



Summary

Background: Limited data in GAN training causes discriminator overfitting and training instability.

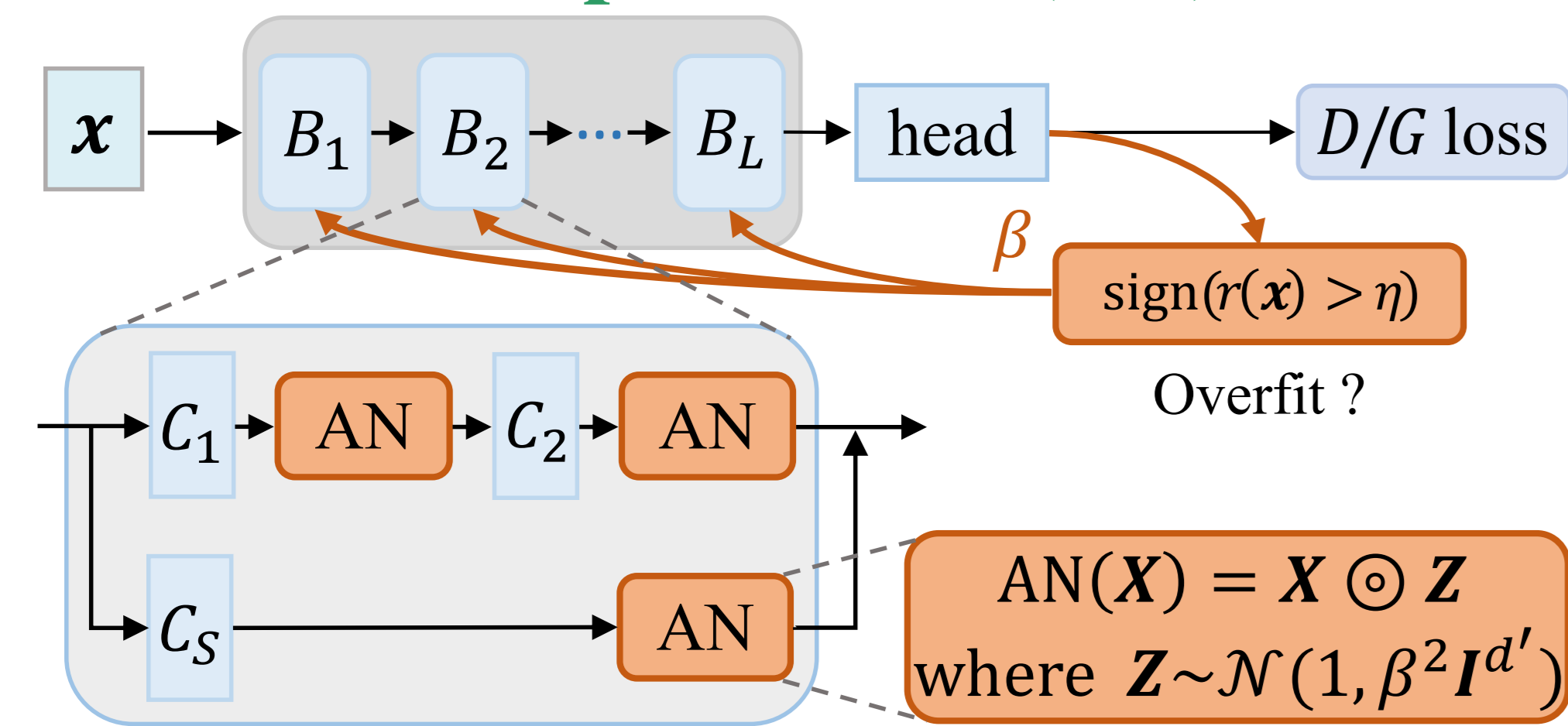
Goal: To improve the generalization of GANs.

Contributions:

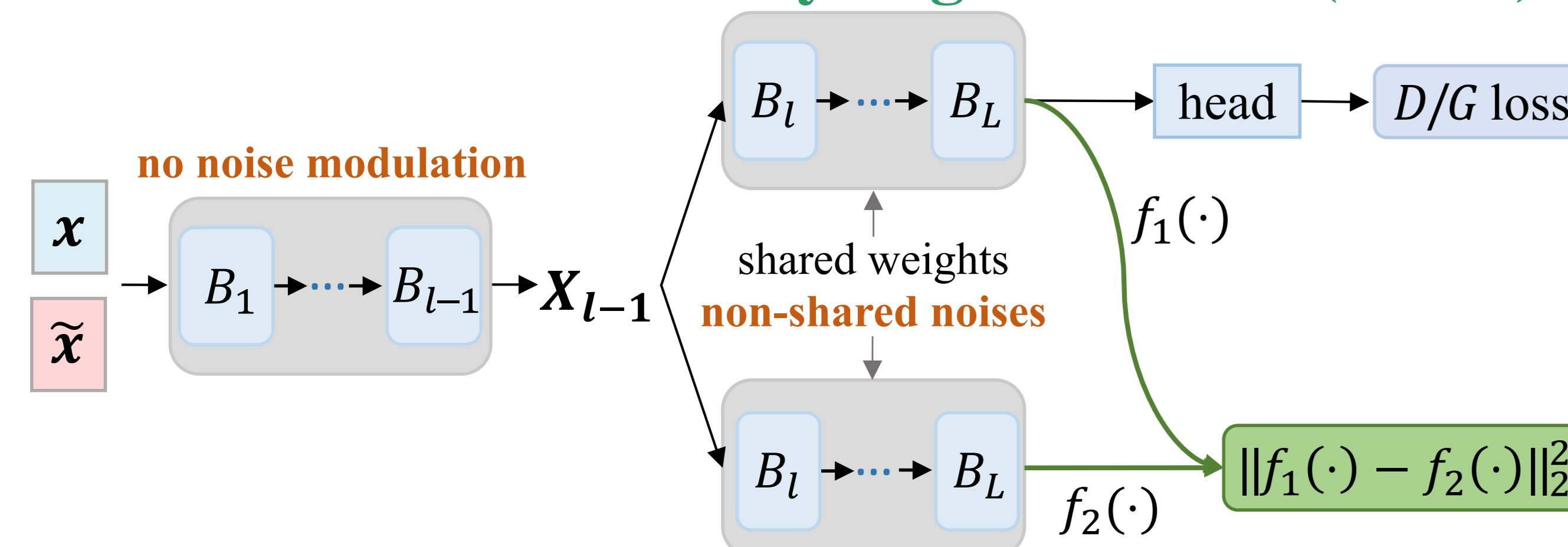
- We use an adaptive multiplicative noise to modulate latent features of discriminator to boost generalization of GAN.
- We introduce NICE to enforce the discriminator consistency across varying noise modulations, implicitly penalizing first and second-order gradients of discriminator latent features to improve the stability of training.
- We showcase theoretical and practical effectiveness of NICE in preventing discriminator overfitting. We achieve superior performance in image generation with limited data.

Pipeline

Discriminator with adaptive noise (AN)^a:



Noise-modulated Consistency rEgularization (NICE):



Update β : control the variance of noise by monitoring $r(\mathbf{x}) = \mathbb{E}[\text{sign}(D(\mathbf{x}))]$. Update $\beta_{t+1} = \beta_t + \Delta\beta \cdot \text{sign}(r(\mathbf{x}) > \eta)$.

NICE: weight regularization → better generalization

NICE: gradient penalization → stable training

^a d' : feature size. \odot : expands \mathbf{Z} to $d' \times d^H \times d^W$ then performs element-wise multiplication. B_l : l -th block. C_S : Convolution in skip branch. f : feature extractor. $\mathbf{x}/\tilde{\mathbf{x}}$: real/fake image. η : a threshold.

Method

Reducing the weight norms of D improves generalization:

n : dataset size. \mathcal{H}/\mathcal{G} : D/G sets. $\forall h \in \mathcal{H}, \|h\|_\infty \leq \Delta$. μ/ν : measures on real/fake data. $\hat{\mu}_n/\nu_n$: empirical measures. Assume $d_{\mathcal{H}}(\hat{\mu}_n, \nu_n) - \inf_{\nu \in \mathcal{G}} d_{\mathcal{H}}(\hat{\mu}_n, \nu) \leq \epsilon$.

$$d_{\mathcal{H}}(\mu, \nu_n) - \inf_{\nu \in \mathcal{G}} d_{\mathcal{H}}(\mu, \nu) \leq \underbrace{2R_n^{(\mu)}(\mathcal{H})}_{\text{Generalization error of GAN.}} + \underbrace{2\Delta\sqrt{2\log(1/\delta)/n}}_{\text{Complexity of } D.} + \epsilon$$

For $\forall i \in \{1, \dots, n\}, \|\mathbf{x}^{(i)}\|_2 \leq q$ and a t -layer fully-connected network parameterized from set $\mathcal{V} = \{\mathbf{v}_\theta : \|\mathbf{W}_i\|_{\text{lip}} \leq k_i, \|\mathbf{W}_i^T\|_{2,1} \leq b_i\}$:

$$R_n^{(\mu)}(\mathcal{V}) \leq \frac{q}{\sqrt{n}} \cdot \left(\prod_{i=1}^t k_i\right) \cdot \left(\sum_{i=1}^t \underbrace{b_i^{2/3}/k_i^{2/3}}_{\text{Weight norm.}}\right)^{3/2}$$

Rademacher complexity.

Multiplicative noise modulation reduces weight norms:

\mathbf{w}_k : the k -th column vector of the second layer weight \mathbf{W}_2 . \hat{a}_k : mean feature norm ≥ 0 . β^2 : variance of noise. \mathbf{y} : label. Multiplicative noise modulation \mathbf{z} on the latent feature $\mathbf{a}^{(i)}$ in a two-layer net induces weight regularization.

$$\begin{aligned} \hat{L}_{\text{noise}}(\mathbf{w}) &:= \hat{\mathbb{E}}_i \mathbb{E}_z [\|\mathbf{y}^{(i)} - \mathbf{W}_2(\mathbf{z} \odot \mathbf{a}^{(i)})\|_2^2] \\ &= \hat{\mathbb{E}}_i [\|\mathbf{y}^{(i)} - \mathbf{W}_2 \mathbf{a}^{(i)}\|_2^2] + \underbrace{\beta^2 \sum_k \hat{a}_k \|\mathbf{w}_k\|_2^2}_{\text{Implicit regularization on } \|\mathbf{w}_k\|_2.} \end{aligned}$$

Noise modulation causes gradient norm amplification:

$$\begin{aligned} \min_{\theta_a} L_D^{\text{AN}} &:= \mathbb{E}_{\tilde{\mathbf{a}}} \mathbb{E}_z [h(\mathbf{z} \odot \tilde{\mathbf{a}})] - \mathbb{E}_{\mathbf{a}} \mathbb{E}_z [h(\mathbf{z} \odot \mathbf{a})] \\ &\approx \mathbb{E}_{\tilde{\mathbf{a}}} [h(\tilde{\mathbf{a}})] - \mathbb{E}_{\mathbf{a}} [h(\mathbf{a})] \\ &\quad + \frac{\beta^2}{2} (\mathbb{E}_{\tilde{\mathbf{a}}} [\sum_k \tilde{a}_k^2 H_{kk}^{(h)}(\tilde{\mathbf{a}})] - \mathbb{E}_{\mathbf{a}} [\sum_k a_k^2 H_{kk}^{(h)}(\mathbf{a})]) \end{aligned}$$

$$\begin{aligned} \min_{\theta_g} L_G^{\text{AN}} &:= -\mathbb{E}_z \mathbb{E}_{\tilde{\mathbf{a}}} [h(\mathbf{z} \odot \tilde{\mathbf{a}})] \\ &\approx -\mathbb{E}_{\tilde{\mathbf{a}}} [h(\tilde{\mathbf{a}})] - \frac{\beta^2}{2} \mathbb{E}_{\tilde{\mathbf{a}}} [\sum_k \tilde{a}_k^2 H_{kk}^{(h)}(\tilde{\mathbf{a}})] \end{aligned}$$

$\mathbf{a}/\tilde{\mathbf{a}}$: real/fake feature. $H^{(h)}(\mathbf{a})$: Hessian of h at \mathbf{a} . \odot : element-wise product.

Consistency regularization (NICE) lowers gradient norm:

$$\begin{aligned} \ell^{\text{NICE}}(\mathbf{a}) &:= \mathbb{E}_{z_1, z_2} [(f(z_1 \odot \mathbf{a}) - f(z_2 \odot \mathbf{a}))^2] \\ &\approx 2\beta^2 \sum_k a_k^2 \nabla_k^2 f(\mathbf{a}) + \beta^4 \sum_{j,k} a_j^2 a_k^2 (H_{jk}^{(f)}(\mathbf{a}))^2 \end{aligned}$$

$\nabla f(\mathbf{a}), H^{(f)}(\mathbf{a})$: gradient and Hessian matrix of feature extractor f at \mathbf{a} .

$H_{jk}^{(f)}$: (j, k) -th entry of $H^{(f)}$.

We apply NICE on real & fake images when training G & D .

Experimental Results

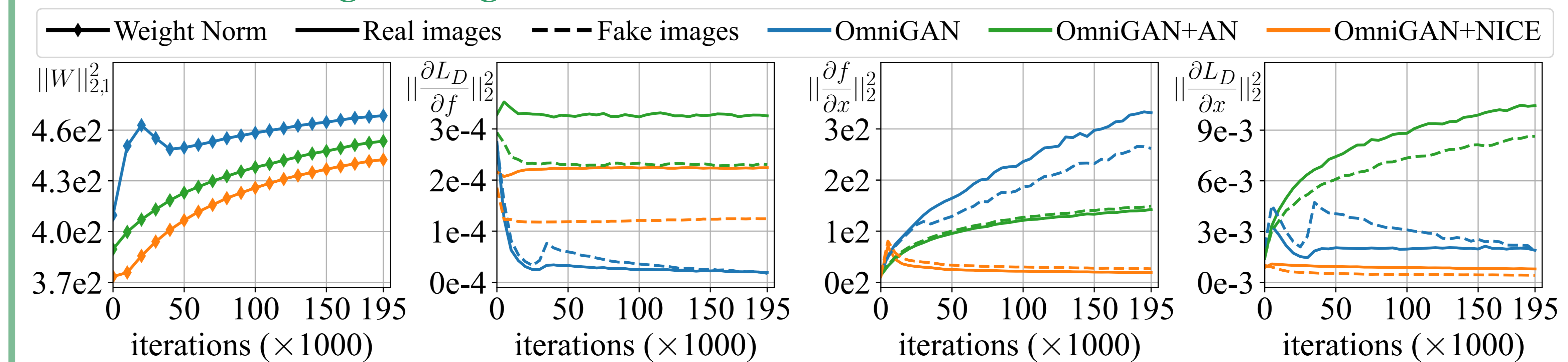
Comparison with the state of the art:

Method	CIFAR-10			CIFAR-100			FID ↓ on ImageNet		
	100% data	20% data	10% data	100% data	20% data	10% data	10%	5%	2.5%
BigGAN	9.21/5.48	8.74/16.20	8.24/31.45	11.02/7.86	9.94/25.83	7.58/50.79	38.30	91.16	133.80
+NICE	9.50/4.19	8.96/8.51	8.73/13.65	10.99/6.31	10.32/13.17	8.96/19.53	31.89	43.21	56.83
LeCam+DA	9.45/4.32	9.01/8.53	8.81/12.64	11.25/6.45	10.12/15.96	9.17/22.75	32.82	56.75	63.49
+NICE	9.52/3.72	9.12/6.92	8.99/9.86	11.28/5.72	10.54/10.02	9.35/14.95	26.51	35.70	38.62
OmniGAN+ADA	10.24/4.95	9.41/27.04	7.86/40.05	13.07/6.12	12.07/13.54	8.95/44.65	20.32	22.35	28.79
+NICE	10.38/2.25	10.18/4.39	10.08/5.49	13.82/3.78	12.75/6.28	12.04/9.32	21.44	24.72	31.45

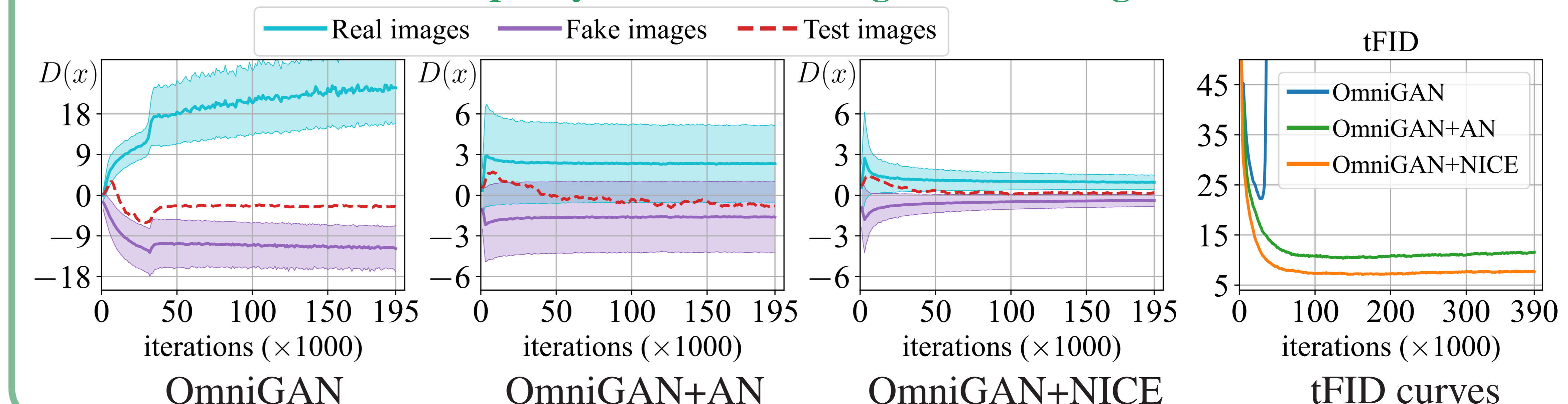
Method (FID↓)	Obama	GrumpyCat	Panda	AnimalCat	AnimalDog
	StyleGAN2	80.20	48.90	34.27	71.71
StyleGAN2+NICE	24.56	18.78	8.92	25.25	46.56

Method (FID↓ on FFHQ)	100	1K	2K	5K
	StyleGAN2	179	100.16	54
ADA	85.8	21.29	15.39	10.96
ADA-Linear	82	19.86	13.01	9.39
InsGen	45.75	18.21	11.47	7.83
FakeCLR	42.56	15.92	9.90	7.25
ADA+NICE	38.42	14.57	8.85	6.48

NICE reduces weight and gradient norms in the discriminator:



NICE minimizes the discrepancy between training and test images:



Generated Images:

