



United Nations  
Educational, Scientific and  
Cultural Organization

Egyesült Nemzetek  
Nevelésügyi, Tudományos és  
Kulturális Szervezete

100th anniversary of Roland Eötvös  
(1848-1919), physicist, geophysicist,  
and innovator of higher education  
Commemorated in association with UNESCO

Eötvös Loránd (1848-1919) fizikus,  
geofizikus és a felsőoktatás  
megújítójának 100. évfordulója  
Az UNESCO-val közösen emlékezve



*Lajos Völgyesi*

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Kiss B., Fenyvesi E.,  
Péter G., Somlai L.,  
Égető Cs., Deák L.,  
Barnaföldi G., Gróf Gy.,  
Harangozó P., Lévai P.,  
Ván P.*



# *Torsion Balance and Remeasurement of the Eötvös experiment*

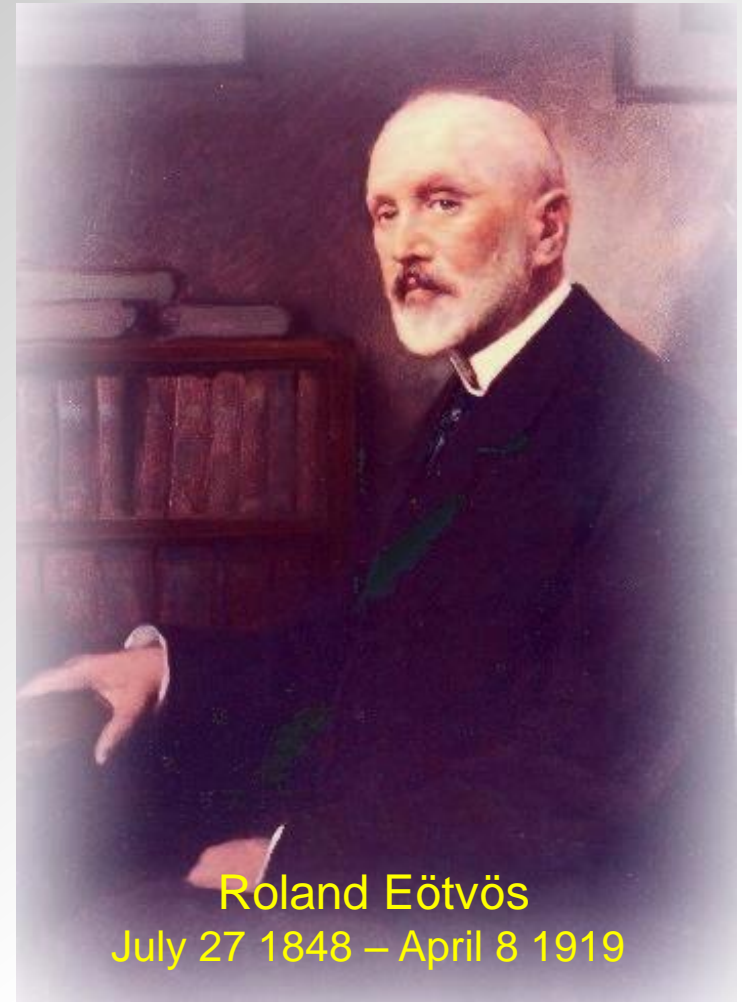


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## 100th anniversary of Roland Eötvös (1848-1919), physicist, geophysicist, and innovator of higher education

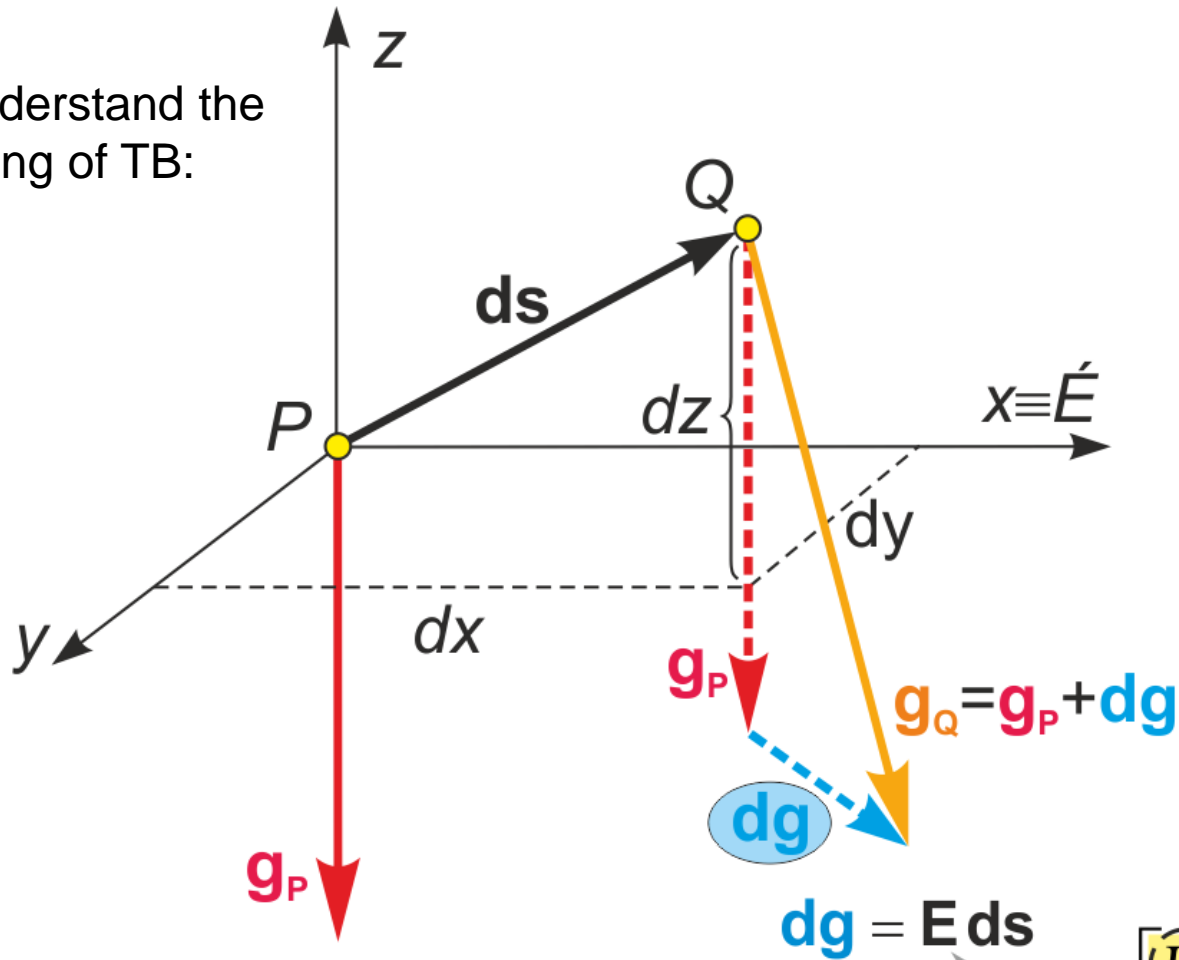
Commemorated in association with UNESCO

- Roland Eötvös was born in 1848 and died in 1919 so we celebrate the 100th anniversary of his death this year.
- **United Nations Educational, Scientific and Cultural Organization (UNESCO) declared the year 2019 as “Eötvös year”.**
- In 2017 we decided to celebrate this anniversary, by re-measure the Eötvös experiment for validating the equivalence of gravitational and inertial mass.
- When we started to study descriptions of the previous measurements, we found a possible explanation for the known systematic error and from this moment our plan of re-measurement became really serious.
- Eötvös became a world famous physicist by his torsion balance. In the next we will discuss the base principle and short history of the torsion balance and then the preparations and present status of our new equivalence experiment.



**Roland Eötvös**  
July 27 1848 – April 8 1919

for to understand the functioning of TB:



$$dg = E ds$$

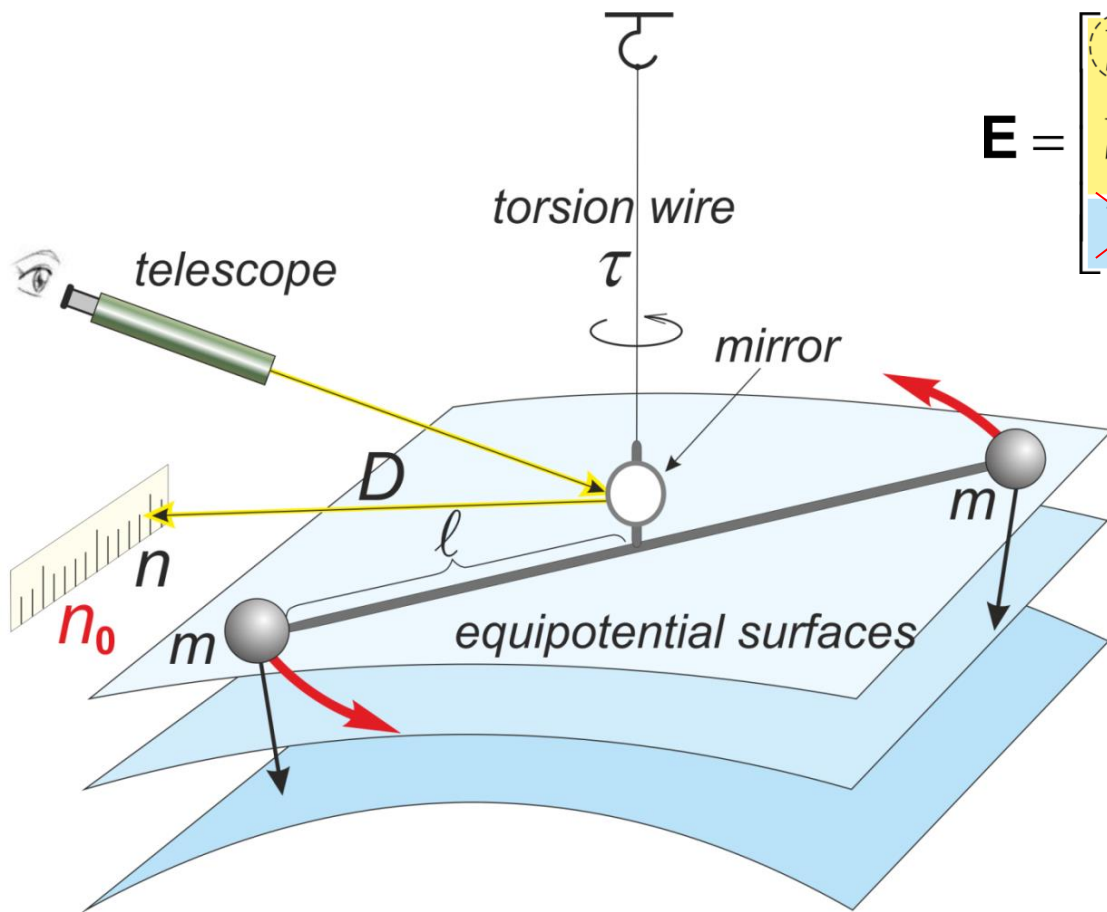
$$E = \begin{bmatrix} W_{xx} & W_{xy} & W_{xz} \\ W_{yx} & W_{yy} & W_{yz} \\ W_{zx} & W_{zy} & W_{zz} \end{bmatrix}$$

From torsion balance measurements:

$$W_{\Delta}, W_{xy}$$

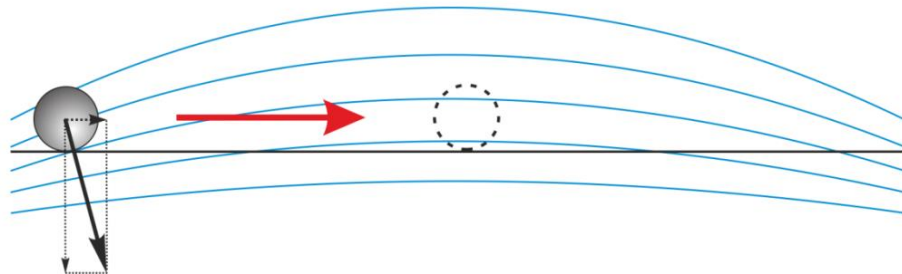
$$W_{zx}, W_{zy}$$

$$(W_{\Delta} = W_{yy} - W_{xx})$$



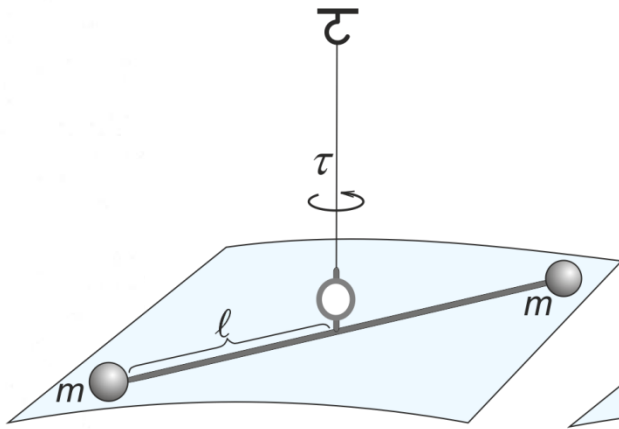
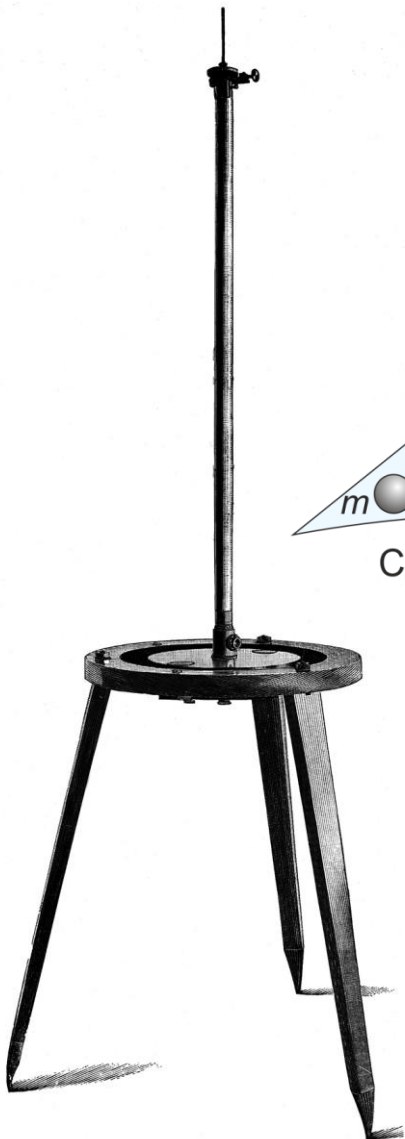
$$\mathbf{E} = \begin{bmatrix} W_{xx} & W_{xy} & W_{xz} \\ W_{yx} & W_{yy} & W_{yz} \\ W_{zx} & W_{zy} & W_{zz} \end{bmatrix}$$

**Curvature variometer** was the classic Coulomb (Cavendish) balance, comprising a horizontal beam with two identical masses at each end, suspended on a torsion wire.

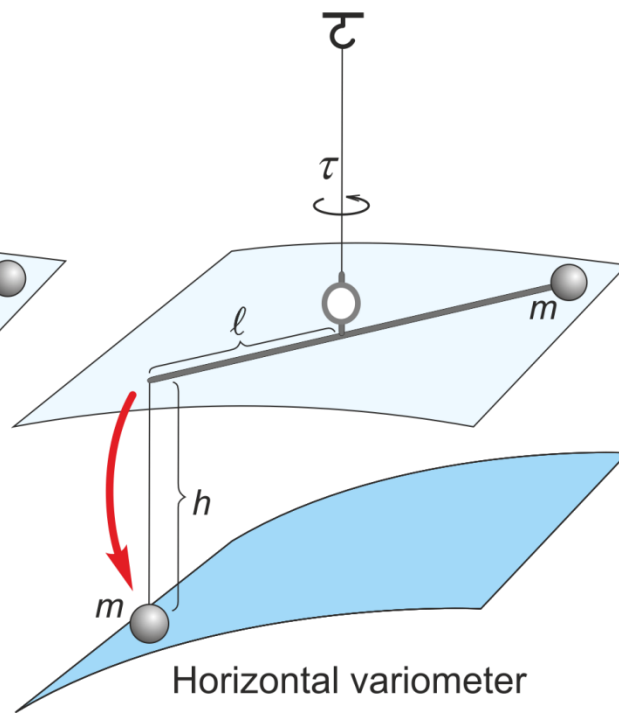


(spherical symmetry  $\rightarrow$  torsion-free damped position  $n_0$ )

If the equipotential surface deviates from a sphere there are small horizontal forces turning the beam into direction of the smallest curvature, namely this balance can measure the degree of deviation of the equipotential surface from the spherical shape.

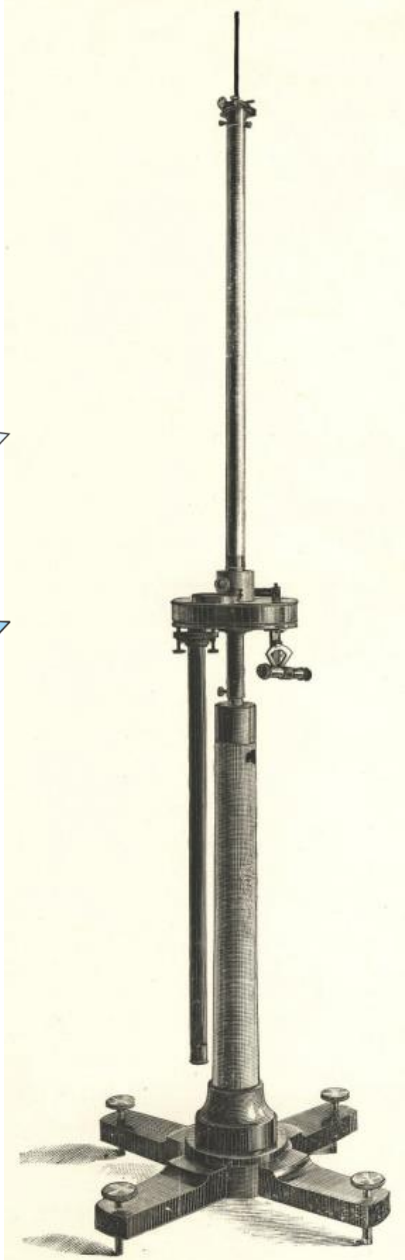


Curvature variometer



Horizontal variometer

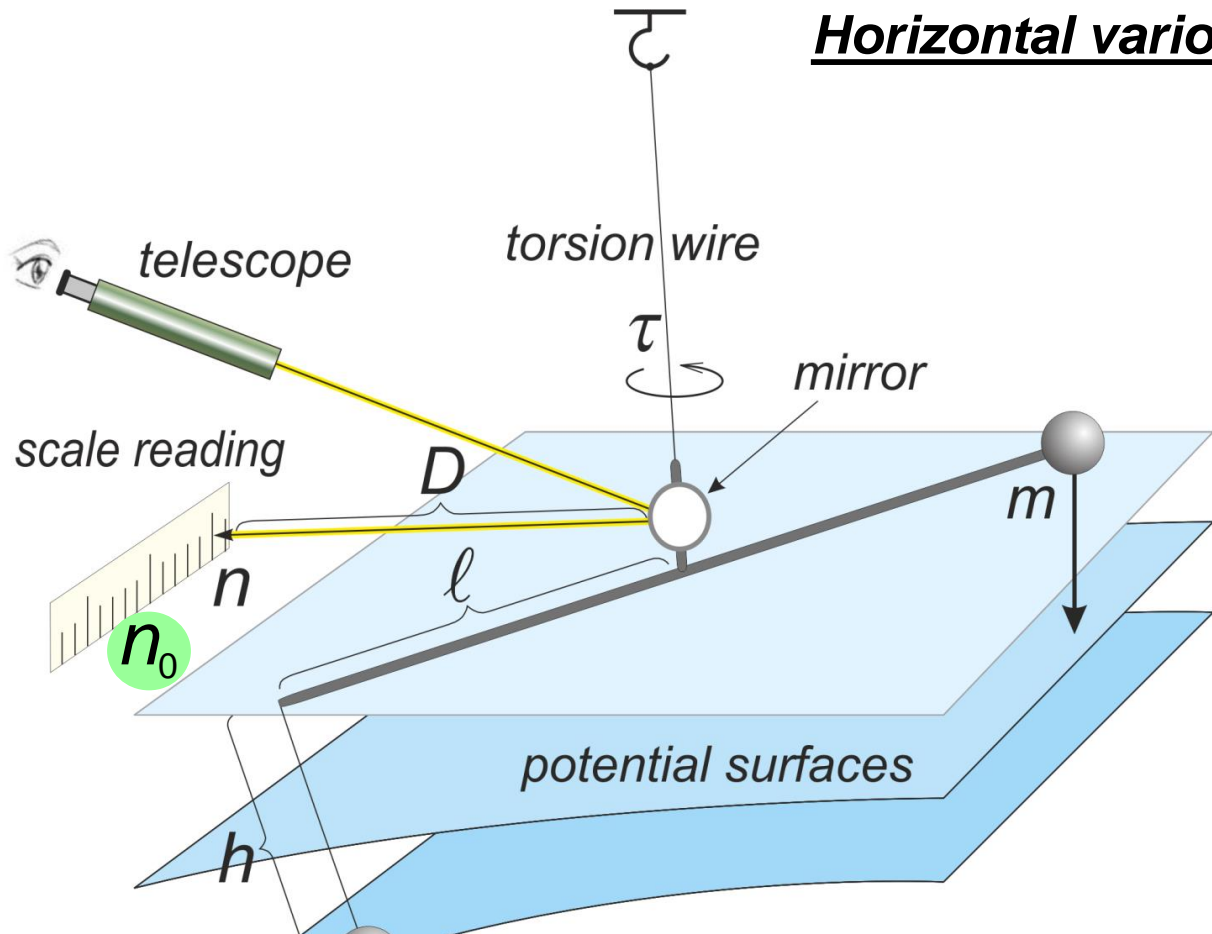
The great invention of Eötvös was that he took one of the masses off the beam and suspended it with a thin wire in a deeper position.



**Horizontal variometer**  
Eötvös (1890)

**Curvature variometer**  
Eötvös (1890)

# Horizontal variometer



$$\mathbf{E} = \begin{bmatrix} W_{xx} & W_{xy} & W_{xz} \\ W_{yx} & W_{yy} & W_{yz} \\ W_{zx} & W_{zy} & \cancel{W_{zz}} \end{bmatrix}$$

$$n - n_0 = \frac{DK}{\tau} (W_{\Delta} \sin 2\alpha + 2W_{xy} \cos 2\alpha) + \frac{2Dhlm}{\tau} (W_{zy} \cos \alpha - W_{zx} \sin \alpha)$$

$$W_{\Delta} = W_{yy} - W_{xx}$$

torsion-free position



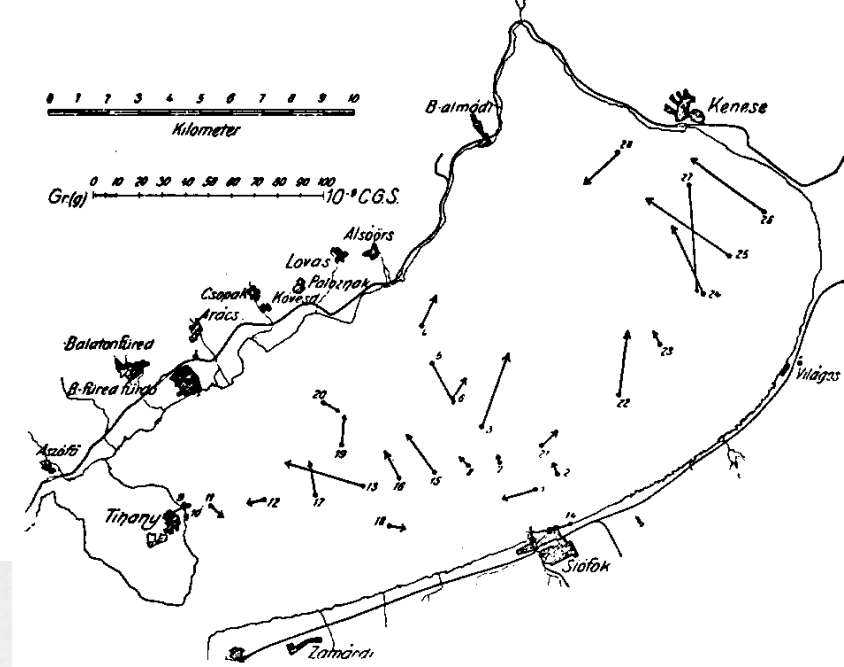
First Eötvös torsion balance:  
**Horizontal variometer**, 1890



*First field measurement: Ság-hill survey, 1891.*



Balaton-balance (1898)



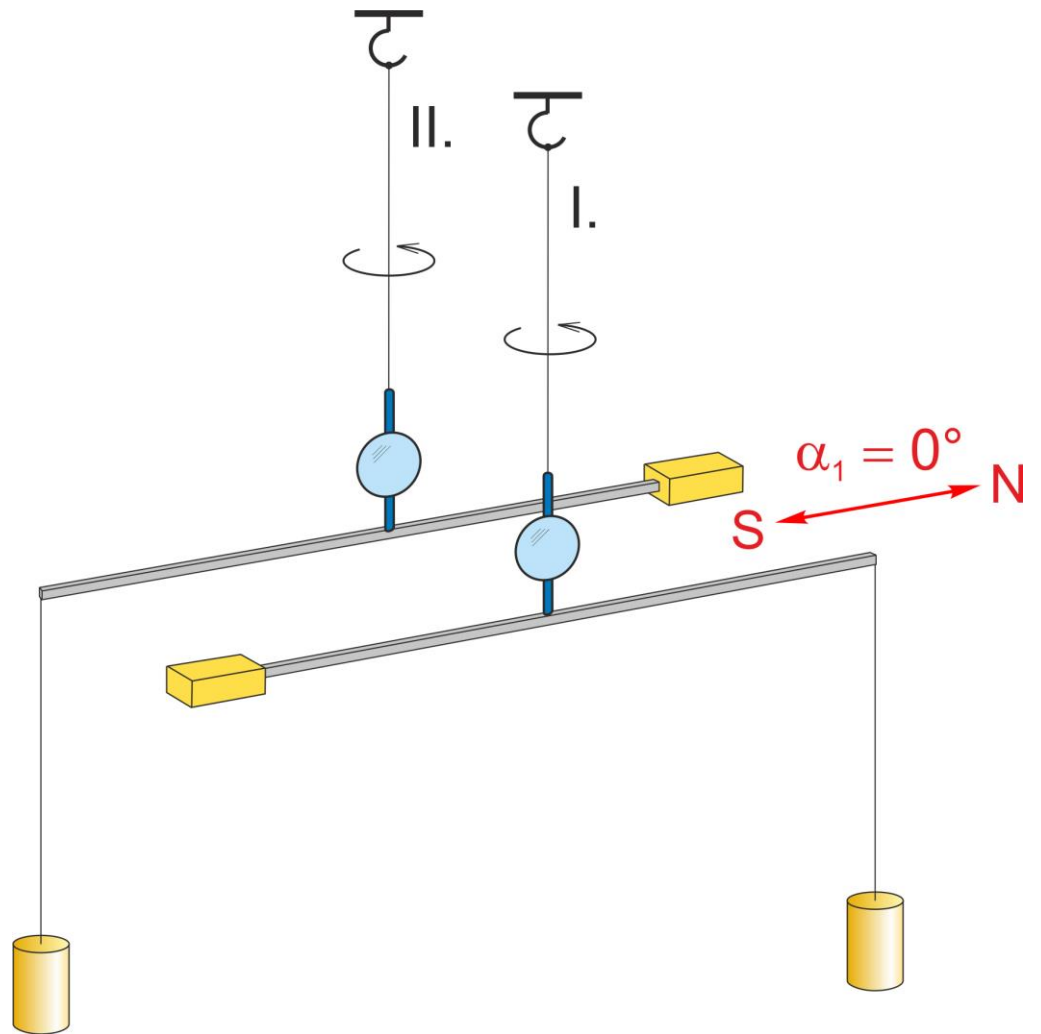
Expedition on Lake Balaton (1901, 1903)







“Large double balance”  
(1902)



$$n_1 - n_0 = \frac{DK}{\tau} (W_{\Delta} \sin 2\alpha + 2W_{xy} \cos 2\alpha) + \frac{2Dhlm}{\tau} (W_{zy} \cos \alpha - W_{zx} \sin \alpha)$$

$$n_2 - n_0^* = \frac{DK}{\tau} (W_{\Delta} \sin 2\alpha + 2W_{xy} \cos 2\alpha) + \frac{2Dhlm}{\tau} (W_{zy} \cos \alpha - W_{zx} \sin \alpha)$$

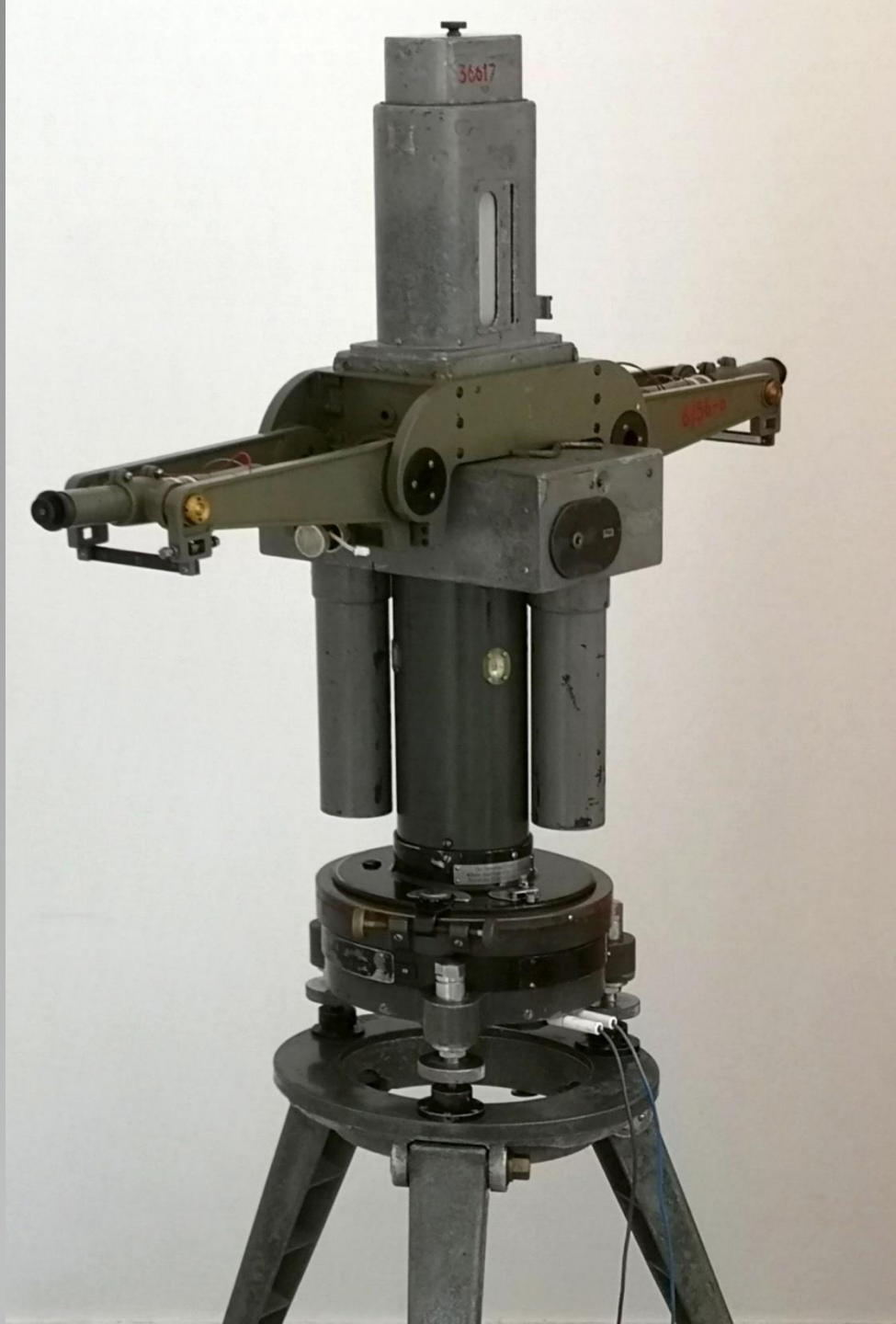
Eötvös-Pekár Balance  
(*Small Double Balance*)  
1926, 1928, 1930

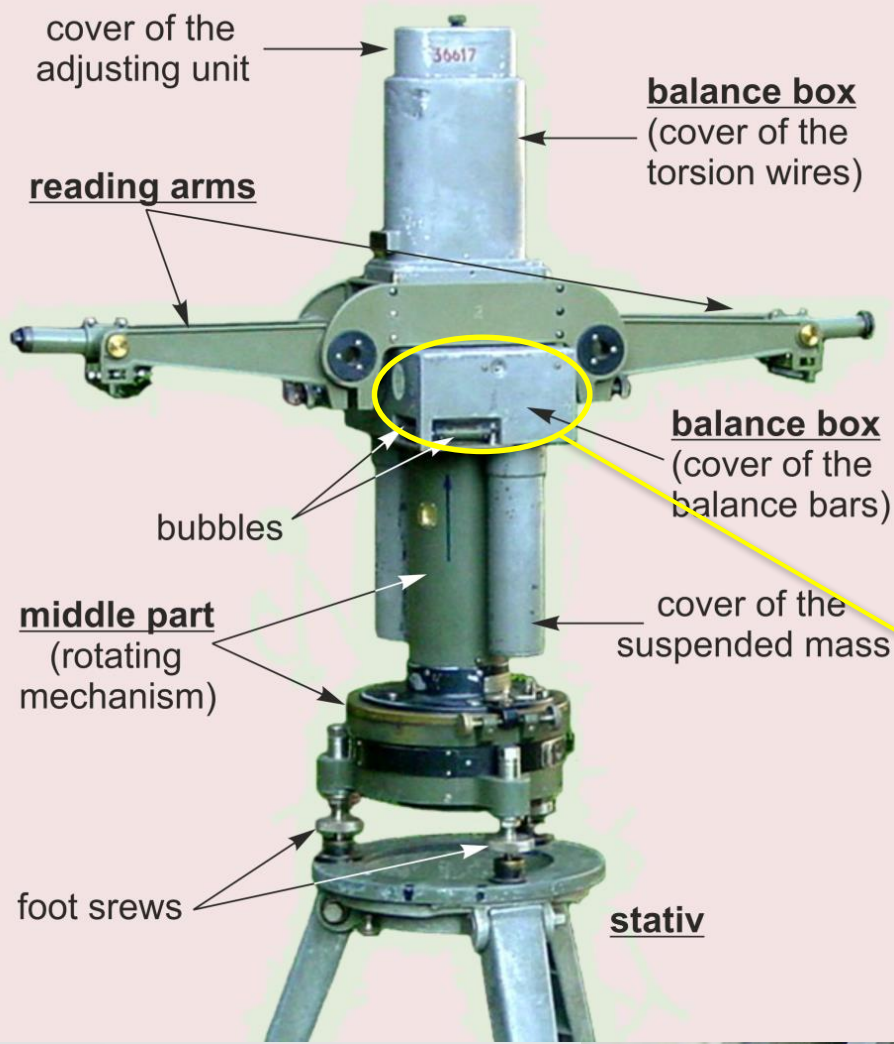
successful for field  
measurements,  
non-automatic operation,  
very accurate and reliable,  
easily replaceable masses,  
**best usable for equivalence  
measurements**



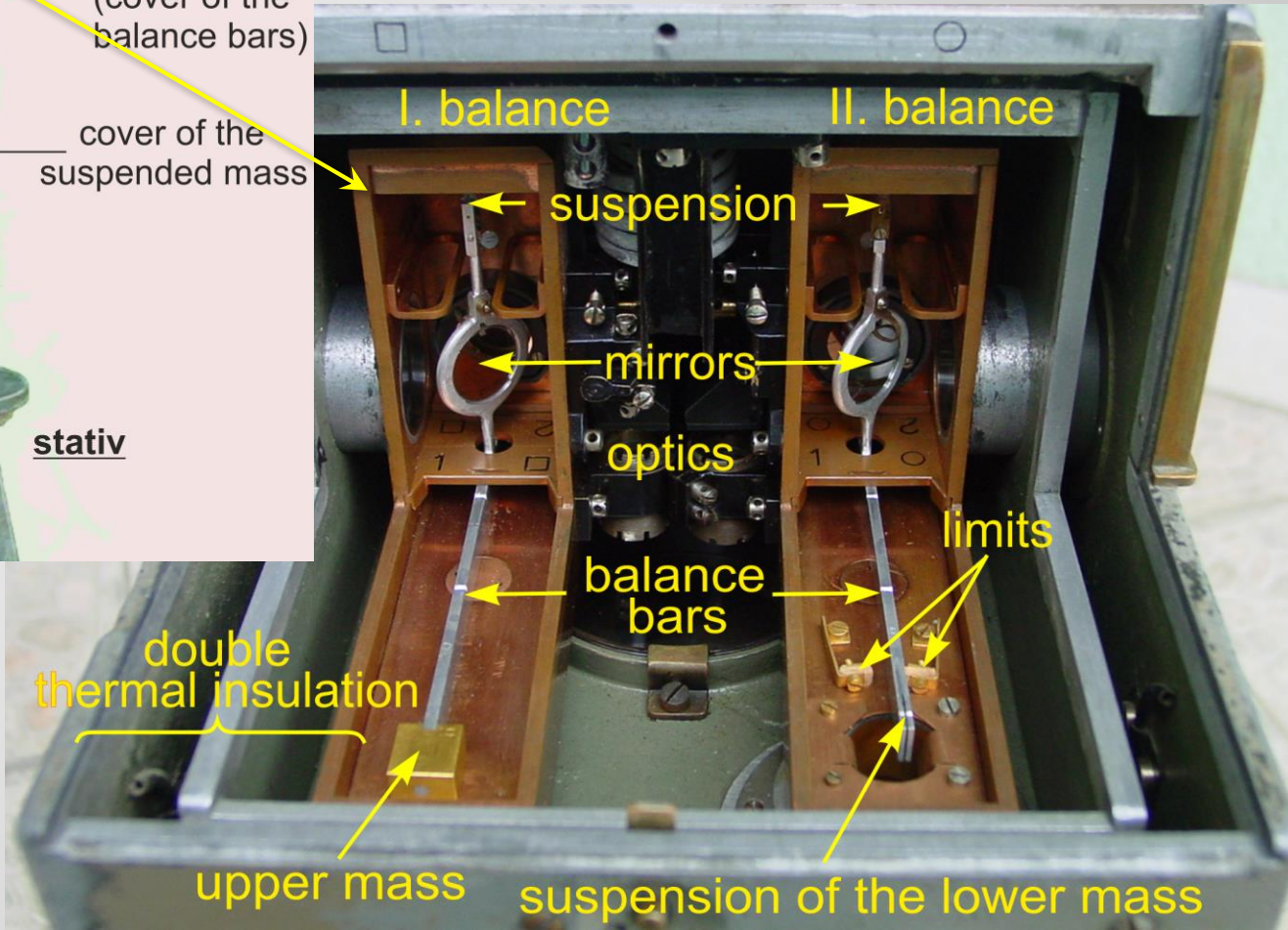
# Eötvös-Rybár Balance (*AutERBal Balance*) 1928

successful for field  
measurements,  
automatic operation with photo  
registration,  
not so accurate and reliable,  
difficult to replace the masses,  
hard to use for equivalence  
measurements





*Look inside the torsion balance*





E54 (1954)

well suitable for field measurements

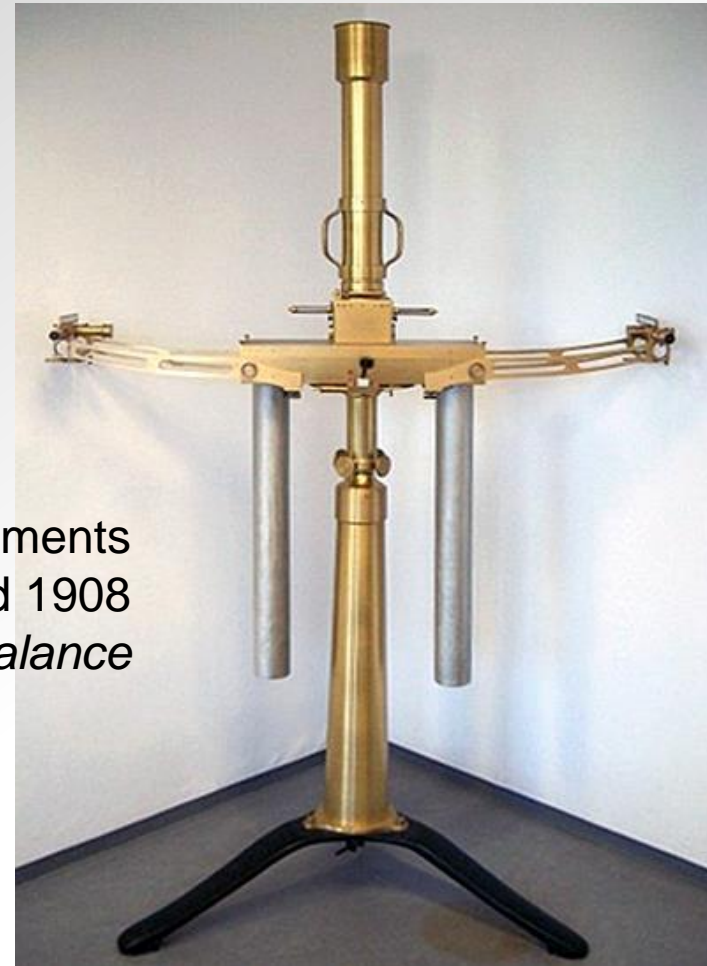
# *Equivalence principle*

## *The Eötvös experiment*

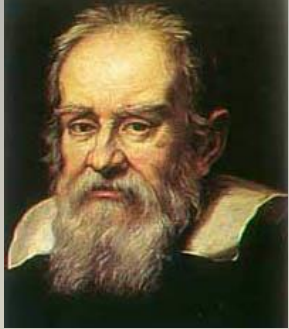
First experiment in 1896  
by *Curvature Variometer*



EPF measurements  
between 1906 and 1908  
by *Large Double Balance*



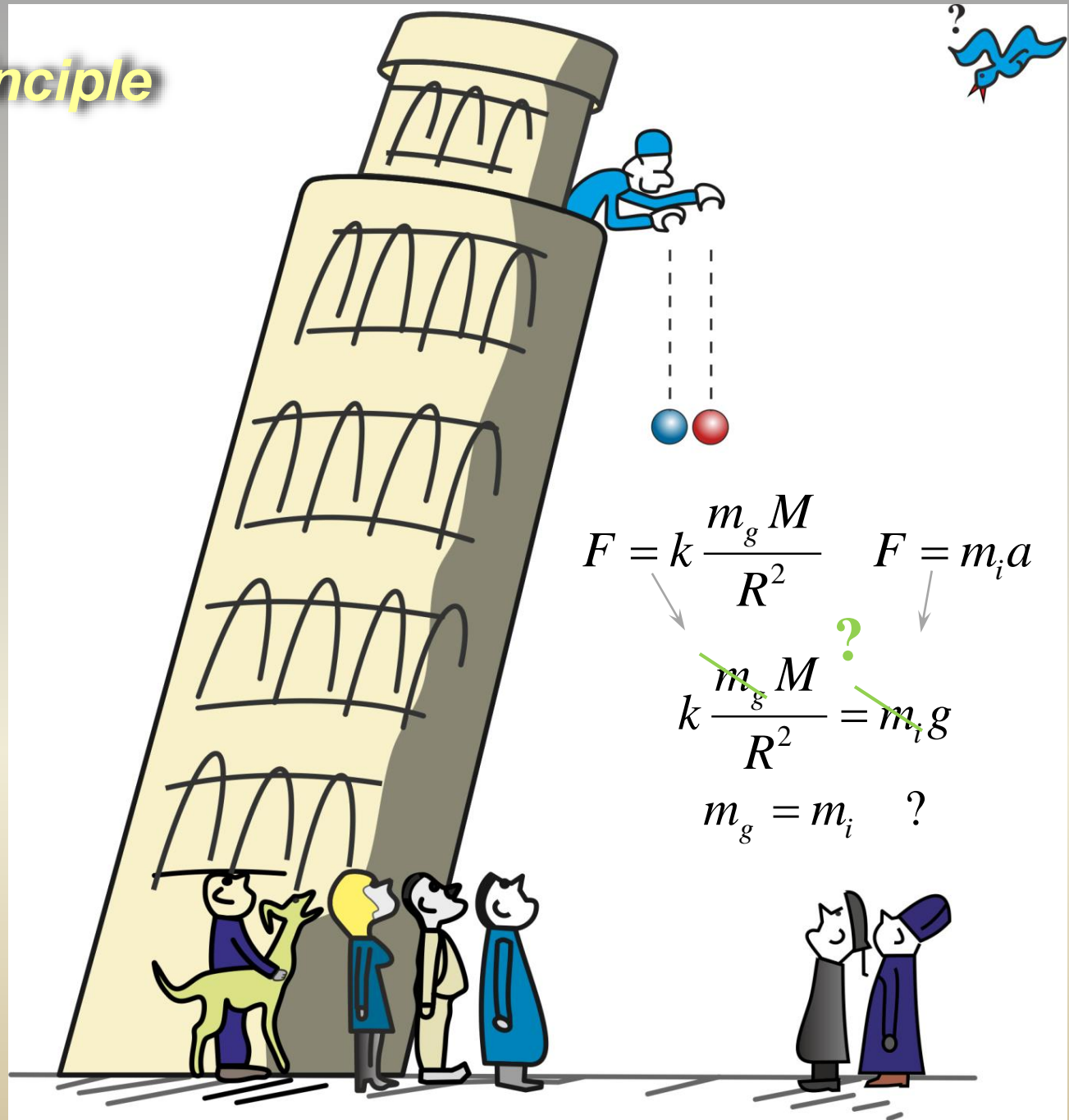
# Equivalence principle

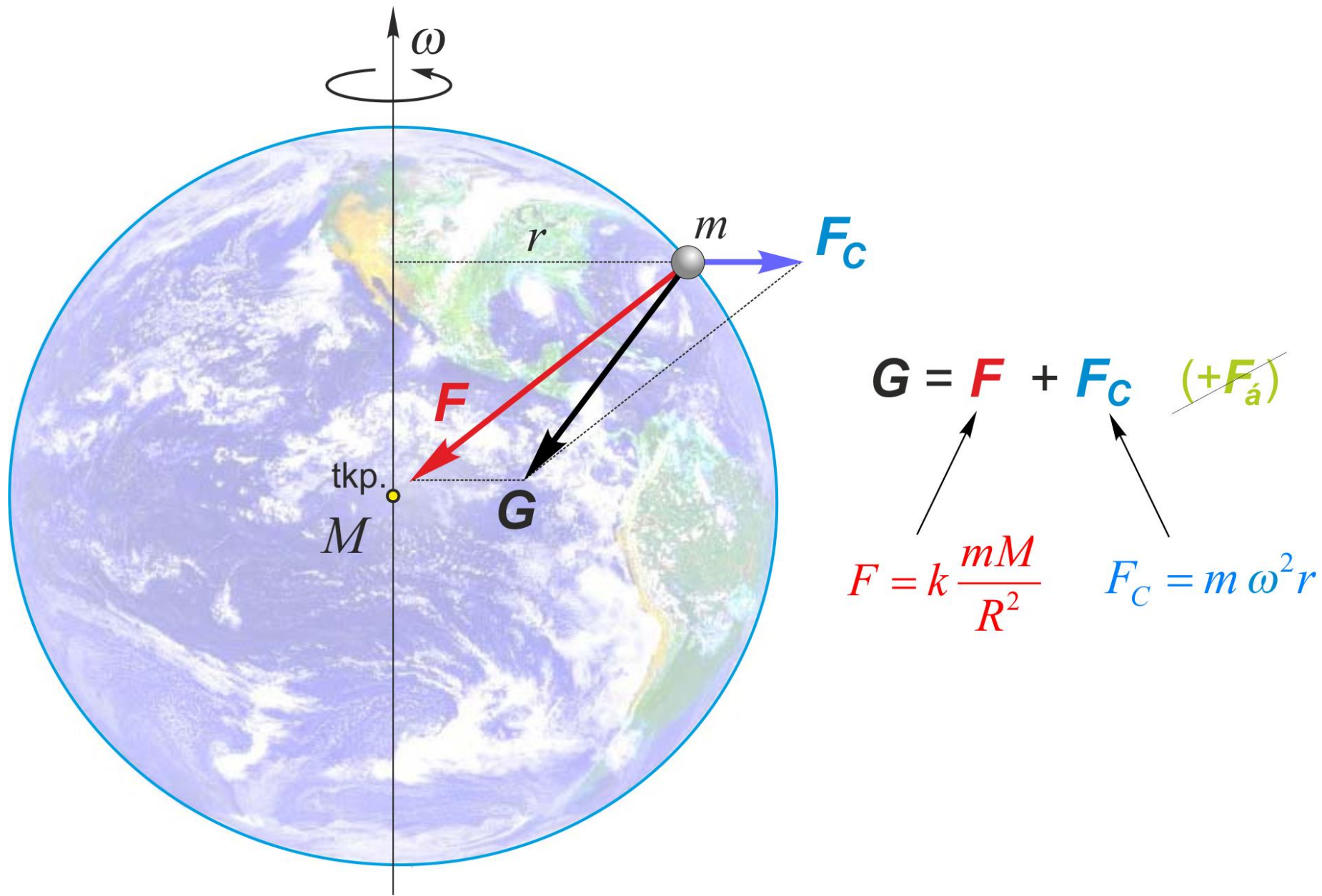


Galileo Galilei  
1564-1642

Galilei (?)  
Simon Stevin, 1586

*Base question:*  
Is the gravitation  
depends on the material?



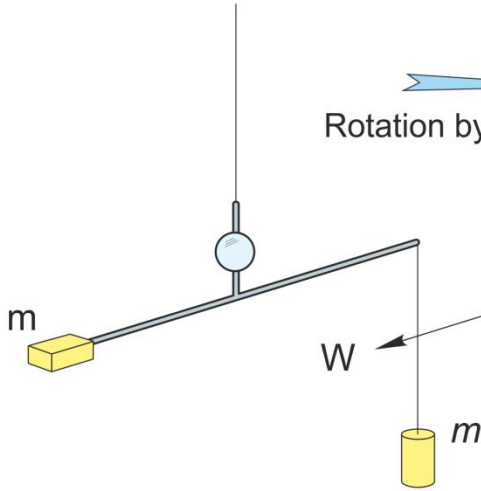




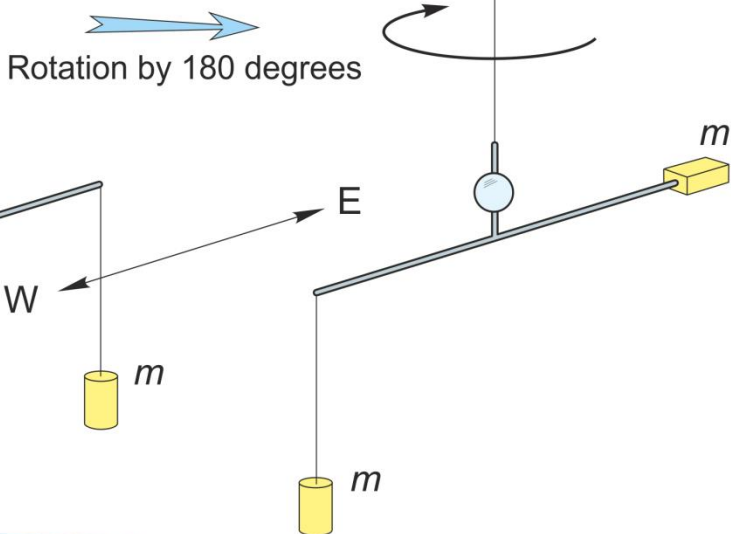


**Mass exchanging measurement strategy**

1st measurement

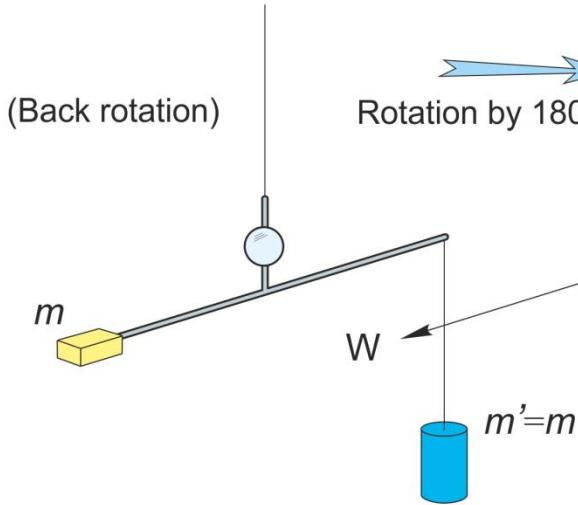


2nd measurement

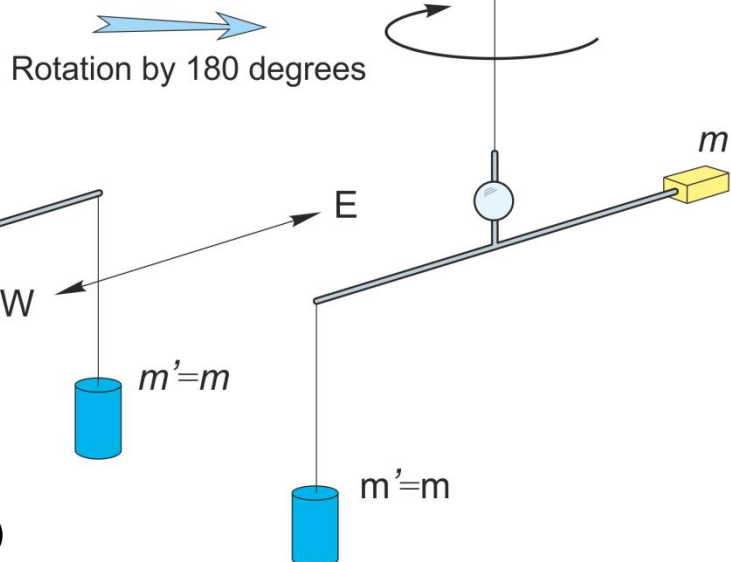


Replacement of masses

3rd measurement

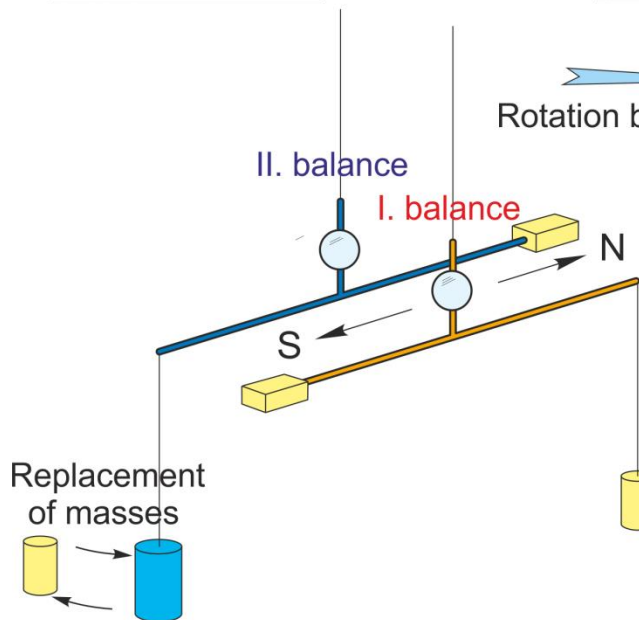


4th measurement

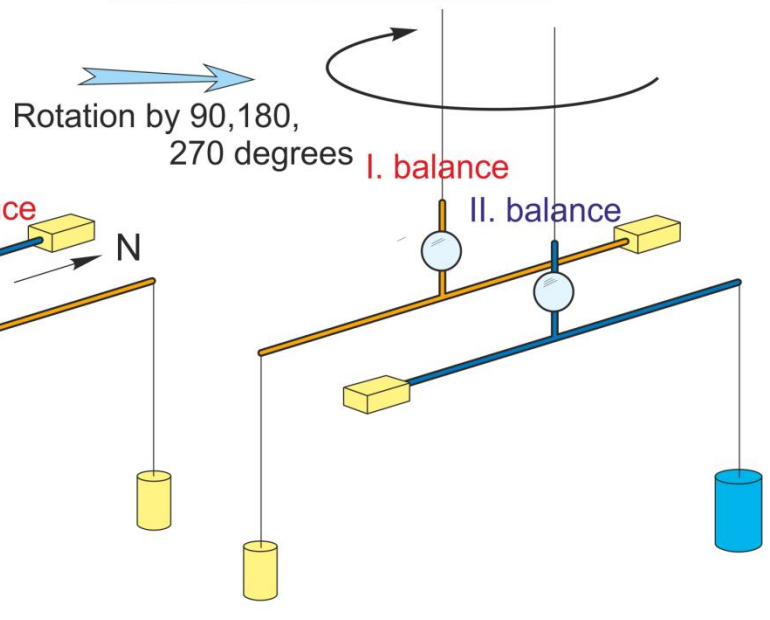


(The damped position should be recorded in each azimuth )

1st measurement

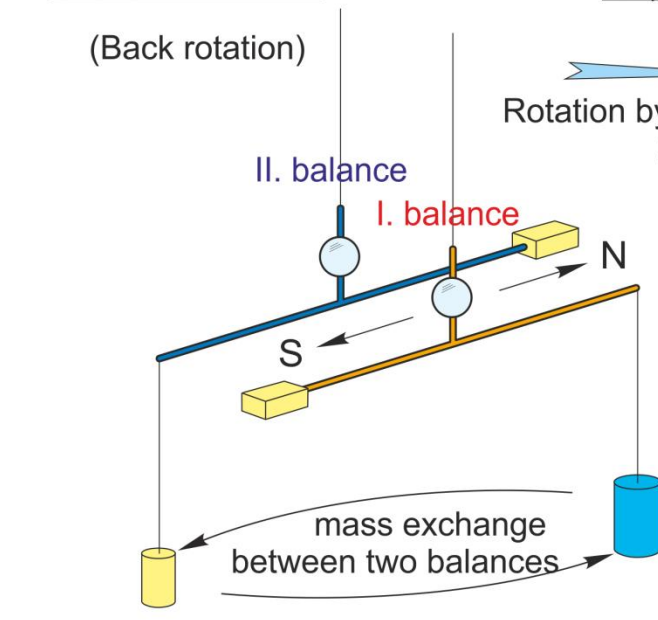


2nd, 3rd, 4th measurements

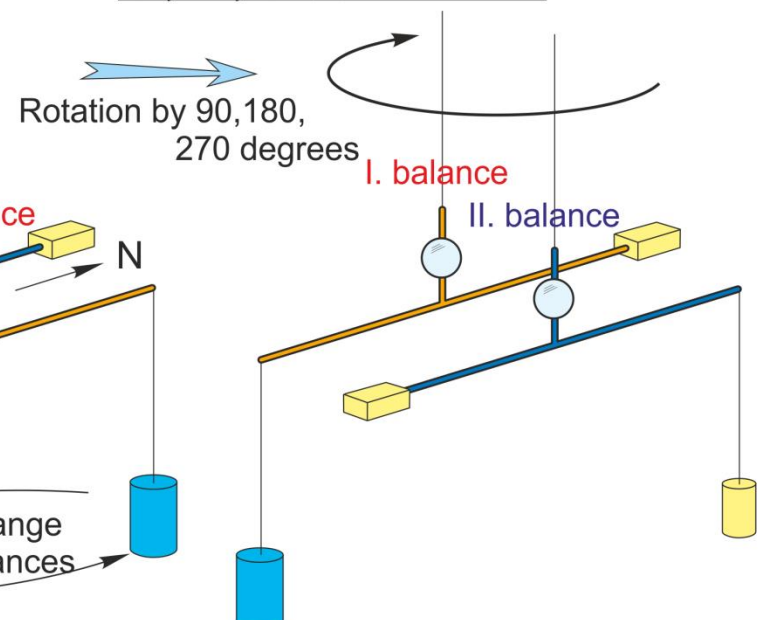


5th measurement

(Back rotation)



6th, 7th, 8th measurements



## *The biggest enemy of the torsion balance measurements is the man himself!*

- The mass of the observer's body changes the damped position of the torsion balance,
- Going to instrument the noise of the observer's steps cause ground vibrations, which also disturbs the damped position of the torsion balance.

### **Solution for these problems *two important enhancements:***

- 1. Computer-controlled scan on a CCD sensor instead of visual reading*
- 2. Using remote-controlled rotation mechanics*



*Preparing the Eötvös-Pekár torsion balance for Eötvös experiment*

*The preparatory work of the measurements took place for more than one year at the Department of Geodesy and Surveying of BME*

MÉRÉS  
A MŰSZER  
SZABAD HO



LED light illuminating the scale

new barcode scale

reading by CCD camera

optical modification

original optical reading

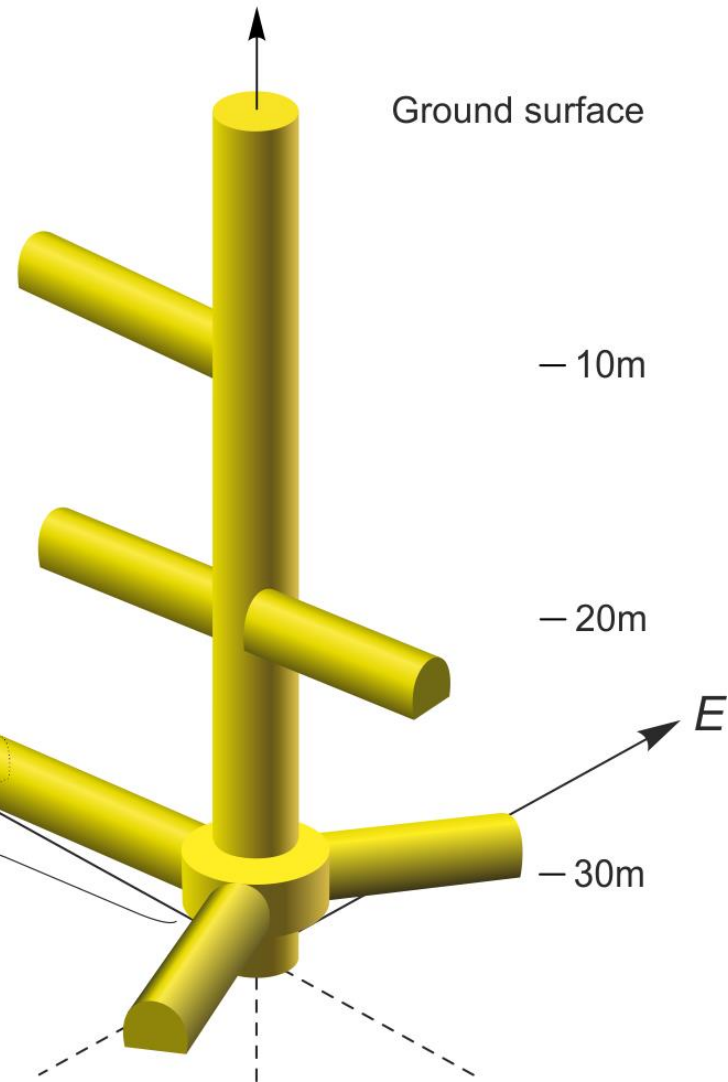
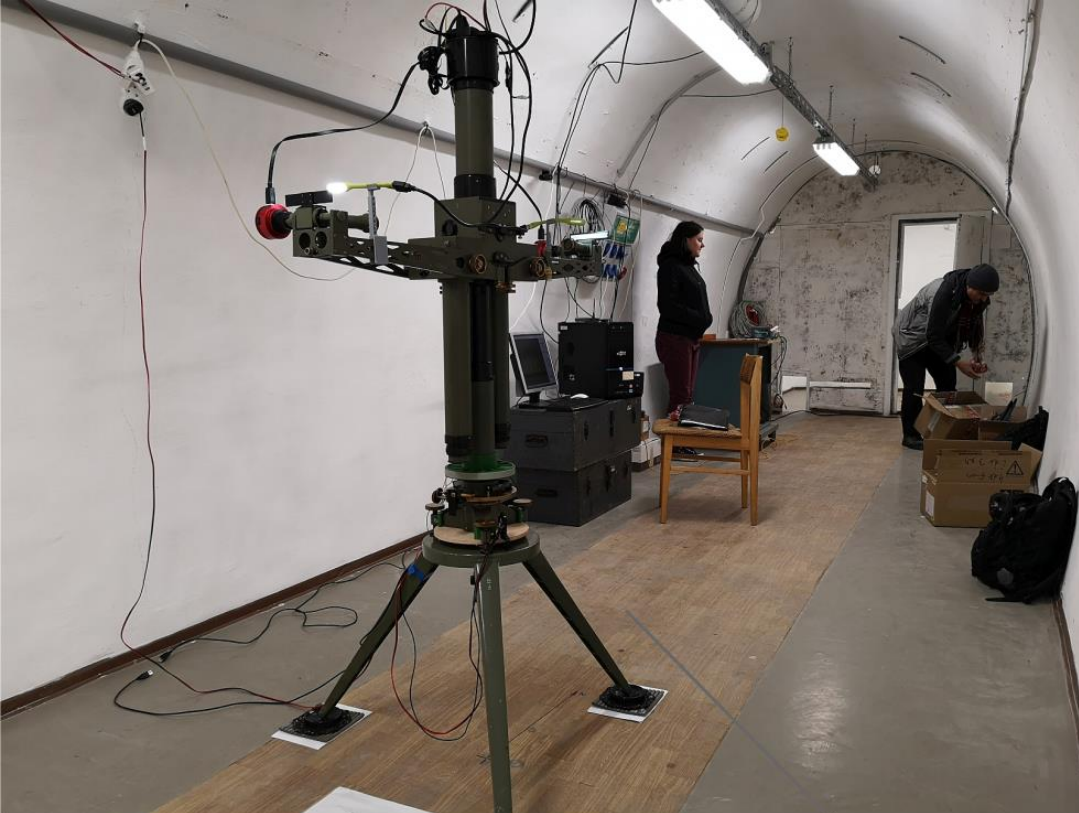
Originally: **single reading** after the damped position of the T.balance with accuracy of **0.1 scale division**

Now with CCD sensor: **continuous reading** (up to 10 readings/sec) with accuracy of **0.002 div**

## ***Computer-controlled rotation mechanics***

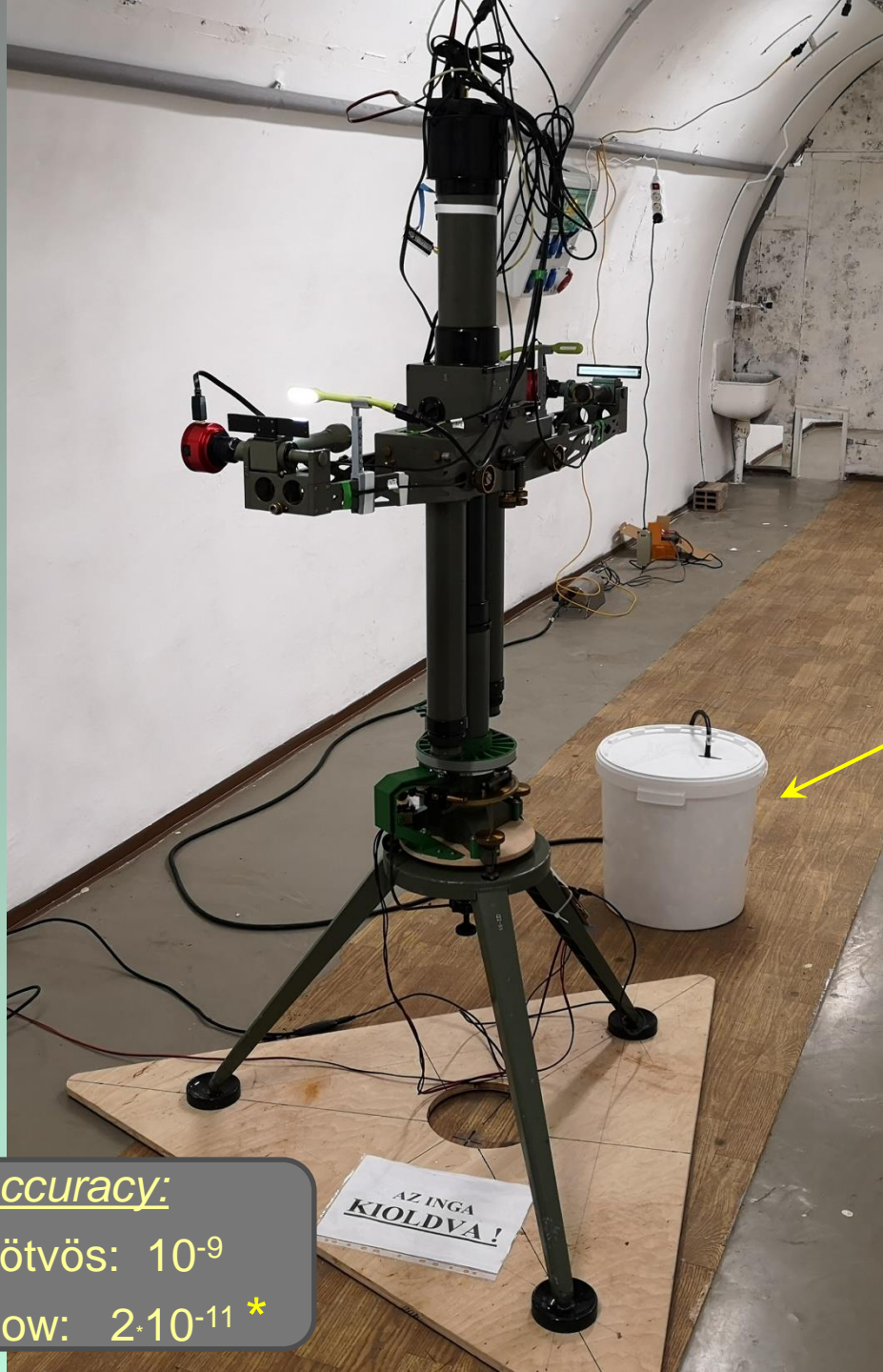
*Using RENISHAW optical encoder,  
position (azimuth) readout accuracy  
is under arcseconds*





*Location of measurements:* Jánossy Underground Laboratory of Wigner Research Center for Physics





Accuracy:

Eötvös:  $10^{-9}$

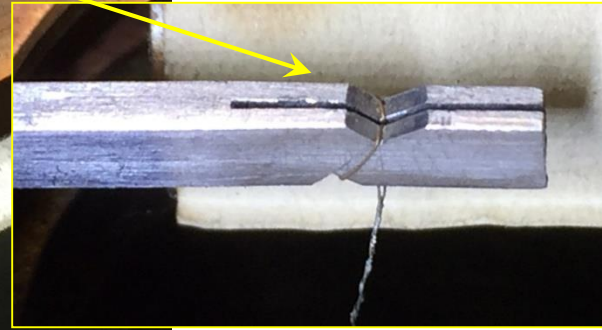
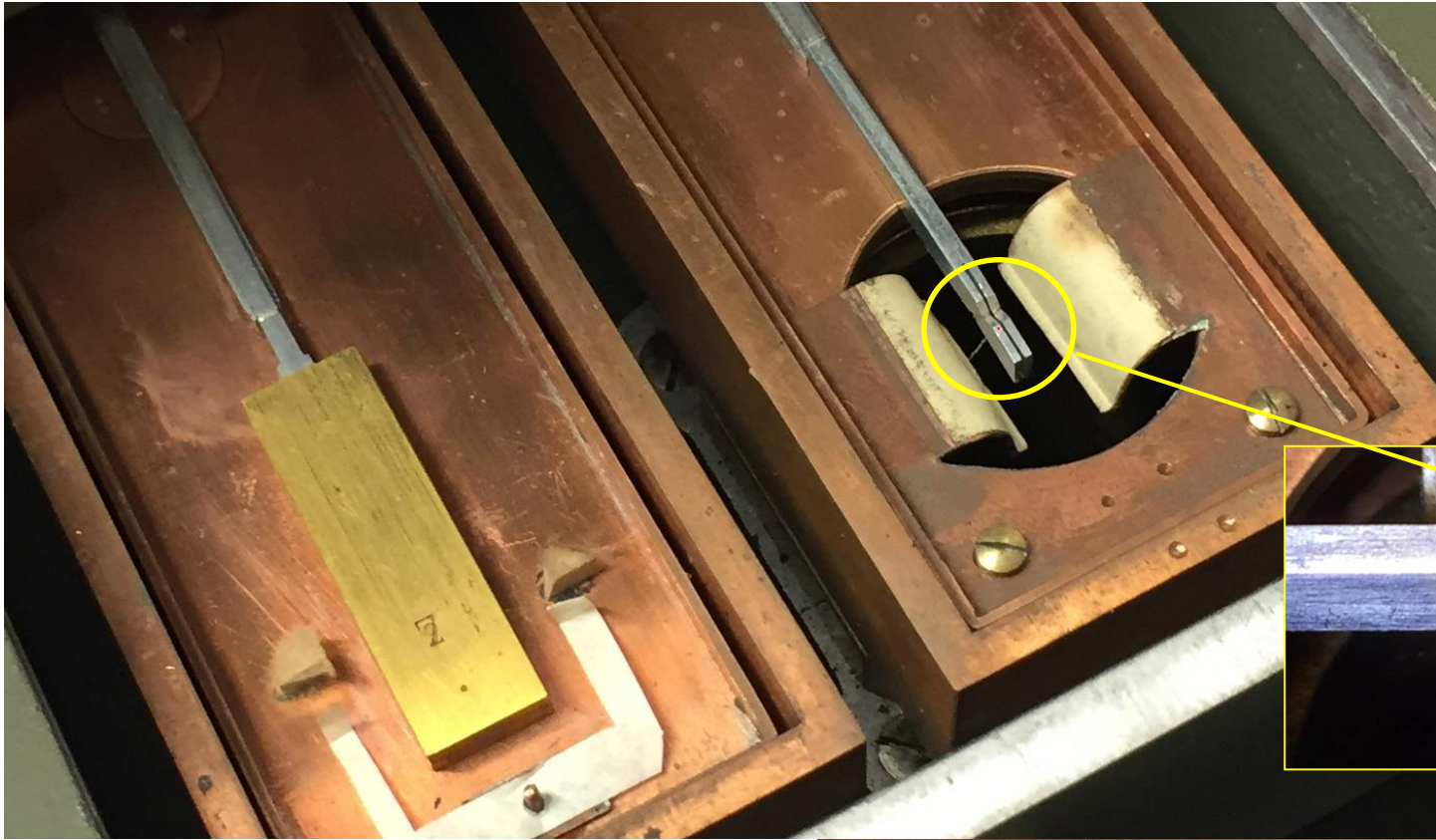
Now:  $2 \cdot 10^{-11}$  \*

Güralp 3T compact  
three-component  
broadband seismometer

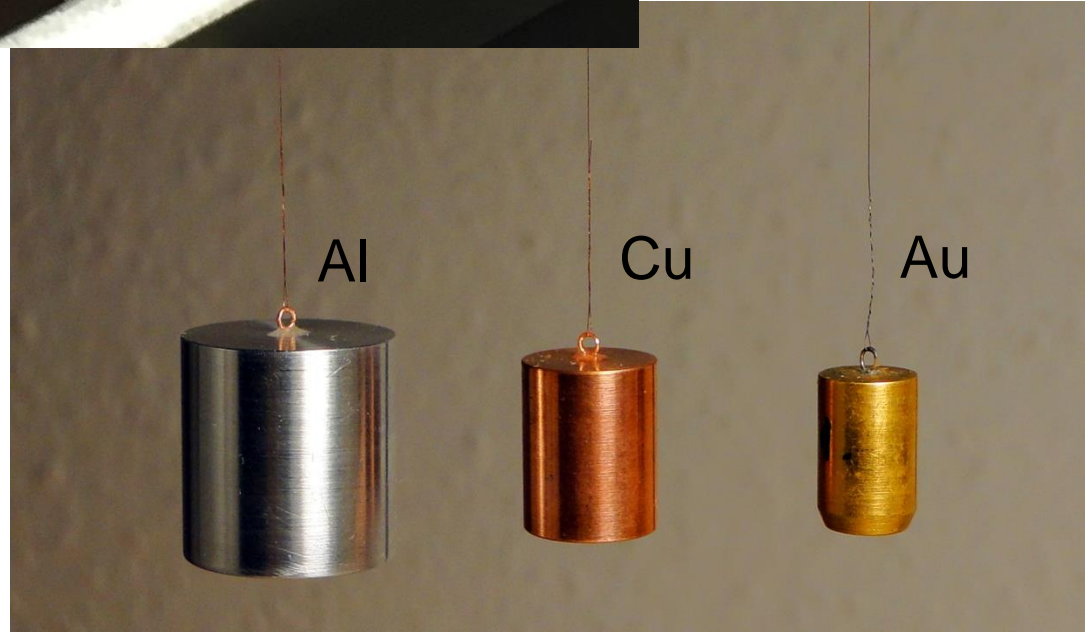


\* Recently our biggest problem is the elimination of the small microseismic ground vibrations and the infrasound pressure changes

Tömegcserék



Replacement of test masses





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*An important event:  
the actual equivalence measurements started at night on May 14. 2019.*



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## ***Present state:***

- Preparation of the measurement site is completed.
- Torsion balance has been restructured.
- Calibration measurements have been made.
- The new remote controlled rotation mechanism works well.
- CCD sensors, Led light illuminating and the scales are suitable for the measurements.
- The necessary control and evaluation software have been written and tested.
- Some of the test masses have been made, the replacement of masses is solved.
- ***Equivalence measurements started.***



# The staff of the experiment:



*Völgyesi L.*



*Szondy Gy.*



*Tóth Gy.*



*Ván P.*



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**1EÖTVÖS**

[www.eotvos100.hu](http://www.eotvos100.hu)



*Fenyvesi E.*



*Kiss B.*



*Péter G.*



*Harangozó P.*



*Gróf Gy.*



*Lévai P.*



*Barnaföldi G.*



*Deák L.*



*Égető Cs.*



*Somlai L.*

*In the next presentation Tóth Gy. takes a report about the measurements and the first results*