# **Bolt: Accelerated Data Mining with Fast Vector Compression**

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## Problem

- Computing on large datasets is costly in terms of both compute time and storage space
- Goal: reduce these costs for datasets that consist of (or can be converted to) dense vectors
  - E.g., image descriptors, not-too-sparse feature vectors, embeddings
- Approach: compress the vectors and operate directly on compressed representations



## Roadmap

- Problem and Assumptions
- Background and Related Work
- Algorithm
- Theoretical Results
- Experimental Results
- Conclusion



## Scenario / Assumptions

 ${\scriptstyle \bullet} {\rm We}$  have a collection of "data" vectors  ${\mathcal X}$ 

- Vectors may be inserted/deleted at any time
- $\ensuremath{\mathsf{\mathsf{\mathsf{W}e}}}$  receive "query" vectors q
  - $\bullet Want \ dot \ products \ / \ distances \ between \ q \ and \ each \ vector \ in \ \mathcal{X}$
- •We have a **training set** and a training phase before any queries are received
- Vectors are all the same length
- Computing on CPU (GPU future work)



## **Problem Statement Setup**

Let  $\mathbf{q} \in \mathbb{R}^J$  be a *query* vector and let  $\mathcal{X} = \{\mathbf{x}_1, \ldots, \mathbf{x}_N\}, \mathbf{x}_i \in \mathbb{R}^J$  be a collection of *database* vectors. Further let  $d : \mathbb{R}^J \times \mathbb{R}^J \to \mathbb{R}$  be a distance or similarity function that can be written as:

$$d(\mathbf{q}, \mathbf{x}) = f\left(\sum_{j=1}^{J} \delta(q_j, x_j)\right)$$
(1)

where  $f : \mathbb{R} \to \mathbb{R}, \, \delta : \mathbb{R} \times \mathbb{R} \to \mathbb{R}.$ 



#### **Problem Statement**

Construct three functions  $g : \mathbb{R}^J \to \mathcal{G}, h : \mathbb{R}^J \to \mathcal{H}$ , and  $\hat{d} : \mathcal{G} \times \mathcal{H} \to \mathbb{R}$  such that for a given approximation loss  $\mathcal{L}$ ,

$$\mathcal{L} = E_{\mathbf{q},\mathbf{x}}[(d(\mathbf{q},\mathbf{x}) - \hat{d}(g(\mathbf{q}),h(\mathbf{x})))^2]$$
(2)

the computation time T,

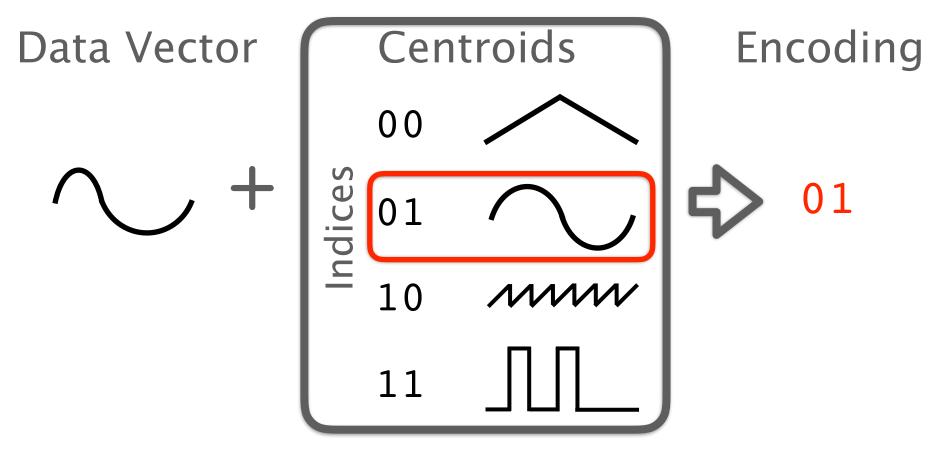
$$T = T_g + T_h + T_d \tag{3}$$

is minimized, where  $T_g$  is the time to encode received queries **q** using g,  $T_h$  the time to encode  $\mathcal{X}$  using h, and  $T_d$  the time to compute the approximate distances between the encoded queries and encoded database vectors.



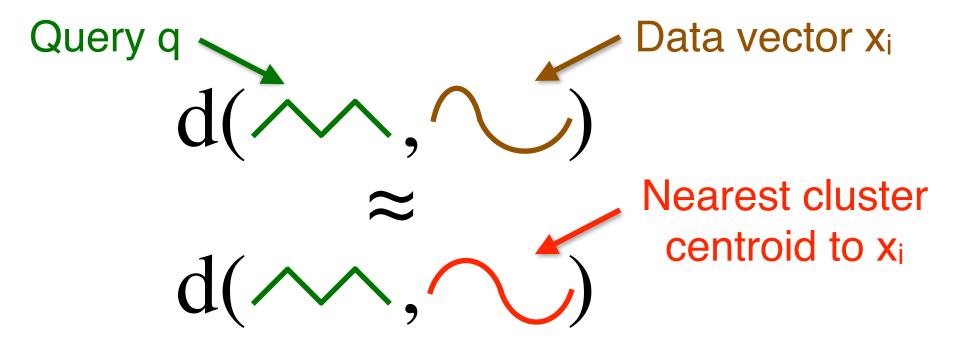
#### **Background: K-Means Quantization**

- Simple way to quantize a vector: k-means
- Encoding is index of nearest centroid



#### **Background: K-Means Quantization**

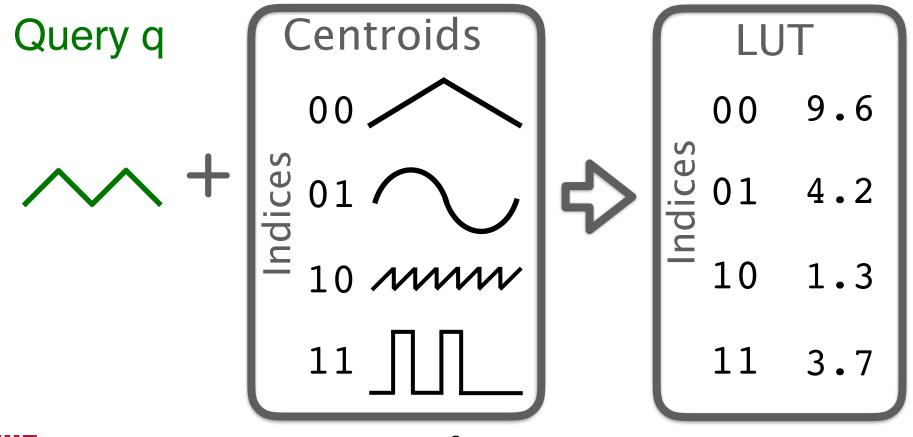
 Can approximate distance to vector with distance to its nearest centroid





#### **Background: K-Means Quantization**

- K centroids  $\Rightarrow$  only K possible distances
  - Precompute them all, then use a look-up table (LUT)
  - E.g., distance to encoding 01 = LUT[01] = 4.2



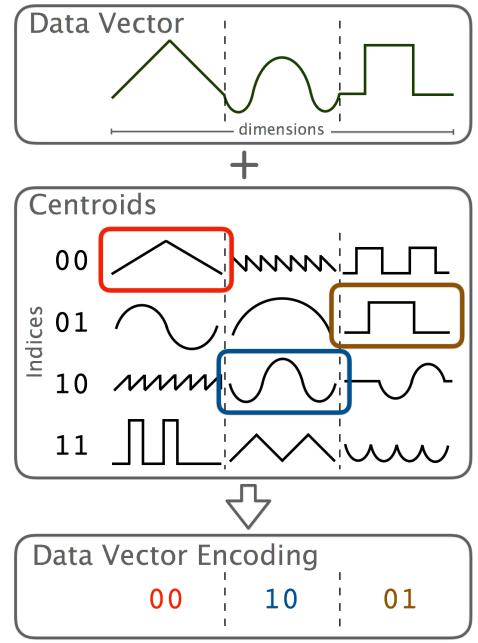
#### **Background: Product Quantization**

- Only K centroids is a problem
  - Small K ⇒ can't capture distribution or distinguish distances
  - Large K ⇒ huge encoding cost
- Solution: treat the vector as M separate subvectors and encode each separately
  - ► K<sup>M</sup> possible encodings



# Product Quantization Data Encoding

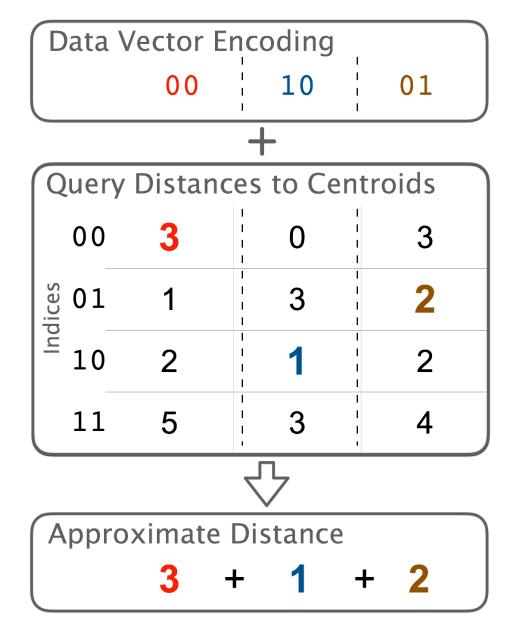
- Learn K-means centroids separately in each subspace
- Run K-means quantization in each subspace
- Concatenate encodings





## Product Quantization Distances

- For each query, compute lookup table for each subspace (each column on the right)
- Sum distances from each subspace





#### **Product Quantization Complexity**

- Encoding x<sub>i</sub>
  - K-means quantize each and concatenate encodings
  - O(KD) time, K = # of centroids, D = dimensionality
- Encoding q
  - Compute M look-up tables (LUTs) for the M subspaces
  - O(KD) time
- Approximating d(q, x<sub>i</sub>)
  - Perform 1 lookup in each of the M LUTs
  - O(M) time (and M << D)



## Bolt

- Similar to PQ, but 10+ times faster
  - While retaining compatibility with published extensions/complementary techniques

- Idea 1: Use more subvectors, fewer centroids
- Idea 2: Approximate look-up tables

Secret sauce is using both together...



# Bolt: M bigger, K smaller

- Encoding times are O(KD) no M!
- Everyone uses K=256 so each subspace is 1 byte
- Use K = 16 instead; each subspace is 4 bits
- No loss in capacity (in theory):
  - ► 8B PQ code  $\rightarrow$  K = 256, M = 8
    - $256^8 = 2^{64}$  possible encodings
  - ► 8B Bolt code  $\rightarrow$  K = 16, M = 16
    - $16^{16} = 2^{64}$  possible encodings



# Bolt: M bigger, K smaller

- On its own, setting K = 16 is strictly worse for distance computations
  - Less ability to exploit structure
  - Slower

• But when combined with Idea 2...



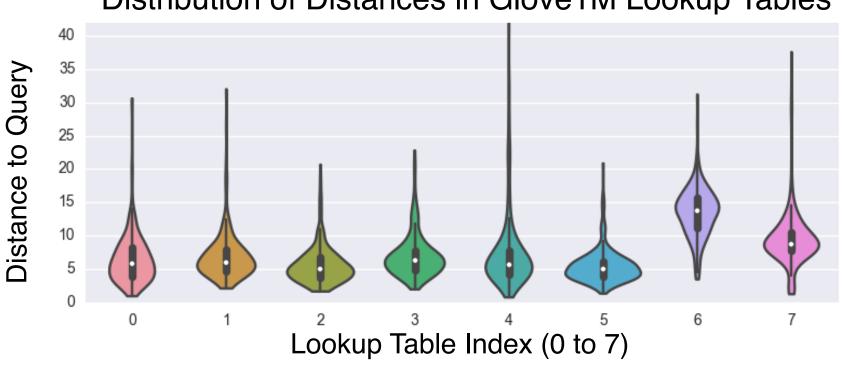
# **Bolt: Approximate LUTs**

- Do lookup tables really need 32bit precision?
- Quantize to 8 bits, [0,255]



# **Bolt: Approximate LUTs**

But directly quantizing fails miserably...

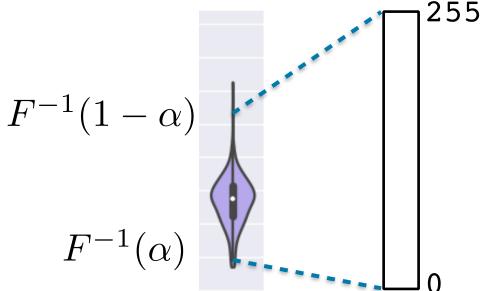


Distribution of Distances in Glove1M Lookup Tables



# **Bolt: Approximate LUTs**

- Solution: Learn a quantization function for each LUT at training time
- Find quantile α that minimizes quantization error when distances in [α, 1-α] are linearly scaled to [0, 255]
- Cheap to evaluate, so just try α in {0, .005, ..., .05} and take the best





## **Bolt: Secret Sauce**

- Using ideas 1 and 2, we have 16 centroids per LUT, and 1B per LUT entry
- ▶ 16B LUTs, 4 bit indices into it

- Magic: Hardware vectorization!
  - 16B LUT fits in a SIMD register, not L1 cache
  - Can do 32 lookups in parallel by byte shuffling



## **Bolt: Vectorization**

- dists = zeros(32)
- codes = 32xM block of X encodings
- LUTS = Mx16 lookup tables for query
- for i = 1 to 32: // PQ

code = codes[i]

for m = 1 to M:

dists[i] += LUTS[m][code[m]]

for m = 1 to M: // Bolt

dists += LUTS[m, codes[:, m]] // O(1)



## **Theoretical Guarantees**

- Error in distance and dot product computations bounded by PQ quantization error + LUT quantization error
- If distribution of LUT entries is any Gaussian, Subgaussian, Laplace, or Exponential, quantization error has O(exp(-ε)) concentration bound
- Overall probability of error ε in distances using PQ-style approach is O(exp(-ε<sup>2</sup>))



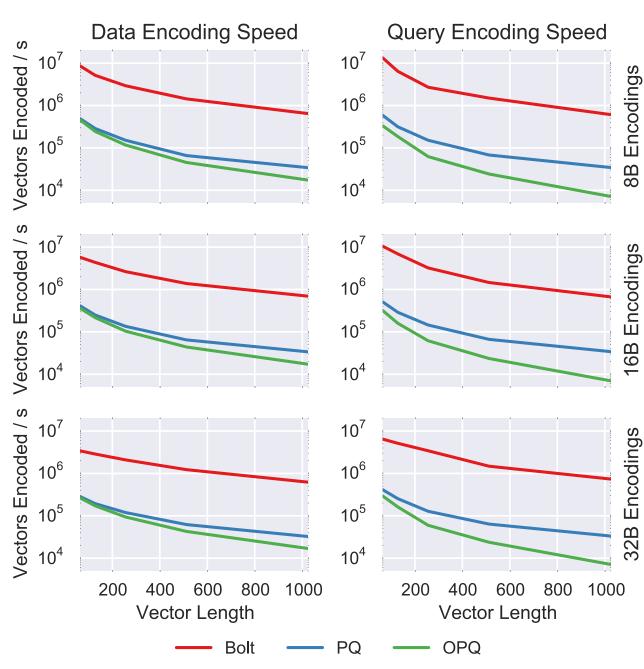
## Experiments

- Metrics:
  - # of vectors compressed / sec
  - # of distances computed / sec
  - Recall@R for nearest neighbors
  - Correlation of approx. distances with true distances
- Comparisons:
  - ▶ PQ, OPQ, BLAS/raw floats, binary embedding
  - Bolt without quantization



## Encoding Speed

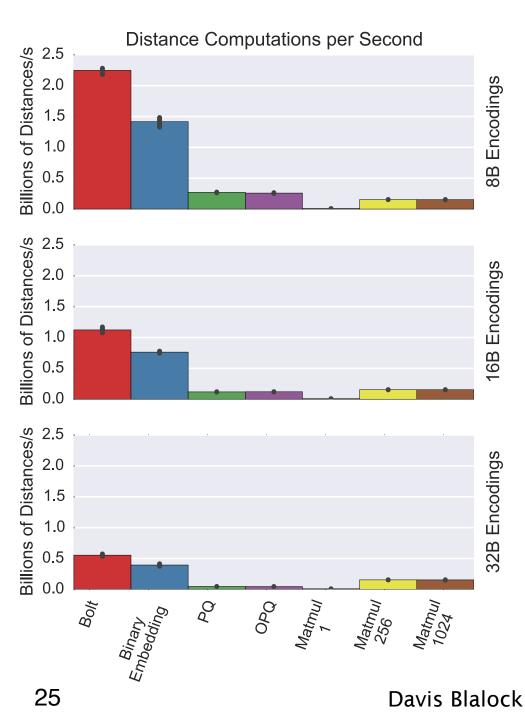
- Over 3GB/s for 8B codes
- Throughput inversely proportional to code length





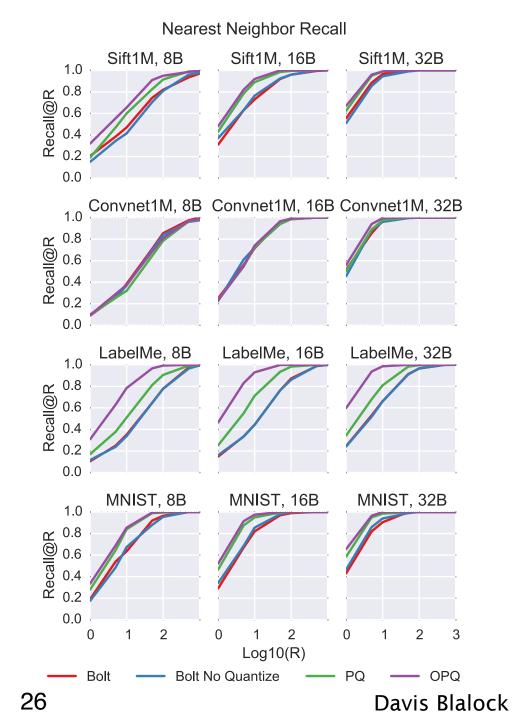
## Distance Computation Speed

- Faster than even hardware popent used by binary embedding
- Matmul{#} refers to batching queries
- 10x faster than PQ/ OPQ, 100x more than raw floats (Matmul1)



## Nearest Neighbor Recall

- Have to retrieve more points than other algorithms for a given level of compression
- Our LUT quantization causes no loss in accuracy

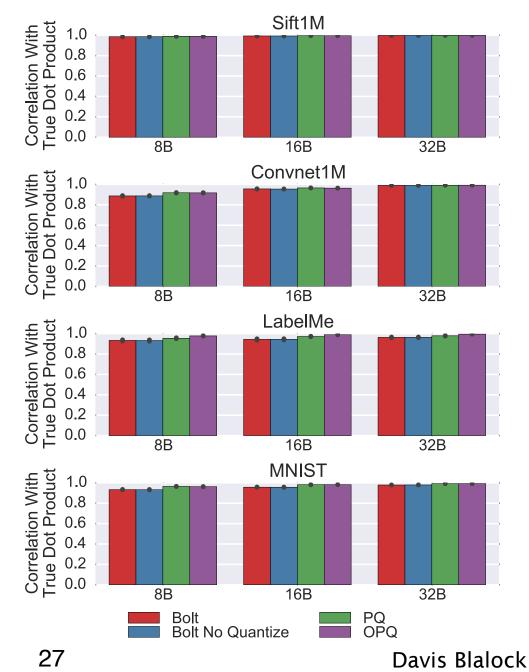




#### Quality of Approximate Dot Products

## Dot Product Accuracy

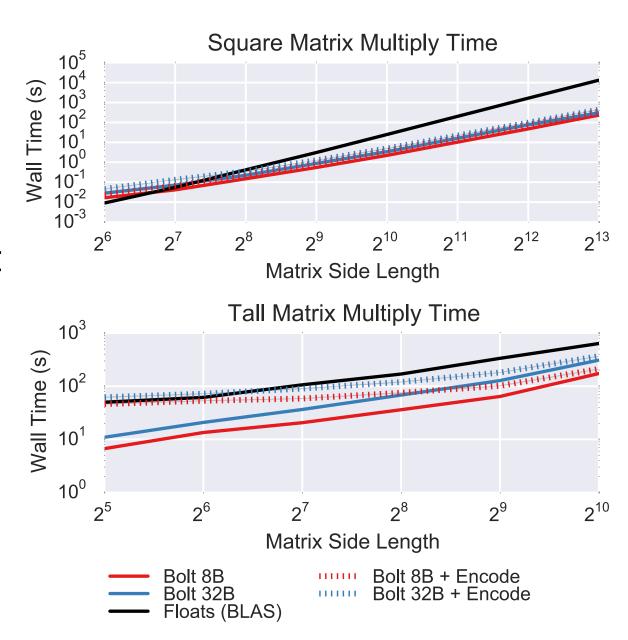
- Bolt dot products are slightly less accurate than others
- But highly accurate in absolute terms





# Matrix Multiplies

Multiplying matrices via dot products in a for loop is faster than BLAS, even when we must encode the matrices first



## Conclusion

- Bolt compresses vectors of data at multiple GB/s in a single thread
- Bolt's compressed representation can be used to compute approximate distances and dot products with:
  - High accuracy
  - Greater speed than any other algorithm, by a large margin
- The key is vectorized table lookups enabled by learned quantization functions





