

Erriez MCP23017 library for Arduino
1.0.0

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Chapter 1

MCP23017 16-pin I2C IO-expander library for Arduino

This is a MCP23017 16-pin I2C IO-expander library for Arduino with interrupt change/edge support and extensive examples.

Library features

- I2C interface
- Input/output/read/write/toggle/mask control per pin or per 16-pins
- Configurable pullup per pin
- Interrupt change/falling/rising per pin
- Interrupt edge handled by the library, because the chip supports pin change / level only.
- Low-power support
- Generic examples / AVR / ESP8266 / ESP32 support

Hardware

The following targets are supported:

- AVR: UNO, MINI, Pro Mini 8/16 MHz, ATmega2560, Leonardo
- ARM: DUE
- ESP8266: Mini D1 & D2, NodeMCU
- ESP32: Lolin D32

Examples

Extensive examples are located [here](#).

Documentation

Doxygen API documentation is located [here](#).

Getting started LED blink

```
{C++}
#include <Arduino.h>
#include <Wire.h>
#include <ErriezMCP23017.h>

// PORTA: pins 0..7
// PORTB: pins 8..15
#define LED_PIN          8 // Pin B0

// Default I2C Address 0x20
#define MCP23017_I2C_ADDRESS  0x20

// Create MCP23017 object
ErriezMCP23017 mcp = ErriezMCP23017(MCP23017_I2C_ADDRESS);

void setup()
{
    // Initialize Wire
    Wire.begin();
    Wire.setClock(400000);

    // Initialize MCP23017
    while (!mcp.begin()) {
        // MCP23017 not detected
        delay(3000);
    }

    // LED pin output
    mcp.pinMode(LED_PIN, OUTPUT);
}

void loop()
{
    mcp.digitalWrite(LED_PIN, HIGH);
    delay(1000);
    mcp.digitalWrite(LED_PIN, LOW);
    delay(1000);
}
```

Library installation

Please refer to the [Wiki](#) page.

Other Arduino Libraries and Sketches from Erriez

[Erriez Libraries and Sketches](#)

Chapter 2

Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

ErriezMCP23017	
Erriez MCP23017 I2C IO-Expander class	7

Chapter 3

File Index

3.1 File List

Here is a list of all documented files with brief descriptions:

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Chapter 4

Class Documentation

4.1 ErriezMCP23017 Class Reference

Erriez MCP23017 I2C IO-Expander class.

```
#include <ErriezMCP23017.h>
```

Public Member Functions

- [ErriezMCP23017](#) (uint8_t i2cAddress=MCP23017_I2C_ADDRESS, TwoWire *twoWire=&Wire)
ErriezMCP23017 Constructor.
- bool [begin](#) (bool reset=true)
Initialize MCP23017.
- void [pinMode](#) (uint8_t pin, uint8_t mode)
Set direction of a single pin.
- void [digitalWrite](#) (uint8_t pin, uint8_t level)
Set state of a single pin.
- int [digitalRead](#) (uint8_t pin)
Get state of a single pin.
- void [setPortDirection](#) (uint16_t outputPins)
Set PORT direction all pins.
- uint16_t [getPortDirection](#) ()
Get PORT direction all pins.
- void [setPortPullup](#) (uint16_t pullupPins)
Set PORT pullup all pins.
- uint16_t [getPortPullup](#) ()
Get PORT pullup all pins.
- void [pinWrite](#) (uint8_t pin, bool level)
Set pin state.
- void [pinToggle](#) (uint8_t pin)
Toggle state of a single pin (only for output pins)
- bool [pinRead](#) (uint8_t pin)
Read state of a single pin (input and output pins)
- void [portWrite](#) (uint16_t value)
Set all pin states.

- void [portToggle](#) (uint16_t value)
Toggle pin states (output pins only)
- void [portMask](#) (uint16_t maskSet, uint16_t maskClear)
Clear and set pin states.
- uint16_t [portRead](#) ()
Read PORT of all pins (input and output pins)
- void [setInterruptPolarityINTA](#) (bool activeHigh)
Set interrupt polarity INTA.
- uint16_t [getPortInterruptMask](#) ()
Get interrupt mask all pins.
- void [setPortInterruptEnable](#) (uint16_t pins)
Enable interrupt change on pins.
- void [setPortInterruptDisable](#) (uint16_t pins)
Disable interrupt on pins.
- bool [interruptINTA](#) ()
MCP23017 INTA pin changed.
- uint16_t [registerRead](#) (uint8_t reg)
MCP23017 I2C read register.
- void [registerWrite](#) (uint8_t reg, uint16_t value)
MCP23017 I2C write register.
- uint8_t [getI2CStatus](#) ()
Return status of the last I2C write, returned by Wire endTransfer()
- void [dumpRegisters](#) (HardwareSerial *serial)
Print I2C registers on serial port.

Public Attributes

- uint16_t [portState](#)
Port state since last [portRead\(\)](#) call.
- uint16_t [pinsChanged](#)
Pins change on interrupt enabled pins since last [intPinChanged\(\)](#) call.
- uint16_t [pinsFalling](#)
Falling edge on interrupt enabled pins since last [intPinChanged\(\)](#) call.
- uint16_t [pinsRising](#)
Rising edge on interrupt enabled pins since last [intPinChanged\(\)](#) call.

4.1.1 Detailed Description

Erriez MCP23017 I2C IO-Expander class.

Definition at line 135 of file ErriezMCP23017.h.

4.1.2 Constructor & Destructor Documentation

4.1.2.1 ErriezMCP23017()

```
ErriezMCP23017::ErriezMCP23017 (
    uint8_t i2cAddress = MCP23017\_I2C\_ADDRESS,
    TwoWire * twoWire = &Wire )
```

[ErriezMCP23017](#) Constructor.

The constructor initializes internal variables and does not call I2C functions

Parameters

<i>i2cAddress</i>	7-bit MCP23017 I2C device address
<i>twoWire</i>	Default is Wire object to select I2C bus.

Definition at line 38 of file ErriezMCP23017.cpp.

4.1.3 Member Function Documentation

4.1.3.1 begin()

```
bool ErriezMCP23017::begin (
    bool reset = true )
```

Initialize MCP23017.

Parameters

<i>reset</i>	Perform resetting registers to default values (Default enabled)
--------------	-----------------------------------------------------------------

Return values

<i>true</i>	MCP23017 detected
<i>false</i>	MCP23017 not detected

Definition at line 55 of file ErriezMCP23017.cpp.

4.1.3.2 digitalRead()

```
int ErriezMCP23017::digitalRead (
    uint8_t pin )
```

Get state of a single pin.

Parameters

<i>pin</i>	Pin number 0..15 (PORTA = 0..7, PORTB = 8..15)
------------	------------------------------------------------

Return values

<i>HIGH</i>	= 1
<i>LOW</i>	= 0

Definition at line 145 of file ErriezMCP23017.cpp.

4.1.3.3 digitalWrite()

```
void ErriezMCP23017::digitalWrite (
    uint8_t pin,
    uint8_t state )
```

Set state of a single pin.

Parameters

<i>pin</i>	Pin number 0..15 (PORTA = 0..7, PORTB = 8..15)
<i>state</i>	HIGH = 1 LOW = 0

Definition at line 132 of file ErriezMCP23017.cpp.

4.1.3.4 dumpRegisters()

```
void ErriezMCP23017::dumpRegisters (
    HardwareSerial * serial )
```

Print I2C registers on serial port.

This function is optimized away by the compiler when not used

Parameters

<i>serial</i>	Serial port
---------------	-------------

Definition at line 494 of file ErriezMCP23017.cpp.

4.1.3.5 getI2CStatus()

```
uint8_t ErriezMCP23017::getI2CStatus ( )
```

Return status of the last I2C write, returned by Wire endTransfer()

Return values

0	Success
1	Data too long to fit in transmit buffer
2	Received NACK on transmit of address
3	Received NACK on transmit of data
4	Other error

Definition at line 480 of file ErriezMCP23017.cpp.

4.1.3.6 getPortDirection()

```
uint16_t ErriezMCP23017::getPortDirection ( )
```

Get PORT direction all pins.

Returns

PORT direction pins 0..15, Arduino compatible:
Bit value '0': INPUT
Bit value '1': OUTPUT

Definition at line 174 of file ErriezMCP23017.cpp.

4.1.3.7 getPortInterruptMask()

```
uint16_t ErriezMCP23017::getPortInterruptMask ( )
```

Get interrupt mask all pins.

Returns

Interrupt enabled

Definition at line 345 of file ErriezMCP23017.cpp.

4.1.3.8 getPortPullup()

```
uint16_t ErriezMCP23017::getPortPullup ( )
```

Get PORT pullup all pins.

Returns

PORT pull-up pins 0..15:
Bit value '0': Pull-up disabled
Bit value '1': Pull-up enable

Definition at line 203 of file ErriezMCP23017.cpp.

4.1.3.9 interruptINTA()

```
bool ErriezMCP23017::interruptINTA ( )
```

MCP23017 INTA pin changed.

The application should call this function when the MCP23017 INTA pin changed. Default: Falling edge This function re

Return values

<i>true</i>	At least one pin changed
<i>false</i>	No pins changed (Pin pulse was too short, or INTA edge did not match)

Returns

portState: PORT state since last [portRead\(\)](#) call
 pinsChanged: Changed pins on interrupt pins since last call
 pinsFalling: Falling edge on interrupt pins since last call
 pinsRising: Rising edge on interrupt pins since last call

Definition at line 401 of file ErriezMCP23017.cpp.

4.1.3.10 `pinMode()`

```
void ErriezMCP23017::pinMode (
    uint8_t pin,
    uint8_t mode )
```

Set direction of a single pin.

Parameters

<i>pin</i>	Pin number 0..15 (PORTA = 0..7, PORTB = 8..15)
<i>mode</i>	OUTPUT: Configure pin as output INPUT: Configure pin as input INPUT_PULLUP: Configure pin with input pull-up

Definition at line 95 of file ErriezMCP23017.cpp.

4.1.3.11 `pinRead()`

```
bool ErriezMCP23017::pinRead (
    uint8_t pin )
```

Read state of a single pin (input and output pins)

Parameters

<i>pin</i>	Pin number 0..15 (PORTA = 0..7, PORTB = 8..15)
------------	------------------------------------------------

Return values

<i>HIGH</i>	= 1
-------------	-----

Return values

<i>LOW</i>	= 0
------------	-----

Definition at line 248 of file ErriezMCP23017.cpp.

4.1.3.12 pinToggle()

```
void ErriezMCP23017::pinToggle (
    uint8_t pin )
```

Toggle state of a single pin (only for output pins)

Parameters

<i>pin</i>	Pin number 0..15 (PORTA = 0..7, PORTB = 8..15)
------------	------------------------------------------------

Definition at line 233 of file ErriezMCP23017.cpp.

4.1.3.13 pinWrite()

```
void ErriezMCP23017::pinWrite (
    uint8_t pin,
    bool level )
```

Set pin state.

Parameters

<i>pin</i>	Pin number 0..15 (PORTA = 0..7, PORTB = 8..15)
<i>level</i>	HIGH = 1, LOW = 0

Definition at line 217 of file ErriezMCP23017.cpp.

4.1.3.14 portMask()

```
void ErriezMCP23017::portMask (
    uint16_t maskSet,
    uint16_t maskClear )
```

Clear and set pin states.

Parameters

<i>maskSet</i>	Bit value '1': Pins to HIGH
<i>maskClear</i>	Bit value '1': Pins to LOW

Definition at line 293 of file ErriezMCP23017.cpp.

4.1.3.15 portRead()

```
uint16_t ErriezMCP23017::portRead ( )
```

Read PORT of all pins (input and output pins)

Returns

State of all 16 pins

Definition at line 305 of file ErriezMCP23017.cpp.

4.1.3.16 portToggle()

```
void ErriezMCP23017::portToggle (
    uint16_t value )
```

Toggle pin states (output pins only)

Parameters

<i>value</i>	16 pins, bit value '0' = unchanged, '1' = toggle
--------------	--------------------------------------------------

Definition at line 278 of file ErriezMCP23017.cpp.

4.1.3.17 portWrite()

```
void ErriezMCP23017::portWrite (
    uint16_t value )
```

Set all pin states.

Parameters

<i>value</i>	16 pins, bit value '0' = LOW, '1' = HIGH
--------------	------------------------------------------

Definition at line 265 of file ErriezMCP23017.cpp.

4.1.3.18 registerRead()

```
uint16_t ErriezMCP23017::registerRead (
    uint8_t reg )
```

MCP23017 I2C read register.

Parameters

<i>reg</i>	MCP23017 register
------------	-------------------

Returns

MCP23017 register value

Definition at line 441 of file ErriezMCP23017.cpp.

4.1.3.19 registerWrite()

```
void ErriezMCP23017::registerWrite (
    uint8_t reg,
    uint16_t value )
```

MCP23017 I2C write register.

Parameters

<i>reg</i>	MCP23017 register
<i>value</i>	MCP23017 value

Definition at line 461 of file ErriezMCP23017.cpp.

4.1.3.20 setInterruptPolarityINTA()

```
void ErriezMCP23017::setInterruptPolarityINTA (
    bool activeHigh )
```

Set interrupt polarity INTA.

Parameters

<i>activeHigh</i>	HIGH = 1: Active high, LOW = 0: Active low (default)
-------------------	------------------------------------------------------

Definition at line 320 of file ErriezMCP23017.cpp.

4.1.3.21 `setPortDirection()`

```
void ErriezMCP23017::setPortDirection (
    uint16_t outputPins )
```

Set PORT direction all pins.

Parameters

<i>outputPins</i>	PORT direction pins 0..15, Arduino compatible: Bit value '0': INPUT Bit value '1': OUTPUT
-------------------	-------------------------------------------------------------------------------------------------

Definition at line 159 of file ErriezMCP23017.cpp.

4.1.3.22 `setPortInterruptDisable()`

```
void ErriezMCP23017::setPortInterruptDisable (
    uint16_t pins )
```

Disable interrupt on pins.

Parameters

<i>pins</i>	Pins to disable
-------------	-----------------

Definition at line 375 of file ErriezMCP23017.cpp.

4.1.3.23 `setPortInterruptEnable()`

```
void ErriezMCP23017::setPortInterruptEnable (
    uint16_t pins )
```

Enable interrupt change on pins.

The MCP23017 does not support edge interrupts. This is handled by software.

Parameters

<i>pins</i>	Pins to enable interrupt change
-------------	---------------------------------

Definition at line 357 of file ErriezMCP23017.cpp.

4.1.3.24 setPortPullup()

```
void ErriezMCP23017::setPortPullup (
    uint16_t pullupPins )
```

Set PORT pullup all pins.

Parameters

<i>pullupPins</i>	Set PORT pull-up pins 0..15: Bit value '0': Pull-up unchanged Bit value '1': Pull-up enable
-------------------	---------------------------------------------------------------------------------------------------

Definition at line 188 of file ErriezMCP23017.cpp.

The documentation for this class was generated from the following files:

- [src/ErriezMCP23017.h](#)
- [src/ErriezMCP23017.cpp](#)

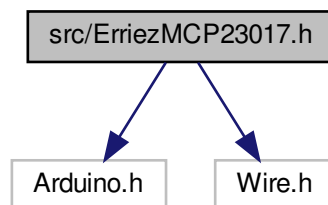
Chapter 5

File Documentation

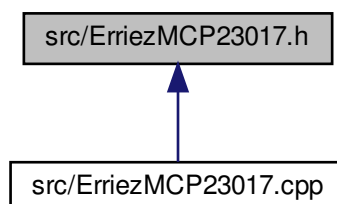
5.1 src/ErriezMCP23017.h File Reference

MCP23017 I2C IO expander library for Arduino.

```
#include <Arduino.h>
#include <Wire.h>
Include dependency graph for ErriezMCP23017.h:
```



This graph shows which files directly or indirectly include this file:



Classes

- class [ErriezMCP23017](#)
Erriez MCP23017 I2C IO-Expander class.

Macros

- #define [MCP23017_I2C_ADDRESS](#) 0x20
Default MCP23017 I2C address.
- #define [MCP23017_REG_IODIR](#) 0x00
Controls the direction of the data I/O for port A.
- #define [MCP23017_REG_IPOL](#) 0x02
Configures the polarity on the corresponding GPIO port bits for port A.
- #define [MCP23017_REG_GPINTEN](#) 0x04
Controls the interrupt-on-change for each pin of port A.
- #define [MCP23017_REG_DEFVAL](#) 0x06
Controls the default comparison value for interrupt-on-change for port A.
- #define [MCP23017_REG_INTCON](#) 0x08
Controls how the associated pin value is compared for the interrupt-on-change for port A.
- #define [MCP23017_REG_IOCON](#) 0x0A
Configuration register A.
- #define [MCP23017_REG_GPPU](#) 0x0C
Controls the pull-up resistors for the port A pins.
- #define [MCP23017_REG_INTF](#) 0x0E
Reflects the interrupt condition on the port A pins.
- #define [MCP23017_REG_INTCAP](#) 0x10
Captures the port A value at the time the interrupt occurred.
- #define [MCP23017_REG_GPIO](#) 0x12
Reflects the value on the port A.
- #define [MCP23017_REG_OLAT](#) 0x14
Provides access to the port A output latches.
- #define [MCP23017_NUM_REGS](#) 0x16
Total number of registers.
- #define [MCP23017_NUM_PINS](#) 16
Total number of pins port A + B.
- #define [MCP23017_MASK_ALL_PINS](#) 0xFFFF
All 16-pins mask.
- #define [MCP23017_MASK_REG_A](#) 0x1E
Address mask to select A registers on even addresses.
- #define [IOCON_BANK](#) 7
Controls how the registers are addressed.
- #define [IOCON_MIRROR](#) 6
INT Pins Mirror bit.
- #define [IOCON_SEQOP](#) 5
Sequential Operation mode bit.
- #define [IOCON_DISSLW](#) 4
Slew Rate control bit for SDA output.
- #define [IOCON_ODR](#) 2
Configures the INT pin as an open-drain output.
- #define [IOCON_INTPOL](#) 1
This bit sets the polarity of the INT output pin.
- #define [REG_IOCON_VALUE](#)
Default MCP23017 configuration.

5.1.1 Detailed Description

MCP23017 I2C IO expander library for Arduino.

Source: <https://github.com/Erriez/ErriezMCP23017> Documentation: <https://erriez.github.io/ErriezMCP23017>

Design notes:

- 1 This library is designed for MCP23017 with I2C interface.
- 2 This library does not support the MCP23S017 with SPI interface. Workaround: None, use another library, or add SPI support to this library.
- 3 The INTB is not enabled in this library, because. INTA and INTB interrupts are ORed to INTA with configuration bit MIRROR=1 in IOCON register. Workaround: The application shall only use INTA.
- 4 Port, direction and pull-up states are cached in variables for speed: No additional register reads are needed.

MCP23017 limitations:

1 The MCP23017 does not support rising or falling edge interrupts. Workaround: None: The MCP23017 support only the following interrupts:

- Pin change (Recommended: Generates interrupt on pin level change)
- Level high (Generates continues interrupts when pin is high)
- Level low (Generates continues interrupts when pin is low)

2 Note: The register IODIR bits are reversed: 0: Output 1: Input Workaround: Be careful with interpreting register IODIR.

MCP23017 major bugs:

1 The INTA pin is released when reading from register GPIO or INTCAP. This happens when the application calls function `pinRead()` or `portRead()`. This is a documented chip limitation. Workaround: None.

2 Register INTF captures only one pin change. The MCP23017 does not update register INTF when multiple interrupts occurs at the same time. Workaround:

1. The application shall read the INTF register with function `getPortIntertuptStatus()` as fast as possible after INTA is asserted. otherwise multiple pin interrupts are lost.
2. The application shall poll pin INTA and read GPIO pin manually to detect pin changes.

5.1.2 Macro Definition Documentation

5.1.2.1 REG_IOCON_VALUE

```
#define REG_IOCON_VALUE
```

Value:

```
((0<<IOCON_BANK) | /* 1 = The registers associated with each port are separated into
different banks. */ \
(1<<IOCON_MIRROR) | /* 1 = INTA and INTB pins are OR'ed to INTA (INTB disabled) */ \
(0<<IOCON_SEQOP) | /* 1 = Sequential operation disabled, address pointer does not
increment. */ \
(0<<IOCON_DISSLW) | /* 1 = Slew rate disabled */ \
(0<<IOCON_ODR) | /* 1 = Open-drain output (overrides the INTPOL bit.) */ \
(0<<IOCON_INTPOL)) /* 1 = Active-high */
```

Default MCP23017 configuration.

Definition at line 124 of file ErriezMCP23017.h.

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