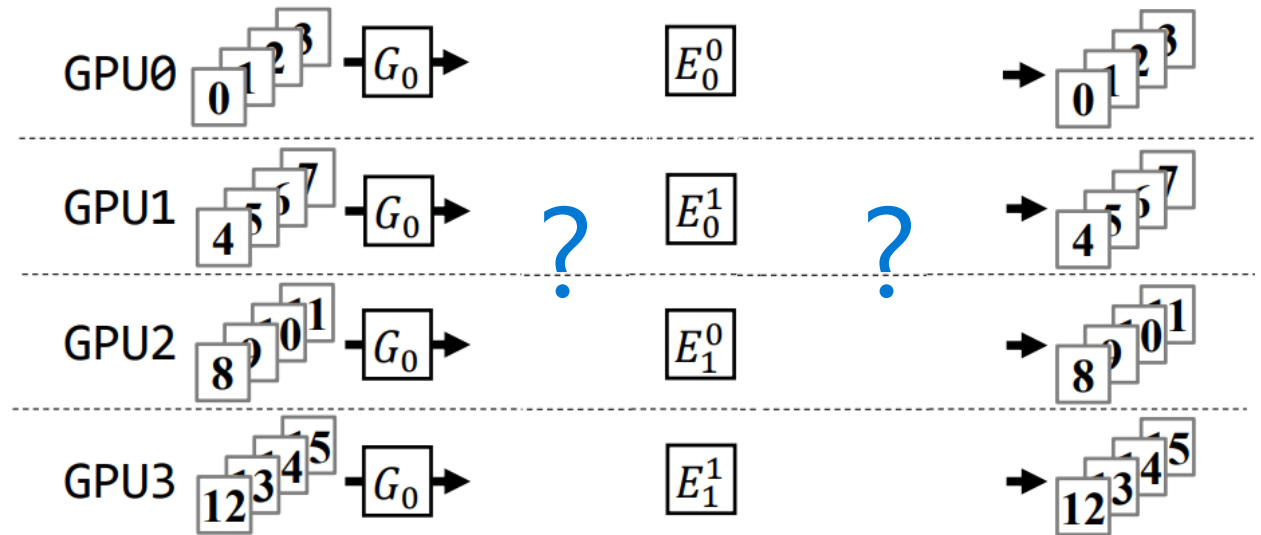
*no-cost*

No location collisions:

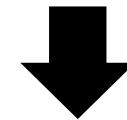
- **Parameter Placement:** evenly sharded
- **Input Layout:** the same as DDP
- **Expert Gradients:** exclude all\_reduce

Eliminate sub-optimal options  $\rightarrow$

- simplified set = { ①, ⑦ }



Base Partition Framework



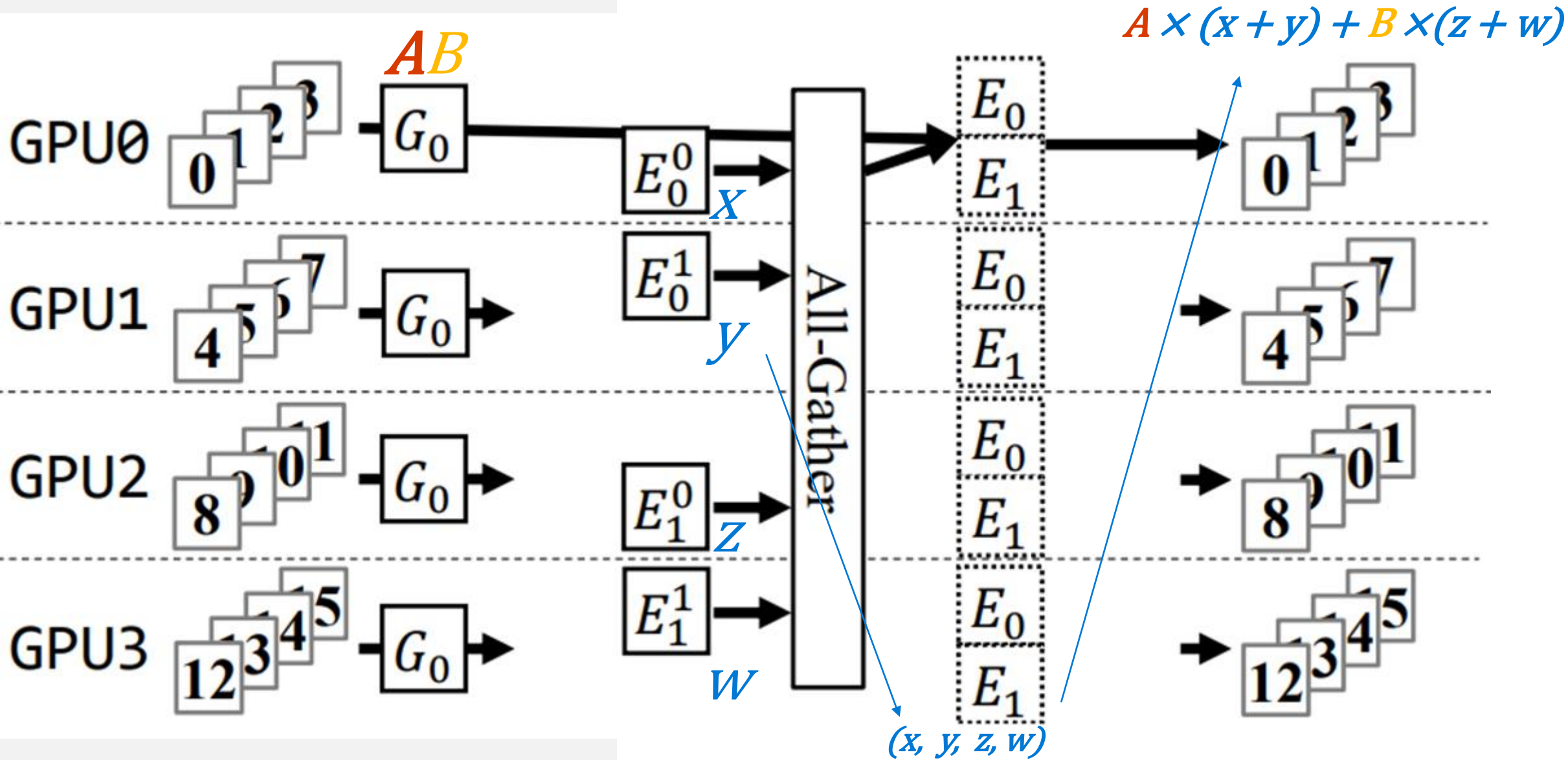
*implement*

Parallelism Method	Communication Complexity	Limitation	Comment
① DP	$\mathcal{O}(P)$	-	Possibly optimal
② MP	$\mathcal{O}(C_g \cdot W)$	-	No better than ⑥
③ EP	$\mathcal{O}(C_g)$	$E/W \geq 1$	No better than ⑥
④ DP+MP	$\mathcal{O}(C_g \cdot r + P/r)$	$1 \leq r \leq W$	No better than ⑦ for any $r$
⑤ EP+DP	$\mathcal{O}(C_g + P/E)$	-	A special case of $r = 1$ in ⑦
⑥ EP+MP	$\mathcal{O}(C_g \cdot \max\{1, W/E\})$	-	A special case of $r = W/E$ in ⑦
⑦ EP+DP+MP	$\mathcal{O}(C_g \cdot W/E)$ - if $r \geq W/E$ $\mathcal{O}(C_g \cdot r + P/E/r)$ - if $1 \leq r < W/E$	-	Possibly optimal

Tensor Parallel Options

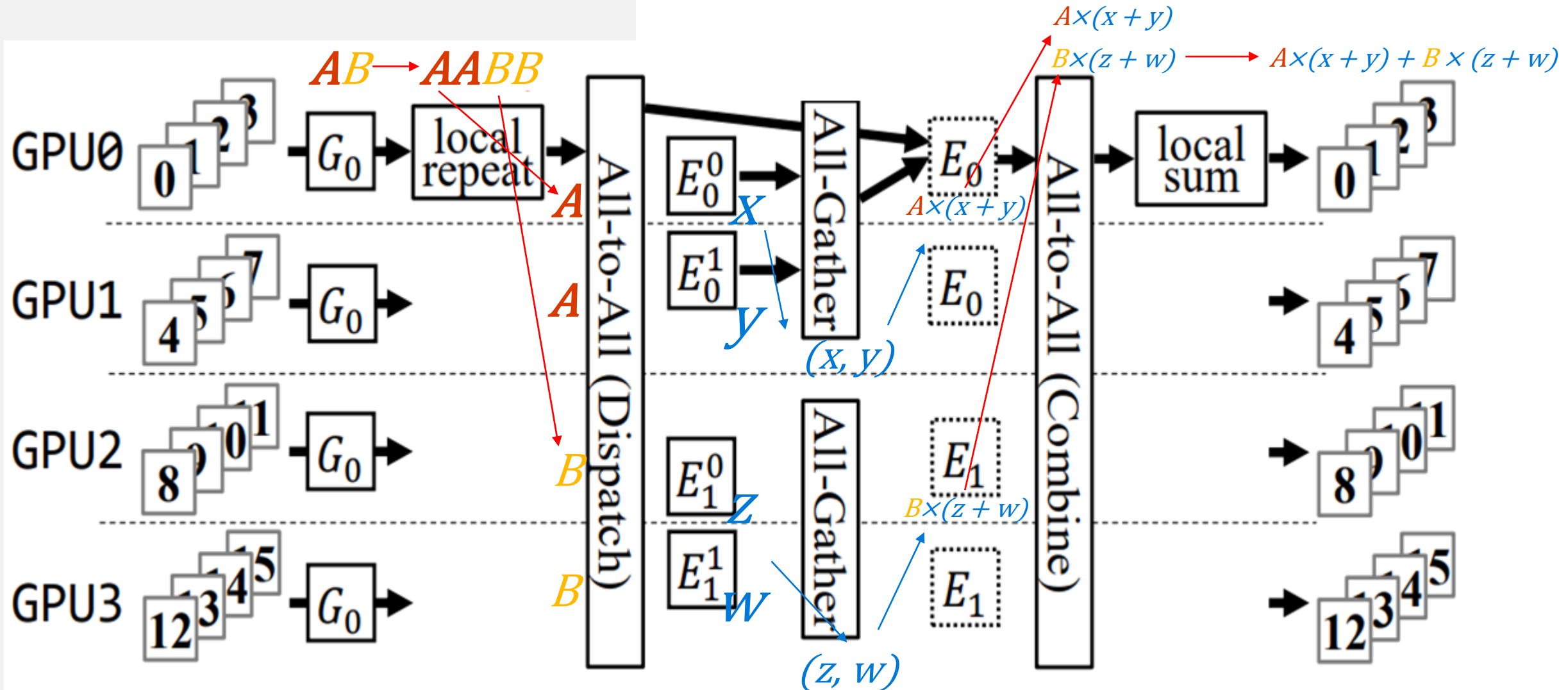
# Switchable Parallelism

*Path 1: Data parallelism*



# Switchable Parallelism

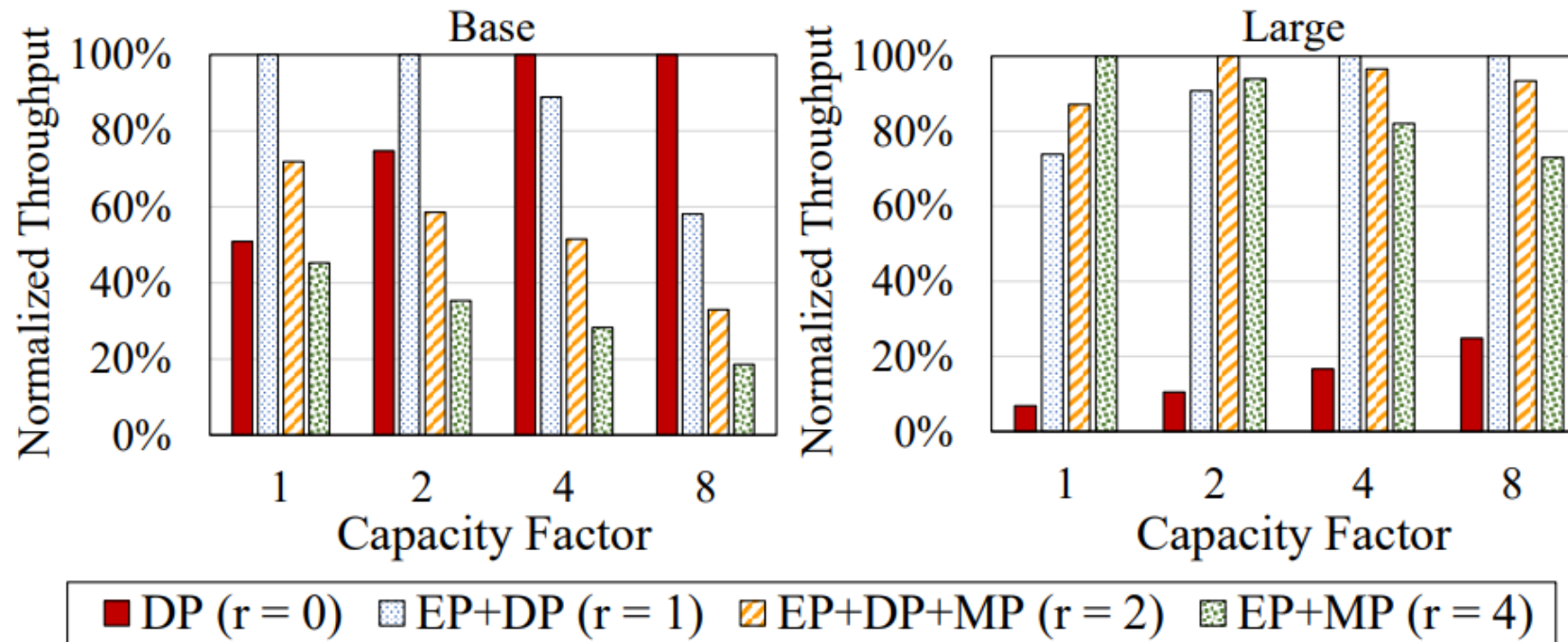
Path 2: Expert + Data + Model parallelism





# Evaluation of Switchable Parallelism

- Multiple Parallelism Throughput on Different Capacity States



64 GPUs (A100) for 16 MoE Experts  
(Larger Capacity Factor Implies Stronger Imbalance)

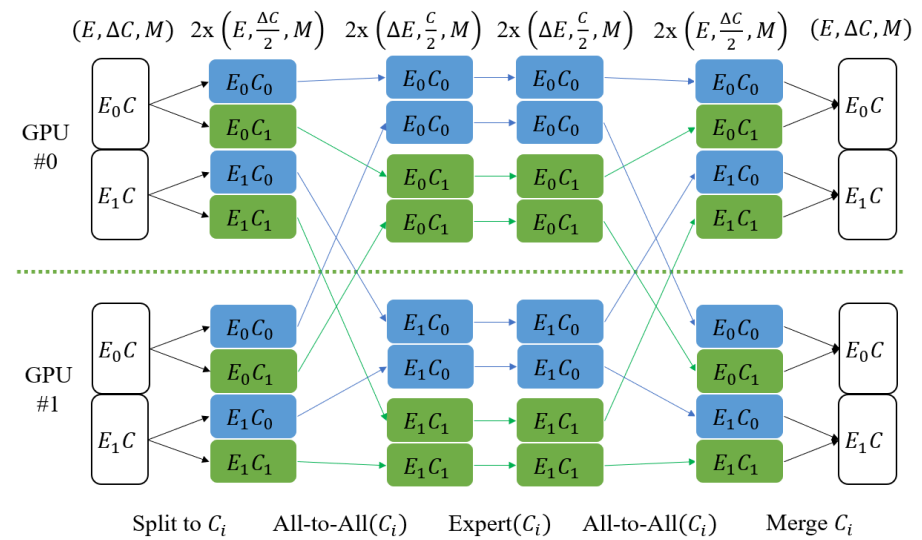
Capacity factor is *monotonic decreasing* with  $r$ .

# Adaptive Pipelining

Concurrent Overlap between network communication and processor computation in dynamic workloads with proper granularities.

"MoE graph  $\rightarrow$  multiple subgraph"

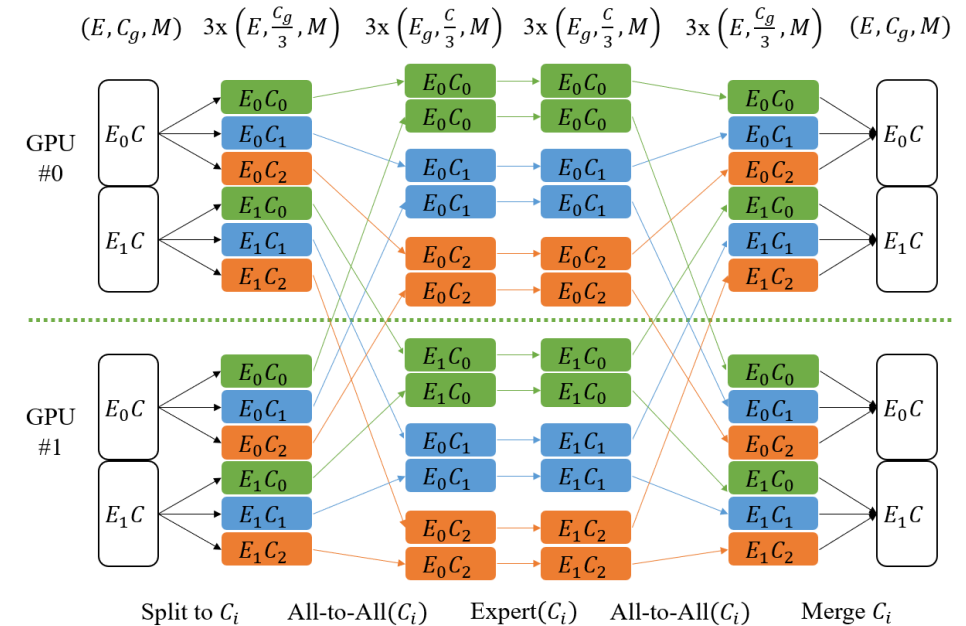
	Input Dispatch (Nvlink/InfiniBand)	Expert FFN (Processor)	Output Combine (Nvlink/InfiniBand)
t0	A2A		
t1	A2A	$T \otimes E$	
t2	A2A	$T \otimes E$	A2A
t3		$T \otimes E$	A2A
t4			A2A



## Example of 2-expert pipelining with degree=2



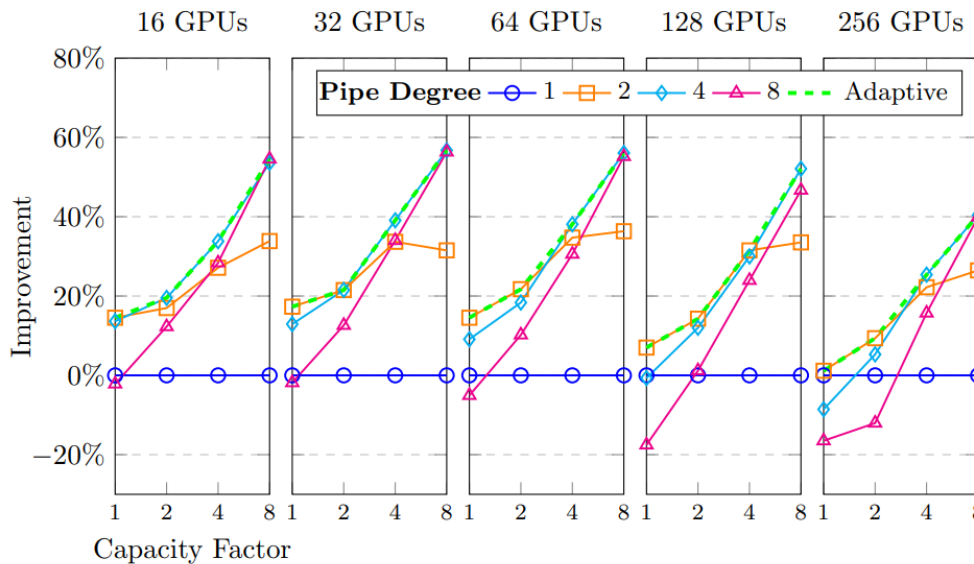
different colors are independent



## Example of 2-expert pipelining with degree=3

# Evaluation of Adaptive Pipelining

- Efficiency of Pipeline Degree on Different Capacity States



16-256 GPUs (A100) with 2 MoE Experts / GPU  
*(Larger Capacity Factor Implies Less Balanced)*

**Optimal Degree Selection is more random, however:**

- ① *Small Pipeline degree*: Not take advantage of overlap.
- ② *Large Pipeline degree*: Overhead of small-slice execution.

*Combined Example to Select Optimal Parallel Options:*

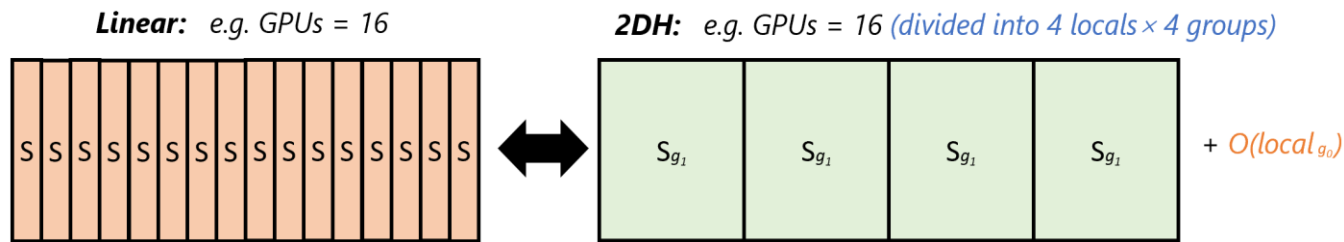
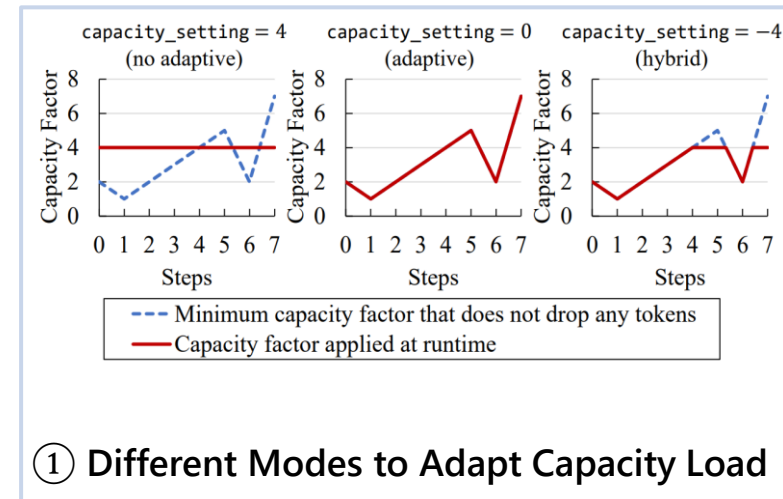
<i>dict</i>	1.00	1.01	...	4.10	...	8.00
value	r=2, o=1	r=2, o=1	...	r=2, o=2	...	r=1, o=4

# Training Time:

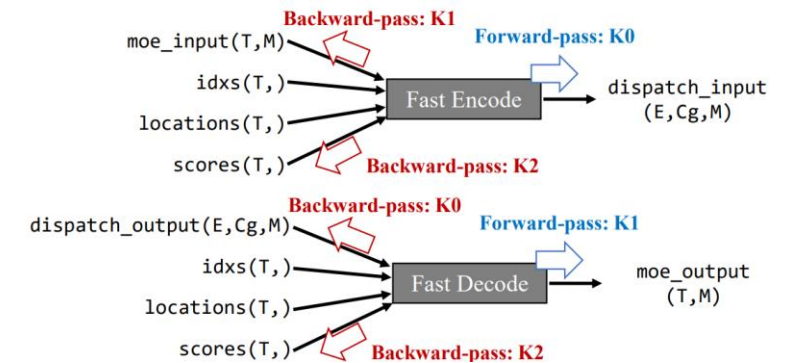
```
for step_id, input_xs, .. in data_loader(..):
    cap_factor, .. = tutel_moe.top_k_routing(input_xs, 1)
    tutel_moe.forward(.., adaptive_r=dict[cap_factor].r,
                      a2a_ffn_overlap_degree=dict[cap_factor].o)
```

# 3 Extra Adaptive Mechanisms or Optimizations

- ① Dynamic sparsity of Top-K & capacity controls (all "switchable");
- ② Adaptive All-to-All algo. for different scales (Linear/2DH + Flexible);
- ③ Deeply fused ops for "Fast Encode" and "Fast Decode" (90%↓ mem);



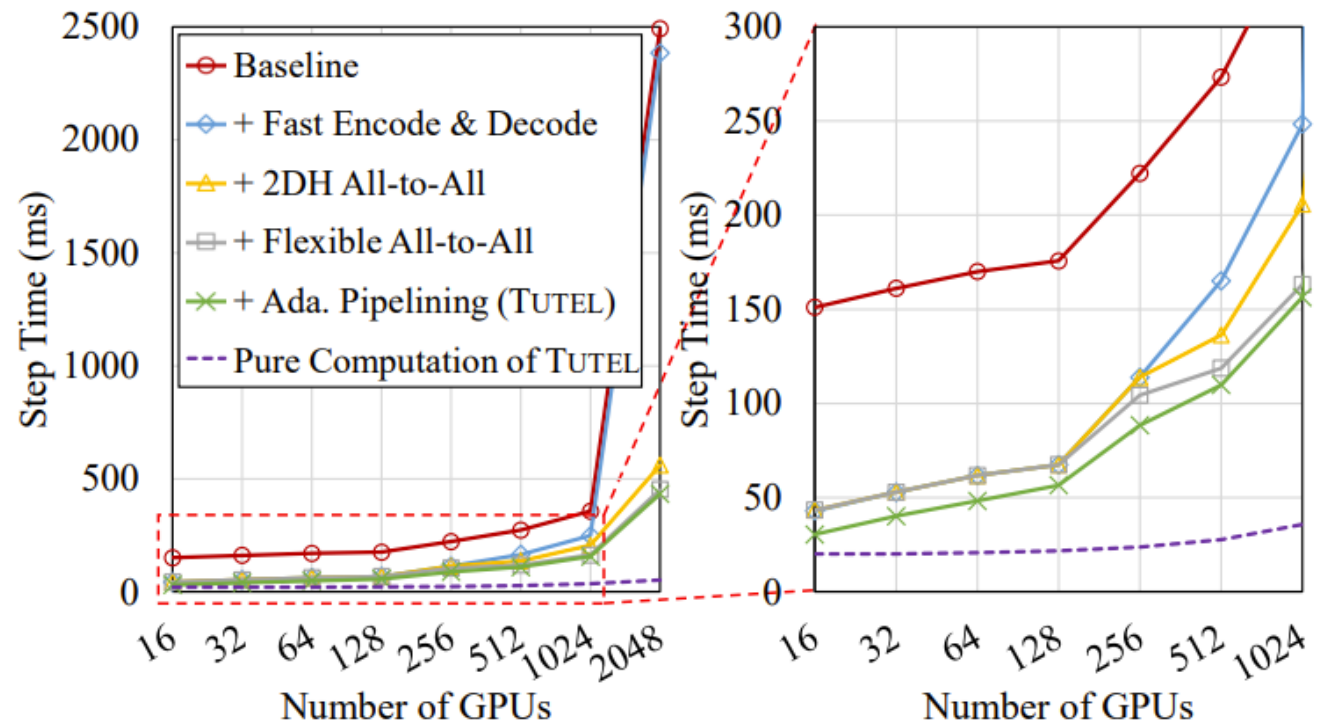
② Linear All2All (Left) for Small Scale      2DH All2All (Right) for Large Scale



③ Fused & Optimized Fast Encode and Decode

# Evaluation of Tutel MoE on 2,048 GPUs (A100)

- 1 Baseline: Fairseq MoE / Deepspeed MoE
- 2 Tutel optimization: Fast Encode & Decode
- 3 above + 2DH All-to-All
- 4 above + Flexible All-to-All
- 5 above + adaptive parallelism
- 6 Tutel computation time per device



Tutel MoE Layer delivers **4.96x** and **5.75x** speedup on 16 A100 and 2,048 A100, respectively



## Adaptive

The first MoE solution to design **online parallelism modification, switch** between different algorithm options and adapt across dynamic MoE workloads.



## At Scale

*Tutel* <sup>[1]</sup> tackles non-scalable MoE, and achieves up to 5.75x **speedup on 2,048 A100** in Azure.



## Deterministic Gains

*Tutel* provides a **gain with reproducible guarantee** for different states of capacity. **No predictors, no penalties and no math-inequivalence** is involved, all of which may result in more harm against static. (throughput. & acc.)

Thank you