Locality Sensitive Hashing

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Introduction

Real world use cases

- Recommendation systems
 - Search similar products / users
- De-duplication
 - Determine which website is canonical
- Security
 - Are similar malicious commands executed.

Core problem

All have O(n) search complexity. With the sheer amount of data this is very problematic.

Exact Nearest Neighbor search

Let:

- *P*, a set of data point: $p, q \in \mathcal{R}^D$
- $d: \mathcal{R}^D \mapsto \mathcal{R}^1$, a distance function
- \triangleright R > 0, a distance threshold.

Given query q can we find a point $p \in P$, where $d(p,q) \leq R$?

Exact Nearest Neighbor search

Voronoi cells

- creation time: $O(n \log n)$
- query time: O(log n)
- ▶ space: O(n^D)
- k-d trees
 - creation time: O(n log n
 - query time in low dimensions: O(log n)
 - query time in high dimensions: O(n)
 - space: O(n)



Curse of dimensionality

All data structures for exact nearest neighbor search suffer from the curse of dimensionality in time or space complexity.

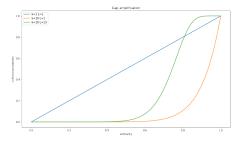
Approximated Nearest Neighbor search

Relaxed definition: The algorithm is allowed to return points $d(p,q) \leq cR$, where c > 1. Define a family of hashers where locality is preserved. let H be a LSH family, such that for every hash function $h \in H$:

An LSH family is useful when $P(h(p) = h(q)) \le P_2$.

Gap amplification

concatenate k hash functions to a single hash (AND operation)
create L separate hash tables (OR operation)



Complexity

Given the number of hash digits k, and the number of hashing tables L, and hashing duration h_t we obtain the following complexities:

- creation time: O(nLkh_t)
- ▶ space: O(nl)
- query time: $O(L \cdot (kh_t + DnP_2^k))$

LSH for cosine similarity

