

Finite Element Method

What is Finite Element Method?

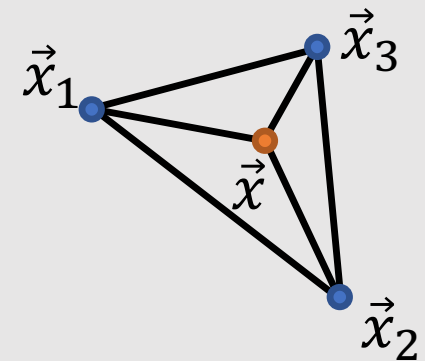
- Solution by energy minimization

$$\vec{x}_{solution} = \underset{\vec{x}}{\operatorname{argmin}} W(\vec{x})$$



- Value inside element is interpolated

$$\vec{x} = \sum_{i \in \text{Nodes}} w_i \vec{x}_i$$



- Energy is sum of the element-wise energy

$$W(\vec{x}) = \sum_{e \in \text{Elements}} W_e(\vec{x})$$

FEM of Laplace Equation on Triangle

Discrete Laplacian \longrightarrow the energy is **sum** of the squared **differences** between neighbors

Continuous Laplacian \longrightarrow the energy is **integration** of the squared **gradient**

$$W(\phi) = \int_{\Omega} \nabla\phi \cdot \nabla\phi \, d\Omega$$

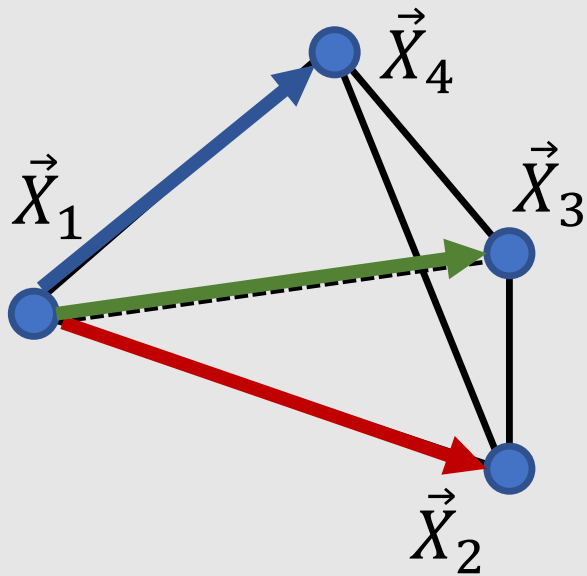
$$W_e(\phi) = \int_{\vec{x} \in Tri} \frac{\partial L_a \phi_a}{\partial \vec{x}} \cdot \frac{\partial L_b \phi_b}{\partial \vec{x}} \, d\vec{x} = \phi_a \phi_b \int_{\vec{x} \in Tri} \frac{\partial L_a}{\partial \vec{x}} \cdot \frac{\partial L_b}{\partial \vec{x}} \, d\vec{x}$$

Making the solution as smooth as possible!



Deformation Gradient Tensor F for Tet.

rest shape

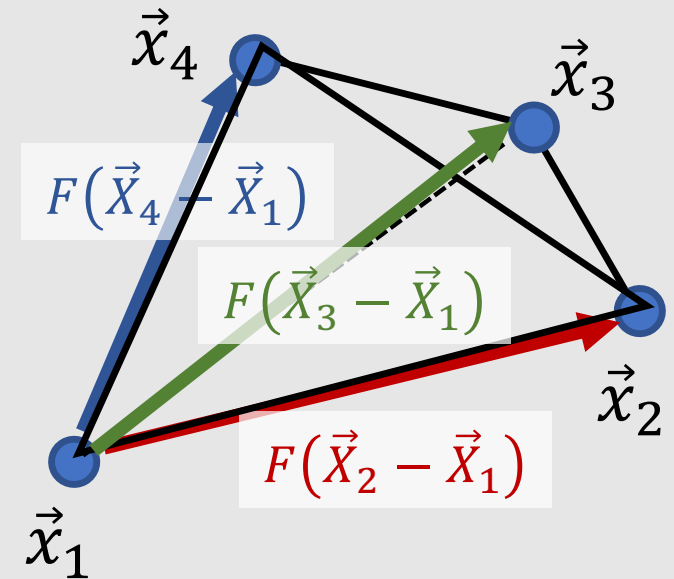


$$(\vec{x}_2 - \vec{x}_1) = F(\vec{X}_2 - \vec{X}_1)$$

$$(\vec{x}_3 - \vec{x}_1) = F(\vec{X}_3 - \vec{X}_1)$$

$$(\vec{x}_4 - \vec{x}_1) = F(\vec{X}_4 - \vec{X}_1)$$

deformed shape

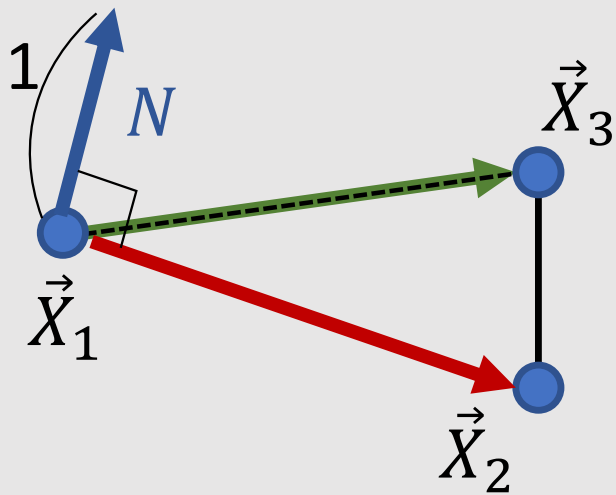


$$[\vec{x}_2 - \vec{x}_1, \vec{x}_3 - \vec{x}_1, \vec{x}_4 - \vec{x}_1] = F[\vec{X}_2 - \vec{X}_1, \vec{X}_3 - \vec{X}_1, \vec{X}_4 - \vec{X}_1]$$

$$F = [\vec{x}_2 - \vec{x}_1, \vec{x}_3 - \vec{x}_1, \vec{x}_4 - \vec{x}_1][\vec{X}_2 - \vec{X}_1, \vec{X}_3 - \vec{X}_1, \vec{X}_4 - \vec{X}_1]^{-1}$$

Deformation Gradient Tensor F for 3D Tri.

rest shape

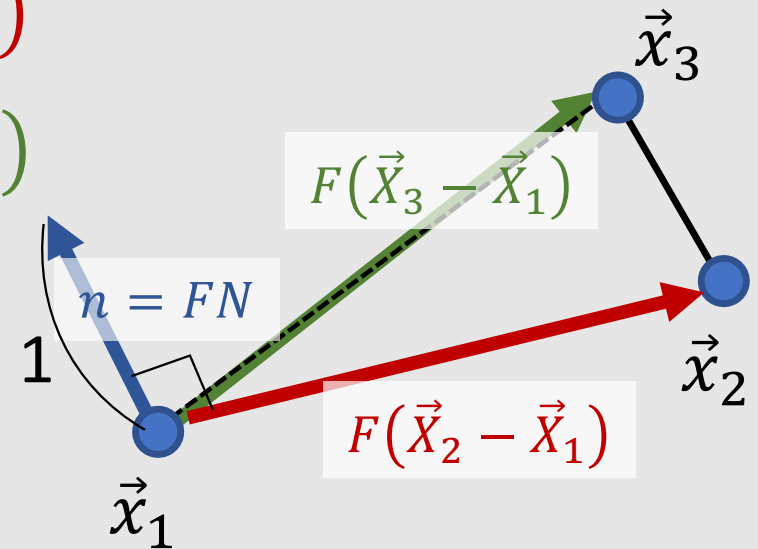


$$(\vec{x}_2 - \vec{x}_1) = F(\vec{X}_2 - \vec{X}_1)$$

$$(\vec{x}_3 - \vec{x}_1) = F(\vec{X}_3 - \vec{X}_1)$$

$$n = FN$$

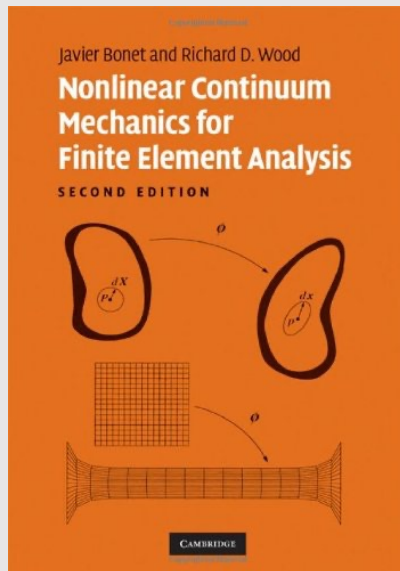
deformed shape



$$[\vec{x}_2 - \vec{x}_1, \vec{x}_3 - \vec{x}_1, n] = F[\vec{X}_2 - \vec{X}_1, \vec{X}_3 - \vec{X}_1, N]$$

$$F = [\vec{x}_2 - \vec{x}_1, \vec{x}_3 - \vec{x}_1, n][\vec{X}_2 - \vec{X}_1, \vec{X}_3 - \vec{X}_1, N]^{-1}$$

Reference



- Bonet, Javier, and Richard D. Wood. 1997. *Nonlinear continuum mechanics for finite element analysis*. Cambridge: Cambridge University Press.