

BAIKEM -Netzwerktreffen
Embedded Systems

Modell-getriebene Entwicklung mit der YAKINDU-Workbench

about me ...



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- ... work at itemis AG, Germany
- ... work on model driven development of embedded systems
- ... work on YAKINDU open source project

about itemis AG ...

founded 2003, ± 145 people

Training, Coaching, Consulting

- Model Driven Development (MDD)
- individual Tools and Toolchains
- Embedded Systems, Mobile Apps, Enterprise Systems

Open Source - Eclipse Strategic Member & Contributor

Eclipse Modeling

- EMF - Eclipse Modeling Framework
- Xtext - Textual Modeling Framework
- Xpand / Xtend - Code Generator Framework
- GEF - Grafical Editing Framework



YAKINDU
is a *modular toolkit*
for *model driven development*
of embedded systems

Yakindu Language Modules



- SCT - statecharts
- Damos - data-flow oriented modeling
- Mscript - math oriented scripting
- CReMa - (requirements) traceability
- CoMo - component model (upcoming)

SCT

Damos

Mscript

CReMa

CoMo

Typesystem, SI-Units

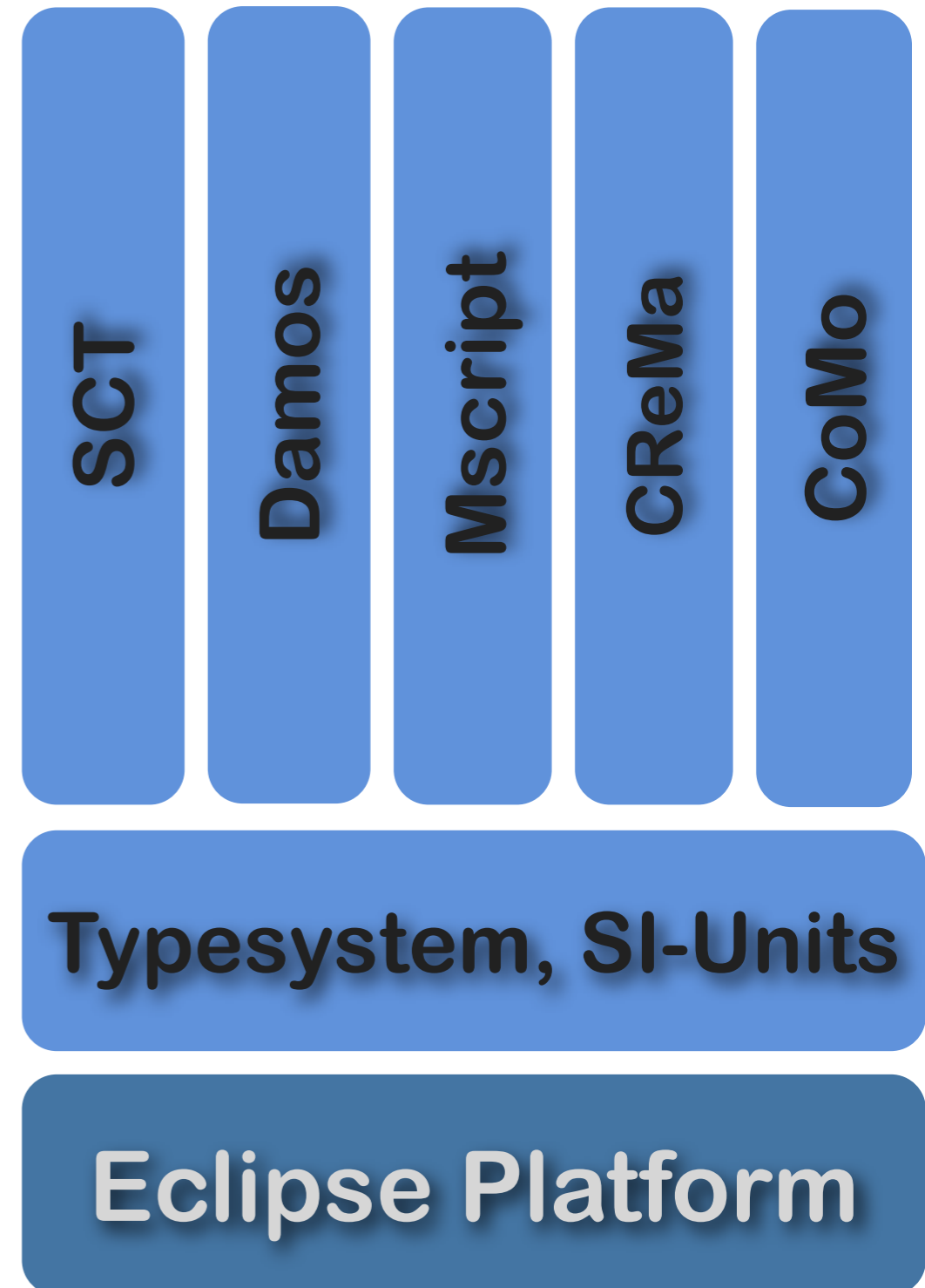
Eclipse Platform

Yakindu Language Modules

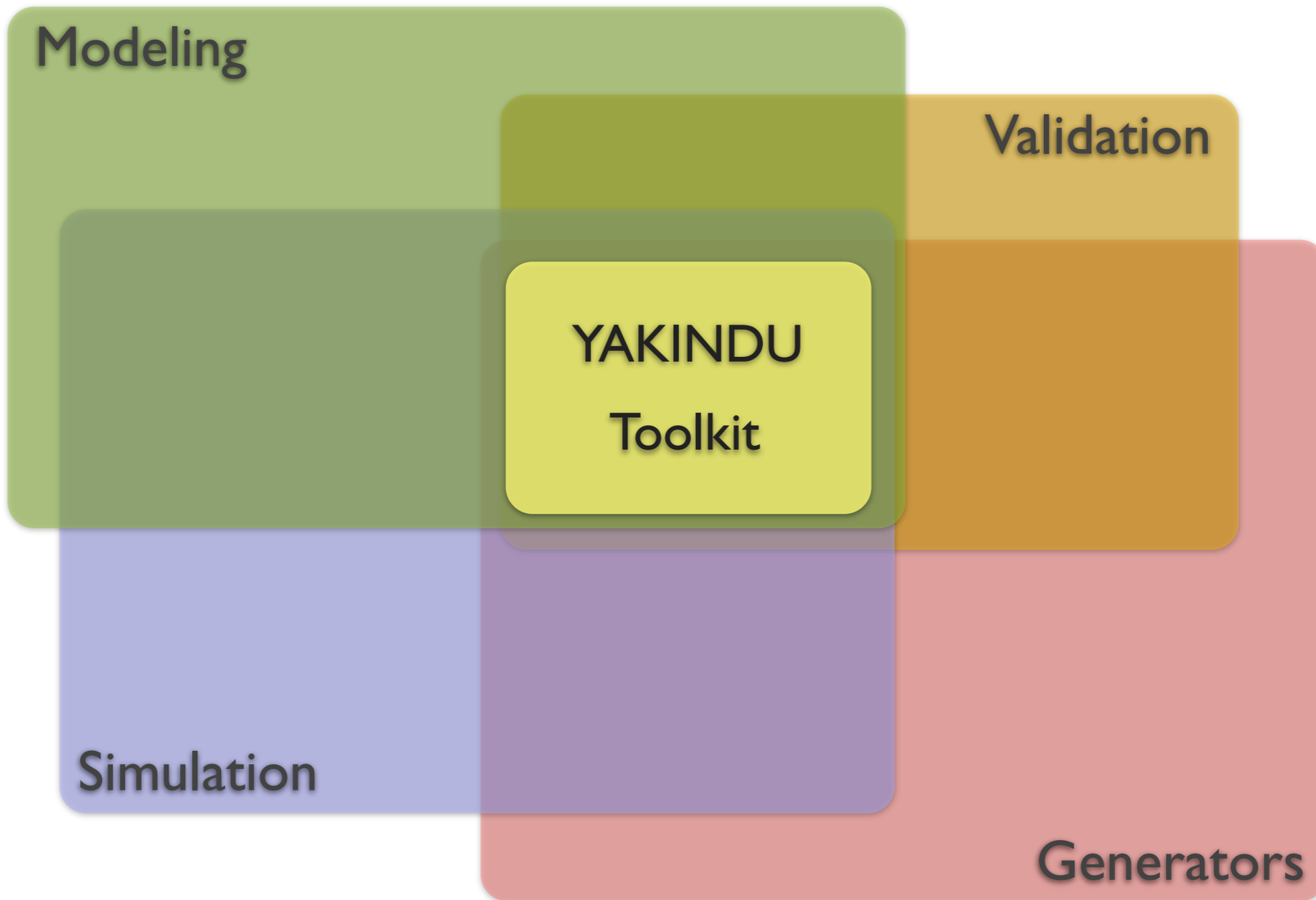


language modules are:

- independent
 - not bound to a specific methodology
 - self contained
 - **can be used on their own**
-
- open & extendable
 - **can be composed to (domain) specific language workbenches**
- ➔ ***Reuse of***
- ***modeling language***
 - ***Tools***



YAKINDU Tools consist of ...



Yakindu is ...

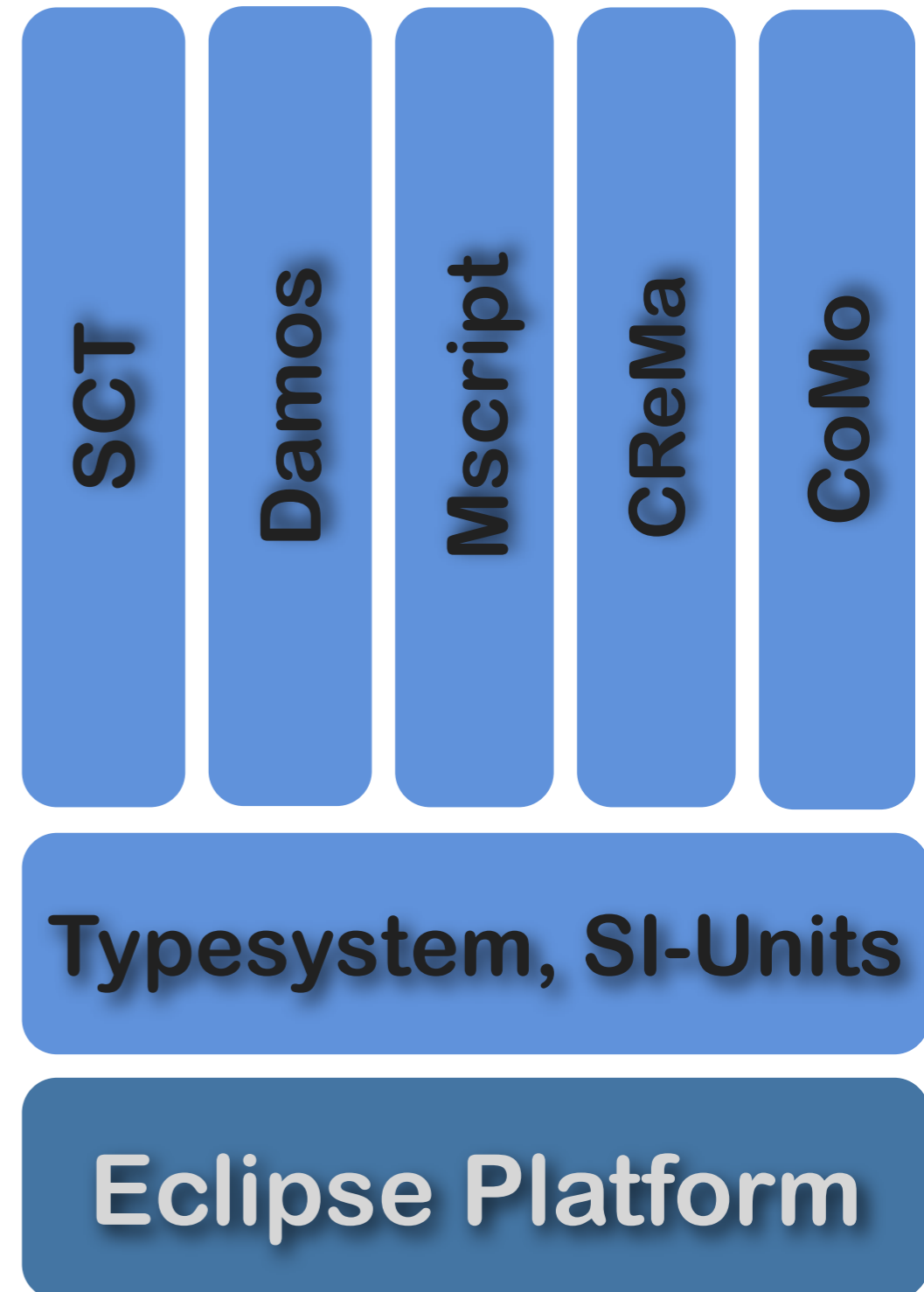


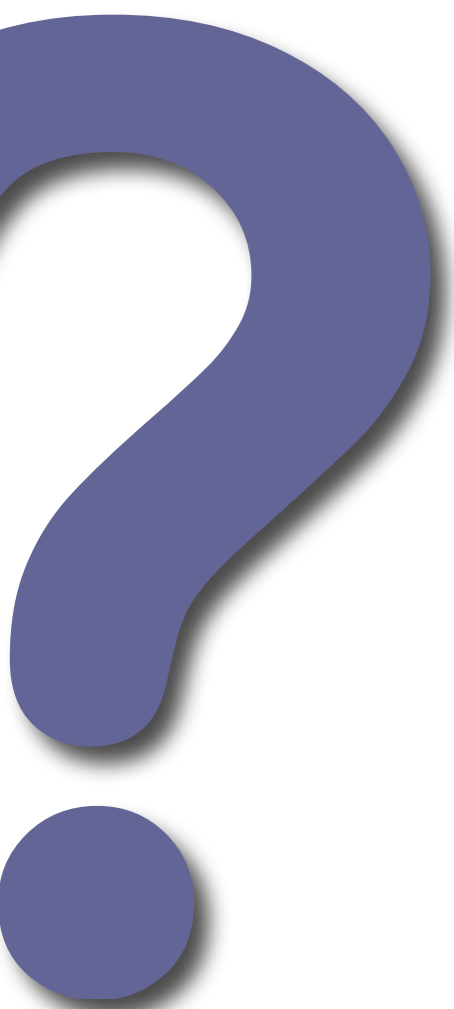
- built on Eclipse
- open source
- available at Eclipse Labs

<http://eclipselabs.org/p/yakindu>

<http://yakindu.org>

Eclipse Project Proposal: 2011





**What is Eclipse
good for ?**

Known as Integrated Development Environment

Eclipse

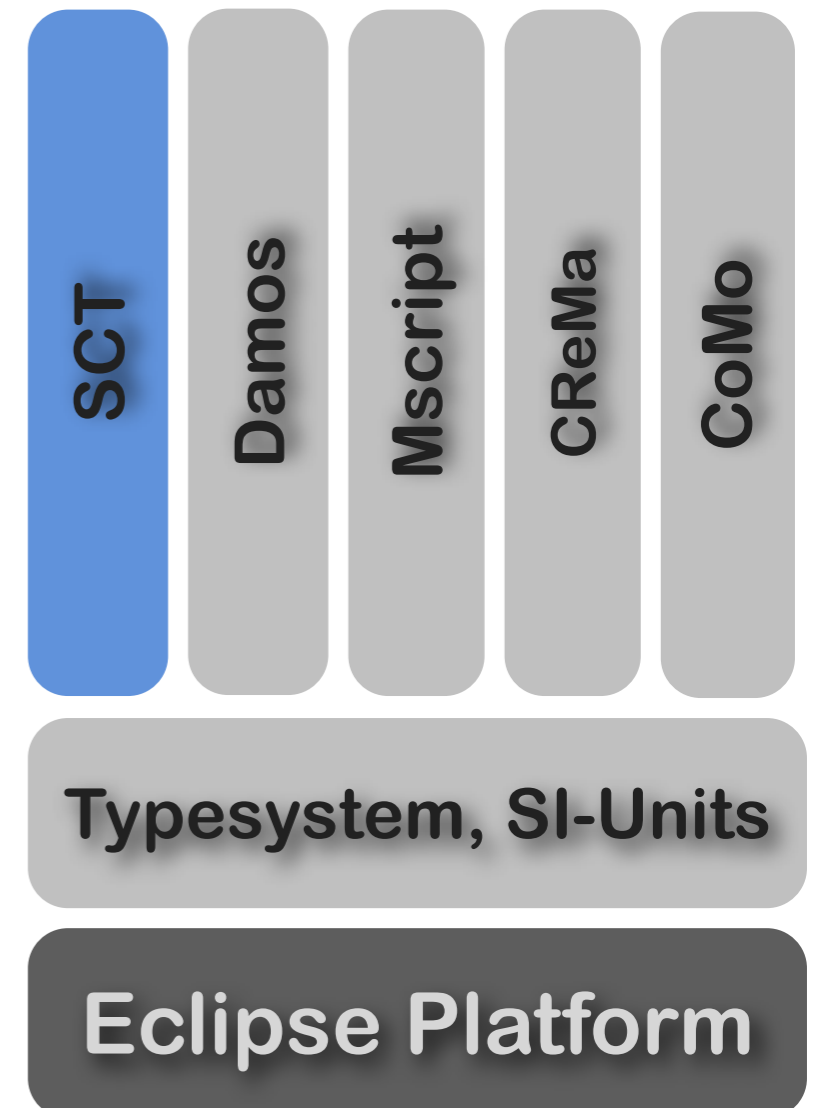
- Application / Tool Platform
- Open Architecture
- Designed for Extensibility
- Strong Modeling Infrastructure
- Open Source
- Reduced Costs

Eclipse

- Eclipse Modeling Framework
- Graphical Editing/Modeling Framework
- Xpand - Generator Framework
- Xtext - DSL Toolkit
- UML2 support
- ...

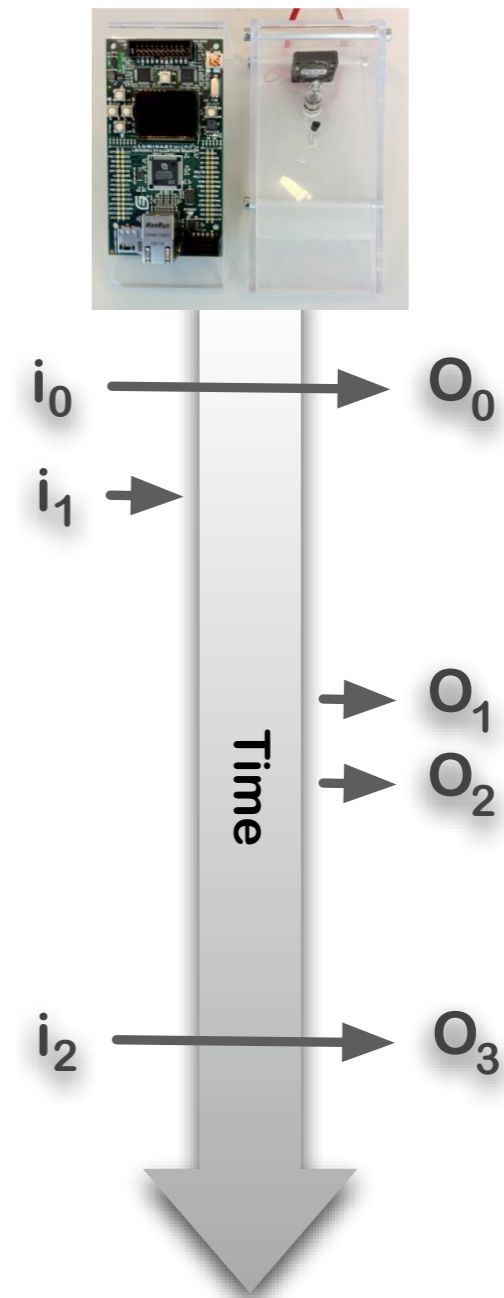


SCT - Statecharts



state machines (aka state charts)

- model reactive systems
- continuously interacts with the environment
- event driven
- focuses on transition of the systems state and it's reactions
- the state of the system evolves depending on previous inputs and time
- typically asynchronous



Yakindu Statechart Tools

heating

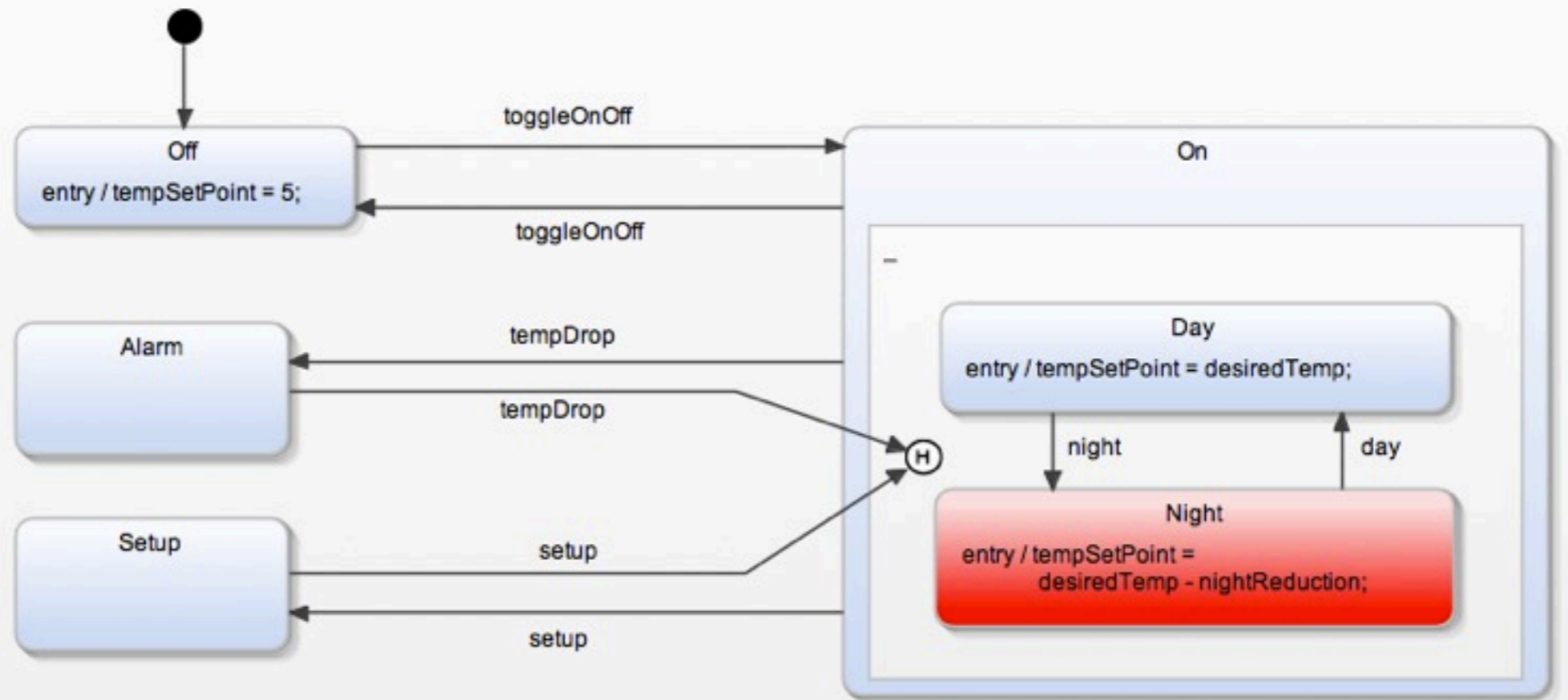
interface hmi:
 in event toggleOnOff
 in event setup
 in event increaseTemp
 in event decreaseTemp

interface controller:
 var tempSetPoint : integer
 in event tempDrop : integer
 in event tempChanged : integer

interface system:
 in event day
 in event night

internal:
 var desiredTemp : integer
 var actualTemp : integer
 var nightReduction : integer = 3
 tempChanged / actualTemp = temp...

main



statechart properties

- based on statecharts as defined by David Harel
- close to UML state machines
- but:
 - YSCs are self contained with an interface well defined by events and variables
 - core execution semantics are cycle-driven and not event-driven
 - allows processing concurrent events
 - event driven behaviour can be defined on top
 - time is an abstract concept for statecharts
 - time control is delegated to the environment
- model interpreter and different flavours of generated code follow the same core semantics

Domain Specific Statecharts

- Improving expressiveness and semantic integration by adopting domain concepts
 - Integration of state based modeling with DSL workbenches
 - SCT2 is built for extendability
-
- Example Domain: HMI Specification

Example DSL: HMI Contract

- Domain-Concepts:
Scene, Transition, Animation, Popup
- Defined by a DSL:
HMI-Contract
- HMI-Contract is a domain interface and supports technical decouplin

```
animation IntroAnimation
```

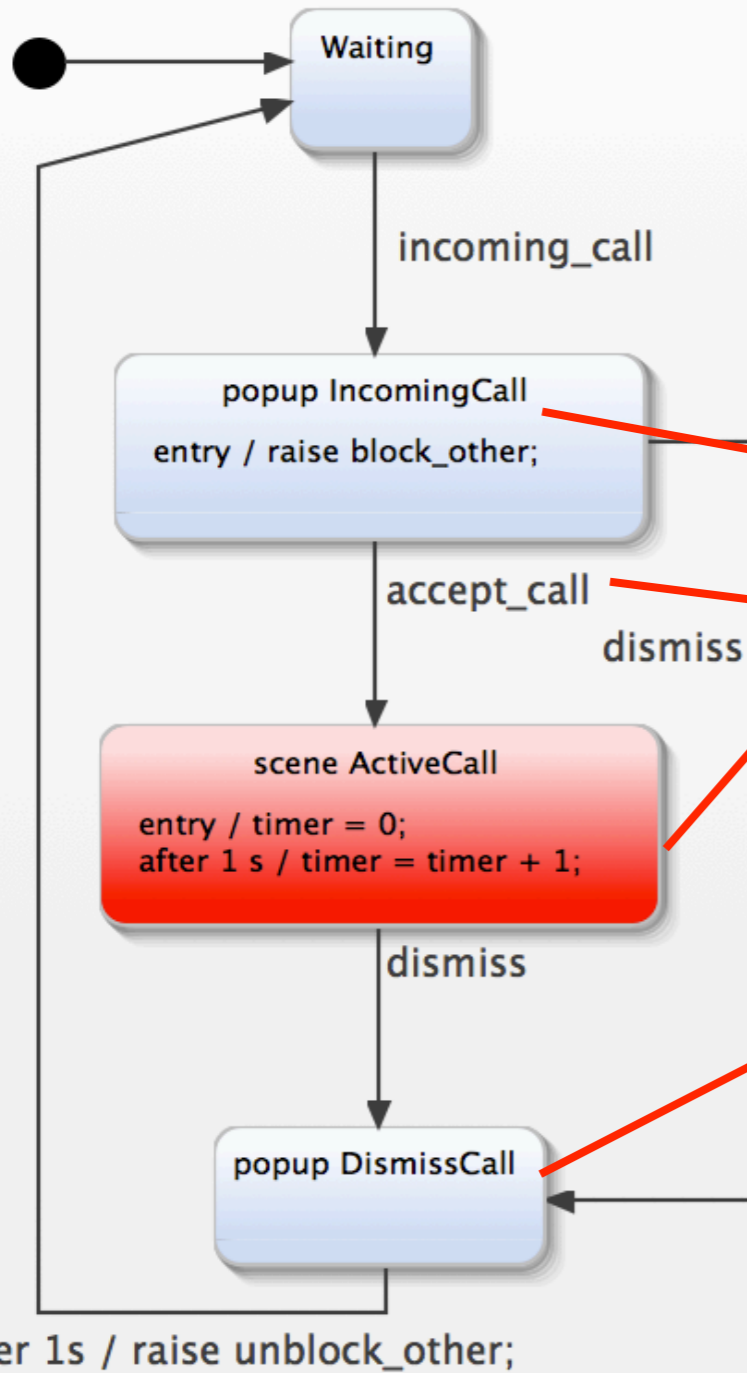
```
scene ActiveCall:
```

```
popup IncomingCall "incoming call ..." accept_call dismiss
```

```
popup DismissCall "finished call ..."
```

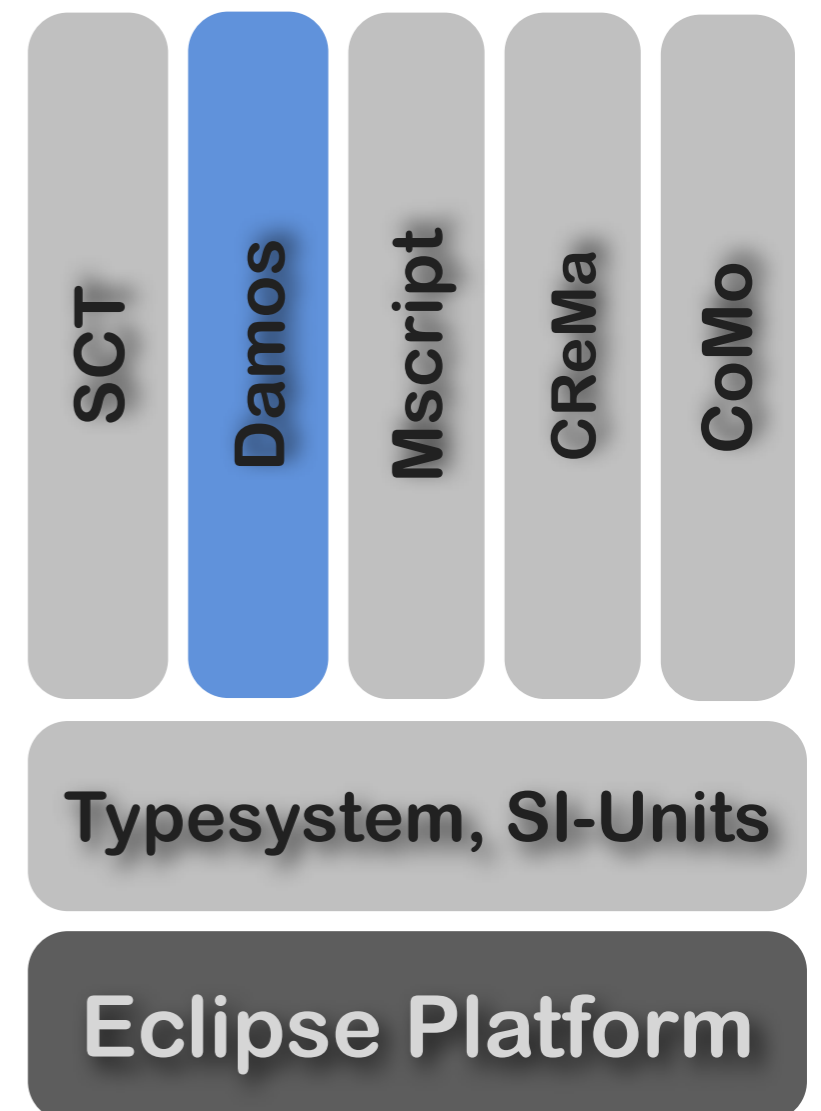
```
popup SpeedAlert "to fast ..." ok
```

CallHandling



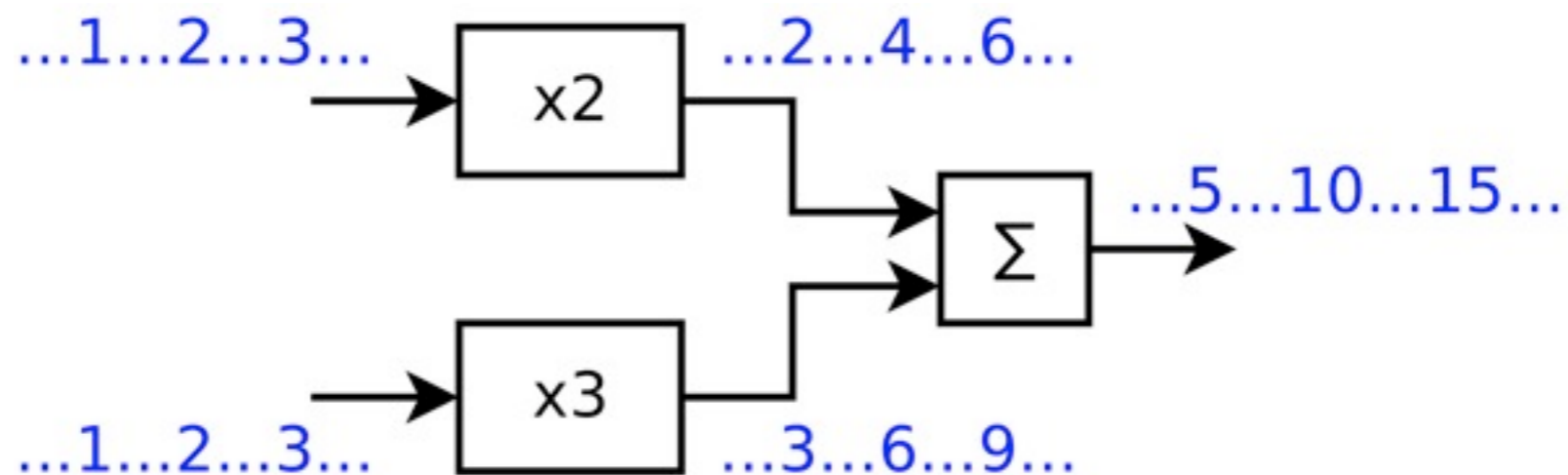
animation IntroAnimation
scene ActiveCall:
popup IncomingCall "incoming call ..."
accept_call dismiss
popup DismissCall "finished call ..."
popup SpeedAlert "to fast ..." ok

Damos - block diagrams

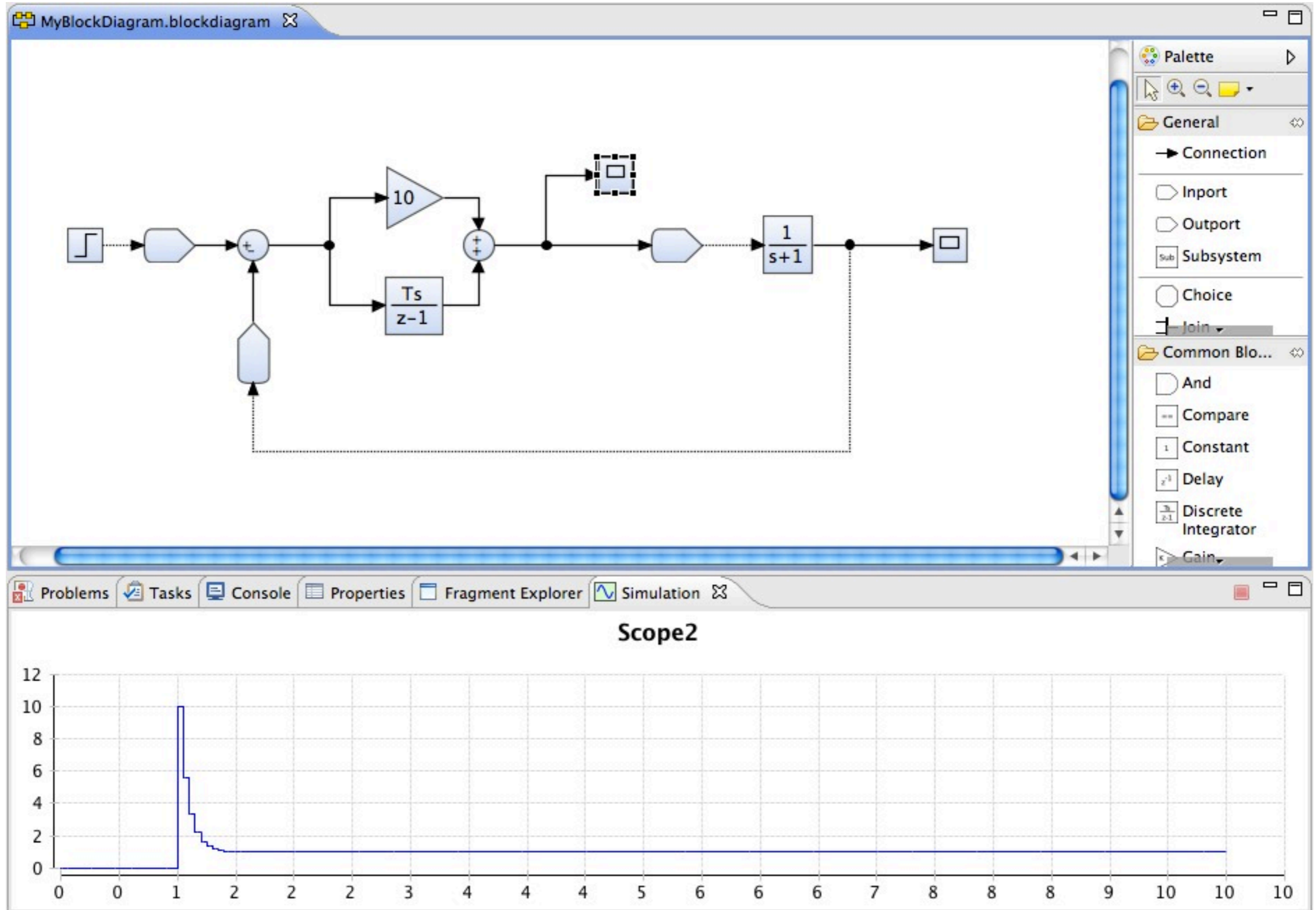


Data Flow-Oriented Modeling

- *Data* as main concept, instead of *state*
- Prevalent notation: Block diagrams
 - Block: System component's transfer function
 - Connection: Data flow (e.g. physical quantities)
- Technical applications: Control systems & digital signal processing



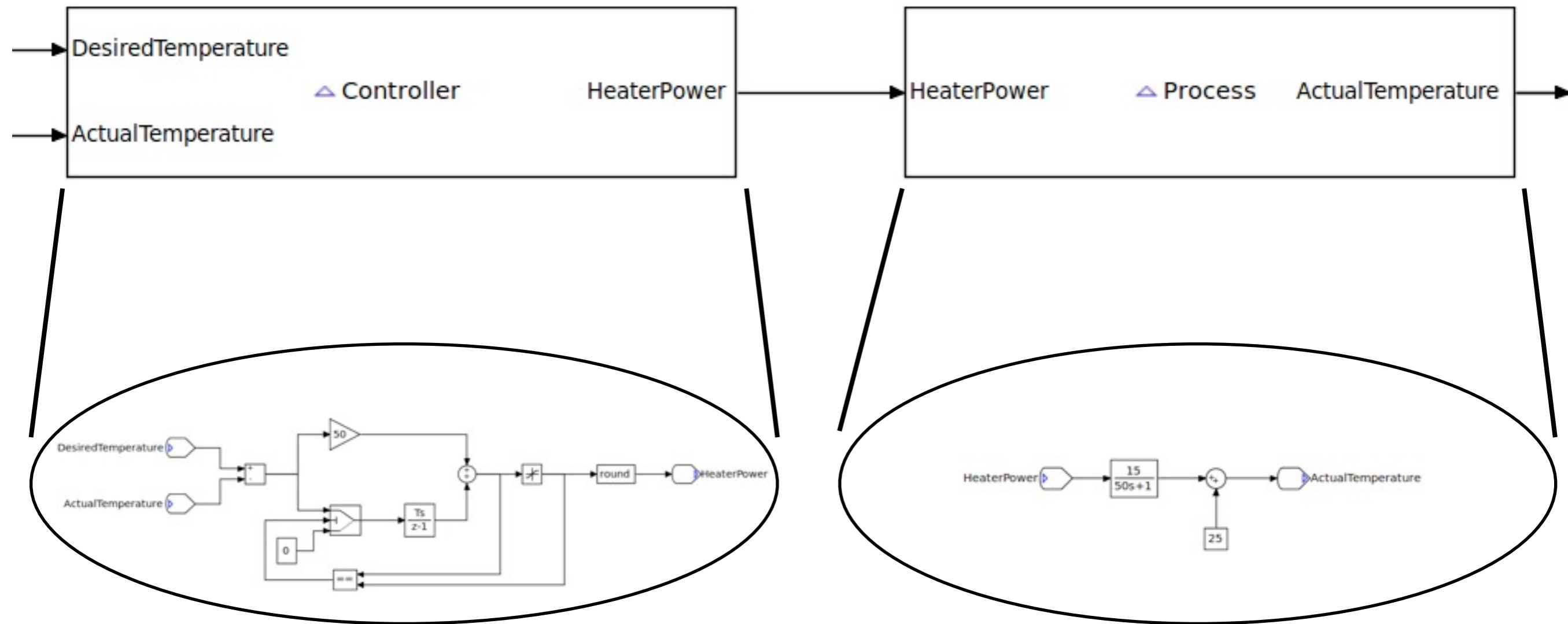
Damos Tooling



Structuring Models

- System components are divided into three categories
 - Device components (e.g. digital controller)
 - Environmental components (e.g. process)
 - Simulation interface components (e.g. step functions and scopes)
- Damos supports „two-dimensional“ structuring
 - Hierarchal structuring using subsystems
 - Cross-cutting structuring using system fragments

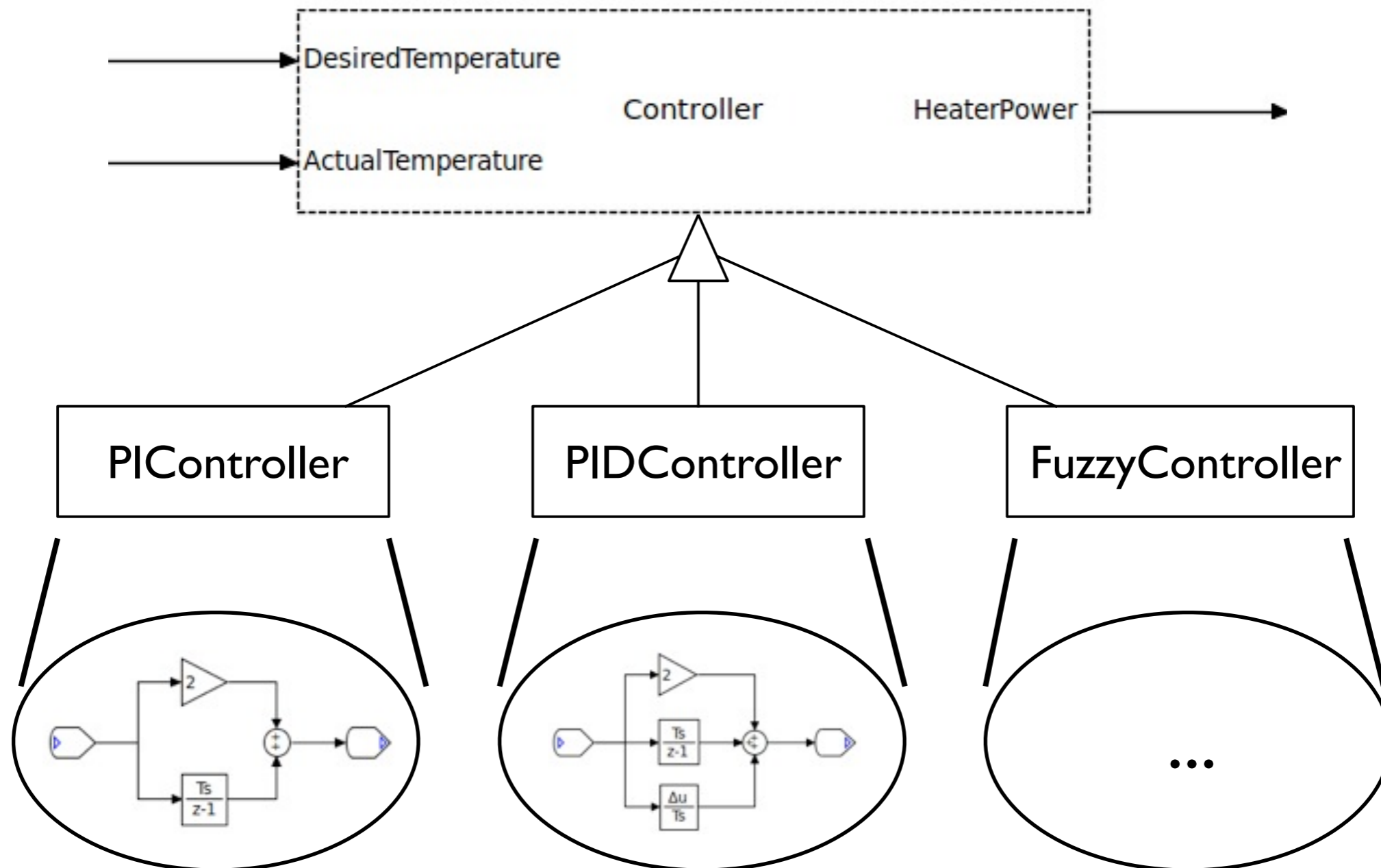
Subsystems



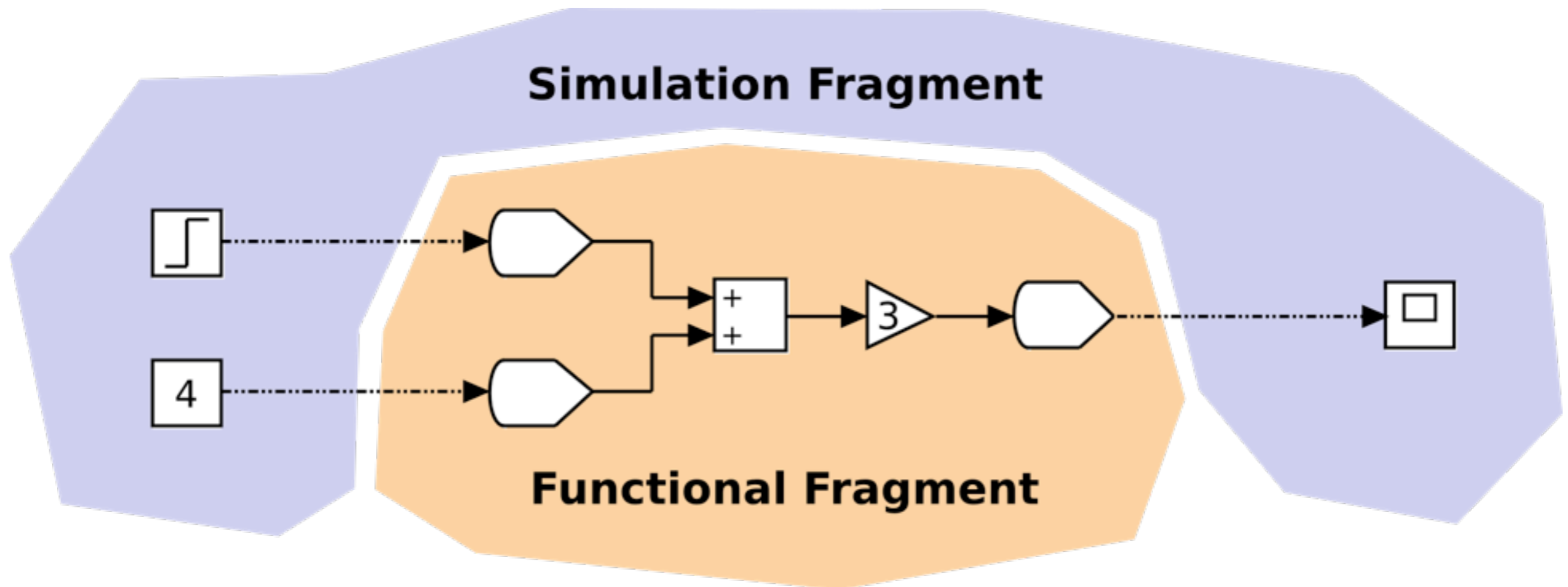
System Interfaces

- Defines system inlets and outlets, and their data types
- Subsystems specify their *provided interface*
- Realizing system is specified with *subsystem realization* model element
- Allows for specifying a subsystem without specifying a realization
- Can be used in product line engineering

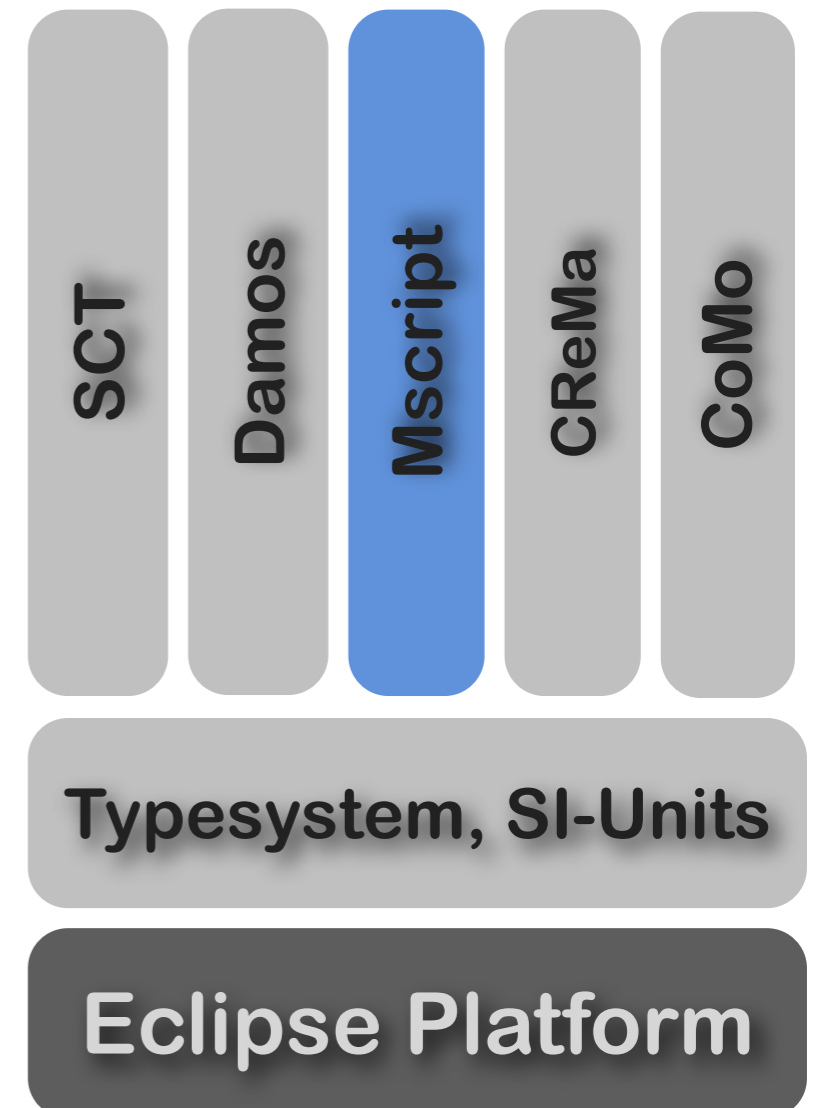
Subsystem Realizations



System Fragments



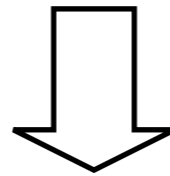
Mscript



Mscript Example

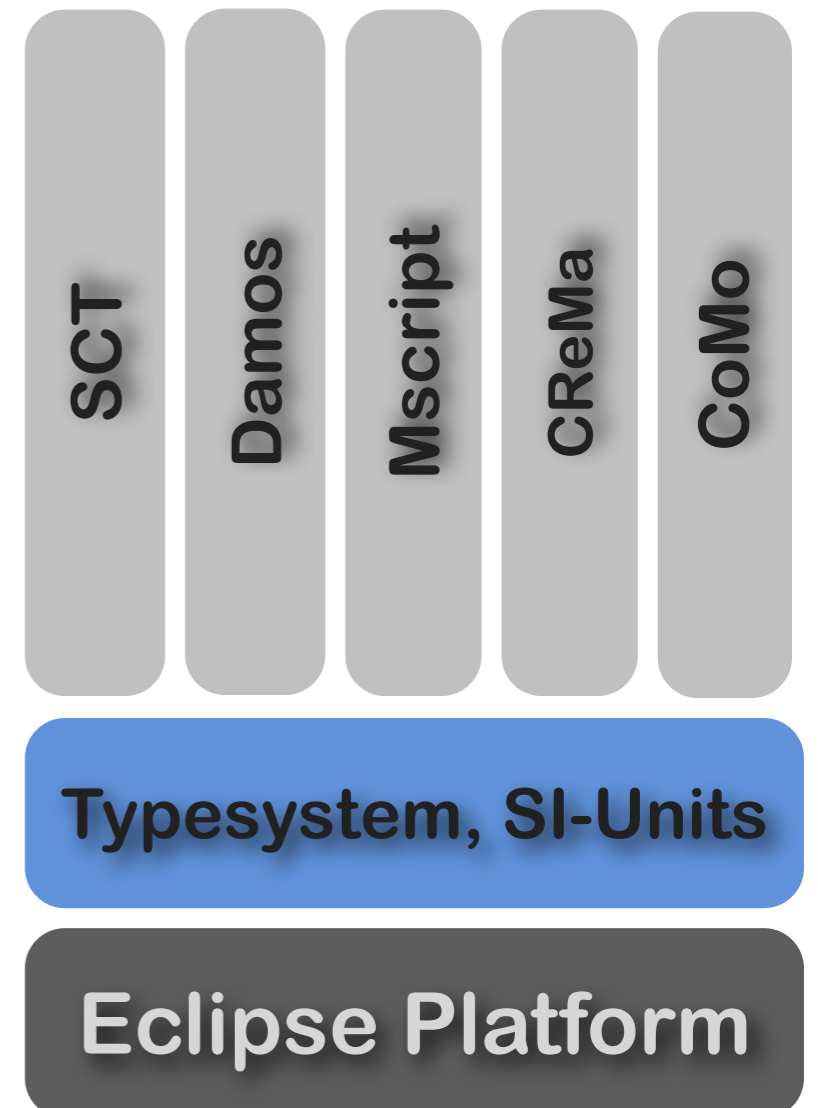
Discrete derivative:

$$y(n) = \frac{x(n) - x(n-1)}{T_s}$$



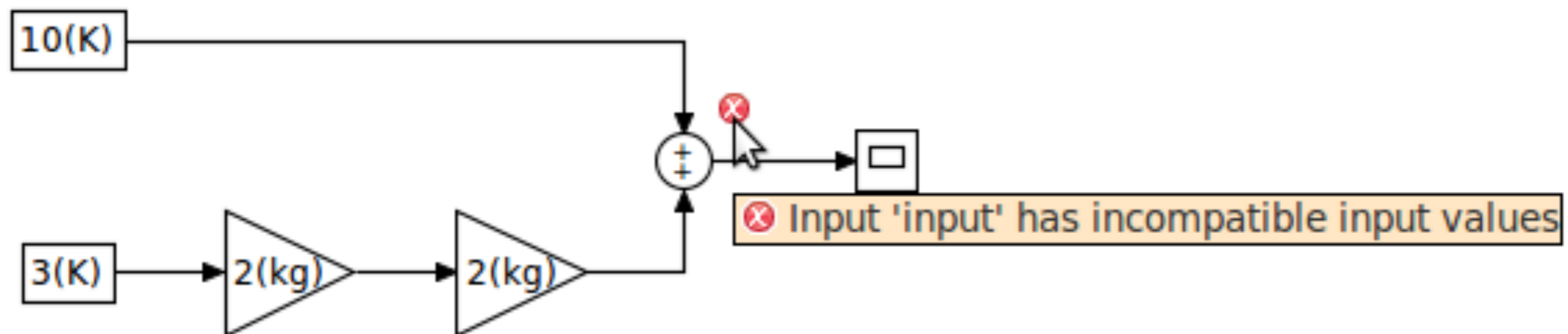
```
stateful func discreteDerivative<xinit, Ts>(x) -> y {  
    x(-1) = xinit;  
    y(n) = (x(n) - x(n-1)) / Ts;  
}
```

Typesystem & SI-Units

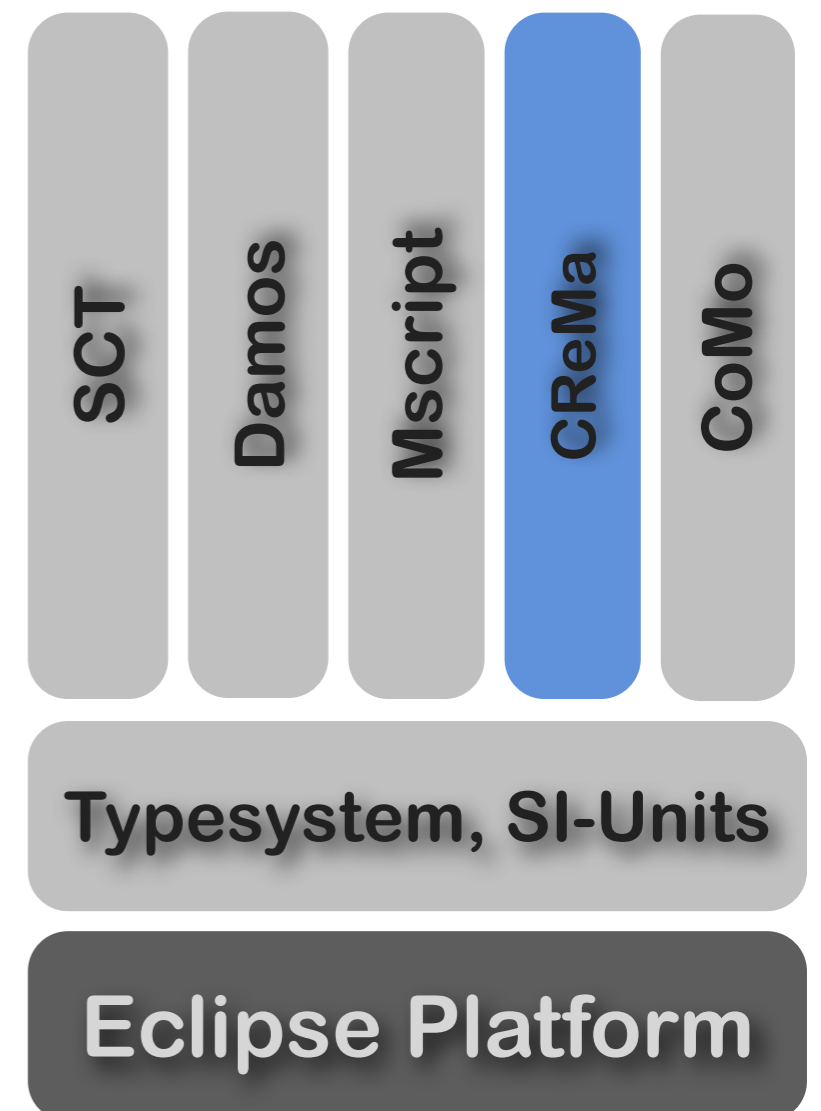


Units of Measurement

- Numeric data types incorporate unit of measurement
- When no unit is specified, dimensionless value is assumed
- Used for model validation



Requirements & Traceability

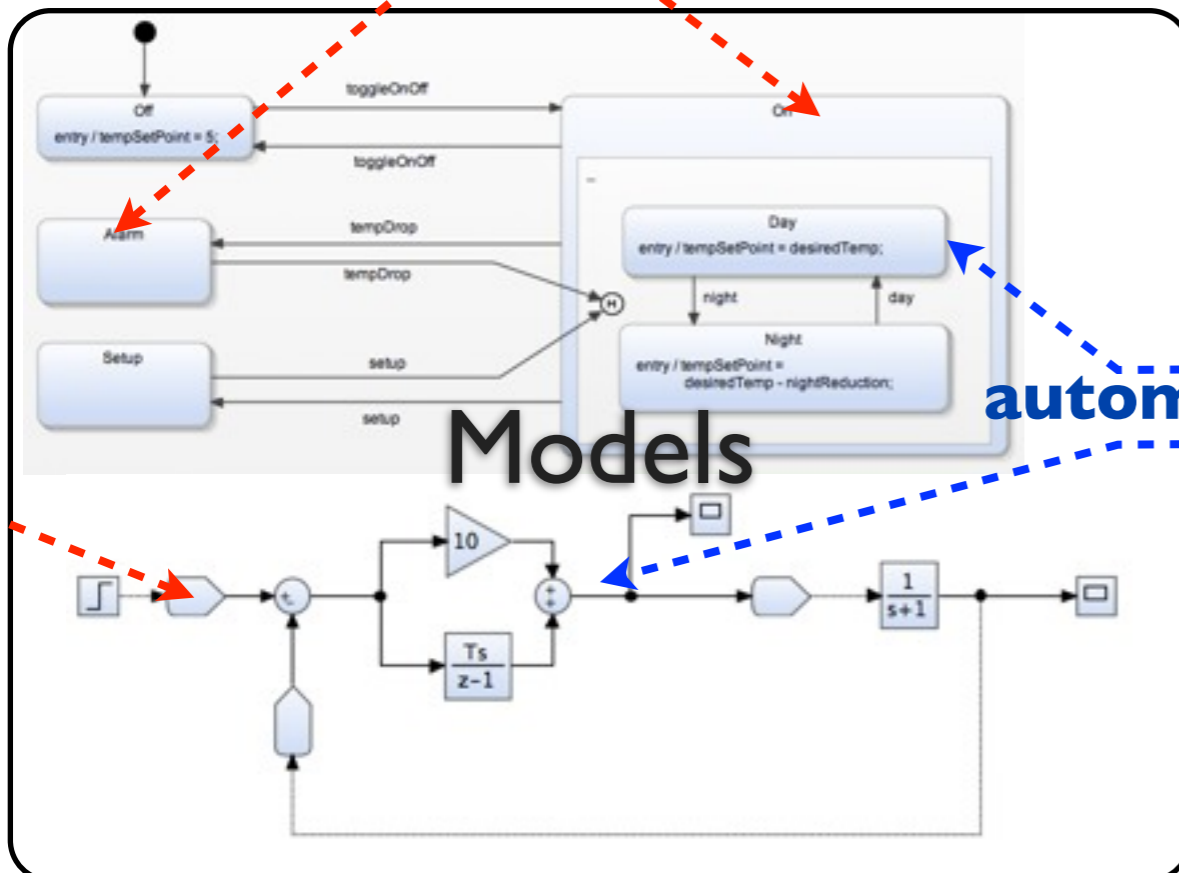


Aim ...

- bring **requirements** into the **development environment** (Eclipse)
- provide **tracing infrastructure**

ID	Description	Link
1	REQ-1	The system shall ...
2	REQ-2	The system shall ...
2.1	REQ-2.1	The system shall ...
3	REQ-3	The system should ...

Requirements



```
class System {
public:
    Scheduler* scheduler;
    InductionLoopComponent* byRoadInduction;
    TrafficLightComponent* byRoadLight;
    TrafficLightComponent* mainRoadLight;
    CrossingControllerComponent* controller;
    TrafficLightControllerComponent* byRoadLightController;
    TrafficLightControllerComponent* mainRoadLightController;

    System(Scheduler& scheduler);
    virtual ~System();

    void connect();
    void raiseTimerEvent(void* handle);
};
```

Code

automated Traces

RIF / ReqIF

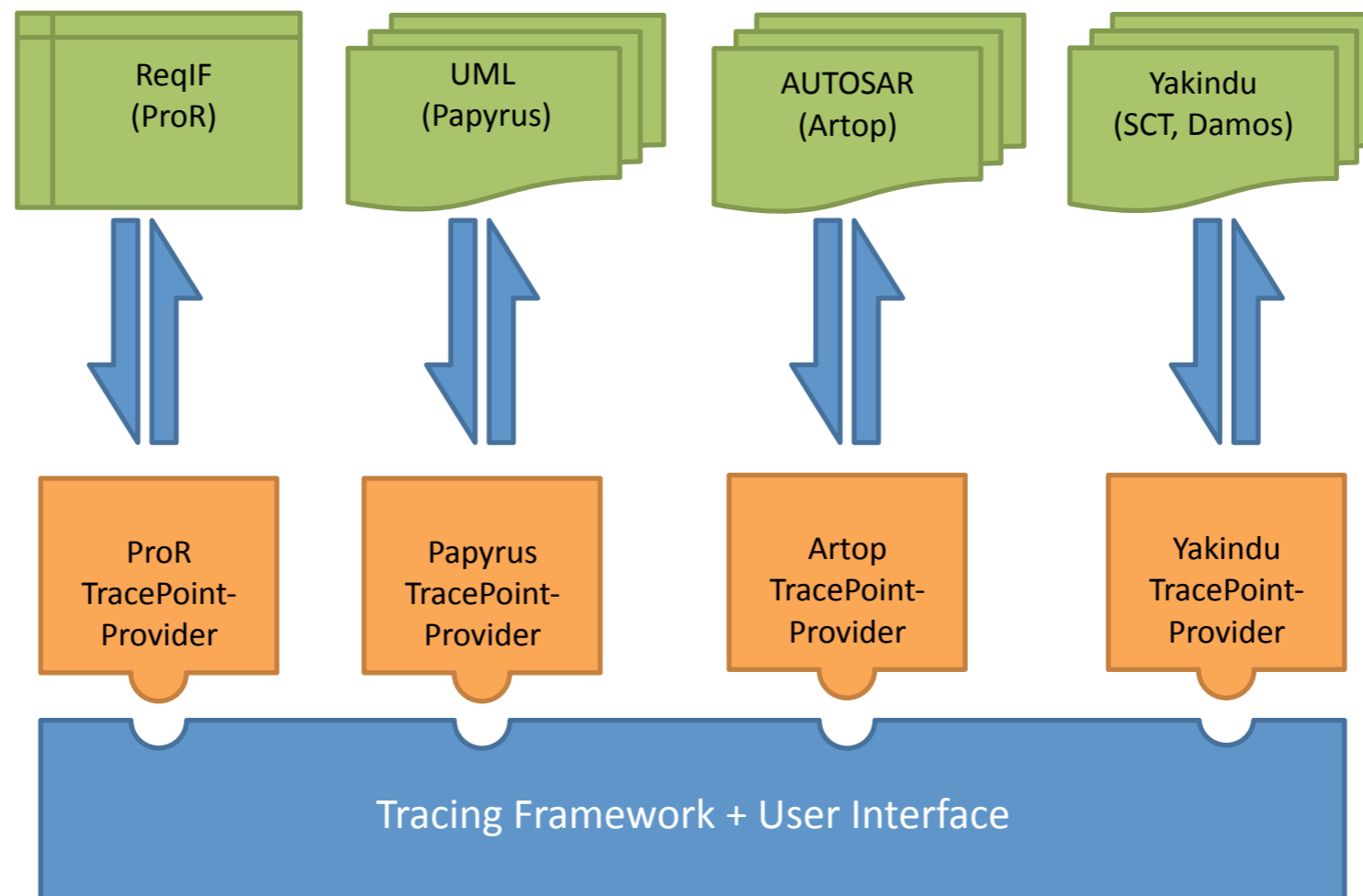
- Ecore Model, including serialization to XML
 - RIF 1.1a - done
 - RIF 1.2 - done
 - ReqIF Beta2 - done
- Derived from the specification by model transformation
- Driven by itemis
- EPL (Eclipse Public License)
- Currently submitting an Eclipse project proposal

Traceability with CReMa

- CReMa - Cross Relational Manager
- Modular & extendable architecture
- Non invasive - don't change the target models
- Targets: requirements, models, code
- Result: any relationships in any context



YAKINDU CReMa



TracePoint A	TracePoint B
RIF://ID-238	UML://GUID-FF-AD-3M
RIF://ID-238	RES://model.uml
UML://GUID-0B-CD-DD	SCT://_hb3fr1654h6

! ?



Questions & Comments