Fast and scalable learning of generative models for chaotic dynamical systems and neural data

Leonard Bereska, Po-Chen Kuo, Manuel Brenner, Daniel Durstewitz Central Institute of Mental Health Mannheim, University of Heidelberg 28.10.2020, Neuromatch 3.0









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Motivation

Diverse biophysical



Manuel Brenner

Inferring Generative Models from Data

Figure from: Koppe, G., Toutounji, H., Kirsch, P., Lis, S., & Durstewitz, D. (2019). Identifying nonlinear dynamical systems via generative recurrent neural networks with applications to fMRI. PLoS Computational Biology, 15.

Piece-wise Linear Recurrent Neural Network

Complete Likelihood

$$\log p_{\theta}(\mathbf{x}, \mathbf{z}) = -\frac{1}{2} (\mathbf{z}_{1} - \boldsymbol{\mu}_{0} - \mathbf{s}_{1})^{T} \boldsymbol{\Sigma}^{-1} (\mathbf{z}_{1} - \boldsymbol{\mu}_{0} - \mathbf{s}_{1})$$
$$-\frac{1}{2} \sum_{t=2}^{T} (\mathbf{z}_{t} - \mathbf{A}\mathbf{z}_{t-1} - \mathbf{W}\boldsymbol{\phi}(\mathbf{z}_{t-1}) - \mathbf{s}_{t})^{T} \boldsymbol{\Sigma}^{-1} (\mathbf{z}_{t} - \mathbf{A}\mathbf{z}_{t-1} - \mathbf{W}\mathbf{z}_{t-1})$$
$$-\frac{1}{2} \sum_{t=1}^{T} (\mathbf{x}_{t} - \mathbf{B}\mathbf{z}_{t})^{T} \boldsymbol{\Gamma}^{-1} (\mathbf{x}_{t} - \mathbf{B}\mathbf{z}_{t})$$

⁴ For fMRI observation model refer to: Koppe, G., Toutounji, H., Kirsch, P., Lis, S., & Durstewitz, D. (2019). Identifying nonlinear dynamical systems via generative recurrent neural networks with applications to fMRI. PLoS Computational Biology, 15.

$$\in \mathbb{R}^{M}$$

$$- W\phi(z_{t-1}) + h_0 + Cs_t + \epsilon_t, \quad \epsilon_t \sim \mathcal{N}(0)$$

 $x_t = Bz_t + \eta_t, \ \eta_t \sim \mathcal{N}(0, \Gamma)$

 $V\phi(z_{t-1}) - s_t)$

Activation Function

 $\phi(z_{t-1}) = \max(0, z_{t-1})$

Increasing Computational Capacity

- Can we reduce the dimensionality of latent space?
- Retain piece-wise linear form

• $z_t = Az_{t-1} + W\phi(z_{t-1}) + h_0 + Cs_t + \epsilon_t$, $\epsilon_t \sim \mathcal{N}(0, \Sigma)$

Neurophysiological analogy: dendritic computation or neuronal diversity

Basis Expansion New activation function in latent model

 $z_t = A z_{t-1} + W \phi(z_{t-1}) + h_0 + C s_t + \epsilon_t, \quad \epsilon_t \sim \mathcal{N}(0, \Sigma)$

 $\phi(z_{t-1}) = \max(0, z_{t-1})$

Variational Inference

Variational Lower Bound

 $p(\mathbf{x}) \geq \mathscr{L}(\theta, \phi, \mathbf{x}) = \mathbb{E}_{q_{\phi}(z|\mathbf{x})}[\log p_{\theta}(x)]$

Complete Likelihood

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$$x = \{x_t | t = 1 \dots I \}$$

 $z = \{z_t | t = 1 \dots T\}$

$$[\mathbf{x}, \mathbf{z})] + \mathbb{E}_{q_{\phi}(z|\mathbf{x})}[\log q_{\phi}(z|\mathbf{x})]$$

Mean-Field Approximation

Benchmark Dynamical Systems

Lorenz Attractor

Lorenz-96 System

$$\frac{dx_i}{dt} = (x_{i+1} - x_{i-2})x_{i-1} - x_i + F$$

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Results - Lorenz-96 System

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Results - Lorenz-96 System

Summary

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Basis expansion:

- Improves inference
- Encourages learning of more interesting dynamics
- Reduces dimensionality of the latent space

Acknowledgements: This work was funded by the German Science Foundation (DFG) through individual grant Du 354/10-1 to Daniel Durstewitz, and via the Excellence Cluster Structures at Heidelberg University (EXC-2181 – 390900948).

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9

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Piece-wise Linear Recurrent Neural Network

Latent Model $z_r \in \mathbb{R}^M$

Observation Model $x_t = Bz_t + \eta_t, \ \eta_t \sim \mathcal{N}(\mathbf{0}, \Gamma)$

Complete Likelihood

$$\log p_{\theta}(\mathbf{x}, \mathbf{z}) = -\frac{1}{2} (\mathbf{z}_{1} - \boldsymbol{\mu}_{0} - \mathbf{s}_{1})^{T} \boldsymbol{\Sigma}^{-1} (\mathbf{z}_{1} - \boldsymbol{\mu}_{0} - \mathbf{s}_{1})$$
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Global vs. Local Metrics Kullback-Leibler Divergence vs. Mean Squared Error

low $\tilde{KL}_{\mathbf{X}}$ =.06, high MSE=2.48

Figure from: Koppe, G., Toutounji, H., Kirsch, P., Lis, S., & Durstewitz, D. (2019).

high $\tilde{KL}_{\mathbf{X}}$ =.71, low MSE=1.40

9

Identifying nonlinear dynamical systems via generative recurrent neural networks with applications to fMRI. PLoS Computational Biology, 15.