# Data Visualization Laboratory work №8 Nonlinear Dimension Reduction



Dimensionality reduction techniques are employed in data science to transform high-dimensional data into a lower-dimensional space while preserving the underlying relationships between data points. This is beneficial for visualization, data analysis, and machine learning algorithms that struggle with high-dimensional data.

## 8.1. Multidimensional Scaling (MDS)

MDS aims to minimize a stress function, typically squared error, that measures the difference between the original pairwise distances  $(d_{ij})$  and the distances  $(d'_{ij})$  in the lower-dimensional embedding. Here's a basic formula for the stress function:

$$Stress = \sum_{ii} (d_{ij} - d'_{ij})^2 \to \min$$
(1)

where i and j iterate over all data points. MDS uses optimization algorithms to iteratively adjust the low-dimensional coordinates to minimize this stress function.

### 8.2. Isomap

Isomap leverages geodesic distances, which are the shortest path distances between points along the underlying manifold. It first constructs a nearest neighbors graph to capture the local structure. Here's the formula for a typical knearest neighbors graph:

Connect points  $p_i$  and  $p_j$  if  $p_j$  is among the *k* nearest neighbors of  $p_i$  (and vice versa).

Then, Isomap computes geodesic distances using Floyd-Warshall algorithm or other shortest path algorithms. Finally, classical MDS is applied to the geodesic distance matrix to obtain the low-dimensional representation.

## 8.3. t-Distributed Stochastic Neighbor Embedding (t-SNE)

t-SNE defines a probability distribution  $(p_{ij})$  in the high-dimensional space that represents the likelihood of data point  $p_i$  being a neighbor of  $p_j$ . A common choice is the Gaussian distribution:

$$p_{ii} = \exp(-\|p_i - p_i\|^2 / (2\sigma^2))$$
(2)

where  $\sigma$  is a hyperparameter controlling the neighborhood size. t-SNE then defines a similar probability distribution  $(q_{ij})$  in the low-dimensional embedding and uses Kullback-Leibler divergence to measure the difference between these distributions:

$$KL(P || Q) = \sum_{ij} p_{ij} log(p_{ij} / q_{ij})$$
(3)

t-SNE optimizes this divergence to ensure the low-dimensional embedding retains the local structure of the high-dimensional data.

#### **8.4 Python implementation**

One of the implementations of manifold learning algorithm is implemented by scikit-learn library <u>https://scikit-learn.org/stable/modules/manifold.html</u>/

There are two basic examples of using such methods:

- 1. For S-like dataset <u>https://scikit-</u> learn.org/stable/auto\_examples/manifold/plot\_compare\_methods.html
- 2. For MNIST-dataset <u>https://scikit-</u> learn.org/stable/auto\_examples/manifold/plot\_lle\_digits.html

#### Variants of tasks

- 1. Download dataset according your variant https://github.com/a-vodka/dv/tree/master/lab/dataset
- Perform dimension reduction using Isomap, Locally Linear Embedding, Multi-dimensional Scaling (MDS), t-distributed Stochastic Neighbor Embedding (t-SNE) onto 2D and 3D space.
- 3. Analyze results. Find, which methods gives best results for your dataset.