

LOGIC SYNTHESIS AND TWO-LEVEL LOGIC OPTIMIZATION

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Outline

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- Overview of logic synthesis.
- Combinational-logic design:
 - Background.
 - Two-level forms.
- Exact minimization.
- Covering algorithms.
- Boolean relations.

Logic synthesis and optimization

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- Determine microscopic structure of the circuit.
- Explore (*area-delay*) trade-off:
 - Combinational circuits:
 - * I/O delay.
 - Sequential circuits:
 - * *cycle-time*.
- Explore (*power-delay*) trade-off:
- Enhance circuit *testability*.

Circuit implementation issues

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- Implementation styles:
 - Two-level (e.g. PLA macro cells).
 - Multi-level (e.g. cell-based, array-based).
- Operation:
 - Combinational.
 - Sequential:
 - * Synchronous
 - * Asynchronous.

Design flow in logic synthesis

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- Circuit capture:
 - Tabular specifications of functions or *finite-state machines* (FSMs).
 - Schematic capture.
 - Hardware Description Languages (HDLs).
- Synthesis and optimization:
 - Map circuit representation to abstract model.
 - Transformations on abstract model.
 - Library binding.

Abstract models

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- Models based on graphs.
- Useful for:
 - Machine-level processing.
 - Reasoning about properties.
- Derived from language models by compilation.

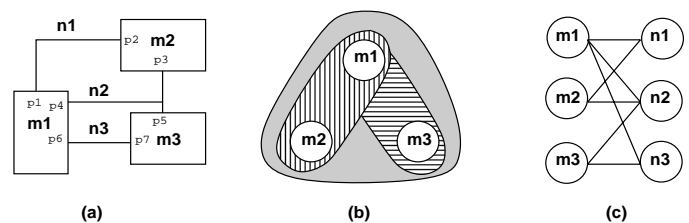
Structural views

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- Netlists:
 - Modules, nets, incidence.
 - Ports.
 - Hierarchy.
- Incidence (sparse) matrix of a graph.

Example

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Logic functions

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- Black-box model of a combinational module.
- Defined on Boolean Algebra.
- *Support variables* correspond to module inputs.
- Logic functions may have multiple outputs and be *incompletely specified*.

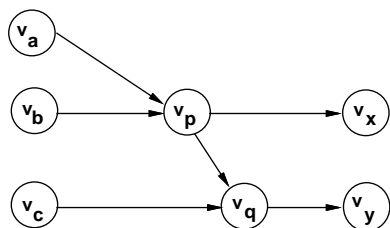
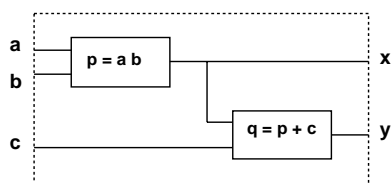
Logic networks

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- Mixed structural/behavioral views.
- Useful for multiple-level logic (combinational and sequential).
- Interconnection of modules:
 - Logic gates.
 - Logic functions.

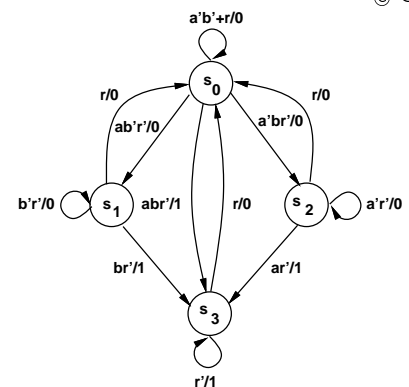
Example

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State diagrams

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- Model behavior of sequential circuits.
- Graph:
 - Vertices = states.
 - Edges = transitions.

Major logic synthesis problems

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- Optimization of logic function representation.
 - Minimization of two-level forms.
 - Optimization of Binary Decision Diagrams (BDDs).
- Synthesis of combinational multiple-level logic networks.
 - Optimization of area, delay, power, testability.
- Optimization of FSM models.
 - State minimization, encoding.
- Synthesis of sequential multiple-level logic networks.
 - Optimization of area, delay, power, testability.
- Library binding.
 - Optimal selection of library cells.

Combinational logic design background

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- Boolean algebra:
 - Quintuple $(B, +, \cdot, 0, 1)$
 - Binary Boolean algebra $B = \{0, 1\}$
- Boolean function:
 - Single output: $f : B^n \rightarrow B$.
 - Multiple output: $f : B^n \rightarrow B^m$.
 - Incompletely specified:
 - * *don't care* symbol *.
 - * $f : B^n \rightarrow \{0, 1, *\}^m$.

The *don't care* conditions

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- We don't care about the value of the function.
- Related to the environment:
 - Input patterns that never occur.
 - Input patterns such that some output is never observed.
- Very important for synthesis and optimization.

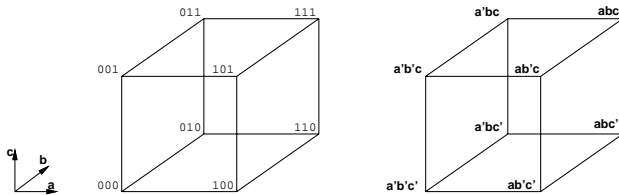
Definitions

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- Scalar function:
 - *ON – set*: subset of the domain such that f is true.
 - *OFF – set*: subset of the domain such that f is false.
 - *DC – set*: subset of the domain such that f is a *don't care*.
- Multiple-output function:
 - Defined for each component.

Cubical representation

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Definitions

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- Boolean *variables*.
- Boolean *literal*: variable and complement.
- *Product* or *cube*: product of literals.
 - *Hypercube* in the Boolean space.
- *Implicant*: product implying a value of a function (usually TRUE).
 - *Vertex* in the Boolean space.
- *Minterm*: product of all input variables implying a value of a function (usually TRUE).
 - *Vertex* in the Boolean space.

Tabular representations

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- *Truth table*:
 - List of all minterms of a function.
- *Implicant table* or *cover*:
 - List of implicants of a function sufficient to define function.
- Remark:
 - Implicant tables are smaller in size.

Example of truth table

$$x = ab + a'c; \quad y = ab + bc + ac$$

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abc	xy
000	00
001	10
010	00
011	11
100	00
101	01
110	11
111	11

Example of implicant table

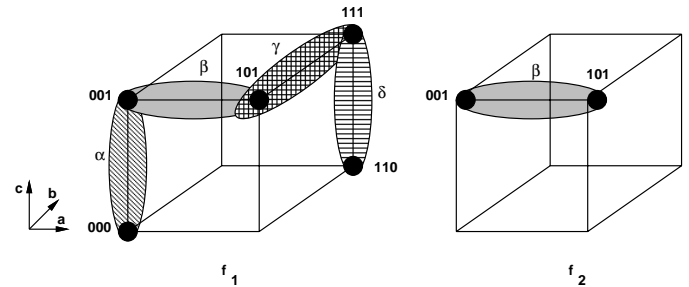
$$x = ab + a'c; \quad y = ab + bc + ac$$

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abc	xy
001	10
*11	11
101	01
11*	11

Cubical representation of minterms and implicants

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- $f_1 = a'b'c' + a'b'c + ab'c + abc + abc'$

- $f_2 = a'b'c + ab'c$

Two-level logic optimization motivation

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- Reduce size of the representation.
- Direct implementation:
 - PLAs – reduce size and delay.
- Other implementation styles (e.g. multi-level):
 - Reduce amount of information.
 - Simplify local functions and connections.

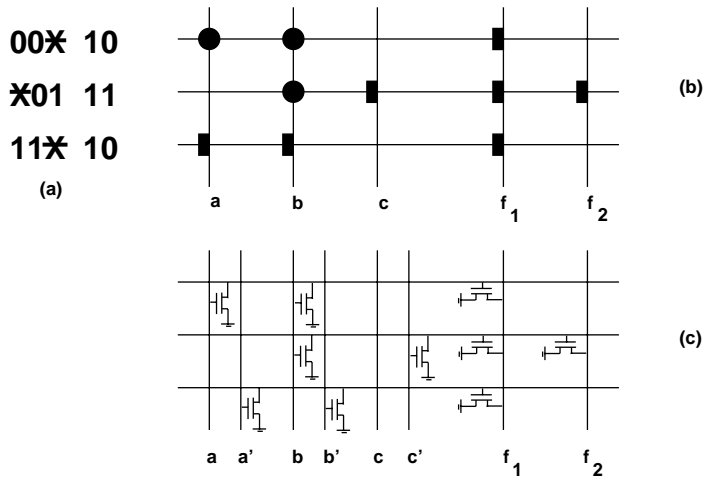
Programmable logic arrays

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- Macro-cells with rectangular structure.
- Implement any multi-output function.
- Layout easily generated by module generators.
- Fairly popular in the seventies/eighties (NMOS).
- Still used for control-unit implementation.

Programmable logic array

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- $f_1 = a'b' + b'c + ab$ $f_2 = b'c$

Two-level optimization

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- Assumptions:
 - Primary goal is to reduce the number of implicants.
 - All implicants have the same cost.
 - Secondary goal is to reduce the number of literals.
- Rationale:
 - Implicants correspond to PLA rows.
 - Literals correspond to transistors.

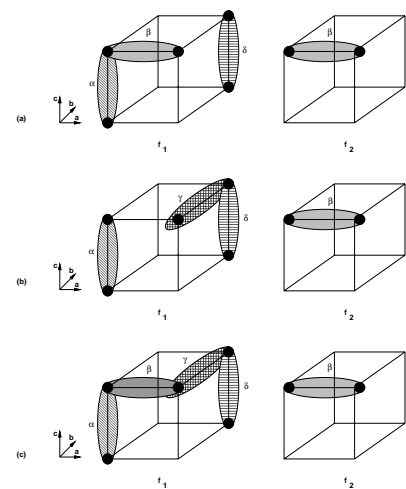
Definitions

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- *Minimum cover*:
 - Cover of the function with minimum number of implicants.
 - Global optimum.
- *Minimal cover or irredundant cover*:
 - Cover of the function that is not a proper superset of another cover.
 - No implicant can be dropped.
 - Local optimum.
- *Minimal cover w.r.t. 1-implicant containment*:
 - No implicant is contained by another one.
 - Weak local optimum.

Example

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- $f_1 = a'b'c' + a'b'c + abc + abc'$
- $f_2 = a'b'c + ab'c$

Definitions

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- *Prime* implicant:
 - Implicant not contained by any other implicant.
- *Prime* cover:
 - Cover of prime implicants.
- *Essential* prime implicant:
 - There exist some minterm covered only by that prime implicant.

Logic minimization

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- *Exact* methods:
 - Compute minimum cover.
 - Often impossible for large functions.
 - Based on *Quine McCluskey* method.
- *Heuristic* methods:
 - Compute minimal covers (possibly minimum).
 - Large variety of methods and programs:
 - * MINI, PRESTO, ESPRESSO.

Exact logic minimization

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- *Quine's theorem*:
 - There is a minimum cover that is prime.
- Consequence:
 - Search for minimum cover can be restricted to prime implicants.
- *Quine McCluskey* method:
 - Compute prime implicants.
 - Determine minimum cover.

Prime implicant table

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- Rows: minterms.
- Columns: prime implicants.
- Exponential size:
 - 2^n minterms.
 - Up to $3^n/n$ prime implicants.
- Remark:
 - Some functions have much fewer primes.
 - Minterms can be grouped together.

Example

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• Function: $f = a'b'c' + a'b'c + ab'c + abc + abc'$

• Primes:

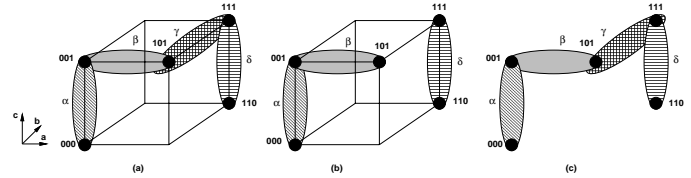
α	00*	1
β	*01	1
γ	1*1	1
δ	11*	1

• Implicant table:

	α	β	γ	δ
000	1	0	0	0
001	1	1	0	0
101	0	1	1	0
111	0	0	1	1
110	0	0	0	1

Example

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Minimum cover early methods

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• Reduce table:

- Iteratively identify essentials, save them in the cover, remove covered minterms.

• *Petrick's* method.

- Write covering clauses in *pos* form.
- Multiply out *pos* form into *sop* form.
- Select cube of minimum size.
- *Remark:*
 - * Multiplying out clauses is exponential.

Example Petrick's method

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• *pos* clauses:

$$-(\alpha)(\alpha + \beta)(\beta + \gamma)(\gamma + \delta)(\delta) = 1$$

• *sop* form:

$$-\alpha\beta\delta + \alpha\gamma\delta = 1$$

• Solutions:

$$-\{\alpha, \beta, \delta\}$$

$$-\{\alpha, \gamma, \delta\}$$

Matrix representation

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- View table as Boolean matrix: \mathbf{A} .
- Selection Boolean vector for primes: \mathbf{x} .
- Determine \mathbf{x} such that:
 - $\mathbf{A} \mathbf{x} \geq \mathbf{1}$.
 - Select enough columns to cover all rows.
- Minimize cardinality of \mathbf{x} :
 - Example: $\mathbf{x} = [1101]^T$

Example

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$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

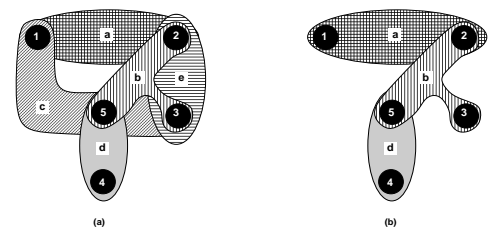
Covering problem

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- Set covering problem:
 - A set S . (Minterm set).
 - A collection C of subsets. (Implicant set).
 - Select fewest elements of C to cover S .
- Intractable.
- Exact method:
 - Branch and bound algorithm.
- Heuristic methods.

Example edge-cover of a hypergraph

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Branch and bound algorithm

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- Tree search of the solution space:
 - Potentially exponential search.
- Use bounding function:
 - If the lower bound on the solution cost that can be derived from a set of future choices exceeds the cost of the best solution seen so far:
 - Kill the search.
- Good pruning may reduce run-time.

Branch and bound algorithm

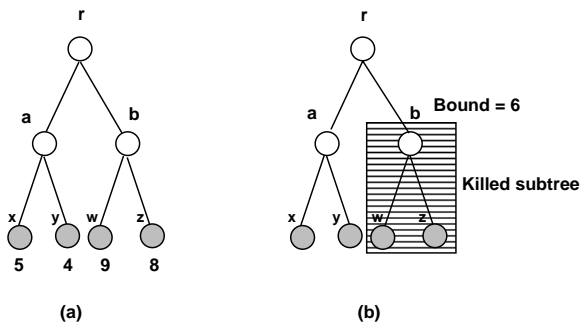
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```

BRANCH_AND_BOUND {
  Current_best = anything;
  Current_cost = ∞;
  S = s0;
  while (S ≠ ∅) do {
    Select an element in s ∈ S;
    Remove s from S ;
    Make a branching decision based on s
    yielding sequences {si, i = 1, 2, ..., m};
    for ( i = 1 to m) {
      Compute the lower bound bi of si;
      if (bi ≥ Current_cost)
        Kill si;
      else {
        if (si is a complete solution ) {
          Current_best = si;
          Current_cost = cost of si ;
        }
        else
          Add si to set S;
      }
    }
  }
}
    
```

Example

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Branch and bound algorithm for covering Reduction strategies

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- Partitioning:
 - If **A** is block diagonal:
 - * Solve covering problem for corresponding blocks.
- Essentials (EPI):
 - Column incident to one (or more) row with single 1:
 - * Select column.
 - * Remove covered row(s) from table.

Branch and bound algorithm for covering

Reduction strategies

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- Column (implicant) dominance:

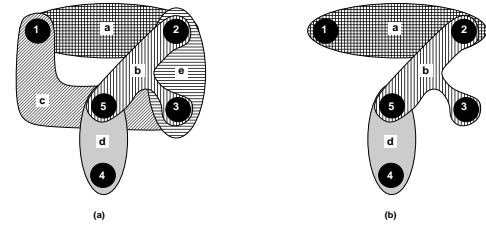
- If $a_{ki} \geq a_{kj} \forall k$:
 - * remove column j .

- Row (minterm) dominance:

- If $a_{ik} \geq a_{jk} \forall k$:
 - * Remove row i .

Example

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$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \end{bmatrix}$$

Example reduction

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- Fourth column is essential.
- Fifth column is dominated.
- Fifth row is dominant.

- $\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$

Branch and bound covering algorithm

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```

EXACT_COVER( $\mathbf{A}, \mathbf{x}, \mathbf{b}$ ) {
    Reduce matrix  $\mathbf{A}$  and update corresponding  $\mathbf{x}$ ;
    if ( $Current\_estimate \geq |\mathbf{b}|$ ) return( $\mathbf{b}$ );
    if ( $\mathbf{A}$  has no rows) return ( $\mathbf{x}$ );
    Select a branching column  $c$ ;
     $x_c = 1$  ;
     $\tilde{\mathbf{A}} = \mathbf{A}$  after deleting  $c$  and rows incident to it;
     $\tilde{\mathbf{x}} = EXACT\_COVER(\tilde{\mathbf{A}}, \mathbf{x}, \mathbf{b})$ ;
    if ( $|\tilde{\mathbf{x}}| < |\mathbf{b}|$ )
         $\mathbf{b} = \tilde{\mathbf{x}}$  ;
     $x_c = 0$  ;
     $\tilde{\mathbf{A}} = \mathbf{A}$  after deleting  $c$  ;
     $\tilde{\mathbf{x}} = EXACT\_COVER(\tilde{\mathbf{A}}, \mathbf{x}, \mathbf{b})$ ;
    if ( $|\tilde{\mathbf{x}}| < |\mathbf{b}|$ )
         $\mathbf{b} = \tilde{\mathbf{x}}$  ;
    return ( $\mathbf{b}$ );
}
    
```

Bounding function

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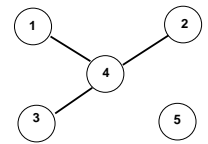
- Estimate lower bound on the covers derived from the current \mathbf{x} .
- The sum of the ones in \mathbf{x} , plus bound on cover for local \mathbf{A} :
 - Independent set of rows:
 - * No 1 in same column.
 - Build graph denoting pairwise independence.
 - Find clique number.
 - Approximation (lower) is acceptable.

Example

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$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 \end{bmatrix}$$

- Row 4 independent from 1,2,3.
- Clique number is 2.



- Bound is 2.

Example

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$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

- There are no independent rows.
- Clique number is 1 (one vertex).
- Bound is $1 + 1$ (already selected essential).

Example

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$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

- Choose first column:
 - Recur with $\tilde{\mathbf{A}} = [11]$.
 - * Delete one dominated column.
 - * Take other column (essential).
 - New cost is 3.
- Exclude first column:
 - Find another solution with cost 3 (discarded).

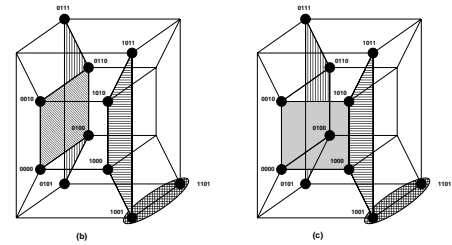
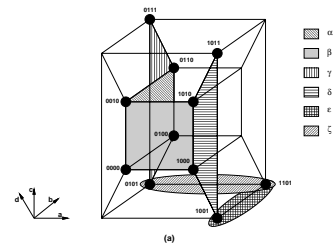
ESPRESSO-EXACT

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- Exact minimizer [Rudell].
- Exact *branch and bound* covering.
- Compact implicant table:
 - Group together minterms covered by the same implicants.
- Very efficient. Solves most problems.

Example

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α	0**0	1
β	*0*0	1
γ	01**	1
δ	10**	1
ϵ	1*01	1
ζ	*101	1

Example Prime implicant table (after removing essentials)

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	α	β	ϵ	ζ
0000,0010	1	1	0	0
1101	0	0	1	1

Recent developments

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- Many minimization problems can be solved exactly today.
- Usually bottleneck is table size.
- Implicit representation of prime implicants:
 - Methods based on BDDs [COUDERT]:
 - * To represent sets.
 - * To do dominance simplification.
 - Methods based on signature cubes [MCGEER]:
 - * Represent set of primes.

Summary

Exact two-level minimization of logic functions

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- Based on derivatives of Quine-McCluskey method.
- Many minimization problems can be now solved exactly.
- Usual problems are memory size and time.

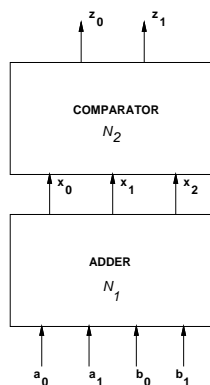
Boolean relations

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- Generalization of Boolean functions.
- More than one output pattern may correspond to an input pattern.
- Some *degrees of freedom* in finding an implementation:
 - More general than *don't care* conditions.
- Problem:
 - Given a Boolean relation, find minimum cover of a compatible function.

Example

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- Compare:
 - $a + b > 4$?
 - $a + b < 3$?

Example

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a_1	a_0	b_1	b_0	x
0	0	0	0	{ 000, 001, 010 }
0	0	0	1	{ 000, 001, 010 }
0	0	1	0	{ 000, 001, 010 }
0	1	0	0	{ 000, 001, 010 }
1	0	0	0	{ 000, 001, 010 }
0	1	0	1	{ 000, 001, 010 }
0	0	1	1	{ 011, 100 }
0	1	1	0	{ 011, 100 }
1	0	0	1	{ 011, 100 }
1	0	1	0	{ 011, 100 }
1	1	0	0	{ 011, 100 }
0	1	1	1	{ 011, 100 }
1	1	0	1	{ 011, 100 }
1	0	1	1	{ 101, 110, 111 }
1	1	1	0	{ 101, 110, 111 }
1	1	1	1	{ 101, 110, 111 }

Example (2) Minimum implementation

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a_1	a_0	b_1	b_0	x
0	*	1	*	010
1	*	0	*	010
1	*	1	*	100
*	*	*	1	001
*	1	*	*	001

- Remark:

- Circuit is no longer an adder.

Minimization of Boolean relations

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- Since there are many possible output values there are many logic functions implementing the relation.
 - Compatible functions.
- Find a function with minimum cardinality.
- Do not enumerate all possible functions:
 - May be too many.
- Represent the primes of all possible functions:
 - Compatible primes (*c-primes*).

Minimization of Boolean relation

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- Exact:

- Find a set of compatible primes.
- Solve a *binate* covering problem.
 - * Consistency relations.

- Heuristic:

- Iterative improvement [GYOCRO].

Example

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- Boolean relation:

0	0	0	{ 00 }
0	0	1	{ 00 }
0	1	0	{ 00 }
0	1	1	{ 10 }
1	0	0	{ 00 }
1	0	1	{ 01 }
1	1	0	{ 00,11 }
1	1	1	{ 00,11 }

- Compatible primes:

α	0	1	1	10
β	1	0	1	01
γ	1	1	0	11
δ	1	1	1	11
ϵ	*	1	1	10
ζ	1	*	1	01
η	1	1	*	11

Example

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- Input 011 – output 10.
 - Covering clause $(\alpha + \epsilon)$.
- Input 111 – output 00 or 11.
 - No implicant – 00 – correct.
 - Either η or $\epsilon \cup \zeta$ – output 11 – correct.
 - Only ϵ or ζ is selected – output 10 or 01 – WRONG.
 - Covering clause $\eta + \epsilon\zeta + \epsilon'\zeta'$ – binate.
- Overall covering clause:
 $(\alpha + \epsilon) \cdot (\beta + \zeta) \cdot (\epsilon + \zeta' + \eta) \cdot (\epsilon' + \zeta + \eta)$

Binate covering

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- Covering problem with *binate clause*.
- Implications:
 - The selection of a prime may exclude other primes.
- No guarantee of finding a feasible solution:
 - Inconsistent clauses.
- *Minimum-cost satisfiability* problem.
 - Much harder to solve than unate cover.
 - Branch and bound algorithm.
 - BDD-based methods.

Summary Boolean relations

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- Generalization of Boolean functions.
 - Many possible output patterns.
- Useful for modeling:
 - Cascaded blocks.
 - Portions of multiple-level networks.
- More degree of freedom in implementation.
- Harder problem to solve.